

Group Theory Notes

Harsh Jaluka

Contents

1	List of groups with definitions and representations	2
1.1	$SO(3) : \{R \in Aut(\mathbb{V}), R^T R = 1, det(R) = 1\}$	2
1.2	$SU(2)$	3
1.3	$Sp(1)$	3
1.4	S_3	3
1.5	Other groups	4
2	Definitions	5
3	Isomorphisms	6
4	Notation	6
5	Maps	7

1 List of groups with definitions and representations

1.1 $SO(3) : \{R \in Aut(\mathbb{V}), R^T R = 1, \det(R) = 1\}$

- “Special Orthogonal Group” (“3D rotation group”)
- $SO(3) \subset Aut(\mathbb{R}^3)$
- Fundamental/defining/vector representation is the identity map
- Lie algebra $\mathfrak{so}(3) = \{r \in End(\mathbb{V}); r^T = -r\}$
 - an (imaginary) basis: $J_k := i\vec{e}_k^\times \in i\mathfrak{so}(3) \subset \mathfrak{so}(3, \mathbb{C})$
 - defining representation $\rho_{\mathfrak{so}(3)}(J_k) = i\vec{e}_k^\times \in i\mathfrak{so}(3) \subset iEnd(\mathbb{R}^3)$
 - Lie bracket expansion: $\llbracket J_i, J_j \rrbracket = i\epsilon_{ijk} J_k$
 - N -dimensional irrep labelled by non-negative ‘spin’ $j = \frac{1}{2}(N-1)$
 - * representation space spanned by

$$|m\rangle, \quad m \in \{-j, -j+1, \dots, j-1, j\}$$

- * action of generators $J_z, J_\pm = J_x \pm iJ_y$

$$\begin{aligned} \rho(J_z) |m\rangle &= m |m\rangle \\ \rho(J_\pm) |m\rangle &= c_m^\pm |m \pm 1\rangle \end{aligned}$$

where

$$c_m^\pm = \sqrt{(j \mp m)(j \pm m + 1)}$$

- * unitarity

$$\rho(J_z)^\dagger = \rho(J_z), \quad \rho(J_+)^\dagger = \rho(J_-)$$

- * application: spherical harmonics (TODO)
- * character polynomial

$$P_j(q) = \sum_{k=0}^{2j} q^{2k-2j} = \frac{q^{2j+1} - q^{-2j-1}}{q - q^{-1}}$$

- * the tensor product of two representations with spin j and j' yields

$$P_{j \otimes j'}(q) = P_j(q)P_{j'}(q) = \frac{q^{2j+1} - q^{-2j-1}}{q - q^{-1}} \frac{q^{2j'+1} - q^{-2j'-1}}{q - q^{-1}}$$

$$= \sum_{k=0}^{2j'} P_{j+j'-k}(q)$$

w in the last step, assume $j' \leq j$. If not, $P_{-k} = -P_{k-1}$

– Casimir invariant $C = J_k \otimes J_k = J_z \otimes J_z + \frac{1}{2}J_+ \otimes J_- + \frac{1}{2}J_- \otimes J_+$ with

$$\rho(C)|m\rangle = j(j+1)|m\rangle$$

1.2 $SU(2)$

- double cover of $SO(3)$
- Lie algebra $\mathfrak{su}(2) = \{m \in \text{End}(\mathbb{C}^2); m = -m^\dagger, \text{tr}(m) = 0\}$
 - an (imaginary) basis: $J_k = \frac{1}{2}\sigma_k \in i\mathfrak{su}(2)$ where σ_k Pauli matrices
 - defining representation $\rho_{\mathfrak{su}(2)}(J_k) = \frac{1}{2}\sigma_k \in i\mathfrak{su}(2) \subset \text{End}(\mathbb{C}^2)$
 - Lie bracket expansion: $\llbracket J_i, J_j \rrbracket = i\epsilon_{ijk}J_k$

1.3 $Sp(1)$

- Lie algebra $\mathfrak{sp}(1)$
 - defining representation $\rho_{\mathfrak{sp}(1)}(-iJ_x) = \frac{1}{2}\hat{\mathbf{i}}$ and similarly $J_y \rightarrow \hat{\mathbf{j}}$ and $J_z \rightarrow \hat{\mathbf{k}}$
 - * symplectic

$$\rho_{\mathfrak{sp}(1)}(a)^\dagger = -\rho_{\mathfrak{sp}(1)}(a)$$

1.4 S_3

- $|S_3| = 3! = 6$ elements
- all elements can be written in terms of two elementary permutations σ_1, σ_2 which satisfy $(\sigma_1)^2 = (\sigma_2)^2 = (\sigma_1\sigma_2)^2 = 1$
- can be viewed as symmetry group of an equilateral triangle
-

1.5 Other groups

1. $SO(2)$: orthogonal matrices with unit determinant
2. (Reals, +)
3. $O(2)$
 - dihedral group is a subgroup
4. (Reals/0, x)
5. S_n , $n > 1$
 - “symmetric group”
 - all $n!$ permutations of a set of n elements
6. $U(1)$: set of unitary 1×1 matrices (unitary: conjugate transpose = inverse)
7. $G(1) = R_\phi(1) : \phi \in R/2\pi Z$
8. $Aut(\mathbb{R}^3)$
9. $Spin(3)$
10. $O(3) = \{R \in Aut(\mathbb{R}^3); R^T R = 1\}$
 - “group of reflections”
 - Lie algebra $\mathfrak{so}(3) = \{r \in End(\mathbb{V}); r^T = -r\}$
11. $C_n = \mathbb{Z}_N = \mathbb{Z}/n\mathbb{Z}$, $n > 1$
 - “cyclic group”
 - integers modulo n under addition
 - abelian
12. $SU(2)_L \times SU(2)_R$
 - double cover of $SO(4)$
13. $\{e\}$
 - “trivial group”
14. A_n , $n > 1$
 - “alternating group”
 - all $n!/2$ even permutations of a set of n elements

2 Definitions

- Lie group: a group whose set G is a differentiable manifold and whose composition rule and inversion are smooth maps on this manifold
- universal cover of a group: a bigger group which contains the original group and is simply connected
- abelian: $ab = ba$
- automorphism: invertible linear transformation from \mathbb{V} to itself
- endomorphism: linear map from \mathbb{V} to itself
- composition rule: group operation (eg addition for group of reals equipped with $+$)
- For any Lie group there is a corresponding Lie algebra with a Lie bracket
 - tangent space of a group at the identity
 - not associative
 - when the Lie algebra is given in terms of matrices, i.e. $\mathfrak{g} \subset \text{End}(\mathbb{V})$, the matrix commutator and the Lie bracket coincide.
- quaternions \mathbb{H} : number field spanned by $1, \hat{\mathbf{i}}, \hat{\mathbf{j}}, \hat{\mathbf{k}}$ with
 - products given by $\hat{\mathbf{i}}\hat{\mathbf{j}} = -\hat{\mathbf{j}}\hat{\mathbf{i}} = \hat{\mathbf{k}}$ and cyclic permutations (\implies non commutativity)
 - closely related to Pauli matrices

$$(1, \hat{\mathbf{i}}, \hat{\mathbf{j}}, \hat{\mathbf{k}}) \equiv (1, -i\sigma_x, -i\sigma_y, -i\sigma_z)$$

- Casimir operator $C \in \mathfrak{g} \otimes \mathfrak{g}$ with $\llbracket a, C \rrbracket = 0, \forall a \in \mathfrak{g}$ where

$$\llbracket a, b \otimes c \rrbracket := \llbracket a, b \rrbracket \otimes c + b \otimes \llbracket a, c \rrbracket$$

- any representation $\rho : \mathfrak{g} \rightarrow \text{End}(\mathbb{V})$ can be lifted to $\rho : \mathfrak{g} \otimes \mathfrak{g} \rightarrow \text{End}(\mathbb{V})$ with

$$\rho(a \otimes b) := \rho(a)\rho(b)$$

- tensor product of Lie algebra representations $\rho_{\otimes} : \mathfrak{g} \rightarrow \text{End}(\mathbb{V}_{\otimes})$ defined as

$$\rho_{\otimes} := \sum_{k=1}^N 1 \otimes \cdots \otimes 1 \otimes \rho_k \otimes 1 \otimes \cdots \otimes 1$$

where $\rho_k : \mathfrak{g} \rightarrow \text{End}(\mathbb{V}_k), k = 1, \dots, N$

- direct sum of Lie algebra representations $\rho_{\oplus} : \mathfrak{g} \rightarrow \text{End}(\mathbb{V}_{\oplus})$ defined as

$$\rho_{\oplus} := \rho_1 \oplus \cdots \oplus \rho_N$$

- character polynomials: define a group element $g(q)$ depending on a formal variable q

$$g(q) = \exp(2 \log(q) J_z) = q^{2J_z}$$

define the character as

$$P_{\rho}(q) = \text{tr } \rho(g(q)) = \sum_k n_k q^{2m_k}$$

where m_k eigenvalues of J_z and n_k corresponding multiplicities

- $q = 1$ gives dimension
- have the property

$$\begin{aligned} P_{\rho \otimes \rho'}(q) &= P_{\rho}(q) P_{\rho'}(q) \\ P_{\rho \oplus \rho'}(q) &= P_{\rho}(q) + P_{\rho'}(q) \end{aligned}$$

–

3 Isomorphisms

- $\mathfrak{so}(3) \equiv \mathfrak{su}(2) \equiv \mathfrak{sp}(1)$
- $\text{Spin}(3) \equiv \text{SU}(2) \equiv \text{Sp}(1) \equiv S^3 \equiv D_3$
- $\text{SO}(3) \equiv \text{SU}(2)/\mathbb{Z}_2$
- icosahedral $\equiv A_5$
- $T \equiv A_4$
- $T_d \equiv O \equiv S_4$

4 Notation

- gothic script represents Lie algebras
- \vec{v}^{\times} denotes the 3×3 anti-symmetric matrix that defines the cross product of \vec{v} with an arbitrary vector \vec{w} via matrix multiplication: $\vec{v}^{\times} \vec{w} = \vec{v} \times \vec{w}$

$$\vec{v}^{\times} := \begin{bmatrix} 0 & -v_z & +v_y \\ +v_z & 0 & -v_x \\ -v_y & +v_x & 0 \end{bmatrix}$$

5 Maps

- adjoint action: $Ad(R) : \mathfrak{g} \rightarrow \mathfrak{g}$ such that $Ad(R)(a_1) := Ra_1R^{-1} =: a_2$ with $a_1, a_2 \in \mathfrak{g}$
- adjoint representation: $Ad : G \rightarrow Aut(\mathfrak{g})$
- adjoint action $ad : \mathfrak{g} \rightarrow End(\mathfrak{g})$ is a linear map such that

$$- ad(a_2)a_1 = a_2a_1 - a_1a_2$$

- “Lie bracket” $[[,]] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$
 - anti-symmetric: $[[a, b]] = -[[b, a]]$
 - Jacobi identity satisfied: $[[a, [[b, c]]]] + [[b, [[c, a]]]] + [[c, [[a, b]]]] = 0$

- exponential map $\exp : \mathfrak{g} \rightarrow G$
 - If matrix group $G \subset Aut(\mathbb{V})$ or if representation $\rho : G \rightarrow Aut(\mathbb{V})$, it coincides with the matrix exponential $\exp : End(\mathbb{V}) \rightarrow Aut(\mathbb{V})$

$$\exp a = \sum_{n=0}^{\infty} \frac{1}{n!} a^n$$

- $\exp a \exp b = \exp C(a, b)$ where $C(a, b)$ Baker-Campbell-Hausdorff formula:

$$C(a, b) = a + b + \frac{1}{2}[[a, b]] + \frac{1}{12}[[a, [[a, b]]]] + \frac{1}{12}[[b, [[b, a]]]] + \dots$$

- $(\exp a)^{-1} = \exp(-a)$
- Lie algebra representation $\rho : \mathfrak{g} \rightarrow End(\mathbb{V})$ such that

$$\rho([[a, b]]) = [\rho(a), \rho(b)]$$

- trivial representation $\rho_0 : \mathfrak{g} \rightarrow End(\mathbb{V})$ with $\rho_0(J_k) = 0$
- adjoint representation $ad : \mathfrak{g} \rightarrow End(\mathfrak{g})$ with $[[a, b]] = ad(a)b$