1. Connection lidar

2. enable block "save trajectoire"
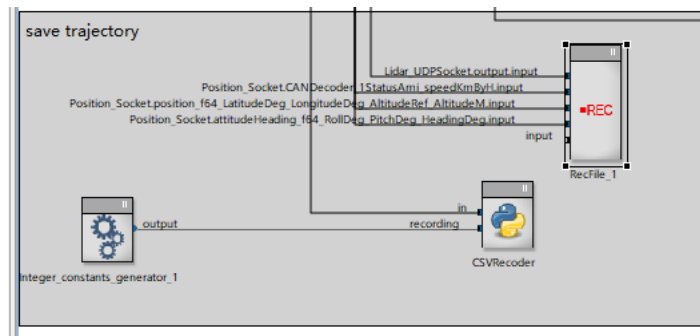
3. Changing the data storage path

Rec data: ;

RecFile_1
RecFile 2.16.0

Path	C:/Users/asus/Documents

Trajectory data:

Open editor :
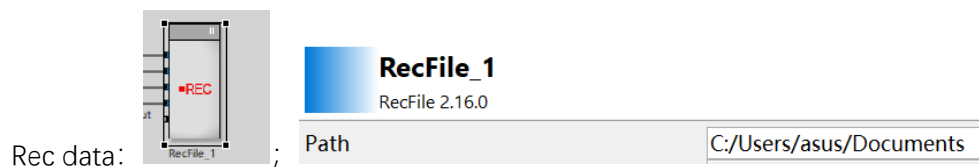
```python
def Birth(self):#Once per execution of the entire project procedure
    print("Python Birth")
    self.trajectoryFile = open("./trajfrainage.csv", "w+") #Create a
    self.trajectoryFile.close()
```

Start driving and you'll get the appropriate data.

After got the data, you disable block "save trajectory" and read "HowToUseData"