➢ First add the rec file to the 'play' module

File   C:/Users/asus/Desktop/20230601_111928_RecFile_1/RecFile_1_20230601_111928
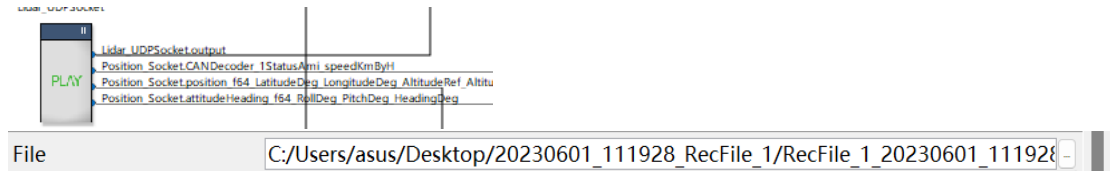
Connecting four outputs

1. Lidar UDPS: ;   2 . CANDecoder:

3. f64 Latitude :   ;   4 . f64 Roll :
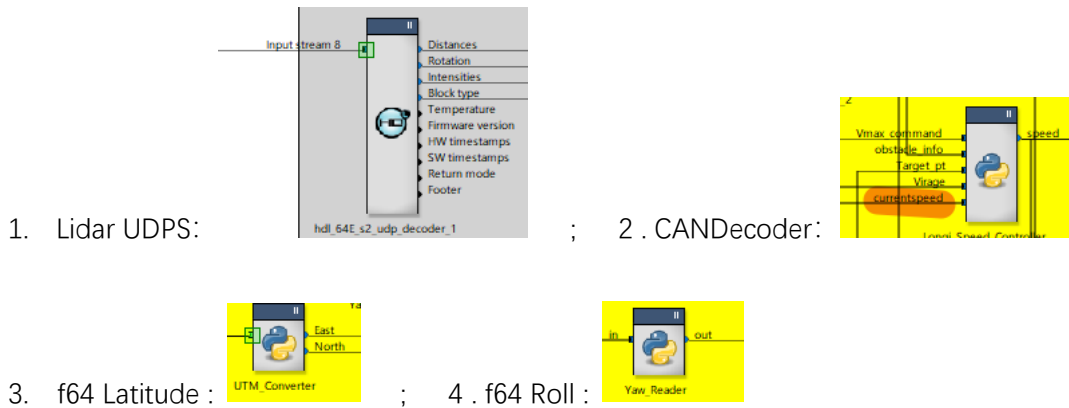
➢ Change the trajectories in python Bridge "Change_Coordinates"
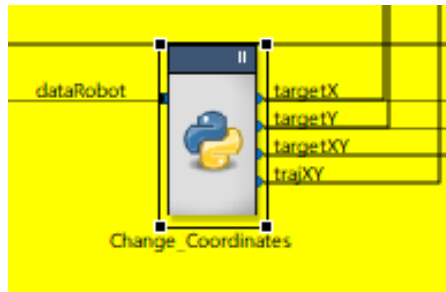
Open editor :

```
    self.add_output("trajXY", rtmaps.types.AUTO, buffer_size=1000)

def Birth(self):
    print("Python Birth")
    self.i = 0
    self.path = "./trajtest.csv"
    self.dist2sec = 5.   #Changing the size increases the point of the guide line
```

Entre your trajectory