

Theoretical Computer Science

Unit 5: Turing Machine

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Lecture No 45: Turing Machine Examples (Part-2)



Example 3:

Q. Design Turing Machine for odd length palindrome over $\Sigma = \{0,1\}$.

Language $L = \{010, 101, 01010, \dots\}$

Logic :

- Take the first character (either 0 or 1), mark it as '*' and move right till the blank symbol
- After blank move left. If the last character matches with the first character then mark it as blank symbol
- In the same way, repeat above cycle to match second symbol with second last symbol and so on.

$$\Sigma = \{ 0, 1 \}$$

$$\Gamma = \{ 0, 1, *, B \}$$

Initial state : q_0

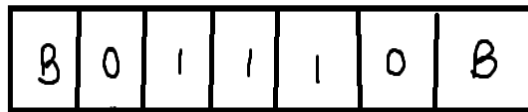
Final state : q_f



Logic in Detail

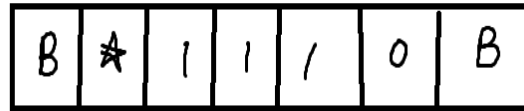
- q0- Take the first character (either 0 or 1) mark it as '*' and move right
- q1- Search for blank symbol, keep as it is and then move left. While doing this skip all 0's and 1's
- q2- Check whether the symbol from left is similar to symbol from right . If yes then mark it as **'B' (If read 0 in state q0)**
- q3- Move left to search for '*'. While doing this skip all 0's and 1's.
- q4- Search for blank symbol, keep as it is and then move left. While doing this skip all 0's and 1's
- q5- Check whether the symbol from left is similar to symbol from right. If yes then mark it as **'B'. (If read 1 in state q0)**
- q6-Move left to search for '*'. While doing this skip all 0's and 1's.
- qf- On q2 and q5 states after moving left if we get '*' that means all symbols are over. then reach to final state i.e. qf.

Consider input string– 01110



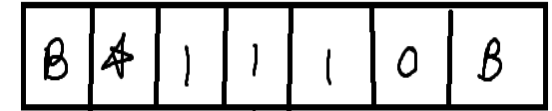
q_0

$\delta(q_0, 0) \rightarrow (q_1, *, R)$



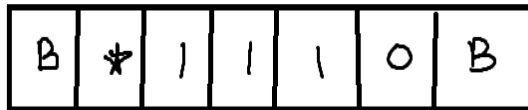
q_1

$\delta(q_1, 1) \rightarrow (q_1, 1, R)$



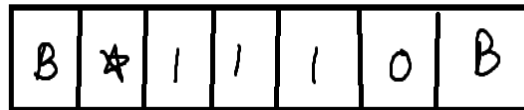
q_1

$\delta(q_1, 1) \rightarrow (q_1, 1, R)$



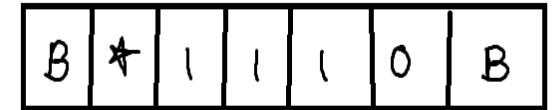
q_1

$\delta(q_1, 1) \rightarrow (q_1, 1, R)$



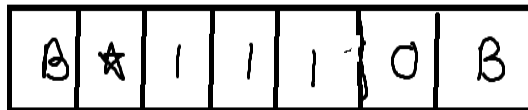
q_1

$\delta(q_1, 0) \rightarrow (q_1, 0, R)$



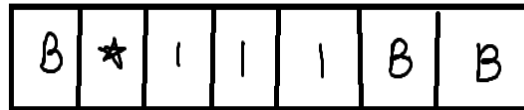
q_1

$\delta(q_1, B) \rightarrow (q_2, B, L)$



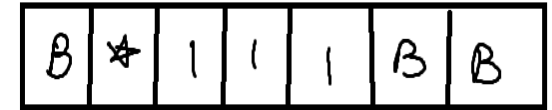
q_2

$\delta(q_2, 0) \rightarrow (q_3, B, L)$



q_3

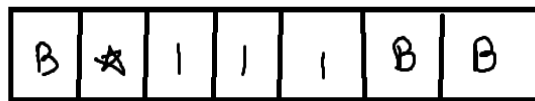
$\delta(q_3, 1) \rightarrow (q_3, 1, L)$



q_3

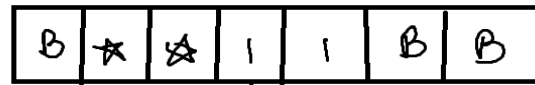
$\delta(q_3, 1) \rightarrow (q_3, 1, L)$





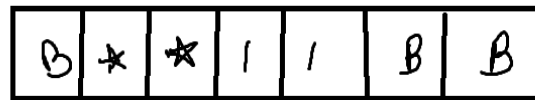
q_3

$\delta(q_3, 1) \rightarrow (q_3, 1, L)$



q_4

$\delta(q_4, 1) \rightarrow (q_4, 1, R)$



q_5

$\delta(q_5, 1) \rightarrow (q_6, \text{B}, L)$



q_0

$\delta(q_0, 1) \rightarrow (q_4, *, R)$



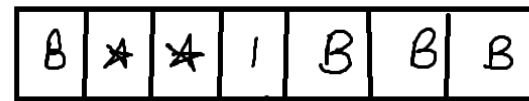
q_3

$\delta(q_3, *) \rightarrow (q_0, *, R)$



q_4

$\delta(q_4, 1) \rightarrow (q_4, 1, R)$



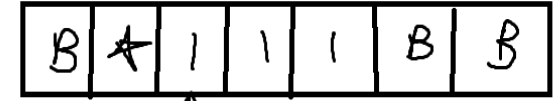
q_6

$\delta(q_6, 1) \rightarrow (q_6, 1, L)$



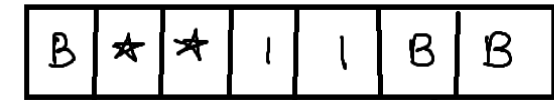
q_4

$\delta(q_4, B) \rightarrow (q_5, B, L)$



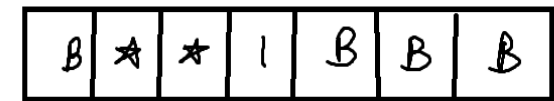
q_0

$\delta(q_0, 1) \rightarrow (q_4, *, R)$



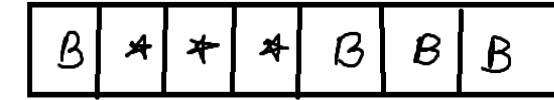
q_4

$\delta(q_4, B) \rightarrow (q_5, B, L)$



q_6

$\delta(q_6, *) \rightarrow (q_0, *, R)$



q_5

$\delta(q_5, *) \rightarrow (q_f, *, S)$

$q_5 \rightarrow q_f \text{ (Accept)}$

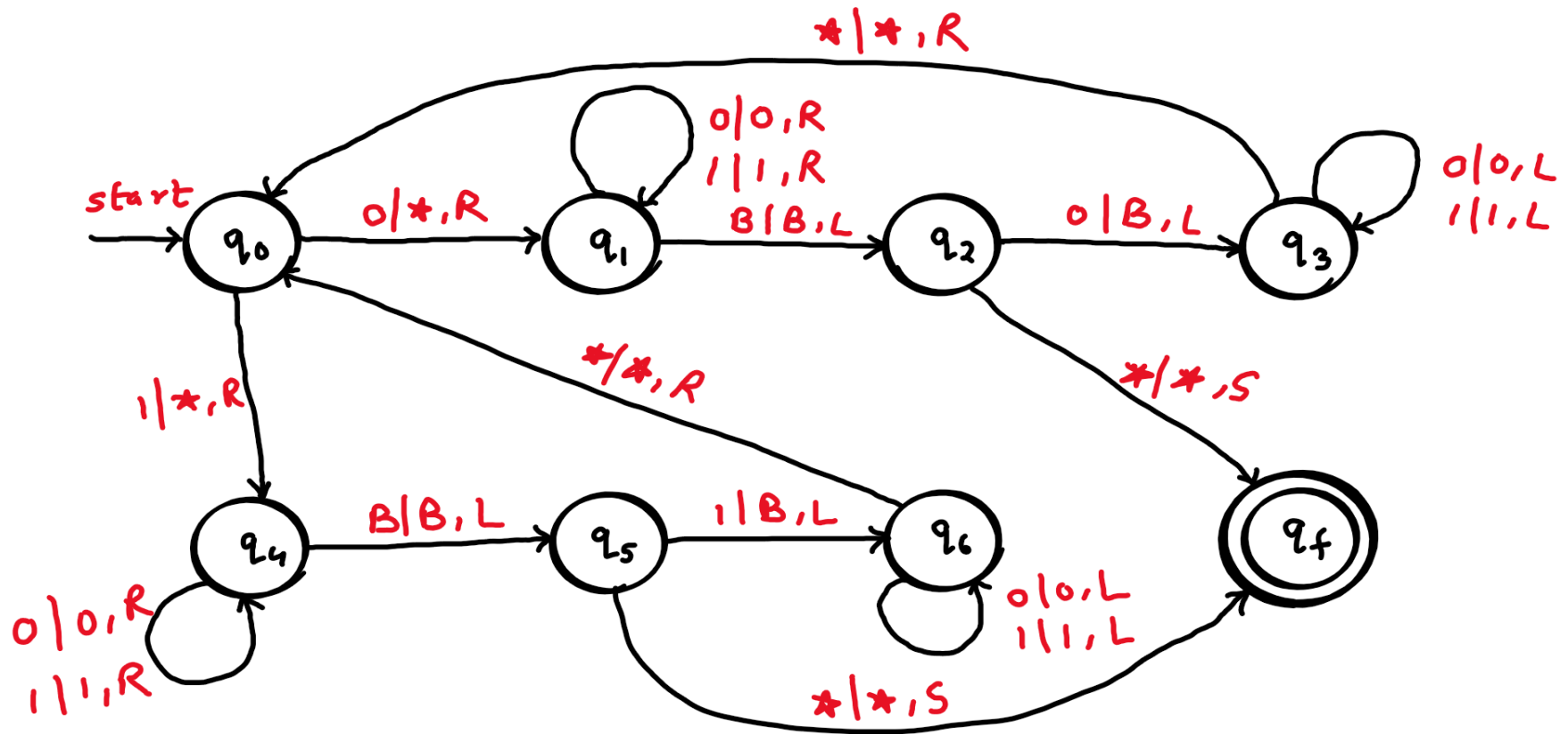


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NAVI MUMBAI

Q \ Γ	0	1	*	B
q0	(q1, *, R)	(q4, *, R)	-	-
q1	(q1, 0, R)	(q1, 1, R)	-	(q2, B, L)
q2	(q3, B, L)	-	(qf, *, S)	-
q3	(q3, 0, L)	(q3, 1, L)	(q0, *, R)	-
q4	(q4, 0, R)	(q4, 1, R)	-	(q5, B, L)
q5	-	(q6, B, L)	(qf, *, S)	-
q6	(q6, 0, L)	(q6, 1, L)	(q0, *, R)	-
qf*	Final State			



Transition Diagram



Example 4:

Q. Design Turing Machine for even length palindrome over $\Sigma = \{a,b\}$.

Language $L = \{abba, baab, \dots\}$

Logic :

- Take the first character (either a or b), mark it as '*' and move right till the blank symbol
- After blank move left. If the last character matches with the first character then mark it as blank symbol
- In the same way, repeat above cycle to match second symbol with second last symbol and so on.

$$\Sigma = \{ a, b \}$$

$$\Gamma = \{ a, b, *, B \}$$

Initial state : q_0

Final state : q_f



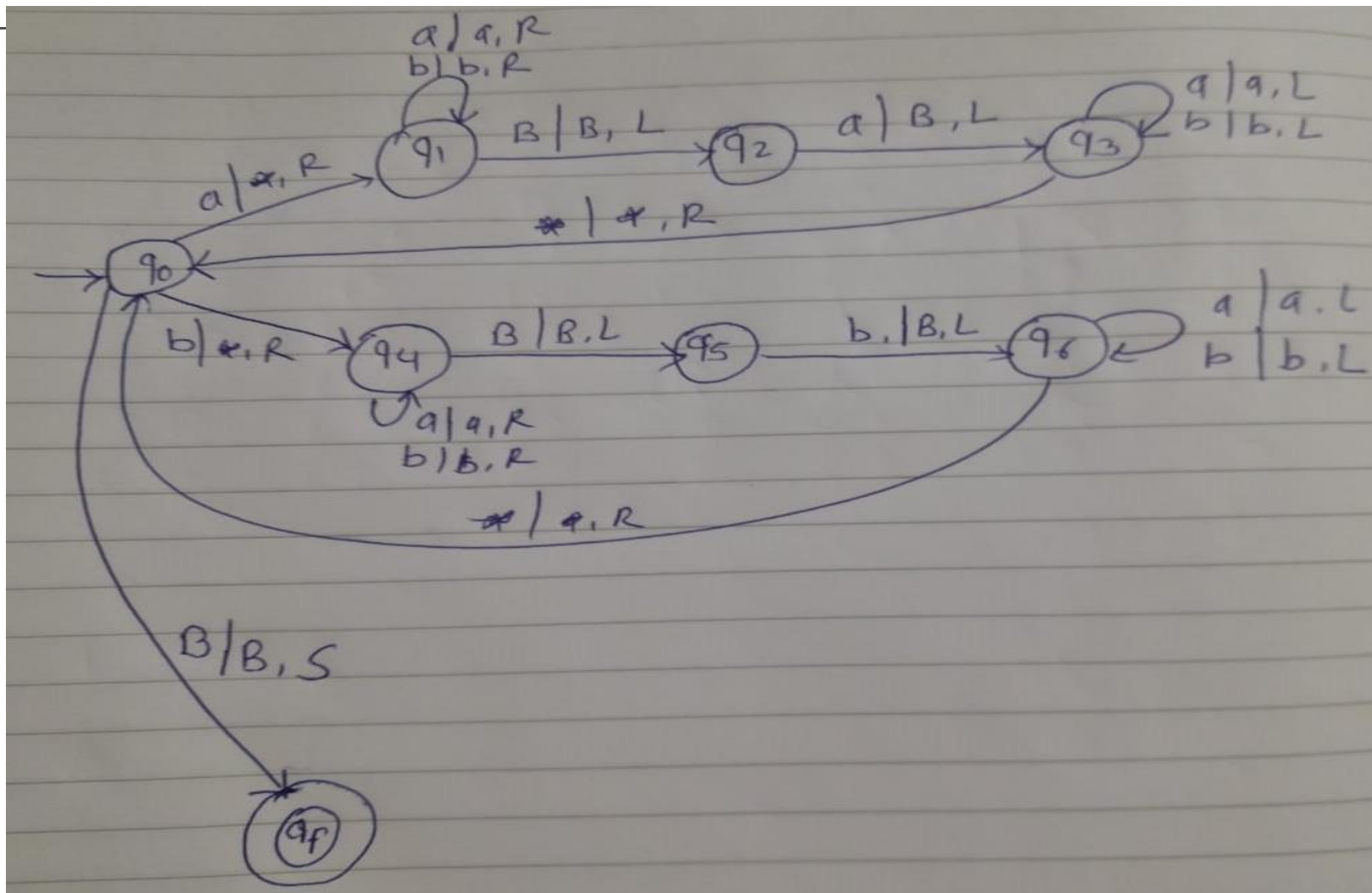
Logic in Detail

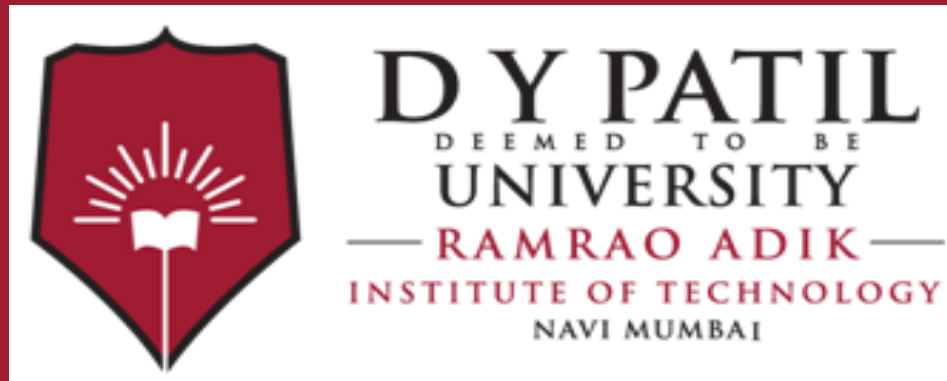
- q0- Take the first character (either a or b) mark it as '*' and move right
- q1- Search for blank symbol, keep as it is and then move left. While doing this skip all a's and b's
- q2- Check whether the symbol from left is similar to symbol from right . If yes then mark it as 'B' **(If read a in state q0)**
- q3- Move left to search for '*'. While doing this skip all a's and b's.
- q4- Search for blank symbol, keep as it is and then move left. While doing this skip all a's and b's
- q5- Check whether the symbol from left is similar to symbol from right. If yes then mark it as 'B'. **(If read b in state q0)**
- q6-Move left to search for '*'. While doing this skip all a's and b's.
- qf- On q0 state after moving right if we get 'B' that means all symbols are over. then reach to final state i.e. qf.

Q \ Γ	a	b	*	B
q0	(q1, *, R)	(q4, *, R)	-	(qf, B, S)
q1	(q1, a, R)	(q1, b, R)	-	(q2, B, L)
q2	(q3, B, L)	-	-	-
q3	(q3, a, L)	(q3, b, L)	(q0, *, R)	-
q4	(q4, a, R)	(q4, b, R)	-	(q5, B, L)
q5	-	(q6, B, L)	-	-
q6	(q6, a, L)	(q6, b, L)	(q0, *, R)	-
qf*	Final State			



Transition Diagram





Thank You

Lecture No 46: Turing Machine Examples (Part-3)



Turing Machine as Function Generator

- Turing machine can compute some functions.
- Its plays a role of function generator.
- TM can perform various arithmetic operations such as addition, subtraction, multiplication and so on.

Example 5:

Q. Design Turing Machine to perform addition of two unary numbers.

- In unary number system,

Value of any number(unary) = Number of 0's

where, 0 is used to represent the unary number.

- The required number will be represented in following format :

$$- (2)_{10} = 00$$

$$- (3)_{10} = 000$$

- Let us assume we want to add two numbers 2 and 3 i.e. (2+3)
- In order to separate the numbers on the tape we will use symbol “1” as a separator.
- Hence, the contents of input tape for numbers 2 and 3 will be :

B	0	0	1	0	0	0	B
---	---	---	---	---	---	---	---

- After addition of 2 and 3, the number of 0's on tape must be 5.
- Thus the output on tape will be as shown below:

B	0	0	0	0	0	B
---	---	---	---	---	---	---



Example 5: (cont..)

$$\Sigma = \{ 0, 1 \}$$

Logic :

q0- Bypass all 0's of first number and move right to search '1'

q1- When we get '1' make it '0' and move right till blank symbol.

q2-After second step there will be one extra '0' on tape. Therefore, when we get blank symbol move left and make the last '0' as blank symbol.

qf- Final state

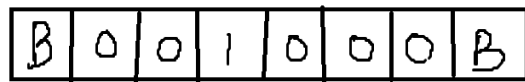
$$\Gamma = \{ 0, 1, B \}$$

Initial state : q_0

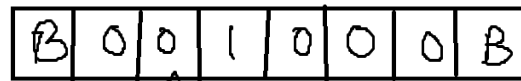
Final state : q_f



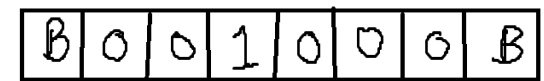
Example Processing : Addition of 2 and 3



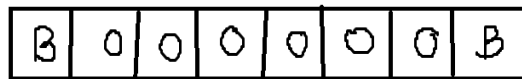
$\delta(q_0, 0) \rightarrow (q_0, 0, R)$



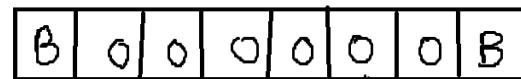
$\delta(q_0, 0) \rightarrow (q_0, 0, R)$



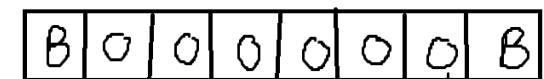
$\delta(q_0, 1) \rightarrow (q_1, \textcolor{red}{0}, R)$



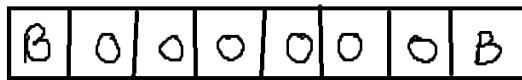
$\delta(q_1, 0) \rightarrow (q_1, 0, R)$



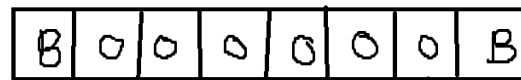
$\delta(q_1, 0) \rightarrow (q_1, 0, R)$



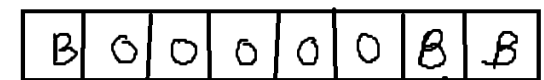
$\delta(q_1, 0) \rightarrow (q_1, 0, R)$



$\delta(q_1, B) \rightarrow (q_2, B, L)$



$\delta(q_2, 0) \rightarrow (q_f, B, S)$

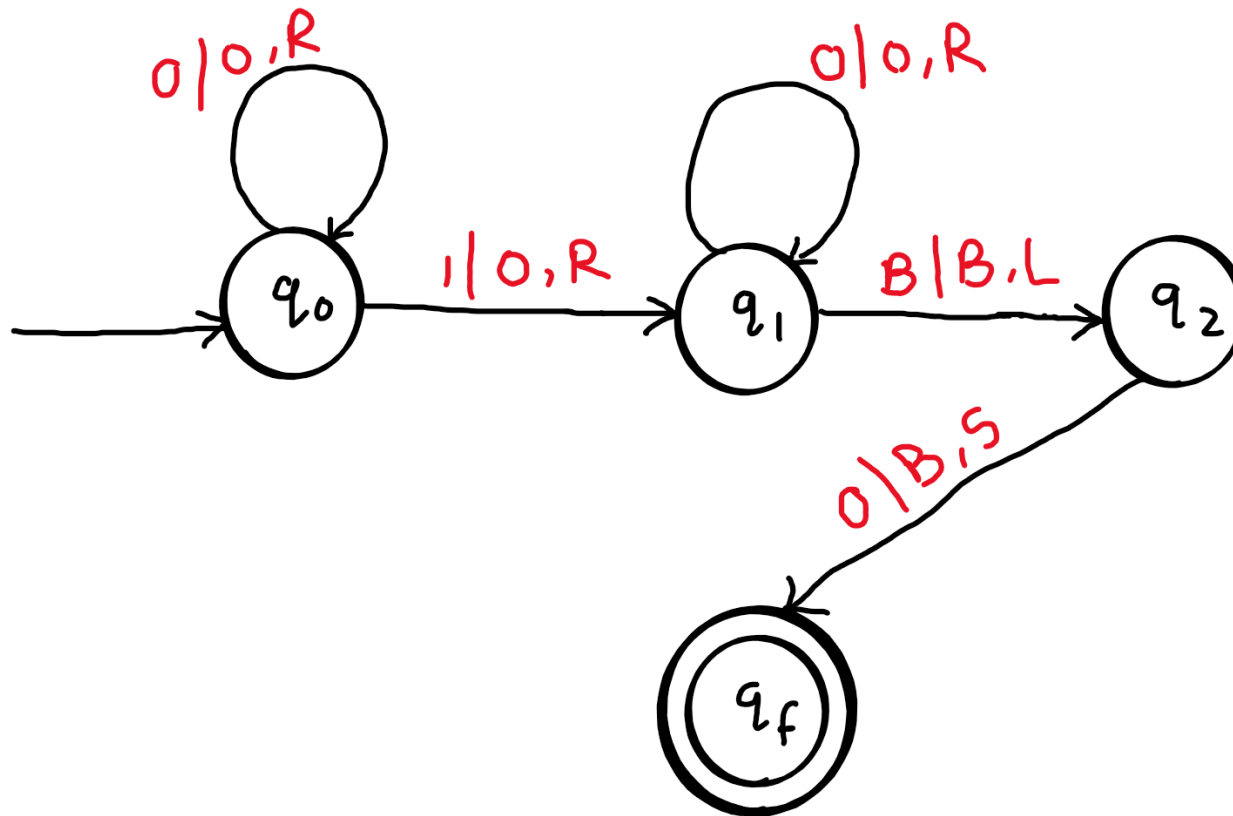


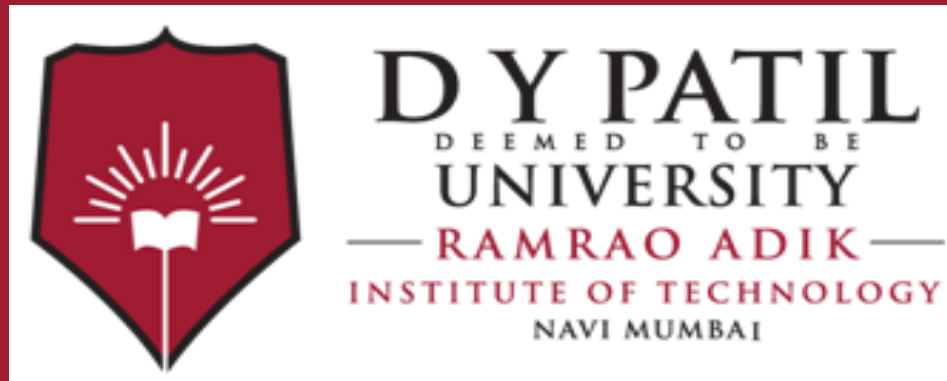
Transition Table

Q \ Γ	0	1	B
$\rightarrow q_0$	$(q_0, 0, R)$	$(q_1, 0, R)$	
q_1	$(q_1, 0, R)$		(q_2, B, L)
q_2	(q_f, B, S)		
q_f^*	Final State		



Transition Diagram





Thank You

Lecture No 47:

Turing Machine Variants, Universal TM



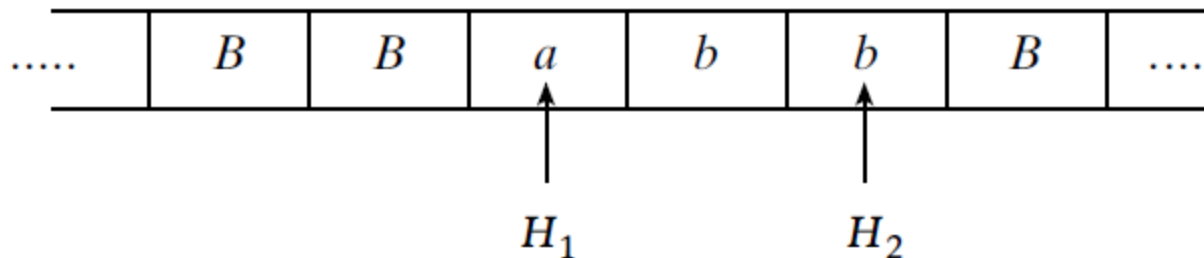
Variants of Turing Machine

- The Turing machine we have discussed so far is called as standard Turing machine
- In order to enhance the power of standard Turing machine many variations of it are suggested.
- Some of the variations are listed below:
 - Multi-Head Turing machine
 - Multi-Tape Turing machine
 - Non-deterministic Turing machine

Variants of Turing Machine (continue...)

Multi-head Turing Machine:

- A multi-head Turing machine contains two or more heads to read the symbols on the same tape.
- In one step all the heads sense the scanned symbols and move or write independently.



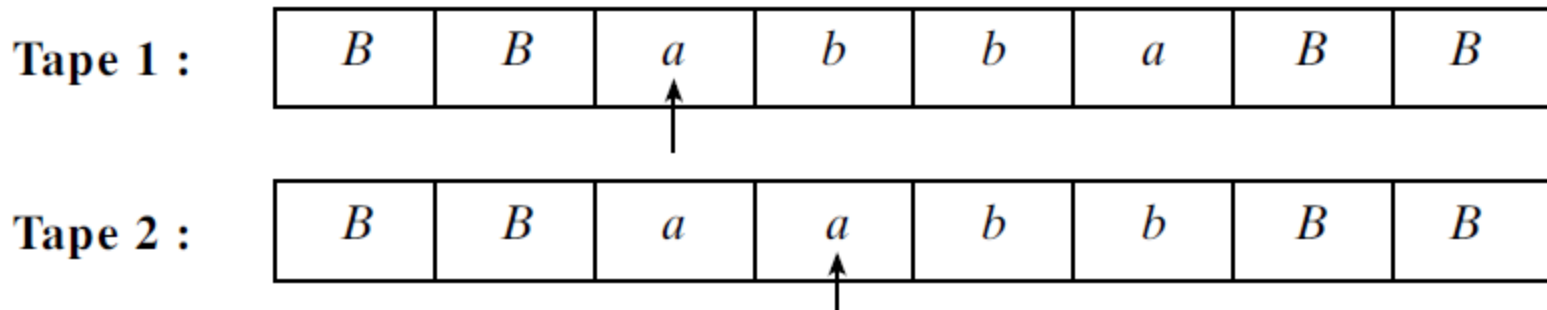
$\delta(\text{the state, symbol under head } H_1, \text{symbol under head } H_2) = (\text{New State}, (S_1, M_1), (S_2, M_2))$



Variants of Turing Machine (continue...)

Multi-tape Turing Machine:

- This type of Turing machine consists of multiple tapes each having an independent head. Each head is capable to perform read/ write operations and the movement includes left or right or no movement.



$\delta(\text{the state, symbol under head of Tape 1, symbol under head of Tape 2})$
 $= (\text{New State}, (S_1, M_1), (S_2, M_2))$



Variants of Turing Machine (continue...)

Non-deterministic Turing Machine:

- In case of standard Turing machine there exists only one possible transition from the current state for the current input. The standard Turing machine is also referred as Deterministic Turing machine.
- But, for non-deterministic Turing machine, it is possible that there are multiple transitions from the current state for the current input
- **Formal definition:** $M = \{Q, \Sigma, \sqsupset, \delta, q_0, F, B\}$

where,

Q : Finite set of states

Σ : Finite set of input symbols

\sqsupset : Finite set of tape symbols which include the blank symbol

δ : The transition function, $Q \times \Sigma \rightarrow 2^Q$ (Power set of Q)

q_0 : Initial state

F : Finite set of final states

B : Blank symbol



Universal Turing Machine

- A limitation of standard Turing Machines is that they are “hardwired”
they execute only one program
- Real Computers are re-programmable

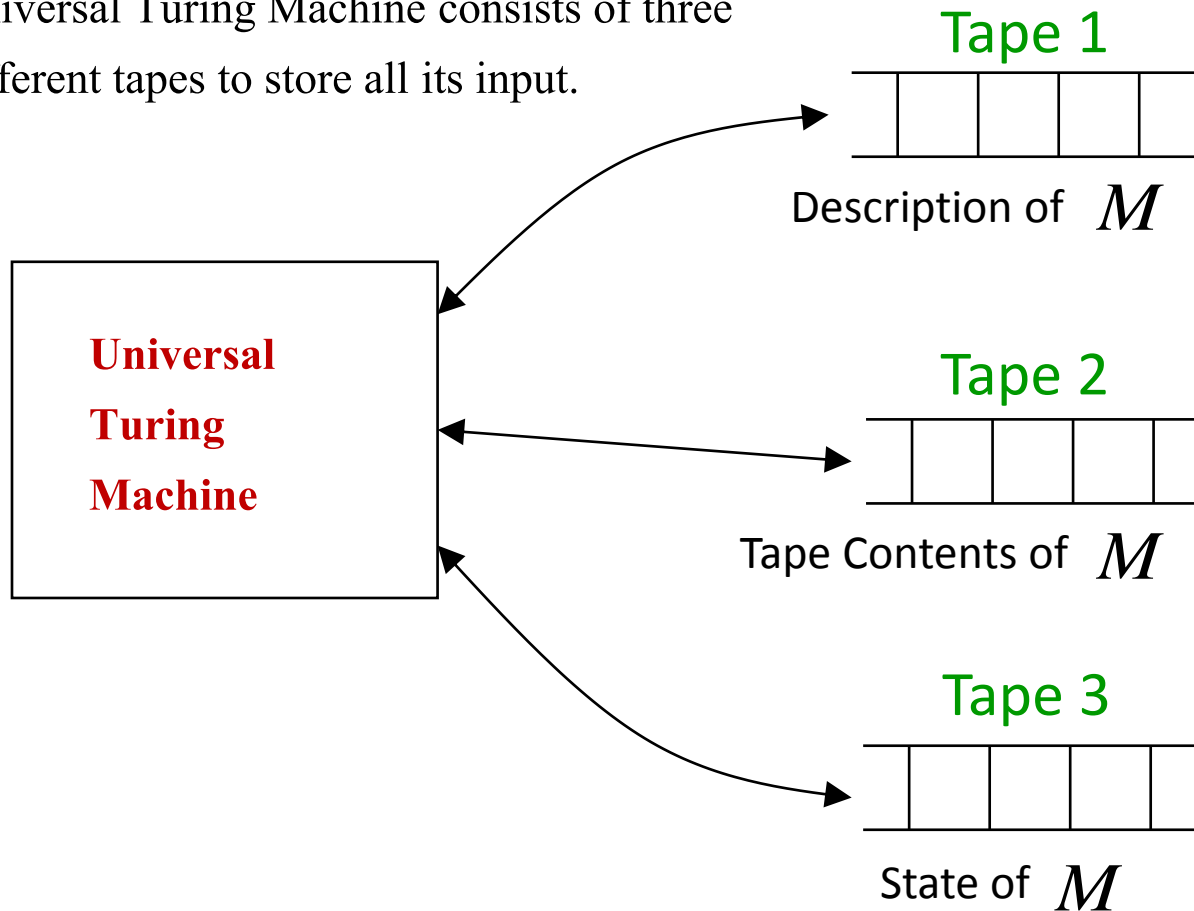
Solution: Universal Turing Machine

- We can construct a single Turing machine which can solve all sorts of problems.
- This type of Turing machine is called as Universal Turing Machine (UTM). Thus,
Universal Turing Machine is a Turing Machine which simulates any other Turing Machine for a given input.
- The input of this Universal Turing Machine consists of:
 - Description of transitions of other Turing machine M
 - Input string of other Turing machine M



Three tapes

Universal Turing Machine consists of three different tapes to store all its input.



Alphabet Encoding

Symbols: a b c d \dots

Encoding: 1 11 111 1111

Transition Encoding

States: q_1 q_2 q_3 q_4 \dots

Encoding: 1 11 111 1111

Transition: $\delta(q_1, a) = (q_2, b, L)$

Encoding: 10101101101

separator

Head Move Encoding

Move: L R

Encoding: 1 11



Alphabet Encoding (continue...)

Turing Machine Encoding

Transitions:

$$\delta(q_1, a) = (q_2, b, L)$$

$$\delta(q_2, b) = (q_3, c, R)$$

Encoding:

1 0 1 0 1 1 0 1 1 0 1 0 0 1 1 0 1 1 1 0 1 1 1 0 1 1

separator

Tape 1 contents of Universal Turing Machine:

binary encoding

of the simulated machine

M

Tape 1

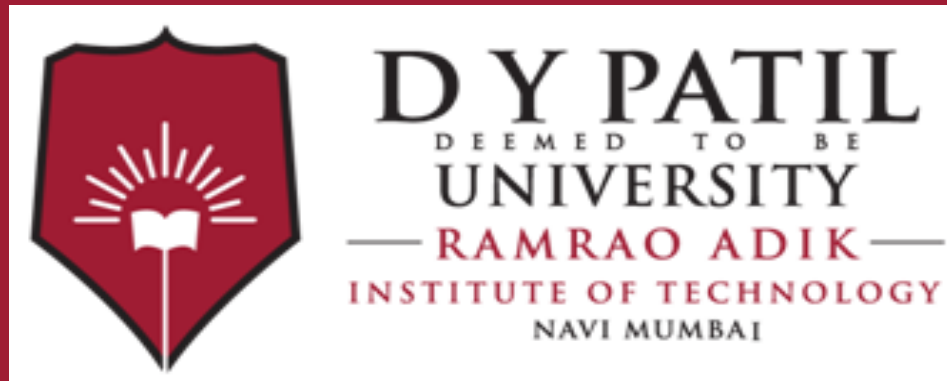
1 0 1 0 1 1 0 1 1 0 1 0 0 1 1 0 1 1 0 1 1 1 0 1 1 0 1 1 0 0 ...



Working

It reads current input and current state from the tape 2 and 3.

Then checks description stored on tape1 and do the transitions according to it.



Thank You