Political Methodology III: Model Based Inference

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Statistical Inference

- Model based inference:
- Assume: data generated via distributional process
- Defines a likelihood function: parameter values → likelihood of parameters, given data
- Derive estimators that identify values that maximize likelihood

 $\mathsf{General\ Likelihood\ Theory} \to \mathsf{Example} \to \mathsf{General\ Theory} \to \mathsf{Example}$

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We're going to be interested in making an inference about θ_0 using the observed data.

Assume we know the correct functional form for f– M^*

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- Idea: values of $\theta \in \Theta$ will be more likely if they make the observed data a higher probability

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We also are only able to infer most likely value given modeling assumptions

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$$y_i = 1$$
 or $y_i = 0$

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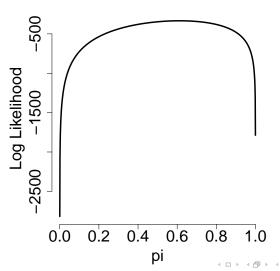
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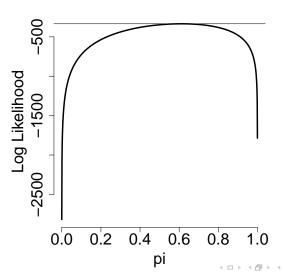
For a fixed set of observations, what does this look like?

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Example: Bernoulli Trials: Simulated Example with $\pi=0.6$



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Look for estimator that optimizes (log)-likelihood

$$l(\pi|\mathbf{y}) = \sum_{i=1}^{n} y_i \log \pi + (n - \sum_{i=1}^{n} y_i) \log(1 - \pi)$$

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$$\begin{array}{rcl} l(\pi|\mathbf{y}) & = & \sum_{i=1}^n y_i \log \pi + (n - \sum_{i=1}^n y_i) \log (1 - \pi) \\ & \underbrace{\frac{\partial l(\pi|\mathbf{y})}{\partial \pi}}_{\text{Score Function}} & = & \frac{\sum_{i=1}^n y_i}{\pi} - \frac{(n - \sum_{i=1}^n y_i)}{1 - \pi} \\ 0 & = & \frac{\sum_{i=1}^n y_i}{\pi^*} - \frac{(n - \sum_{i=1}^n y_i)}{1 - \pi^*} \\ & \underbrace{\frac{(n - \sum_{i=1}^n y_i)}{1 - \pi^*}}_{1 - \pi^*} & = & \underbrace{\sum_{i=1}^n y_i}_{\pi^*} \\ (n - \sum_{i=1}^n y_i) \pi^* & = & (1 - \pi^*) \sum_{i=1}^n y_i \\ & \pi^* n & = & \sum_{i=1}^n y_i \end{array}$$

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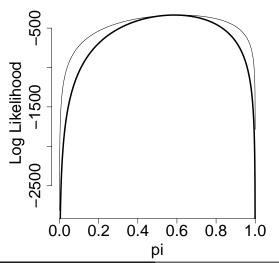
$$\underbrace{\frac{(n - \sum_{i=1}^{n} y_{i})}{1 - \pi^{*}}}_{\text{T}} = \underbrace{\frac{\sum_{i=1}^{n} y_{i}}{\pi^{*}}}_{\text{T}}$$

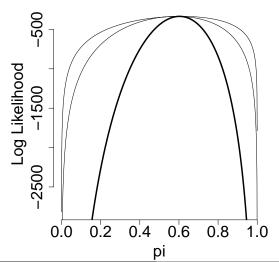
$$(n - \sum_{i=1}^{n} y_{i})\pi^{*} = (1 - \pi^{*})\sum_{i=1}^{n} y_{i}$$

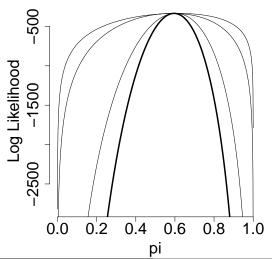
$$\pi^{*}n = \sum_{i=1}^{n} y_{i}$$

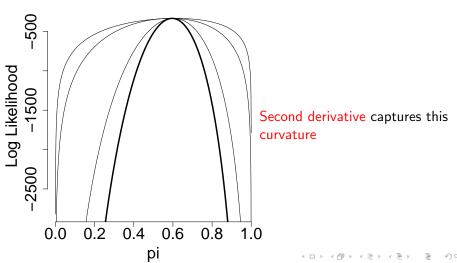
$$\pi^{*}n = \overline{y}$$

Uncertainty About Mode $\pi^* = \overline{y}$ maximizes $L(\pi|\mathbf{y})$.









The Fisher Information measures the information that y conveys about the parameter θ . Define it using the two equivalent definitions:

Definition

The Fisher Information for a log-likelihood $l(\theta|\mathbf{Y})$ is

$$I(\theta) = E \left[\left(\frac{\partial l(\theta | \mathbf{Y})}{\partial \theta} \right)^{2} | \theta \right]$$
$$= -E \left[\left(\frac{\partial^{2} l(\theta | \mathbf{Y})}{\partial \theta \partial \theta} \right) | \theta \right]$$

The observed Fisher information for a sample of n observations is given by

$$I_n(\theta) = -\frac{\partial^2}{\partial \theta^2} l(\theta | \boldsymbol{y})$$

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Inverting the information provides the asymptotic variance for the maximum likelihood estimator (under some regulatory conditions we will discuss later)

$$\begin{array}{lcl} \mathsf{Variance}(\theta^*) & = & \frac{1}{I_n(\theta^*)} \\ \\ \mathsf{Standard} \; \mathsf{Error}(\theta^*) & = & \sqrt{\frac{1}{I_n(\theta^*)}} \end{array}$$

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- Curvature determines sampling distribution of maximum likelihood estimator

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Large sample properties given incorrect model

1) The MLE gets as "close" as possible to the true answer

Definition

Consistent Let $\widehat{\theta}_n$ be an estimator for θ , with sample size n. Then $\widehat{\theta}_n$ converges in probability to θ if, for all $\epsilon>0$,

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Proposition

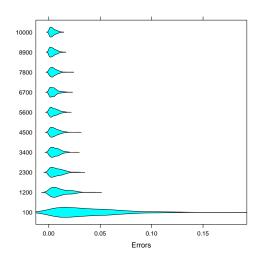
MLE is consistent: Assume y_1, y_2, \ldots, y_n are simple random samples from $p(y|\theta_0)$. Define θ_n^* as the mle estimator with sample size n.

Then, as $n \to \infty$, $\theta_n^* \to \theta_0$ (in probability)

Simulated example with $\pi=0.6$ and increasing n

Simulated example with $\pi=0.6$ and increasing n Distribution of $|\pi^*-0.6|$

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 $\widehat{\theta}_n$, with cdf $F_n(x)$, converges in distribution to random variable Y with cdf F(x) if

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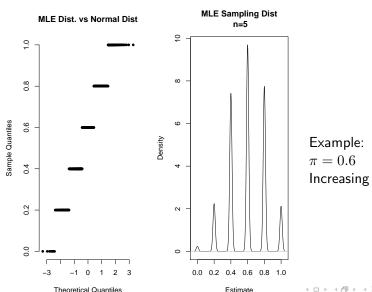
- MLE central limit theorem

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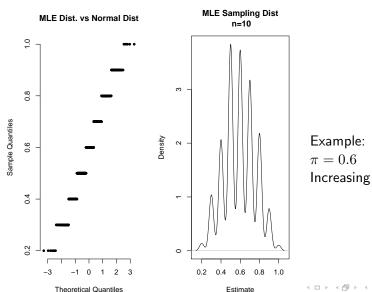
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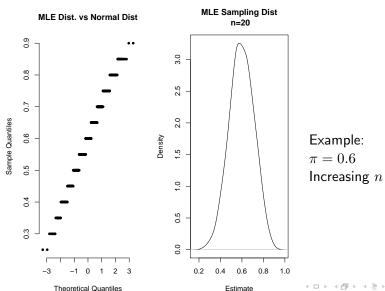
- MLE central limit theorem
- As we have more observations, the MLE converges, in distribution to a normal distribution

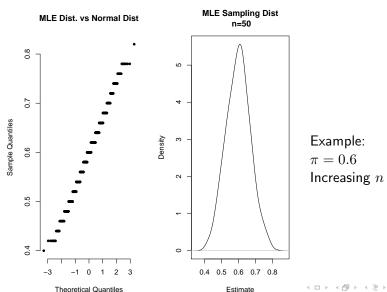


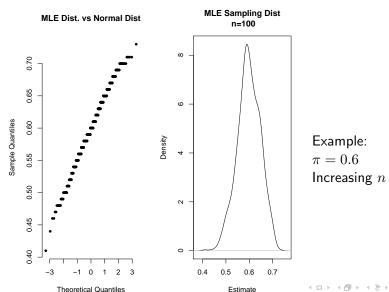
Increasing n

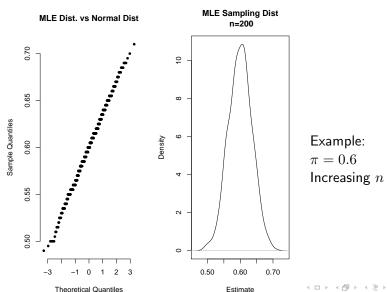


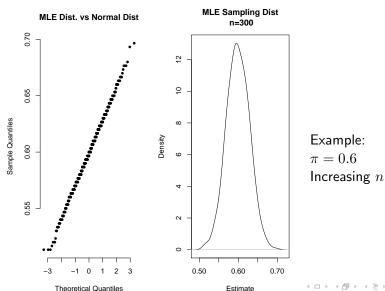
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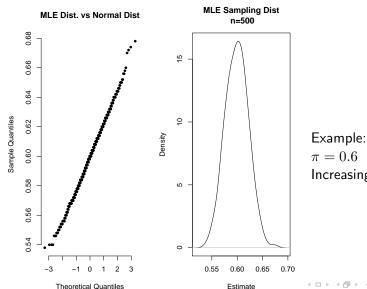




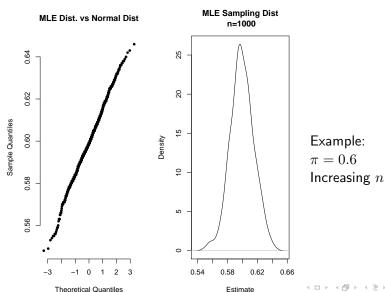




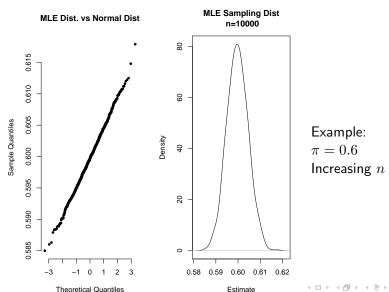




Increasing n



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Returning to Our Examples

Summary: θ^* is an MLE and θ_0 is the true value and we know the right distributional family

- 1) As $n \to \infty$, $\theta_n^* \to \theta_0$
- $2) \ \mbox{ As } n \to \infty \mbox{, } \sqrt{n}(\theta_n^* \theta_0) \to \mbox{Normal}(0, \frac{1}{I(\theta_0)})$

where $I(\theta_0)=-\frac{\partial^2}{\partial\pi^2}l(\theta_0|y)$ or curvature of log-likelihood at true value of θ_0

Two-parameter MLE

Multivariate Normal Distribution

Suppose that we have a vector of random variables,

$$\boldsymbol{X} = (X_1, X_2, \dots, X_k)$$

Then we'll say that $X \sim \text{Multivariate Normal}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ where,

$$\mathbf{\mu} = (\mu_1, \mu_2, \dots, \mu_k)
\mathbf{\Sigma} = \begin{pmatrix}
\sigma_1^2 & Cov(X_1, X_2) & Cov(X_1, X_3) & \dots & Cov(X_1, X_n) \\
Cov(X_1, X_2) & \sigma_2^2 & Cov(X_2, X_3) & \dots & Cov(X_2, X_n) \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
Cov(X_1, X_k) & Cov(X_2, X_k) & Cov(X_3, X_k) & \dots & \sigma_k^2
\end{pmatrix}$$

Multivariate Normal Distribution

$$f(\boldsymbol{x}) = \frac{1}{(2\pi)^{k/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\boldsymbol{x} - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1}(\boldsymbol{x} - \boldsymbol{\mu})\right)$$

Suppose that we simple random samples y_1, y_2, \dots, y_n from multivariate distribution $p(y|\theta_0)$.

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Inverting the Fisher-information matrix provides Variance-Covariance

Matrix

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$$l(\mu, \sigma^2 | \mathbf{y}) = -\sum_{i=1}^n \frac{(y_i - \mu)^2}{2\sigma^2} - \frac{n}{2}log(2\pi) - \frac{n}{2}\log(\sigma^2)$$

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$$= -\sum_{i=1}^{n} \frac{(y_{i} - \mu)^{2}}{2\sigma^{2}} - \frac{n}{2}\log(\sigma^{2}) + \mathbf{c}$$

Let's find μ^* and $(\sigma^2)^*$ that maximizes log-likelihood.

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$$\frac{\partial l(\mu, \sigma^{2})|\mathbf{y}|}{\partial \mu} = -\sum_{i=1}^{n} \frac{2(y_{i} - \mu)}{2\sigma^{2}}$$

$$\frac{\partial l(\mu, \sigma^{2})|\mathbf{y}|}{\partial \sigma^{2}} = -\frac{n}{2\sigma^{2}} + \frac{1}{2\sigma^{4}}\sum_{i=1}^{n} (Y_{i} - \mu)^{2}$$

$$0 = -\sum_{i=1}^{n} \frac{2(y_i - \mu^*)}{2\sigma^2}$$
$$0 = -\frac{n}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^{n} (y_i - \mu^*)^2$$

Solving for μ and σ^2 yields,

$$\mu^* = \frac{\sum_{i=1}^n y_i}{n}$$

$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (y_i - \overline{y})^2$$

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Because normal distribution \Rightarrow that mle of μ and σ^2 are independent! This is an asymptotic result: results will vary with small sample sizes.

Up next:

- 1) Linear regression in maximum likelihood
- 2) Logit/Probit
- 3) Numerical optimization