

Part 1A Groups - Theorems, Lemmas and Proofs

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1 Basic Definitions and Examples

Lemma 1.1. *Let $(G, *)$ be a group, then,*

(i) *The identity is unique.*

(ii) *The inverses are unique.*

Proof. Suppose we have two identity elements e and e' . Then $\forall x \in G, x * e = x = x * e'$ and $x * e' = x = e' * x$. Now $e = e' * e = e'$ so $e = e'$.

Given an element $g \in G$ suppose g has two inverses, h and h' . Then $g * h = e = h * g$ and $g * h' = e = h' * g$. Now $h = h * e = h * (g * h') = (h * g) * h' = e * h' = h'$. \square

Lemma 1.2. *If $g : A \rightarrow B$ and $f : B \rightarrow C$ are both injective/surjective/bijective, then so is $f \circ g$.*

Proof. (i) $f(g(x)) = f(g(y)) \Rightarrow g(x) = g(y) \Rightarrow x = y$ since f and g are injective.

(ii) Given $z \in C \exists y \in B : f(y) = z$, but given any $y \in B \exists x \in A : g(x) = y$. So given $z \in C \exists x \in A : f(g(x)) = z$.

(iii) If f and g are both bijective this means $f \circ g$ is injective and surjective, so it is bijective. \square

Lemma 1.3. *Let $(G, *_g)$ and $(H, *_h)$ be groups and $\theta : (G, *_g) \rightarrow (H, *_h)$ a homomorphism. Then $Im(\theta) = \theta(G) = \{\theta(g) : g \in G\}$ is a subgroup under $*_h$ of $(H, *_h)$.*

Proof. Given two elements $\theta(x)$ and $\theta(y)$, consider $\theta(x) *_h \theta(y) = \theta(x *_g y)$ which is in $Im(\theta)$. Now consider $\theta(x) *_h \theta(e_g) = \theta(x) = \theta(e_g) *_h \theta(x)$, so we have an identity, namely $\theta(e_g)$. Suppose we are given an element $\theta(g) \in Im(G)$ then consider $\theta(g) *_h \theta(g^{-1}) = \theta(g *_g g^{-1}) = \theta(e_g)$. So $\theta(g)^{-1} = \theta(g^{-1})$. Consider $(\theta(x) *_h \theta(y)) *_h \theta(z) = \theta((x *_g y) *_g z) = \theta(x *_g (y *_g z)) = \theta(x) *_h (\theta(y) *_h \theta(z))$ \square

Lemma 1.4. (i) *Let F, G and H all be groups and $\theta : G \rightarrow H$ and $\phi : F \rightarrow G$ both be homomorphisms/isomorphisms, then so is the composition $\theta \circ \phi$.*

(ii) *Let F and G be groups (as above) and let $\phi : F \rightarrow G$ be an isomorphism. Then ϕ^{-1} is an isomorphism.*

Proof. (i) Consider $(\theta \circ \phi)(x) *_h (\theta \circ \phi)(y) = \theta(\phi(x)) *_h \theta(\phi(y)) = \theta(\phi(x) *_g \phi(y)) = \theta(\phi(x *_f y)) = (\theta \circ \phi)(x *_f y)$. This proves the result for homomorphisms. The result for isomorphism requires also the composition to be a bijection, this is proved in Lemma 1.2.

(ii) Since ϕ is bijective we know ϕ^{-1} exists and is bijective. Since ϕ^{-1} is bijective $\forall x, y \in G \exists! x', y' \in F$ such that $x' = \phi^{-1}(x)$ and $y' = \phi^{-1}(y)$. As ϕ is an homomorphism we have $\phi(x'y') = \phi(x')\phi(y')$ so $x'y' = \phi^{-1}(\phi(x')\phi(y'))$. Substituting for x' and y' , $\phi^{-1}(x)\phi^{-1}(y) = \phi^{-1}(xy)$ immediately. \square

2 The Symmetric and Dihedral Groups

Proposition 2.1. *$Sym(X)$ is a group under composition of functions.*

Proof. The elements of $Sym(X)$ are all bijections from X to itself. The compositions of two bijections from X to X is again a permutation of X . The identity function maps every element to itself. Since these maps are bijections their inverses exist. Also composition of functions is associative. \square

Lemma 2.2. *If $\sigma, \tau \in S_n$ are disjoint cycles then $\sigma \circ \tau = \tau \circ \sigma$, i.e. they commute.*

Proof. Let σ be represented in cycle notation by (a_1, a_2, \dots, a_k) and τ by (b_1, b_2, \dots, b_l) where $a_i \neq b_j \forall i, j$. Now take any element $x \in S_n$. If $x \notin \{a_i, b_j\} 1 \leq i \leq k, 1 \leq j \leq l$ Then $\sigma(\tau(x)) = x = \tau(\sigma(x))$. If $x = a_i$ for some $1 \leq i \leq k$ then $\sigma(\tau(a_i)) = \sigma(a_i) = a_{i+1} = \tau(a_{i+1}) = \tau(\sigma(a_i))$, where we take addition to be *mod k*. A similar argument works for if $x = b_j$ for some j . \square

Theorem 2.3. Every permutation in S_n can be written uniquely as a product of disjoint cycles (up to order).

Proof. An inductive proof on n . If $n = 1$ there is only one permutation (1) this is a disjoint cycle. Assume that all permutations of a set of size $n < k$ can be written as the product of disjoint cycles. Now consider $\sigma \in S_k$, consider the sequence $1, \sigma(1), \sigma(1)^2, \sigma(1)^3, \dots$. Now as S_k is finite there must be some repeating in this sequence, suppose $\sigma(1)^i = \sigma(1)^j$ where $i < j$ is the first repeated term of the sequence. But by taking the inverse σ of both sides i times we find that $\sigma(1)^{j-i} = 1$, this is the first repeating term. Let $m = j - i$. Consider the set $S = \{1, \sigma(1), \sigma(1)^2, \dots, \sigma(1)^{m-1}\}$, if $S = Q$ where $Q = \{1, 2, 3, \dots, k\}$ then we have a k -cycle and we are done. If $S \neq Q$ then $\sigma = (1, \sigma(1), \sigma(1)^2, \dots, \sigma(1)^{m-1})\tau$, where τ is a permutation of the set $S - Q = \{t \in S : t \notin Q\}$. Now as this set has an order smaller than k we can write it as a product of disjoint cycles say $\tau_1\tau_2 \dots \tau_k$. So that $\sigma = (1, \sigma(1), \sigma(1)^2, \dots, \sigma(1)^{m-1})\tau_1\tau_2 \dots \tau_k$, hence we have the required result for $n = k$ so by induction it holds for all n . To prove uniqueness we can prove that all cycles are disjoint or equal. To prove they are unique suppose $\sigma_1\sigma_2 \dots \sigma_k = \sigma = \sigma_1^*\sigma_2^* \dots \sigma_l^*$, if $\sigma_1(i) = j$ then there must be some p such that $\sigma_p^*(i) = j$ since the cycles are disjoint. Then consider $\sigma_1(j)$ by the same reasoning we $\sigma_1(j) = \sigma_p^*(j)$, inductively this shows $\sigma_1 = \sigma_p^*$ and we can cancel them. This process can continue to show the o factorisations are the same. \square

Lemma 2.4. Let $g \in G$. Then $g^n = e$ iff $o(g)|n$

Proof. Let $m = o(g)$. Suppose $g^n = e$, then by Euclid's Algorithm this is equal to g^{qm+r} for some q and r with $0 \leq r < m$. Now $e = g^n = (g^m)^q g^r$ but $g^m = e$ so, $g^r = e$ but this means $r = 0$ by the minimality of m . So $o(g)$ must divide n . Now we prove the result the other way, suppose $n = qm$, then $g^n = g^{qm} = (g^m)^q = e$, hence if m divides n then the result holds, and we have shown the iff. \square

Lemma 2.5. Let $\sigma, \tau \in S_n$ be disjoint cycles in S_n . Then $o(\sigma\tau) = \text{lcm}(\sigma^*, \tau^*)$. (σ^* is the length of σ , τ^* is similar).

Proof. Consider $(\sigma\tau)^n = \sigma^n\tau^n$ because Lemma 2.2 tells us they commute. If n is the order of $\sigma\tau$ then n is the smallest positive integer such that for all $i \in \mathbb{Z}_n$, $(\sigma\tau)^n(i) = i$. This is true if and only if $\sigma^n = e$ and $\tau^n = e$. But then $\sigma^*|n$ and $\tau^*|n$, so the smallest such n is $\text{lcm}(\sigma^*, \tau^*)$. \square

Proposition 2.6. Any $\sigma \in S_n$ ($n \geq 2$) can be written as a product of disjoint cycles.

Proof. Let σ be expressed as the product of disjoint cycles, say $\sigma_1, \sigma_2, \dots, \sigma_r$. Take any of these cycles suppose it is represented in cycle notation by (a_1, a_2, \dots, a_k) , then we can express this as $(a_1a_2)(a_2a_3) \dots (a_{k-1}a_k)$. The same holds for all σ_i so we can express σ as the product of transpositions. \square

Lemma 2.7. The function

$$\begin{aligned} \text{sgn} : S_n &\longrightarrow \{\pm 1\} \\ \sigma &\longmapsto \text{sgn}(\sigma) \end{aligned}$$

is well defined.

Proof. First we show that the identity can be written as the product of an even number of permutations. Suppose the identity permutation on $\{1, 2, \dots, n\}$ is even. The base case $n = 2$ holds since $(12)^n = e$ iff n is even. Suppose the identity of the set $\{1, 2, \dots, n-1\}$. Now consider $I = \tau_1\tau_2 \dots \tau_m$ where each of the τ_i is a transposition acting on $\{1, 2, \dots, n\}$. $m \neq 1$, so $m \geq 2$. Suppose τ_m does not fix n , then we have for some a, b, c

$$\begin{aligned} \tau_{m-1}\tau_m &= \begin{aligned} (nb)(na) &= (abn) &= (na)(ab) \\ (ab)(na) &= (anb) &= (nb)(ab) \\ (bc)(na) &= (na)(bc) \\ (na)(na) &= I &= (ab)(ab) \end{aligned} \end{aligned}$$

So we can write I where the first transposition fixes n . We can now continue this process until we have that $\tau_2, \tau_3, \dots, \tau_m$ fix n . But since we have the identity this means τ_1 fixes n too. So we can write $I = \tau_1 \tau_2 \dots \tau_m$ which acts on $\{1, 2, \dots, n-1\}$, which by the induction hypothesis must be even. Now suppose that a permutation can be expressed in two different ways as the product of transpositions. If $\tau_1 \tau_2 \dots \tau_m = \tau = \tau_1^* \tau_2^* \dots \tau_p^*$, then $I = \tau_1 \tau_2 \dots \tau_m \tau_p^* \tau_{p-1}^* \dots \tau_1^*$, but we know this must have even length, so p and m are either both even or both odd. □

Theorem 2.8. *Let $n \geq 2$. The map*

$$\begin{aligned} \text{sgn} : (S_n, \circ) &\longrightarrow (\{\pm 1\}, \times) \\ \sigma &\longmapsto \text{sgn}(\sigma) \end{aligned}$$

is a well defined, non-trivial homomorphism.

Proof. Lemma 2.7 shows it is well-defined. A transposition is mapped to -1 , so the mapping is non-trivial. Suppose σ and τ are elements in S_n , if σ can be written as the product of m transpositions and τ can be written as the product of n then $\sigma\tau$ can be written as the product of $m+n$, so $\text{sgn}(\sigma\tau) = (-1)^{m+n} = (-1)^m(-1)^n = \text{sgn}(\sigma)\text{sgn}(\tau)$, so we have a homomorphism. □

Corollary 2.9. *The even permutations of S_n , $n \geq 2$, denoted A_n , form a subgroup of S_n .*

Proof. This follows from the first isomorphism theorem. □

3 Cosets and Lagrange

Lemma 3.1. *Let $H \leq G$ and $g \in G$. Then there is a bijection between H and gH . In particular, if H is finite, $|H| = |gH|$.*

Proof. Let $\psi : H \rightarrow gH$ such that $\psi(h) = gh$ where $h \in H$ and $g \in G$. If $gh_1 = gh_2 \Rightarrow h_1 = h_2$ by pre-multiplying by g^{-1} . So $\psi(h_1) = \psi(h_2) \Rightarrow h_1 = h_2$, so ψ is injective. Take any gh in gH , now $\exists h \in H$ such that $\psi(h) = gh$ so the mapping is surjective. (h are uniquely defined so there is no need to show the map is automatically well-defined.) □

Lemma 3.2. *Let $H \leq G$. The left cosets of H in G form a partition of G , i.e.*

- (i) *each $g \in G$ lies in some coset of H .*
- (ii) *for $a, b \in G$, $aH \cap bH \neq \emptyset \Rightarrow aH = bH$.*

Proof. (i) As $e \in H$, $g = ge \in gH$.

(ii) If $aH \cap bH \neq \emptyset$ then there exists $h_1, h_2 \in H$ such that $ah_1 = bh_2$. This means $a = bh_2h_1^{-1}$. So $aH = \{ah : h \in H\} = \{bh_2h_1^{-1}h : h \in H\} \subset bH$. The reverse inclusion follows by a similar argument so $aH = bH$. (The same holds for right cosets by a similar argument.) □

Lemma 3.3. *Let $H \leq G$ and $a, b \in G$. Then $aH = bH$ iff $a^{-1}b \in H$.*

Proof. If $aH = bH$ then $\exists h_1, h_2 \in H$ such that $ah_1 = bh_2$ so $a^{-1}b = h_1h_2^{-1} \in H$. If $a^{-1}b \in H$ then $a^{-1}b = h$ for some $h \in H$. So $a = bh^{-1} \in bH$ and as $a \in aH$, $aH \cap bH \neq \emptyset$, hence by Lemma 3.2 $aH = bH$. □

Theorem 3.4. *Lagrange's Theorem - Let H be a subgroup of a finite group G . Then the order of H divides the order of the group G .*

Proof. As G is finite we have a finite number of cosets. By Lemma 3.2 the cosets H of G form a partition of G . So G is the disjoint union of its cosets, $G = g_1H \cup g_2H \cup \dots \cup g_kH$. So $|G| = |g_1H| \cup |g_2H| \cup \dots \cup |g_kH|$. But by Lemma 3.1 every coset has the same size as $|H|$, so $|G| = k|H|$. $\frac{|G|}{|H|} = k$, so the order of H divides the order of G . □

Corollary 3.5. *Lagrange's corollary - Let G be a finite group and $g \in G$ then $o(g)|G$. In particular $g^{|G|} = e$.*

Proof. The element g (by composition with itself) produces the finite cyclic subgroup $\{e, g, g^2, \dots, g^{o(g)-1}\}$, this group has order $o(g)$. As this is a subgroup the result follows from Theorem 3.4. \square

Corollary 3.6. *If $|G| = p$ for some prime p , then G is cyclic.*

Proof. As p is prime $p \geq 2$, so G has some non-identity element g . But by Lagrange's corollary the order of g must divide p . So $o(g)$ is 1 or p . Since $g \neq e$, g must have order p , so $\langle g \rangle = G$. So G is cyclic. \square

Theorem 3.7. (Fermat-Euler Theorem) - *Let $n \in \mathbb{N}$, $a \in \mathbb{Z}$ and $hcf(a, n) = 1$. Then $a^{\phi(n)} \equiv 1 \pmod{n}$*

Proof. There is rather a lot to set up. Let $n \in \mathbb{N}$, define $R_n = \{0, 1, \dots, n-1\}$. And let $R_n^* = \{a \in R_n : hcf(a, n) = 1\}$, also \times_n is multiplication modulo n .

We claim that (R_n^*, \times_n) is a group. (Define \bar{b} to be $b \in R_n$ such that $b \equiv \bar{b} \pmod{n}$) Suppose $a, b \in R_n^*$ then $hcf(a, n) = 1 = hcf(b, n) \Rightarrow hcf(ab, n) = 1$. So $hcf(\bar{a}\bar{b}, n) = 1$, we have closure. The identity is 1. Let $a \in R_n^*$, so by Bezout there exists $u, v \in \mathbb{Z}$ such that $au + nv = 1$, so $\bar{u} \in R_n^*$ satisfies $\bar{u} = a^{-1}$. Multiplication modulo n is associative. Now we prove Fermat-Euler.

R_n^* is the group of all integers a coprime to n , so $|R_n^*| = \phi(n)$. Let $a \in \mathbb{Z}$, such that $hcf(a, n) = 1$, so $\bar{a} \in R_n^*$. By Lagrange $\bar{a}^{\phi(n)} = \bar{a}^{|R_n^*|} = 1$ in R_n^* . So $a^{\phi(n)} \equiv 1 \pmod{n}$. \square

4 Normal Subgroups, Quotient Groups and Homomorphisms

Proposition 4.1. *Let $K \trianglelefteq G$. The following are equivalent,*

- (i) $gK = Kg \forall g \in G$
- (ii) $gKg^{-1} = K \forall g \in G$
- (iii) $gkg^{-1} \in K \forall k \in K, g \in G$

Proof. Assume (i) holds then $gk = \hat{k}g$ for some $k, \hat{k} \in K$. So $gkg^{-1} = \hat{k} \in K$. This proves (i) \Rightarrow (iii). If we now assume (iii), then $gKg^{-1} \subset K$. As this holds for all g we can replace g by g^{-1} , so we have $g^{-1}Kg \subset K$, which means $K \subset gKg^{-1}$. So $gKg^{-1} = K$. (iii) \Rightarrow (ii). Finally, (i) is immediate from (ii) by right multiplication by g . \square

Lemma 4.2. *If K is a subgroup of G of index two then K is normal in G .*

Proof. K has index 2, this means that K has two left cosets and two right cosets. One coset is always K itself. Take $g \notin K$. Then gK is the other left coset, Kg is the other right coset, and $K \cup gK = G = K \cup Kg$. But these are disjoint unions, so $gK = Kg$. By Lemma 4.2 this means that K is normal. \square

Theorem 4.3. *If $K \trianglelefteq G$, the set $(G : K)$ of left cosets of K in G is a group, denoted $\frac{G}{K}$, under the operation coset multiplication i.e. $gK * hK = ghK$*

Proof. First we need to show coset multiplication is well defined. Namely if $a_1K = a_2K$ and $b_1K = b_2K$ then $a_1K * b_1K = a_2K * b_2K$. Now $a_1K * b_1K = a_1b_1K = a_1(b_2K) = (a_1K)b_2 = (a_2K)b_2 = a_2(Kb_2) = a_2b_2K$. Now if $a, b \in G$, then abK is a coset of K , so we have closure. $eK = K$ is the identity. Given aK , consider $aK * a^{-1}K = K = a^{-1}KaK$, so we have inverses. Finally, if $a, b, c \in G$, then $aK * (bK * cK) = aK * bcK = abcK = abK * cK = (aK * bK) * cK$ so associativity holds too. \square

Theorem 4.4. *First Isomorphism Theorem - Let G, H be groups and $\theta : G \rightarrow H$ a group homomorphism. Then,*

- (i) $Im(\theta) \leq H$
- (ii) $Ker(\theta) \trianglelefteq G$
- (iii) $\frac{G}{Ker\theta} \cong Im(\theta)$

Proof. (i) Let $Im(x), Im(y) \in Im(\theta)$. $\theta(x)\theta(y) = \theta(xy) \in Im(\theta)$. The identity of H is in $Im(\theta)$ since $\theta(e_G) = e_H$. Let $\theta(x') \in Im(\theta)$, consider $\theta(x')\theta((x')^{-1}) = \theta(x'(x')^{-1}) = \theta(e_G) = e_H$, so inverses exist. Associativity holds due to the homomorphism.

(ii) Take two elements $x, y \in Ker(\theta)$, consider $\theta(xy) = \theta(x)\theta(y) = e_H$. So $xy \in Ker(\theta)$. The identity is e_G . Take any $x \in Ker(\theta)$, consider $xx^{-1} = e_G$, but $\theta(x^{-1}) = (\theta(x))^{-1} = e_H$. So $x^{-1} \in Ker(\theta)$. G is associative so associativity is inherent in $Ker(\theta)$. Now take any $g \in G$, consider $\theta(gkg^{-1})$ where $k \in Ker(\theta)$. $\theta(gkg^{-1}) = \theta(g)\theta(k)\theta(g^{-1}) = \theta(g)(\theta(g))^{-1} = e_H$. So $gkg^{-1} \in Ker(\theta), \forall g \in G, k \in Ker(\theta)$. So the kernel is a normal subgroup.

(iii) Define $\varphi : G \setminus Ker(\theta) \rightarrow \theta(G)$ by $\varphi(gKer(\theta)) = \theta(g)$. We need to show this map is well-defined, a homomorphism, injective and surjective.

Well-defined - Suppose $aKer(\theta) = bKer(\theta)$, then $a = bk$ for some $k \in Ker(\theta)$. Now $\varphi(aKer(\theta)) = \theta(a) = \theta(bk) = \theta(b) = \varphi(bKer(\theta))$, so the map is well-defined.

Homomorphism - $\varphi(aKer(\theta))\varphi(bKer(\theta)) = \theta(a)\theta(b) = \theta(ab) = \varphi(abKer(\theta))$.

Injective - If $\varphi(aKer(\theta)) = \varphi(bKer(\theta))$ then $\theta(a) = \theta(b)$. Consider $\theta(ab^{-1}) = \theta(a)(\theta(b))^{-1} = e_H$, so $ab^{-1} \in Ker(\theta)$, hence $aKer(\theta) = bKer(\theta)$ by Lemma 3.3. So $\varphi(aKer(\theta)) = \varphi(bKer(\theta)) \Rightarrow aKer(\theta) = bKer(\theta)$. so φ is injective.

Surjective - Take any element $x \in Im(\theta)$, then there exists $g \in G$ such that $\theta(g) = x$. But then $\varphi(gKer(\theta)) = \theta(g) = x$. So φ is surjective. \square

Lemma 4.5. A homomorphism $\theta : G \rightarrow H$ is injective iff $Ker(\theta) = \{e_G\}$.

Proof. If θ is injective then $\theta(x) = y$ for at most one $x \in G$, which immediately shows $Ker(\theta) = \{e_G\}$. If $Ker(\theta) = \{e_G\}$ then consider $\theta(x) = \theta(y) \Rightarrow \theta(x)\theta(x^{-1}) = \theta(y)\theta(x^{-1}) \Rightarrow \theta(e_G) = \theta(xy^{-1})$ but $Ker(\theta) = \{e_G\}$ so $xy^{-1} = e \Rightarrow x = y$ so θ is injective. \square

Lemma 4.6. (i) Let $N \trianglelefteq G$ and $H \leq G$, then $NH \leq G$

(ii) Let $N \trianglelefteq G$ and $M \trianglelefteq G$, then $NM \trianglelefteq G$

Proof. (i) First, since all $n \in N, h \in H$ are in G , this means all $nh \in N \in G$. Now take $n_1h_1, n_2h_2 \in NH$, consider $n_1h_1n_2h_2$, as N is normal $h_1N = Nh_1$ so $h_1n_1 = \hat{n}h_1$ for some $\hat{n} \in N$. So $n_1\hat{n}h_1h_2 \in NH$. The identity is still $e_Ge_G = e_G$. Associativity is inherent since G is a group. Now take any $nh \in NH$, select the element $(h^{-1}n^{-1}h)h^{-1}$. $h^{-1}n^{-1}h$ is an element of G of the form ghg^{-1} so we can be sure it's in N (so $(h^{-1}n^{-1}h)h^{-1} \in NH$) Now $nh(h^{-1}n^{-1}h)h^{-1} = e_G$, so we have inverses.

(ii) Part (i) immediately tells us $NM \leq G$. Let $n \in N, m \in M, g \in G$, consider $gnmg^{-1}$. Since N normal $gN = Ng$ so $gn = \hat{n}g$ for some $\hat{n} \in N$. Similarly, $gm = \hat{m}g$ for some $\hat{m} \in M$. So $gmn^{-1} = \hat{m}gng^{-1} = \hat{m}\hat{n}gg^{-1} = \hat{m}\hat{n} \in MN$. This holds for all $g \in G$, so MN is normal in G . \square

5 Direct Products and Small Groups

Lemma 5.1. Let $(h, k) \in H \times K$, then $o((h, k)) = (o(h), o(k))$.

Proof. Consider raising (h, k) to the power n . $(h, k)^n = (h^n, k^n)$. Now $o((h, k))$ is the smallest integer n such that $(h^n, k^n) = (e_H, e_K) \Leftrightarrow h^n = e_H$ and $k^n = e_K$, the smallest such n is $lcm(o(h), o(k))$ \square

Corollary 5.2. $C_m \times C_n \cong C_{mn}$ iff $hcf(m, n) = 1$.

Proof. First note $|C_m \times C_n| = mn$. Now $C_m \times C_n \cong C_m \times C_n \Leftrightarrow C_m \times C_n$ contains an element of order $mn \Leftrightarrow lcm(m, n) = 1 \Leftrightarrow hcf(m, n) = 1$. \square

Proposition 5.3. Let G be a group with subgroups H and K . If

(i) each element of G can be written as hk with $h \in H$ and $k \in K$

(ii) $H \cap K = \{e\}$

(iii) $hk = kh \forall h \in H, k \in K$

then $G \cong H \times K$ and we call G the internal direct product of H and K .

Proof. Define the map $\varphi : H \times K \rightarrow G$ by $\varphi((h, k)) = hk$. If we can show this is an isomorphism we are done. Suppose $h_1k_1 = h_2k_2$ then $h_2^{-1}h_1 = k_2k_1^{-1} = e$ by (ii). So we have $h_1 = h_2$ and $k_1 = k_2$. So $\varphi(h_1, k_1) = \varphi(h_2, k_2) \Rightarrow (h_1, k_1) = (h_2, k_2)$, φ is injective. Take any $g \in G$, by (i) we know there is $(h, k) \in H \times K$ such that $\varphi((h, k)) = g$, φ is surjective. Now consider (using (iii)) $\varphi(h_1k_1h_2k_2) = \varphi(h_1h_2, k_1k_2) = (h_1, k_1)(h_2, k_2) = \varphi((h_1, k_1))\varphi((h_2, k_2))$, so φ is a homomorphism. \square

6 Group Actions

Lemma 6.1. *Suppose G acts on the non-empty set X . Fix $g \in G$, then the map $\phi_g : X \rightarrow X$ such that $x \rightarrow \rho(g, x)$ is a permutation.*

Proof. By the definition of the map X is mapped to X . Now take ϕ_g , consider $\phi_{g^{-1}}(\phi_g(x)) = \phi_{gg^{-1}}(x) = \phi_e(x) = x$. So an inverse map exists so ϕ_g must be bijective, this defines a permutation of X . (So $\phi_g \in \text{Sym}(X)$) \square

Proposition 6.2. *Suppose G acts on the set X . Then the map $\varphi : G \rightarrow \text{Sym}(X)$ such that $g \rightarrow \phi_g$ (where ϕ_g is as in Lemma 6.2) is a homomorphism.*

Proof. Take any $g_1, g_2 \in G$ and any $x \in X$, then $\varphi(g_1g_2)(x) = \phi_{g_1g_2}(x) = (g_1g_2)(x) = g_1(g_2(x)) = g_{g_1}(\phi_{g_2}(x)) = \varphi(g_1)\varphi(g_2)(x)$. I'm unsure of the validity of this one, please advise me. \square

Theorem 6.3. (Cayley's Theorem) - *Any group G is isomorphic to a subgroup of $\text{Sym}(X)$ for some set X .*

Proof. Let G act on the set $X = G$, with G acting by left multiplication. (This is the left regular action.) This is an action because (for any $x \in X$ and $g_1, g_2 \in G$) $ex = x$ and $g_1g_2x = (g_1g_2)x$. Since G acts we have a homomorphism $\varphi : G \rightarrow \text{Sym}(G)$. Now if $g_1x = g_2x \Rightarrow g_1 = g_2$, so the homomorphism is injective. So $G \cong \text{Im}(\varphi) \leq \text{Sym}(G)$. \square

Lemma 6.4. *The distinct orbits form a partition of X .*

Proof. Let the group G act on the set X . Every element $x \in X$ is in at least one orbit since $e(x) = x$. Now suppose two orbits, $\text{Orb}(x)$ and $\text{Orb}(y)$ have a common element z , then $g_1x = z$ and $g_2y = z$ for some $g_1, g_2 \in G$. Now take any point $u \in \text{Orb}(x)$, $u = gx = gg_1^{-1}z = (gg_1^{-1}g_2)(g_2y)$ so $\forall u \in \text{Orb}(x) \subset \text{Orb}(y)$. The reverse inclusion holds by a similar argument. So $\text{Orb}(x) = \text{Orb}(y)$, orbits are distinct or equal. \square

Lemma 6.5. *$\text{Stab}_G(x)$ is a subgroup of G .*

Proof. Since $e(x) = x$, $e \in \text{Stab}_G(x)$. Now if $g_1, g_2 \in G$ then $(g_1g_2)(x) = g_1(g_2(x)) = g_1(x) = x$, so we have closure. Take any $g \in G$, then consider $g^{-1}(g(x)) = (g^{-1}g)(x) = e(x)$, so we have inverses. As G is a group associativity is inherent. \square

Theorem 6.6. (Orbit-Stabiliser Theorem) - *Let G be a finite group acting on a set X . Let $x \in X$, then $|G| = |\text{Stab}_G(x)||\text{Orb}_G(x)|$.*

Proof. Let $(G : \text{Stab}_G(x))$ be the set of left cosets of $\text{Stab}_G(x)$ in G . Let $\varphi : \text{Orb}_G(x) \rightarrow (G : \text{Stab}_G(x))$ such that $g(x) \rightarrow g\text{Stab}_G(x)$. Suppose $g_1(x) = g_2(x) \Leftrightarrow g_2^{-1}g_1(x) = x \Leftrightarrow g_2^{-1}g_1 \in \text{Stab}_G(x) \Leftrightarrow g_1\text{Stab}_G(x) = g_2\text{Stab}_G(x)$, so the map is well defined and injective. Now take any $g\text{Stab}_G(x) \in (G : \text{Stab}_G(x))$, $\varphi(g(x)) = g\text{Stab}_G(x)$ so we have a surjective map, hence φ is a well-defined bijection. \square

Theorem 6.7. (Cauchy's Theorem) - *Let G be a finite group and p be a prime with p divides $|G|$. Then there exists an element in G of order p .*

Proof. We are looking for non-trivial solutions to the equation $g^p = 1$, McKay's idea is to look at a more general equation. Namely, let $X = \{(x_1, x_2, \dots, x_p) : x_1 x_2 \cdots x_p = e\}$ with all the $x_i \in G$. Let the cyclic group C_p ($\langle a \rangle$) act on X , so that $a^k(x_1, x_2, \dots, x_p) = (x_{1+k}, x_{2+k}, \dots, x_{p+k})$ where addition is $(\text{mod } p)$. This is an action. $|X| = |G|^{p-1}$ since x_p is predetermined by the $p-1$ (independent) previous terms. By the orbit-stabiliser theorem the orbits of elements in X is 1 or p . Orbits of size 1 correspond to elements of X of the form $x^p = e$, we know we have at least one since $e^p = e$ is trivially a solution. But as $|X| = |G|^{p-1}$ (and p divides $|G|$), $|X| \equiv 0 \pmod{p}$. So there must at least $p-1$ other elements that satisfy $x^p = e$, (and hence $g^p = e$). \square

Proposition 6.8. *Let p be a prime and G a group of order p^n , for some $n \geq 1$ ($n \in \mathbb{N}$). Then the centre $Z(G)$ is non-trivial. I.e. $|Z(G)| \geq |\{e\}|$.*

Proof. If $a \in G$ is in the centre then $ga = ag \forall g \in G$. This can also be written as $gag^{-1} = a$. Let G act on itself ($X = G$) by conjugation. So $g(x) = gxg^{-1}$. Consider orbits of $x \in X$, by the orbit-stabiliser theorem (and Lagrange) we know orbits must be of size $1, p, p^2, \dots, p^n$. We know $|G| \equiv 0 \pmod{p}$, but if we look at G as the union of its disjoint orbits (we know we have one of size 1 namely $\{e\}$), this means there must be at least $p-1$ other orbits of size 1. Orbits of size 1 correspond to elements of the centre (since if $gag^{-1} = a \forall g \in G$ the orbit of a is just $\{a\}$). \square

Lemma 6.9. *Let G be a finite group and $Z(G)$ be the centre of G . If $G \setminus Z(G)$ is cyclic then G is abelian.*

Proof. First note the centre is a normal subgroup so the set of left cosets of $Z(G)$ in G is a group. As $G \setminus Z(G)$ is cyclic every coset can be written in the form $a^i Z(G)$ for some $a \in G$, where $0 \leq i \leq k-1$ ($k = |G|/|Z(G)|$). So every element in G is of the form $a^i c$, where $c \in Z(G)$. Now let G act on itself by conjugation. Consider the action of $a^i c_1$ on $a^j c_2$ ($a^i, a^j \in G, c_1, c_2 \in Z(G)$), we have $a^i c_1 (a^j c_2) = a^i c_2 a^j c_1 a^{k-i} c_2^{-1} = a^i a^j a^{k-i} c_2 c_1 c_2^{-1} = a^j c_2 c_2^{-1} c_1 = a^j c_2$. So the orbit of any $g \in G$ contains only g . But this means every element is in the centre, so the group is abelian. \square

Corollary 6.10. *Suppose $|G| = p^2$ for some prime p . Then G is abelian and, up to isomorphism there are only two groups of order p^2 , namely C_{p^2} and $C_p \times C_p$.*

Proof. From proposition 6.8, we know the centre of G is non-trivial. So $|Z(G)| = p$ or p^2 . First consider if $|Z(G)| = p$, $G \setminus Z(G)$ has order p , so it must be isomorphic to C_p . From Lemma 6.9 we know G group must be abelian. By Lagrange G contains two elements of order p . Let these be b, c with $b \neq c$ (let the corresponding subgroups be B, C , with $B \neq C$). Suppose $\langle b \rangle \cap \langle c \rangle \neq \{e\}$, then $b^i = c^k$ for some $1 \leq i, k \leq p-1$, but this element generates both B and C which is a contradiction. All conditions of proposition 5.3 are met so we see $G \cong C_p \times C_p$. Now consider if $|Z(G)| = p^2$, $G \setminus Z(G)$ is trivial (cyclic) so G is abelian. G contains an element of order p^2 so it must be the cyclic group C_{p^2} . \square

Theorem 6.11. *The permutations π and σ in S_n are conjugate in S_n iff they are of the same cycle type.*

Proof. If π and σ are conjugate then there exists some element $\tau \in S_n$ such that $\sigma = \tau \pi \tau^{-1}$. Let $\pi(i) = j$, σ is simply a relabelling of π because $(\tau \pi \tau^{-1})(\tau(i)) = \tau \pi(i) = \tau(j)$ (*). So σ is τ with every element x in τ relabelled as $\tau(x)$. So they have the same cycle type. Given two permutations π and σ in S_n of the same cycle type, we can show they are conjugate as follows, list the cycles of π above the cycles of σ , aligning cycles of the same length with one another. Now interpret this as the two-line presentation of a permutation, and call it τ then $\tau \pi \tau^{-1} = \sigma$ by (*). \square

Corollary 6.12. *The number of distinct conjugacy classes in S_n is given by $p(n)$, the number of partitions of n into positive integers i.e. $n = n_1 + n_2 + \dots + n_k$ with $n_1 \geq n_2 \geq \dots \geq n_k \geq 1$.*

Proof. From Theorem 6.11 we see that the conjugacy classes of S_n are the cycle types. Each cycle type corresponds to a partition of n . So the number of cycle types is the number of partitions and the result holds. \square

Cycle Type (Conjugacy Class)	Size	Sign
e	1	+
2	10	-
2,2	15	+
2,3	20	-
3	20	+
4	30	-
5	24	+

Theorem 6.13. A_5 is a simple group.

Proof. Conjugacy classes split moving from S_5 to A_5 iff they have a cycle type consisting of odd and distinct length cycles. First consider the conjugacy classes of S_5 (these are by Theorem 6.11 just the cycle types). Only the even permutations appear in A_5 , by the above rule the only conjugacy class that will split is 5-cycles. So in A_5 we have conjugacy classes of size 1, 12, 12, 15, 20. A subgroup is normal iff it is the union of some conjugacy classes (it must include $\{e\}$ too). But the union of $\{e\}$ and any combination of the other conjugacy classes is never a divisor of 60, so we cannot (by Lagrange) have a subgroup. So A_5 has no normal subgroups other than the trivial and improper subgroups hence it is simple. \square

7 Matrix Groups

Proposition 7.1. $GL_n(\mathbb{R})$ is a group under matrix multiplication.

Proof. Take any two matrices $A, B \in GL_n(\mathbb{R})$, $AB \in GL_n(\mathbb{R})$ since as $\det(A)\det(B) = \det(AB) \Rightarrow \det(AB) \neq 0$. The identity is I . Multiplication of matrices is associative. Finally, as the members of $GL_n(\mathbb{R})$ have non-zero determinants their inverses exist. \square

Proposition 7.2. The map $\text{Det} : GL_n(\mathbb{R}) \rightarrow (\mathbb{R} \setminus \{0\}, \times)$, such that $A \rightarrow \det A$, is a surjective homomorphism.

Proof. Take any $A, B \in GL_n(\mathbb{R})$, the determinant property $\det(A)\det(B) = \det(AB)$ immediately tells us we have a homomorphism. Take any $x \in \mathbb{R} \setminus \{0\}$, consider the matrix A with entries $a_{11} = x, a_{ii} = 1$ ($2 \leq i \leq n$), and $a_{ij} = 0$ where $i \neq j$, this matrix is in $GL_n(\mathbb{R})$ and has $\det(A) = x$, so the map is surjective. \square

Proposition 7.3. $O_n(\mathbb{R})$ is a subgroup of $GL_n(\mathbb{R})$.

Proof. $O_n(\mathbb{R})$ are the set of n by n orthogonal matrices. Orthogonal matrices have determinant ± 1 so $O_n(\mathbb{R}) \subset GL_n(\mathbb{R})$. Take any two $A, B \in O_n(\mathbb{R})$, consider $AB(AB)^T = ABB^T A^T = AA^T = I$, so $AB \in O_n(\mathbb{R})$. The identity matrix is orthogonal. The inverse of an orthogonal matrix A is A^T , which is also orthogonal. Finally, associativity is inherent. \square

Lemma 7.4. Let $\mathbf{A} \in O_n(\mathbb{R})$ and $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$

(i) $\mathbf{Ax} \cdot \mathbf{Ay} = \mathbf{x} \cdot \mathbf{y}$

(ii) $|\mathbf{Ax}| = |\mathbf{x}|$

Proof. To me this becomes more obvious in suffix notation. Let A have entries a_{ij} , then $Ax \cdot Ay = \sum_i x'_i y'_i$ where $x'_i = \sum_j a_{ij} x_j$ and $y'_i = \sum_k a_{ik} y_k$. So using the summation convention we have $Ax \cdot Ay = a_{ij} x_j a_{ik} y_k = a_{ij} a_{ik} x_j y_k$, but $a_{ij} a_{ik}$ is $AA^T = I$, so $Ax \cdot Ay = \delta_{jk} x_j y_k = x_j y_j$ which is the scalar product of x and y .

(ii) follows from (i) with $x = y$. \square

Proposition 7.5. Let $\mathbf{A} \in SO_3(\mathbb{R})$. Then \mathbf{A} has an eigenvector with corresponding eigenvalue 1.

Proof. A has an eigenvector because every square matrix does. Now consider $\det(A - I) = \det(A^T) \det(A - I) = \det(I - A^T) = -\det(A^T - I) = -\det((A - I)^T) = -\det(A - I)$. So $\det(A - I) = 0$ so A has a eigenvalue of 1. \square

Theorem 7.6. Let $\mathbf{A} \in SO_3(\mathbb{R})$. Then \mathbf{A} is conjugate to a matrix of the form

$$\begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

for some $\theta \in [0, 2\pi)$. In particular, \mathbf{A} is a rotation about an axis through the origin.

Proof. By proposition 7.5 there exists \vec{v} which is an eigenvector of A with eigenvalue 1. Let $\{e_1, e_2, e_3\}$ be the standard orthonormal basis of \mathbb{R}^3 . There is some $P \in SO_3(\mathbb{R})$ such that $P\vec{v} = e_3$. Now, $PAP^{-1}(e_3) = e_3$, and if Π is the plane orthogonal to e_3 ($\Pi = \langle e_1, e_2 \rangle$), then $PAP^{-1} : \Pi \rightarrow \Pi$. So

$$PAP^{-1} = \begin{pmatrix} a & b & 0 \\ c & d & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Where $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is the action on Π . But we know $PAP^{-1} \in SO_3(\mathbb{R})$ so $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = 1$. Also (a, c) and (b, d) must be an orthonormal basis for Π hence $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix}^T = I$. Which means $\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$. \square

Theorem 7.7. Any element of $O_3(\mathbb{R})$ is a product of at most 3 reflections.

Proof. Let $f(x) = Ax$ with $A \in O_3(\mathbb{R})$ and let e_1, e_2, e_3 be the standard orthonormal basis for \mathbb{R}^3 . Now A is an isometry so $|f(e_3) - f(0)| = |e_3 - 0| \Rightarrow |f(e_3)| = |e_3|$. So there is a reflection r_1 in a plane through the origin with $r_1 f(e_3) = e_3$. $r_1 f$ maps the plane Π generated by e_1, e_2 onto itself. Now, there is a reflection r_2 with $r_2(e_3) = e_3$ and $r_2 r_1 f(e_2) = e_2$. So $r_2 r_1 f : e_3 \mapsto e_3, e_2 \mapsto e_2$, so $e_1 \mapsto \pm e_1$. Let r_3 be a reflection in a plane normal e_1 if $r_2 r_1 f(e_1) = -e_1$ and the identity map otherwise. $r_3 r_2 r_1 f = I \Rightarrow f = r_1 r_2 r_3$. \square

Proposition 7.8. Suppose there exists at least 3 values of z in \mathbb{C} such that

$$\frac{az + b}{cz + d} = \frac{\alpha z + \beta}{\gamma z + \delta} \quad (*)$$

$ad - bc \neq 0, \alpha\delta - \beta\gamma \neq 0$. Then there exists $\lambda \neq 0$ such that

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \lambda \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$$

i.e. the two maps agree on all of \mathbb{C}_∞ .

Proof. If we multiply through by the denominators in $(*)$ we get $(az + b)(\gamma z + \delta) = (\alpha z + \beta)(cz + d)$. But since this equality holds for at least 3 values of z then it must be identically equal for all z , so we can compare coefficients. Hence, $a\gamma = \alpha c$, $b\gamma + \delta a = \beta c + \alpha d$ and $b\delta = \beta d$. This is equivalent to,

$$\begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} \mu & 0 \\ 0 & \mu \end{pmatrix}$$

with μ not equal to zero (both determinants on LHS $\neq 0$), inverting the left most matrix we get,

$$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \frac{\mu}{ad - bc} \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

, which is the required form. \square

Theorem 7.9. The set \mathcal{M} of all Möbius maps on \mathbb{C}_∞ is a group under composition. It is a subgroup of $\text{Sym}(\mathbb{C}_\infty)$.

Proof. Take any two Möbius maps

$$f(z) = \frac{az + b}{cz + d} \text{ and } g(z) = \frac{\alpha z + \beta}{\gamma z + \delta}$$

$$f(g(z)) = \frac{(a\alpha + b\gamma)z + (a\beta + b\delta)}{(c\alpha + d\gamma)z + (c\beta + d\delta)}$$

Now consider determinants $(c\beta + d\delta)(a\alpha + b\gamma) - (a\beta + b\delta)(c\alpha + d\gamma) = (ad - bc)(\alpha\beta - \gamma\delta) \neq 0$ so this is a Möbius map. There are special cases but they are tedious. The identity map is $\frac{z+0}{0z+1}$. Composition of functions is associative. The inverse of f is $f^*(z) = \frac{dz-b}{-cz+a}$, but we need to carefully verify this. If $z \neq -d/c, \infty$, then

$$f^*f(z) = \frac{(ad - bc)z}{ad - bc} = z \text{ (since } ad - bc \neq 0)$$

And if $z \neq -a/c, \infty$ then $ff^*(z) = z$. Now $f^*f(-d/c) = f^*(\infty) = -d/c$ and $f^*f(\infty) = f^*(a/c) = \infty$, so as f has an inverse it bijects \mathbb{C}_∞ onto itself, hence \mathcal{M} is a subgroup of $Sym(\mathbb{C}_\infty)$. \square

Theorem 7.10. $(GL_2(\mathbb{C})) \backslash \mathbb{Z} \cong \mathcal{M}$ where $Z = \left\{ \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} \in GL_2(\mathbb{C}), \lambda \neq 0 \right\}$.

Proof. Consider the map $\varphi : GL_2(\mathbb{C}) \rightarrow \mathcal{M}$ defined by

$$\varphi \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) = \frac{az + b}{cz + d}$$

This is a homomorphism because

$$\varphi \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \right) = \varphi \left(\begin{pmatrix} a\alpha + b\gamma & a\beta + b\delta \\ c\alpha + d\gamma & c\beta + d\delta \end{pmatrix} \right) = \varphi \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) \varphi \left(\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \right).$$

The second equality comes from when we proved closure in Theorem 7.9. The kernel of this homomorphism is precisely Z . So by the first isomorphism theorem the result follows. \square

Corollary 7.11. $\frac{SL_2(\mathbb{C})}{\{\pm I\}} \cong \mathcal{M}$.

Proof. $SL_2(\mathbb{C}) \leq GL_2(\mathbb{C})$, where every member of $SL_2(\mathbb{C})$ has determinant 1. The map $\varphi : SL_2(\mathbb{C}) \rightarrow \mathcal{M}$, is still a homomorphism because $SL_2(\mathbb{C})$ is a subgroup (I believe this is correct, please anyone correct me if I am wrong.) The kernel this times is $\{\pm I\}$, so the result follows. \square

Proposition 7.12. Every Möbius map can be written as a composition of maps of the following forms:

- (i) $f(z) = az$; $a \neq 0$ dilation or rotation
- (ii) $f(z) = z + b$; translation
- (iii) $f(z) = \frac{1}{z}$; inversion.

Proof. First, if $c = 0$ then $f(z) = (a/d)z + b/d$ so $f = f_2f_1$ where $f_1(z) = (a/d)z$ and $f_2(z) = z + b/d$. If $c \neq 0$ then $f = f_4f_3f_2f_1$ where $f_1(z) = z + d/c$, $f_2(z) = 1/z$, $f_3(z) = -\frac{ad-bc}{c^2}z$ and $f_4(z) = z + a/c$. \square

Theorem 7.13. The action of \mathcal{M} on \mathbb{C}_∞ is sharply triply transitive.

Proof. Given z_1, z_2, z_3 and w_1, w_2, w_3 , we need to show there is a unique Möbius map, f , such that $f(z_i) = w_i$. First suppose none of the $z_i = \infty$. Then the map g

$$g(z) = \frac{(z_2 - z_3)(z - z_1)}{(z_2 - z_1)(z - z_3)}$$

maps z_1 to 0, z_2 to 1 and z_3 to ∞ . If one of the $z_i = \infty$. Then take some $z_4 \neq z_i$ for $i = 1, 2, 3$. Let $g' = 1/(z - z_4)$, so g' maps the z_i to $g'(z_i)$ where none of the $g'(z_i)$ are infinite. Then we can construct a map

g^* that takes $g'(z_1)$ to 0, $g'(z_2)$ to 1 and $g'(z_3)$ to ∞ . So g^*g' (our new g) takes z_1 to 0, z_2 to 1 and z_3 to ∞ . In a similar manner we can construct a map h such that $h(w_1) = 0, h(w_2) = 1, h(w_3) = \infty$. Then $f = g^{-1}h$ is our required map. Now we need a mini-lemma, if a Möbius map fixes three points then it must be the identity map. Taking the standard Möbius map we see that $z(cz + d) = az + b$, for 3 values of z , so $z(cz + d) \equiv az + b$, which means $c = 0, a = d$ and $b = 0$, this defines the identity map. Now suppose there are two maps f, f' with $f(z_i) = w_i$ and $f'(z_i) = w_i$. Then ff'^{-1} fixes the three z_i so $ff'^{-1} = I$, which means $f = f'$. \square

Theorem 7.14. *Any non-identity Möbius map is conjugate to one of*

(i) $f(z) = \nu z, \nu \neq 0, 1$

(ii) $f(z) = z + 1$

Proof. Consider first the conjugacy classes of $GL_2(\mathbb{R})$, these are the matrices

$$\begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}, \begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix} : \lambda \neq \mu, \lambda \neq 0 \neq \mu \text{ and } \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$$

Now let φ be as in Theorem 7.1 let A and B be conjugate in $GL_2(\mathbb{R})$, so there is $P \in GL_2(\mathbb{R})$ such that $PAP^{-1} = B \Rightarrow \varphi(P)\varphi(A)\varphi(P)^{-1} = \varphi(B)$, so the corresponding Möbius maps are conjugate too. Now $\varphi(\begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}) = z \mapsto z$, $\varphi(\begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}) = z \mapsto \nu z$ where $\nu \neq 0, 1$, finally $\varphi(\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}) = z \mapsto z + \lambda^{-1}$. Now, every matrix that is conjugate to $\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$ is also conjugate to $\begin{pmatrix} 1 & \lambda^{-1} \\ 0 & 1 \end{pmatrix}$ (since for any scalar β , $(\beta P)A(\beta P)^{-1} = \beta P A \beta^{-1} P^{-1} = PAP^{-1} = B$). But $\begin{pmatrix} 1 & \lambda^{-1} \\ 0 & 1 \end{pmatrix}$ is conjugate to $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$, since $\begin{pmatrix} \lambda & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & \lambda^{-1} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \lambda^{-1} & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$. So $z \mapsto z + \lambda^{-1}$ is conjugate to $z \mapsto z + 1$. From this every non-identity Möbius map must be conjugate to $f(z) = \nu z, \nu \neq 0, 1$, or $g(z) = z + 1$ \square

Corollary 7.15. *A non-identity Möbius map f has either*

(i) *two fixed points (0 and ∞) or*

(ii) *one fixed point (∞)*

Proof. Suppose gfg^{-1} , then α is a fixed point of f iff $g(\alpha)$ is a fixed point of h . So the number of fixed points of f is equal to the number of fixed points of h . By Theorem 7.14, if f conjugate to $z \mapsto \nu z$ then since this has two fixed points $0, \infty$, so must f . If f is conjugate to $z \mapsto z + 1$ then ∞ is the only fixed point. \square

Theorem 7.16. *Let $f \in \mathcal{M}$ and C a circle or line in \mathbb{C}_∞ , then $f(C)$ is a circle or line in \mathbb{C}_∞ .*

Proof. The general equation for a line or a circle in \mathbb{C} is $az\bar{z} + b\bar{z} + \bar{b}z + c = 0$ (with $a = 0$ a line). But in \mathbb{C}_∞ Cartesian lines are 'circles' which include the point at ∞ . Now every Möbius is a composition of simpler maps by proposition 7.12, so we can consider each of these individually. For $f(z) = az$ and $f(z) = z + b$, both map Cartesian circles to Cartesian lines and Cartesian lines to Cartesian lines (with $g(\infty), f(\infty) = \infty$), so the result holds for these. Now consider $h(z) = 1/z$, let $w = 1/z$, so the equation of the line or circle becomes $cw\bar{w} + \bar{b}\bar{w} + bw + a = 0$. Which is again of the form of a line or a circle. Finally need to consider special cases. Suppose C passed through the origin, $C = \{z (z \neq 0) : az\bar{z} + b\bar{z} + \bar{b}z = 0\} \cup \{0\}$, we apply $f(z) = 1/z$ separately to get $f(C) = \{\bar{b}\bar{w} + bw + a = 0\} \cup \{\infty\}$ which is an extended line. In a similar way extended lines are mapped to Cartesian circles if they don't pass through the origin and extended lines if they do. \square

Theorem 7.17. *Given $z_1, z_2, z_3, z_4 \in \mathbb{C}_\infty$ all distinct and $w_1, w_2, w_3, w_4 \in \mathbb{C}_\infty$ all distinct, then $\exists f \in \mathcal{M}$ such that $f(z_i) = w_i$ iff $[z_1, z_2, z_3, z_4] = [w_1, w_2, w_3, w_4]$. In particular, Möbius maps preserve cross ratios (i.e. $[z_1, z_2, z_3, z_4] = [f(z_1), f(z_2), f(z_3), f(z_4)]$).*

Proof. First suppose there is a Möbius map f such that that $f(z_i) = w_i$, with all $z_i, w_i \neq \infty$. Then for any j and k (with none of the terms in the fraction being zero or infinity where $j \neq k$)

$$w_j - w_k = f(z_j) - f(w_k) = \frac{(ad - bc)(z_j - z_k)}{(cz_j + d)(cz_k + d)}$$

Hence

$$\frac{(w_1 - w_3)(w_2 - w_4)}{(w_1 - w_3)(w_2 - w_4)} = \frac{(z_1 - z_3)(z_2 - z_4)}{(z_1 - z_3)(z_2 - z_4)}$$

which means $[z_1, z_2, z_3, z_4] = [w_1, w_2, w_3, w_4]$. If any of the $z_i, w_i = \infty$ then the formula for the cross-ratio can be adapted suitably with limits and the result still holds. Now suppose we have $[z_1, z_2, z_3, z_4] = [w_1, w_2, w_3, w_4]$ and let g and h be the Möbius maps such that $g(z_1) = 0, g(z_2) = 1, g(z_4) = \infty$ and $h(w_1) = 0, h(w_2) = 1, h(w_4) = \infty$. Now consider $g(z_3) = [0, 1, g(z_3), \infty] = [g(z_1), g(z_2), g(z_3), g(z_4)] = [z_1, z_2, z_3, z_4] = [w_1, w_2, w_3, w_4] = [h(w_1), h(w_2), h(w_3), h(w_4)] = [0, 1, h(w_3), \infty] = h(w_3)$. Let $f = h^{-1}g$ so that $f(z_i) = w_i$. \square

Corollary 7.18. z_1, z_2, z_3, z_4 lie in some circle or line in \mathbb{C}_∞ iff $[z_1, z_2, z_3, z_4] \in \mathbb{R}$.

Proof. Let z_1, z_2, z_4 lie on some line or circle $C \in \mathbb{C}_\infty$. If g is the Möbius map such that $g(z_1) = 0, g(z_2) = 1$ and $g(z_4) = \infty$, then $f(C) = \mathbb{R} \cup \infty$ (the circle of the real axis and ∞). But

$$[z_1, z_2, z_3, z_4] = [g(z_1), g(z_2), g(z_3), g(z_4)] = [0, 1, g(z_3), \infty] = g(z_3)$$

so $[z_1, z_2, z_3, z_4] \in \mathbb{R}$ iff $g(z_3) \in \mathbb{R}$, which is true iff $z_3 \in C$. \square