# $\begin{tabular}{ll} Multitask\ Pointer\ Network\ for\ Discontinuous\ Constituent\ Parsing\\ An\ application\ to\ the\ German\ language \end{tabular}$

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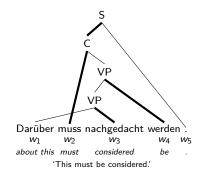
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# Why use a neural network to model German grammar?

- Constituent trees are a syntactic formalism representing phrasal hierarchy in a sentence.
- Free-order languages like German contain many grammatical discontinuities.
- Discontinuous representations introduce computational complexity but can be more valuable for downstream applications.
- Grammar-less neural network-based models have continually pushed the state of the art.
- My model is based on Fernández-González and Gómez-Rodríguez (2022), who propose an architecture based on pointer neural networks in a multi-task setting.
- I achieve state-of-the-art performance across several metrics.

#### Linguistic preliminaries: constituent trees



Let  $w = (w_1, \dots, w_L)$  be a sentence.

#### Definition

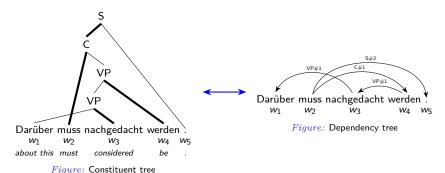
- A constituent tree is a rooted tree whose leaves are the words  $(w_i)_{i=1}^L$  and internal nodes are constituents satisfying some constraints.
- lacksquare A constituent is a triple  $(Z, \mathcal{Y}, h)$  containing, respectively, its label, yield, and lexical head.
- A constituent is *discontinuous* if its yield is not contiguous.

### Reduction to dependency parsing

#### Definition

A dependency tree is a rooted tree spanning the words in the sentence  $(w_i)_{i=1}^L$ . Each edge is labelled and connects a head word (parent) to a dependency (child).

Fernández-González and Martins (2015) show that constituent trees are isomorphic to dependency trees in which the edges contain information about constituent labels and attachment order.



# $Mathematical\ formalisation$

- Regressor: sentence  $(w_i)_{i=1}^L$ .
- Regressand:  $y_i = (y_i^{arc}, y_i^{lab}, y_i^{ord}, y_i^{pos}, y_i^{morph})$  for each i = 1, ..., L.
- Bottom-up approach: think of *arcs* going from every child  $w_i$  to its parent  $y_i^{arc} \in w \setminus w_i$ .



Denote  $y = (y_i)_{i=1}^L$  and with mild abuse of notation let  $y_{< i} = (y_1, \dots, y_{i-1})$  for each  $i = 2, \dots, L$  and  $y_{< 1} = 0$ .

#### Assumption (conditional independence)

For each  $i=1,\ldots,L$ , the random variables  $y_i^{\mathrm{lab}},y_i^{\mathrm{ord}},y_i^{\mathrm{pos}}$  and  $y_i^{\mathrm{morph}}$  are mutually independent conditional on  $y_i^{\mathrm{arc}},\ y_{< i}$  and w.

We can decompose the conditional probability of y given w:

$$\begin{split} p_{w}(y) &= \prod_{i=1}^{L} p_{w}(y_{i} \mid y_{< i}) \\ &= \prod_{i=1}^{L} \bigg\{ p_{w}(y_{i}^{\mathsf{arc}} \mid y_{< i}) p_{w}(y_{i}^{\mathsf{lab}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) \\ &\cdot p_{w}(y_{i}^{\mathsf{ord}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) p_{w}(y_{i}^{\mathsf{pos}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) p_{w}(y_{i}^{\mathsf{morph}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) \bigg\}. \end{split}$$

<sup>&</sup>lt;sup>1</sup>For notational simplicity we have written  $p_w(\cdot) \equiv p(\cdot \mid w)$  and  $p_w(\cdot \mid \cdot) \equiv p(\cdot \mid \cdot, w)$ .

#### Sequence-to-sequence setup

Given an input sentence  $w=(w_i)_{i=1}^L$  we generate *embeddings*  $\omega=(\omega_i)_{i=1}^L$ , where  $\omega_i=\mathsf{WordEmbed}(w_i)\oplus\mathsf{CharEmbed}(w_i)\oplus\mathsf{BertEmbed}(w_i).$ 

- WordEmbed is a simple lookup table.
- CharEmbed is implemented using a CNN á la Chiu and Nichols (2016).
- BERT model pre-trained on German text by Chan et al. (2020).

**Encoder**: feed embeddings through a multi-layer bi-directional LSTM with skip-connections and dropout:

$$e = (e_i)_{i=0,...,L} = \mathsf{BiLSTM}(\omega).$$

( $e_0$  is the initial state and represents the root pseudo-node.)

Decoder: feed embeddings through a single-layer uni-directional LSTM with dropout:

$$d = (d_i)_{i=1,...,L} = \mathsf{LSTM}((e_i)_{i=1,...,L}).$$

(the initial state of the decoder is the final state of the encoder.)

#### Classification tasks: quadratic classifier Building on Dozat and Manning (2016).

- Model conditional probabilities of  $y_i^{\text{lab}}$ ,  $y_i^{\text{ord}}$ ,  $v_{:}^{\text{pos}}$  and  $v_{:}^{\text{morph}}$ .
- Encoder and decoder are shared across tasks.

**Example:** part-of-speech classification.

$$e_i^{\text{pos}} = \text{MLP}_{\text{enc}}^{\text{pos}}(e_i); \quad d_j^{\text{pos}} = \text{MLP}_{\text{dec}}^{\text{pos}}(d_j).$$

Obtain class logits v<sup>pos</sup>:

$$\mathbf{v}_{i,j}^{\mathsf{pos}} = \mathsf{Quad}^{\mathsf{pos}}(\mathbf{e}_i^{\mathsf{pos}}, \mathbf{d}_j^{\mathsf{pos}})$$

$$:= \boldsymbol{e}_{i}^{\mathsf{posT}} \mathsf{U}_{\mathsf{h-d}}^{\mathsf{pos}} \boldsymbol{d}_{j}^{\mathsf{pos}} + \boldsymbol{e}_{i}^{\mathsf{posT}} \mathsf{U}_{\mathsf{h-h}}^{\mathsf{pos}} \boldsymbol{e}_{i}^{\mathsf{pos}} + U_{\mathsf{h}}^{\mathsf{pos}} \boldsymbol{e}_{i}^{\mathsf{pos}} + \boldsymbol{d}_{j}^{\mathsf{posT}} \mathsf{U}_{\mathsf{d-d}}^{\mathsf{pos}} \boldsymbol{d}_{j}^{\mathsf{pos}} + U_{\mathsf{d}}^{\mathsf{pos}} \boldsymbol{d}_{j}^{\mathsf{p$$

Fixing child  $w_i$ , the vector **softmax**( $\mathbf{v}_i^{\text{pos}}$ ) can be interpreted as a probability distribution over its parts of speech conditional on having an arc to w:

$$p^{\mathsf{pos}}(c \mid w_i, y_{< j}, w) = \mathsf{softmax}(\mathbf{v}_{i,j}^{\mathsf{pos}})_c.$$

del conditional probabilities of 
$$y_i^{\text{lab}}$$
,  $y_i^{\text{ord}}$ ,  $y_i^{\text{ord}}$ , and  $y_i^{\text{morph}}$ .

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$$tain class \ logits \ v_{i,j}^{\text{pos}}:$$

$$v_{i,j}^{\text{pos}} = \text{Quad}^{\text{pos}}(e_i^{\text{pos}}, d_j^{\text{pos}})$$

$$\vdots = e_j^{\text{pos}\mathsf{T}} \mathsf{U}_{\text{h-d}}^{\text{pos}} d_j^{\text{pos}} + e_i^{\text{pos}\mathsf{T}} \mathsf{U}_{\text{h-d}}^{\text{pos}} e_i^{\text{pos}} + U_{\text{h-d}}^{\text{pos}} e_i^{\text{pos}} + U_{\text{h-d}}^{\text{pos}} d_j^{\text{pos}} + U_{\text{d}}^{\text{pos}} d_j^{\text{pos}} d_j^{\text{pos}} + U_{\text{d}}^{\text{pos}} d_j^{\text{pos}} d_j^{\text{pos}}$$

### The pointer network: quadratic attention mechanism

Building on Dozat and Manning (2016)'s bi-affine mechanism and drawing from Vinyals et al. (2015).

Obtain dimension-reduced representations:

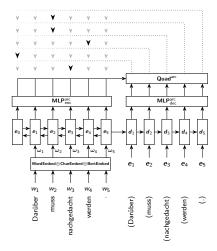
$$e_i^{\mathsf{arc}} = \mathsf{MLP}^{\mathsf{arc}}_{\mathsf{enc}_i}(e_i); \quad d_j^{\mathsf{arc}} = \mathsf{MLP}^{\mathsf{arc}}_{\mathsf{dec}}(d_j).$$

■ Obtain *latent features*  $\mathbf{v}_{i,j}^{arc}$ :

$$\begin{split} \boldsymbol{v}_{i,j}^{\mathsf{arc}} &= \mathsf{Quad}^{\mathsf{arc}}(\boldsymbol{e}_{i}^{\mathsf{arc}}, \boldsymbol{d}_{j}^{\mathsf{arc}}) \\ &\coloneqq \boldsymbol{e}_{i}^{\mathsf{arcT}} \mathsf{U}_{\mathsf{h-d}}^{\mathsf{arc}} \boldsymbol{d}_{j}^{\mathsf{arc}} \\ &+ \boldsymbol{e}_{i}^{\mathsf{arcT}} \mathsf{U}_{\mathsf{h-h}}^{\mathsf{arc}} \boldsymbol{e}_{i}^{\mathsf{arc}} + U_{\mathsf{h}}^{\mathsf{arc}} \boldsymbol{e}_{i}^{\mathsf{arc}} \\ &+ \boldsymbol{d}_{j}^{\mathsf{arcT}} \mathsf{U}_{\mathsf{d-d}}^{\mathsf{arc}} \boldsymbol{d}_{j}^{\mathsf{arc}} + U_{\mathsf{d}}^{\mathsf{arc}} \boldsymbol{d}_{j}^{\mathsf{arc}} + \boldsymbol{u}_{\mathsf{bias}}^{\mathsf{arc}}. \end{split}$$

■ Obtain attention logits  $s_{i,j}^{arc}$ :

$$s_{i,j}^{\mathsf{arc}} = oldsymbol{u}_{\mathsf{agg}}^{\mathsf{arc} \, \mathsf{T}} \mathsf{tanh}(oldsymbol{v}_{i,j}^{\mathsf{arc}}).$$



■ Fixing child  $w_j$ , the vector  $\mathbf{softmax}(\mathbf{s}_{:,j}^{arc})$  can be interpreted as a probability distribution over potential parents:

$$p^{\mathsf{arc}}(w_i \mid y_{< j}, w) = \mathsf{softmax}(s^{\mathsf{arc}}_{:,j})_i.$$

# Inference and Training

#### Training

We find  $\hat{p}$  using SGD with Nesterov momentum, finding a suitably low cross-entropy between the model p and the empirical distribution present in the dataset  $(w^n, y^n)_{n=1}^N$ :

$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{lab}}\mid y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{ord}}\mid y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{lab}}\mid y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{ord}}\mid y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

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$$-\sum_{n=1}^{N}\log\prod_{i=1}^{L_{n}}\left\{p_{w}(y_{i}^{n\operatorname{arc}}\mid y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})p_{w}(y_{i}^{n\operatorname{arc}}, y_{< i}^{n})\right\}$$

#### Inference

Given  $w = (w_i)_{i=1}^L$ , estimate  $y = (y_i)_{i=1}^L$  by maximising the estimated conditional probability:

$$\hat{y} = \arg\max_{y} \left\{ \prod_{i=1}^{L} \left\{ \hat{p}_{w}(y_{i}^{\mathsf{arc}} \mid y_{< i}) \hat{p}_{w}(y_{i}^{\mathsf{lab}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) \right. \\ \left. \cdot \hat{p}_{w}(y_{i}^{\mathsf{ord}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) \hat{p}_{w}(y_{i}^{\mathsf{pos}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) \hat{p}_{w}(y_{i}^{\mathsf{morph}} \mid y_{i}^{\mathsf{arc}}, y_{< i}) \right\} \right\}.$$

The feasible region is very large, so the maximisation is approximated via beam search.

#### Model evaluation

The TIGER treebank is a widely-used corpus of  $\sim 50\,000$  constituent trees. Its main textual hasis is the Frankfurter Rundschau

- $\blacksquare$  97% of the dataset is usable as training examples, with train/dev/test split of 80/10/10%.
- PARSEVAL metrics initially proposed by Black et al. (1991):

$$P = \frac{\text{\# of correct constituents in prediction}}{\text{\# of total constituents in prediction}}$$

$$P = \frac{\text{\# of correct constituents in prediction}}{\text{\# of total constituents in prediction}}; \quad R = \frac{\text{\# of correct constituents in prediction}}{\text{\# of total constituents in reference}}.$$

Model	F1	Disc. F1
Coavoux et al. (2019)	82.7	55.9
Corro (2020)	90.0	62.1
FGonzález & GRodríguez (2022)	89.8	71.0
Chen & Komachi (2023)	89.6	70.9
This work	90.59	84.74

Table: Comparison of overall F1-score (%) and F1-score measured only on discontinuous constituents (disc. F1). Calculated using disco-dop (Van Cranenburgh et al., 2016) as standard practice. All models configured with BFRT

Model	pos m	orph (avr)
Müller et al. (2013)	98.20	98.27
Schnabel & Schütze (2014)	97.50	97.76
Kondratyuk et al. (2018)	98.58	98.97
This work	99.21	99.60

Table: Comparison of part of speech (pos) and morphology accuracies (%). Morphology accuracies are the average of accuracies for case, degree, gender, mood, number, person and tense.

# Appendix: Mathematical justification for quadratic classifier

Notation has been simplified for presentational clarity. Single c is multinoulli and

$$\begin{bmatrix} \boldsymbol{e}_i \\ \boldsymbol{d}_j \end{bmatrix} \mid c \sim \mathcal{N} \left( \begin{bmatrix} \boldsymbol{\mu}_c \\ \boldsymbol{\phi}_c \end{bmatrix}, \begin{bmatrix} \boldsymbol{A}_c & \boldsymbol{Q}_c^\mathsf{T} \\ \boldsymbol{Q}_c & \boldsymbol{B}_c \end{bmatrix}^{-1} \right) \implies \mathbf{d}_j \mid c \sim \mathcal{N} \left( \boldsymbol{\phi}_c, \boldsymbol{P}_c^{-1} \right).$$

The conditional log-probability of c is the following affine quadratic form:

$$\log p(c \mid \mathbf{e}_{i}, \mathbf{d}_{j}) = k_{c} - \frac{1}{2} \left( (\mathbf{e}_{i} - \boldsymbol{\mu}_{c}) + A_{c}^{-1} Q_{c}^{\mathsf{T}} (\mathbf{d}_{j} - \boldsymbol{\phi}_{c}) \right)^{\mathsf{T}} A_{c} \left( (\mathbf{e}_{i} - \boldsymbol{\mu}_{c}) + A_{c}^{-1} Q_{c}^{\mathsf{T}} (\mathbf{d}_{j} - \boldsymbol{\phi}_{c}) \right)$$

$$- \frac{1}{2} (\mathbf{d}_{j} - \boldsymbol{\phi}_{j})^{\mathsf{T}} P_{c} (\mathbf{d}_{j} - \boldsymbol{\phi}_{j}) - \log p(\mathbf{e}_{i}, \mathbf{d}_{j})$$

$$= - \mathbf{e}_{i}^{\mathsf{T}} Q_{c}^{\mathsf{T}} \mathbf{d}_{j} - \frac{1}{2} \mathbf{e}_{i}^{\mathsf{T}} A_{c} \mathbf{e}_{i} - \frac{1}{2} \mathbf{d}_{j}^{\mathsf{T}} (P_{c} + Q_{c} A_{c}^{-1} Q_{c}^{\mathsf{T}}) \mathbf{d}_{j} + \left( \boldsymbol{\mu}_{c}^{\mathsf{T}} A_{c} + \boldsymbol{\phi}_{c}^{\mathsf{T}} Q_{c} \right) \mathbf{e}_{i}$$

$$+ \left( \boldsymbol{\phi}_{c}^{\mathsf{T}} Q_{c} A_{c}^{-1} Q_{c}^{\mathsf{T}} \boldsymbol{\phi}^{\mathsf{T}} P_{c} + \boldsymbol{\mu}_{c}^{\mathsf{T}} Q_{c}^{\mathsf{T}} \right) \mathbf{d}_{j}$$

$$- \boldsymbol{\mu}_{c}^{\mathsf{T}} Q_{c}^{\mathsf{T}} \boldsymbol{\phi}_{c} - \frac{1}{2} \boldsymbol{\mu}_{c}^{\mathsf{T}} A_{c} \boldsymbol{\mu}_{c}$$

$$- \frac{1}{2} \boldsymbol{\phi}^{\mathsf{T}} (P_{c} + Q_{c} A_{c}^{-1} Q_{c}^{\mathsf{T}}) \boldsymbol{\phi} + k_{c}$$

$$- \log p(\mathbf{e}_{i}, \mathbf{d}_{j})$$

$$= \text{cth row of } \mathbf{e}_{i}^{\mathsf{T}} \mathbf{U}_{h-d} \mathbf{d}_{j} + \mathbf{e}_{i}^{\mathsf{T}} \mathbf{U}_{h-h} \mathbf{e}_{i} + \mathbf{d}_{j}^{\mathsf{T}} \mathbf{U}_{d-d} \mathbf{d}_{j} + U_{h} \mathbf{e}_{i} + U_{d} \mathbf{d}_{j} + \mathbf{u}_{bias}$$

$$= \operatorname{constant in } c$$

Memory-efficient implementation: assuming conditional normality:

$$v_{i,j}^c = k^c - \|W_1^c e_i + W_2^c d_j + w_3^c\|_2^2.$$

so throw away

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