

Figure 1.1: Example of a discontinuous constituent tree for the German sentence 'Darüber muss nachgedacht werden.' ('this must be considered.'). Bold lines indicate head words.

## 1 Preliminaries: Constituency Trees

## 2 Encoder-Decoder Setup

Let  $N = \{1, ..., n\}$  be an index set. Given an input sentence  $w = (w_i)_{i \in N}$  we generate a sequence of embeddings  $\boldsymbol{\omega} = (\boldsymbol{\omega}_i)_{i \in N}$  where

$$\omega_i = \mathbf{WordEmbed}(w_i) \oplus \mathbf{CharEmbed}(w_i) \oplus \mathbf{BertEmbed}(w_i)$$

Encoder: feed embeddings through a multi-layer bi-directional LSTM with skip-connections and dropout:

$$\mathbf{e} = (\mathbf{e}_i)_{i=0,\dots,n} = \mathbf{BiLSTM}(\boldsymbol{\omega})$$

**Decoder**: feed embeddings through a single-layer uni-directional LSTM with dropout:

$$\mathbf{d} = (\mathbf{d}_i)_{i=1,\dots,n} = \mathbf{LSTM}(\boldsymbol{\omega})$$

## 3 Bi-affine Attention Mechanism

Goal: given dependency (child)  $w_j$ , choose the most probable head (parent)  $e_i$ . We feed  $\mathbf{e}$  and  $\mathbf{d}$  through MLPs to produce sequences ( $\mathbf{e}^{\mathrm{arc}}$ ,  $\mathbf{d}^{\mathrm{arc}}$ ) of dimension-reduced vectors. These are fed into a bi-affine layer which produces latent features  $\mathbf{v}^{\mathrm{arc}}$  that are then fed into an attention layer, resulting in logits corresponding to strength of an arc.

$$\mathbf{e}^{\mathrm{arc}} = \mathbf{MLP}^{\mathrm{arc}}_{\mathrm{enc}}(\mathbf{e}); \qquad \mathbf{d}^{\mathrm{arc}} = \mathbf{MLP}^{\mathrm{arc}}_{\mathrm{dec}}(\mathbf{d})$$
 (3.1)

$$\mathbf{v}_{i,j}^{\text{arc}} = \mathbf{BiAff}^{\text{arc}}(\mathbf{e}_i^{\text{arc}}, \mathbf{d}_j^{\text{arc}}) \tag{3.2}$$

$$= \mathbf{e}_{i}^{\mathrm{arc}\mathsf{T}} \mathbf{U}_{\mathrm{h-d}}^{\mathrm{arc}} \mathbf{d}_{i}^{\mathrm{arc}} + \mathbf{e}_{i}^{\mathrm{arc}\mathsf{T}} \mathbf{U}_{\mathrm{h-h}}^{\mathrm{arc}} \mathbf{e}_{i}^{\mathrm{arc}} + \mathbf{d}_{i}^{\mathrm{arc}\mathsf{T}} \mathbf{U}_{\mathrm{d-d}}^{\mathrm{arc}} \mathbf{d}_{i}^{\mathrm{arc}}$$

$$(3.3)$$

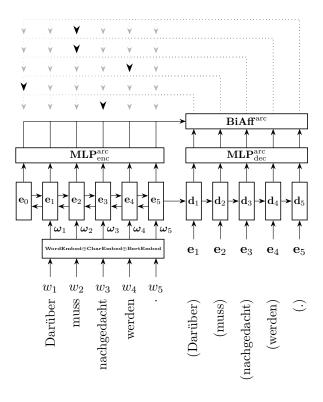
$$+ U_{\rm h}^{\rm arc} \mathbf{e}_i^{\rm arc} + U_{\rm d}^{\rm arc} \mathbf{d}_i^{\rm arc} + \mathbf{u}_{\rm bias}^{\rm arc}$$

$$\tag{3.4}$$

$$s_{i,j}^{\text{arc}} = \mathbf{u}_{\text{agg}}^{\text{arc}\mathsf{T}} \text{tanh}(\mathbf{v}_{i,j}^{\text{arc}})$$
 (3.5)

Fixing dependency j, the vector **softmax**( $\mathbf{s}_{:,j}$ ) can be interpreted as an estimated probability distribution over potential heads.

$$\hat{p}^{\text{arc}}(w_i \mid y_{< j}, w) = \mathbf{softmax}(\mathbf{s}_{:,j}^{\text{arc}})_i.$$



## Bi-affine Classifier for Attachment Order, POS and Morphology 4

Attachment order, POS and morphologies are predicted via a classification. We use a bi-affine classifier which allows us to model probabilities conditional on arcs, and thus use structural cues in addition to encoder/decoder states to better capture the complexity of the language. The encoder and decoder are *shared* across the tasks.

For example suppose we would like to predict the part of speech  $c \in \mathcal{C}$  for word  $w_i$  conditional on its parent being  $w_i$ .

$$e^{pos} = MLP_{enc}^{pos}(e);$$
 $d^{pos} = MLP_{dec}^{pos}(d)$ 

$$(4.1)$$

$$\mathbf{e}^{\text{pos}} = \mathbf{MLP}^{\text{pos}}_{\text{enc}}(\mathbf{e}); \qquad \mathbf{d}^{\text{pos}} = \mathbf{MLP}^{\text{pos}}_{\text{dec}}(\mathbf{d})$$

$$\mathbf{v}^{\text{pos}}_{i,j} = \mathbf{BiAff}^{\text{pos}}(\mathbf{e}^{\text{pos}}_{i}, \mathbf{d}^{\text{pos}}_{j})$$

$$\coloneqq \mathbf{e}^{\text{pos}\mathsf{T}}_{i} \mathbf{U}^{\text{pos}}_{\text{h-d}} \mathbf{d}^{\text{pos}}_{i} + \mathbf{e}^{\text{pos}\mathsf{T}}_{i} \mathbf{U}^{\text{pos}}_{\text{h-h}} \mathbf{e}^{\text{pos}}_{i} + \mathbf{d}^{\text{pos}\mathsf{T}}_{i} \mathbf{U}^{\text{pos}}_{\text{d-d}} \mathbf{d}^{\text{pos}}_{i}$$

$$+ U^{\text{pos}}_{\text{h}} \mathbf{e}^{\text{pos}}_{i} + U^{\text{pos}}_{\text{d}} \mathbf{d}^{\text{pos}}_{i} + \mathbf{u}^{\text{pos}}_{\text{bias}}$$

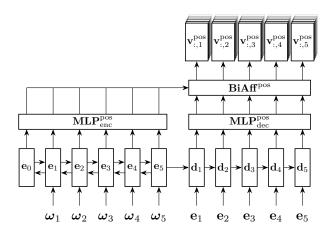
$$(4.3)$$

$$= \mathbf{e}_{i}^{\text{pos} \mathsf{I}} \mathbf{U}_{\text{h-d}}^{\text{pos}} \mathbf{d}_{i}^{\text{pos}} + \mathbf{e}_{i}^{\text{pos} \mathsf{I}} \mathbf{U}_{\text{h-h}}^{\text{pos}} \mathbf{e}_{i}^{\text{pos}} + \mathbf{d}_{i}^{\text{pos} \mathsf{I}} \mathbf{U}_{\text{d-d}}^{\text{pos}} \mathbf{d}_{i}^{\text{pos}}$$

$$\tag{4.3}$$

$$+U_{\rm h}^{\rm pos}\mathbf{e}_{i}^{\rm pos}+U_{\rm d}^{\rm pos}\mathbf{d}_{i}^{\rm pos}+\mathbf{u}_{\rm hias}^{\rm pos} \tag{4.4}$$

$$\hat{p}^{\text{pos}}(c \mid w_i; y_{< j}, w) = \mathbf{softmax}(\mathbf{v}_{i,j}^{\text{pos}})_c$$
(4.5)



Hi there