High order numerical simulation of the underdamped Langevin diffusion

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Introduction

The underdamped Langevin diffusion is given by the following SDE:

$$dQ_t = P_t dt, (1)$$

$$dP_t = -\nabla U(Q_t) dt - \nu P_t dt + \sqrt{\frac{2\nu}{\beta}} dW_t, \qquad (2)$$

where $Q, P \in \mathbb{R}^d$ will represent the position and velocity of a particle moving in a potential $U : \mathbb{R}^d \to \mathbb{R}$ under the influence of a frictional force (with coefficient v > 0) along with a stochastic force given by a d-dimensional Brownian motion W (and inverse temperature β).

The underdamped Langevin equation can be viewed as an extension of Newton's second law and is a key model in statistical mechanics. ([1] is a detailed textbook that surveys these scientific applications)

Introduction

Recently this equation has been applied to computational statistics as, under mild conditions on the potential (see [2] for more details), the process admits a stationary measure with the following density:

$$\varphi(q, p) \propto \exp\left(-\beta \left(U(q) + \frac{1}{2} \|p\|^2\right)\right).$$

Hence by setting U equal to the log density of a target distribution, it is possible to generate samples by simulating a Langevin diffusion.

In practice, (1) can not be solved exactly and must be approximated.

Introduction

Our strategy for discretizing the underdamped Langevin equation is

- 1. Replace the Brownian motion W by a piecewise linear path \widehat{W} .
- 2. Along each piece of \widehat{W} we can approximate (1) using the ODE:

$$d\widehat{Q}_t = \widehat{P}_t \, dt, \tag{3}$$

$$d\widehat{P}_t = f(\widehat{Q}_t) dt - \nu \widehat{P}_t dt + \sigma d\widehat{W}_t, \tag{4}$$

where $f := -\nabla U$ and $\sigma := \sqrt{\frac{2\nu}{\beta}}$.

3. In each step, discretize (3) and (4) with a suitable ODE solver.

To construct the path \widehat{W} , we shall use the below theorem from [3].

Theorem (Brownian motion as a cubic with independent noise)

Consider a standard Brownian motion W over the unit interval [0,1]. Let \widetilde{W} be the (unique) cubic polynomial with a root at 0 such that

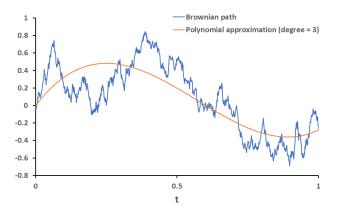
$$\int_0^1 u^k d\widetilde{W}_u = \int_0^1 u^k dW_u, \text{ for } k = 0, 1, 2.$$

Then

$$W = \widetilde{W} + Z$$

where Z is a centred Gaussian process independent of the cubic \widetilde{W} .

Therefore, the cubic polynomial \widetilde{W} is an unbiased estimator for W.



The piecewise linear path \widehat{W} will be designed to resemble this cubic.

Theorem (Pathwise approximation of the cubic polynomial \widehat{W})

There exists a piecewise linear path \widehat{W} on [0,1] and a>0 such that:

- 1. $\widehat{W}_0 = 0$.
- 2. \widehat{W} has three pieces which connect at $\frac{1}{2}(1\pm a)$.
- 3. $\int_0^1 u^k d\widehat{W}_u = \int_0^1 u^k d\widetilde{W}_u$, for k = 0, 1, 2, 3.

Proof.

Note that for any fixed $a \in (0,1)$, the first three integral conditions and \widehat{W}_0 are enough to uniquely determine the piecewise linear path.

Hence, the idea of the proof is to derive a necessary condition for a.

Proof. (continued)

Using the orthogonality of the Legendre polynomials, it follows that

$$\int_0^1 (20u^3 - 30u^2 + 12u - 1) d\widehat{W}_u$$

$$= \int_0^1 (20u^3 - 30u^2 + 12u - 1) d\widetilde{W}_u$$

$$= \int_0^1 (20u^3 - 30u^2 + 12u - 1) (\widetilde{W}_u)' du$$

$$= 0.$$

On the other hand, the above integral can be explicitly computed as

$$\int_0^1 (20u^3 - 30u^2 + 12u - 1) d\widehat{W}_u$$

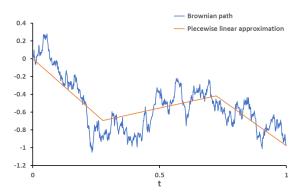
$$= \frac{1}{8} (5a^3 + 5a^2 - a - 1) (\widehat{W}_1 - \widehat{W}_{\frac{1}{2}(1+a)} - \widehat{W}_{\frac{1}{2}(1-a)}).$$

Proof. (continued)

So in order for \widehat{W} to exist, the constant a must satisfy the equation

$$5a^3 + 5a^2 - a - 1 = 0.$$

Therefore by setting $a = \frac{\sqrt{5}}{5}$, we can construct the desired path. \square



In practice, \widehat{W} can be generated on [s,t] using the random variables

$$\begin{split} W_{s,t} &:= W_t - W_s, \\ H_{s,t} &:= \frac{1}{h} \int_s^t W_{s,u} - \frac{u - s}{h} W_{s,t} \, du, \\ K_{s,t} &:= \frac{1}{h^2} \int_s^t \left(W_{s,u} - \frac{u - s}{h} W_{s,t} \right) \left(\frac{1}{2} h - (u - s) \right) du, \end{split}$$

where h = t - s.

It is straightforward to prove that $(W_{s,t}, H_{s,t}, K_{s,t})$ are independent and uniquely determine the cubic polynomial \widetilde{W} (see [3] for details).

Furthermore $W_{s,t} \sim N(0,h)$, $H_{s,t} \sim N(0,\frac{1}{12}h)$ and $K_{s,t} \sim N(0,\frac{1}{720}h)$.

Theorem (Pathwise approximation of the Brownian motion W)

Let \widehat{W} be the piecewise linear path on [s,t] with three pieces which connect the points (s,W_s) , (s+Ah,B), (t-Ah,C), (t,W_t) given by

$$A = \frac{1}{2} - \frac{1}{2\sqrt{5}},$$

$$\frac{1}{2}(B+C) = W_s + \frac{1}{2}W_{s,t} + \frac{1}{1-A}H_{s,t},$$

$$\frac{1}{2}(B-C) = \frac{6}{1-A}K_{s,t} - \frac{1}{2}(1-2A)W_{s,t}.$$

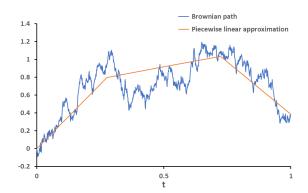
Then \widehat{W} matches the increment $W_{s,t}$, the time areas $(H_{s,t},K_{s,t})$ and

$$\int_s^t (u-s)^2 \, \widehat{W}_{s,u} \, du = \mathbb{E}\left[\left. \int_s^t (u-s)^2 \, W_{s,u} \, du \, \right| W_{s,t}, H_{s,t}, K_{s,t} \, \right].$$

Proof.

The result is a direct consequence of the previous two theorems.

When approximating the underdamped Langevin diffusion on [0, T], we shall generate \widehat{W} on the uniform grid \triangle_N with mesh size $h = \frac{T}{N}$.



Recall that the underdamped Langevin equation is the SDE given by

$$dQ_t = P_t dt, (5)$$

$$dP_t = f(Q_t) dt - vP_t dt + \sigma dW_t.$$
 (6)

Provided that f is twice differentiable, we have the Taylor expansion

$$\begin{pmatrix} Q_t \\ P_t \end{pmatrix} = \begin{pmatrix} Q_s \\ P_s \end{pmatrix} + (\cdots)h + (\cdots)W_{s,t} + (\cdots)\int_s^t W_{s,u} du + (\cdots)h^2 + (\cdots)h^3
+ (\cdots)\int_s^t \int_s^u W_{s,v} dv du + (\cdots)\int_s^t \int_s^u \int_s^v W_{s,r} dr dv du
+ (\cdots)\int_s^t \int_s^u \int_s^v (r-s) dW_r dv du + O(h^4),$$

where (\cdots) are terms involving the vector fields and their derivatives.

Similarly, $(\widehat{Q}, \widehat{P})$ will also have this expansion but with \widehat{W} integrals.

By the previous theorem, these integrals are approximated optimally using \widehat{W} (in an $L^2(\mathbb{P})$ sense) and hence gives the local error estimate

Theorem

Provided the vector field f and its first two derivatives are bounded and Lipschitz continuous, there exist constants C_1 , $C_2 > 0$ such that

$$\mathbb{E}\left[\left\|\begin{pmatrix} Q_t \\ P_t \end{pmatrix} - \begin{pmatrix} \widehat{Q}_t \\ \widehat{P}_t \end{pmatrix}\right\|^2\right] \le \left(1 + C_1 h\right) \mathbb{E}\left[\left\|\begin{pmatrix} Q_s \\ P_s \end{pmatrix} - \begin{pmatrix} \widehat{Q}_s \\ \widehat{P}_s \end{pmatrix}\right\|^2\right] + C_2 h^7, \quad (7)$$

for sufficiently small h.

Sketch Proof.

We derive (7) from the Taylor expansions of (Q_t, P_t) and $(\widehat{Q}_t, \widehat{P}_t)$.

The first term in the estimate follows using the Lipschitz continuity.

Therefore it is helpful to consider the case when $(Q_s, P_s) = (\widehat{Q}_s, \widehat{P}_s)$. As the $O(h^{\frac{7}{2}})$ integrals in both expansions have mean zero, we have

$$\mathbb{E}\left[\begin{pmatrix} Q_t \\ P_t \end{pmatrix} - \begin{pmatrix} \widehat{Q}_t \\ \widehat{P}_t \end{pmatrix}\right] \sim O(h^4). \tag{8}$$

It's important that the above quantity is strictly smaller than $O(h^{\frac{7}{2}})$ so that large (but unbiased) terms disappear in the full expansion of

$$\mathbb{E}\left[\left\|\begin{pmatrix}Q_t\\P_t\end{pmatrix}-\begin{pmatrix}\widehat{Q}_t\\\widehat{P}_t\end{pmatrix}\right\|^2\right].$$

Sketch Proof. (continued)

The explicit calculation required to derive (7) is lengthy but follows the typical argument for $L^2(\mathbb{P})$ error estimation (see [4] for details).

The key idea is that the leading error terms are $O(h^{\frac{7}{2}})$ but unbiased. So by squaring and taking an expectation, the terms that cannot be estimated using Lipschitz continuity will have a size of $O(h^7)$.

The above theorem then leads to the following global error estimate

Theorem (Strong convergence rate of the ODE approximation)

Suppose that $(\widehat{Q},\widehat{P})$ was obtained on [0,T] using a uniform grid \triangle_N with mesh size $h=\frac{T}{N}$ and an initial value $(Q_0,P_0)=(\widehat{Q}_0,\widehat{P}_0)$. Then

$$\left\| \begin{pmatrix} Q_T \\ P_T \end{pmatrix} - \begin{pmatrix} \widehat{Q}_T \\ \widehat{P}_T \end{pmatrix} \right\|_{L^2(\mathbb{P})} \sim O(h^3).$$

Similarly, by comparing the two Taylor expansions we can show that

Theorem (Weak convergence rate of the ODE approximation)

Suppose that $(\widehat{Q},\widehat{P})$ was obtained on [0,T] using a uniform grid \triangle_N with a mesh size of $h=\frac{T}{N}$ and the initial value $(Q_0,P_0)=(\widehat{Q}_0,\widehat{P}_0)$. Then for any polynomial p, there exists a constant $C_p>0$ such that

$$\left| \mathbb{E} \left[p \begin{pmatrix} Q_T \\ P_T \end{pmatrix} \right] - \mathbb{E} \left[p \begin{pmatrix} \widehat{Q}_T \\ \widehat{P}_T \end{pmatrix} \right] \right| \leq C_p h^3,$$

for all sufficiently small step sizes h.

Remark

The ODE driven by \widehat{W} gives a third order numerical method for (1).

Discretization of the underdamped Langevin ODE

Since the ODE driven by \widehat{W} is a third order approximation, it should be discretized using a numerical method that is at least third order.

Due to the structure of (3, 4), we can apply Runge-Kutta-Nyström (RKN) methods, which are explicitly designed for ODEs of the form

$$y'' = F(t, y),$$
 (9)
 $y(0) = y_0, \quad y'(0) = y'_0,$

In addition, we wish for the RKN method to be symplectic since the underdamped Langevin equation is a stochastic Hamiltonian system.

Fortunately, the RKN method proposed by [5] has these properties.

Discretization of the underdamped Langevin ODE

To propagate the numerical solution over [s, t], we use the variables

$$\begin{pmatrix} y_u \\ x_u \end{pmatrix} := \begin{pmatrix} e^{\frac{1}{2}\nu(u-s)} \widehat{Q}_u \\ e^{\nu(u-s)} \widehat{P}_u \end{pmatrix}, \quad \forall u \in [s,t],$$

to represent the system (3, 4) using the following second order ODE

$$\frac{d^{2}y}{du^{2}} = \frac{1}{4}v^{2}y + e^{\frac{1}{2}v(u-s)} \left(f\left(e^{-\frac{1}{2}v(u-s)}y\right) + \sigma \frac{d\widehat{W}}{du} \right), \qquad (10)$$

$$y_{s} = \widehat{Q}_{s}, \quad y'_{s} = \widehat{P}_{s} + \frac{1}{2}v\widehat{Q}_{s}.$$

We can apply RKN methods on the intervals where $\frac{d\widehat{W}}{du}$ is constant.

Discretization of the underdamped Langevin ODE

For the numerical example, we will use the below numerical method.

Definition (A third order three-stage symplectic RKN method)

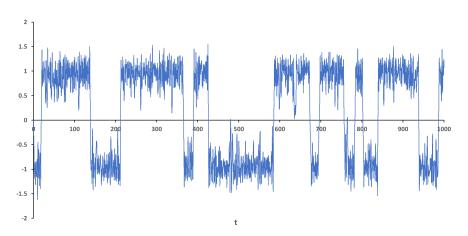
This method is presented in [5] and defined by the Butcher tableau:

0			
0.630847693	0.164217030		
0.536704894	0.139710559	-0.103005664	
	0.260311692	0.4039053382	-0.164217030
	0.260311692	1.094142798	-0.354454490

For the numerical experiment, we shall consider a scalar double-well potential with the same parameters used in the first example of [6]:

$$U(q) = (q^2 - 1)^2,$$
 $v = 1, \quad \beta = 3, \quad (Q_0, P_0) = 0.$

A sample path of the Langevin diffusion obtained by discretizing (3)



Let \widehat{Q}_T be the approximate position at time T computed with $h=\frac{T}{N}$.

We examine the strong and weak convergence using the estimators:

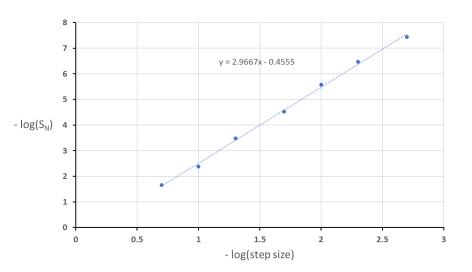
$$S_N := \sqrt{\mathbb{E}\left[\left(\widehat{Q}_T - Q_T^{\text{fine}}\right)^2\right]},\tag{11}$$

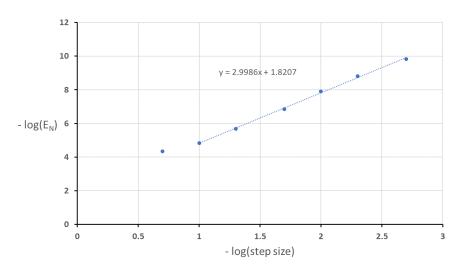
$$E_N := \left| \mathbb{E} \left[\hat{Q}_T^2 \right] - \mathbb{E} \left[\left(Q_T^{\text{fine}} \right)^2 \right] \right|, \tag{12}$$

where the expectations are approximated by Monte-Carlo simulation and $Q_T^{\rm fine}$ denotes the numerical solution of (1) obtained at time T using the proposed method with a "fine" step size of $\min\left(\frac{h}{25}, \frac{T}{50000}\right)$.

We will compute both \widehat{Q}_T and Q_T^{fine} using the same Brownian paths.

For the numerical experiment, we shall use a time horizon of T = 10.





Future work

- ► How well does the proposed numerical method approximate the stationary distribution of the underdamped Langevin diffusion?
- Is this method practical for problems within Bayesian statistics?
- ▶ What are best ODE solvers for discretizing the system (3), (4)?
- Can this methodology be improved by using variable step sizes?

Thank you for your attention!

References 1

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