

Suffix Notation

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1 Lecture 1: Basic Definitions

1.1 Suffix Notation

Let there be a vector $\underline{c} = \underline{a} + \underline{b}$, where $\underline{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\underline{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$. Then \underline{c} is equivalent to:

$$c_i = a_i + b_i$$

In suffix notation:

$$c_j = a_j + b_j \quad j = 1, 2, 3$$

The inner product of two vectors:

$$\begin{aligned} a \cdot b &= a_1b_1 + a_2b_2 + a_3b_3 \\ &= \sum_{j=1}^3 a_jb_j \end{aligned}$$

For a vector $\underline{a} = a_i$, i is a free index. For the dot product above: $\sum_{j=1}^3 a_jb_j$, j is a dummy suffix.

For suffix notation, an index cannot be repeated more than two times in an equation.

Example 1 Write $(a \cdot b)(c \cdot d)$ in suffix notation

Solution 1 Here we take that:

$$a \cdot b = a_jb_j \quad j = 1, 2, 3$$

and that

$$c \cdot d = c_id_i \quad i = 1, 2, 3$$

Now we can say that

$$(a \cdot b)(c \cdot d) = a_jb_jc_id_i \quad i, j = 1, 2, 3$$

Example 2 Write $a_jb_ic_j$ in normal vector notation

Solution 2 We know that

$$a_jb_ic_j = a_jc_jb_i$$

Which is:

$$(a \cdot c)b$$

Example 3 Write the vector notation $\underline{u} + (\underline{a} \cdot \underline{b})\underline{v} = |\underline{a}|^2(\underline{b} \cdot \underline{v})\underline{a}$ in suffix notation

Solution 3 We know that

$$a_jb_ic_j = a_jc_jb_i$$

Which is:

$$(a \cdot c)b$$

Example 4 Write the vector notation $\underline{u} + (\underline{a} \cdot \underline{b})\underline{v} = |\underline{a}|^2(\underline{b} \cdot \underline{v})\underline{a}$ in suffix notation

Solution 4 Firstly:

$$[\underline{u} + (\underline{a} \cdot \underline{b})\underline{v}]_i = [|\underline{a}|^2(\underline{b} \cdot \underline{v})\underline{a}]_i$$

Then,

$$u_i + (a_jb_j)v_i = a_ja_jb_lv_ia_i \quad j, l = 1, 2, 3$$

1.2 The Kronecker Delta $\delta_{i,j}$

The function is defined:

$$\delta_{i,j} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

The suffixes i and j can each take the values 1, 2, 3 so $\delta_{i,j}$ has nine elements.

We can write the function as the identity matrix:

$$\delta_{i,j} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$\delta_{i,j}$ is called a substitution tensor, since its effect when multiplied by a_j is to replace j with i .

$$\begin{aligned} \delta_{i,j}a_j &= \sum_{j=1}^3 \delta_{i,j}a_j \\ &= \delta_{i1}a_1 + \delta_{i2}a_2 + \delta_{i3}a_3 \\ &= \delta_{11}a_1 + \delta_{12}a_2 + \delta_{13}a_3 \\ &\quad + \delta_{21}a_1 + \delta_{22}a_2 + \delta_{23}a_3 \\ &\quad + \delta_{31}a_1 + \delta_{32}a_2 + \delta_{33}a_3 \\ &= a_1 + a_2 + a_3 \end{aligned}$$

From this we can say: $\delta_{i,j}a_i = a_j$ and $\delta_{i,j}a_j = a_i$

Example 5 $\delta_{i,j}$ and dot product

Solution 5

$$\begin{aligned} a \cdot b &= a_i b_i \quad i = 1, 2, 3 \\ &= \delta_{i,j} a_j b_i \\ &= a_j \delta_{i,j} b_i \\ &= a_j b_j \end{aligned}$$

1.4 $\varepsilon_{i,j,k}$ and cross product

Let $\underline{a} = a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}$ and $\underline{b} = b_1 \hat{i} + b_2 \hat{j} + b_3 \hat{k}$. Then their cross product is:

$$\underline{a} \times \underline{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

and in suffix notation, we can write the above as; $(\underline{a} \times \underline{b})_i = \varepsilon_{ijk} a_j b_k$ where j, k are dummy suffixes and must be summed over 1 to 3.

1.5 ε_{ijk} and the scalar triple product

We can take the scalar triple product, $\underline{a} \cdot \underline{b} \times \underline{c}$, then we can do the following:

$$\begin{aligned} \underline{a} \cdot \underline{b} \times \underline{c} &= a_i (\underline{b} \times \underline{c})_i \\ &= a_i \varepsilon_{ijk} b_j c_k \\ &= \varepsilon_{ijk} a_i b_j c_k \\ &= c_k \varepsilon_{ijk} a_i b_j \end{aligned}$$

from the above we show that $\underline{a} \cdot \underline{b} \times \underline{c} = \underline{c} \cdot \underline{a} \times \underline{b}$. We can expand $\varepsilon_{ijk} a_i b_j c_k$ to get:

$$\begin{aligned} &= \varepsilon_{123} a_1 b_2 c_3 + \varepsilon_{231} a_2 b_3 c_1 + \varepsilon_{312} a_3 b_1 c_2 \\ &\quad + \varepsilon_{321} a_3 b_2 c_1 + \varepsilon_{213} a_2 b_1 c_3 + \varepsilon_{132} a_1 b_3 c_2 \\ &= a_1 b_2 c_3 + a_2 b_3 c_1 + a_3 b_1 c_2 - a_3 b_2 c_1 - a_2 b_1 c_3 - a_1 b_3 c_2 \end{aligned}$$

which is the expanded form of the triple scalar product.

1.6 A relation between ε_{ijk} and $\delta_{i,j}$

We are going to prove the following statement:

$$\varepsilon_{ijk} \varepsilon_{klm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$$

Since all of the coordinate axis are the same, just consider $i = 1$:

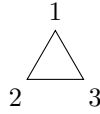
If then $j = 1$, we get that $\varepsilon_{11k} = 0$ and so LHS = 0. Then considering the RHS, we get that $\delta_{1l} \delta_{1m} - \delta_{1m} \delta_{1l} = 0$, so equation holds.

If $j = 2$, then $\varepsilon_{ijk} = \varepsilon_{12k} = 0$, unless $k = 3$, so then only $k = 3$ contributes to the sum. So $\varepsilon_{klm} = \varepsilon_{3lm}$, so zero unless l and m are 1 and 2. So we can conclude that $\varepsilon_{ijk} \varepsilon_{klm} = \varepsilon_{123} \varepsilon_{312}$ or $\varepsilon_{123} \varepsilon_{321}$, so the

1.3 The Alternating Tensor, $\varepsilon_{i,j,k}$

$\varepsilon_{i,j,k}$ is useful for manipulating expressions involving the cross product of two vectors and curl of a vector.

$$\varepsilon_{i,j,k} = \begin{cases} +1 & \text{if } (i, j, k) = (1, 2, 3), (2, 3, 1) \text{ or } (3, 1, 2) \\ -1 & \text{if } (i, j, k) = (3, 2, 1), (2, 1, 3) \text{ or } (1, 3, 2) \\ 0 & \text{if any of } i, j, k \text{ are equal} \end{cases}$$



The +1 case can be also written as 1, 2 or 3 are in clockwise order. So if you take a triangle and then go clockwise around it from the first element, that the order they are in. The -1 are in anticlockwise order. Hence meaning the opposite of clockwise.

The six non-zero elements of ε_{ijk} :

$$\begin{aligned} \varepsilon_{123} &= \varepsilon_{231} = \varepsilon_{312} = +1 \\ \varepsilon_{321} &= \varepsilon_{213} = \varepsilon_{132} = -1 \\ \varepsilon_{ijk} &= 0, \text{ otherwise} \end{aligned}$$

We can take that; $\varepsilon_{ijk} = \varepsilon_{jki}$ as they are in clockwise order. This also implies $\varepsilon_{ijk} = -\varepsilon_{jik}$ because if ijk are in clockwise order then jik must be in counterclockwise order.

LHS is either ± 1 . Looking at RHS, we have either:
 $\delta_{11}\delta_{22} - \delta_{12}\delta_{21}$ or $\delta_{12}\delta_{21} - \delta_{11}\delta_{22}$. This gives ± 1 in
the same permutation as the LHS. So equation holds.
If $j = 3$, then