

The GGCMI Phase II experiment: global crop yield responses to changes in carbon dioxide, temperature, water, and nitrogen levels

James Franke^{a,b,*}, Joshua Elliott^{b,c}, Christoph Müller^d, Alexander Ruane^e, Abigail Snyder^f, Jonas Jägermeyr^{c,b,d,e}, Juraj Balkovic^{g,h}, Philippe Ciais^{i,j}, Marie Dury^k, Pete Falloon^l, Christian Folberth^g, Louis François^k, Tobias Hank^m, Munir Hoffmannⁿ, Cesar Izaurralde^{o,p}, Ingrid Jacquemin^k, Curtis Jones^o, Nikolay Khabarov^g, Marian Kochⁿ, Michelle Li^{b,l}, Wenfeng Liu^{r,i}, Stefan Olin^s, Meridel Phillips^{e,t}, Thomas Pugh^{u,v}, Ashwan Reddy^o, Xuhui Wang^{i,j}, Karina Williams^l, Florian Zabel^m, Elisabeth Moyer^{a,b}

^aDepartment of the Geophysical Sciences, University of Chicago, Chicago, IL, USA

^bCenter for Robust Decision-making on Climate and Energy Policy (RDCEP), University of Chicago, Chicago, IL, USA

^cDepartment of Computer Science, University of Chicago, Chicago, IL, USA

^dPotsdam Institute for Climate Impact Research, Leibniz Association (Member), Potsdam, Germany

^eNASA Goddard Institute for Space Studies, New York, NY, United States

^fJoint Global Change Research Institute, Pacific Northwest National Laboratory, College Park, MD, USA

^gEcosystem Services and Management Program, International Institute for Applied Systems Analysis, Laxenburg, Austria

^hDepartment of Soil Science, Faculty of Natural Sciences, Comenius University in Bratislava, Bratislava, Slovak Republic

ⁱLaboratoire des Sciences du Climat et de l'Environnement, CEA-CNRS-UVSQ, 91191 Gif-sur-Yvette, France

^jSino-French Institute of Earth System Sciences, College of Urban and Environmental Sciences, Peking University, Beijing, China

^kUnité de Modélisation du Climat et des Cycles Biogéochimiques, UR SPHERES, Institut d'Astrophysique et de Géophysique, University of Liège, Belgium

^lMet Office Hadley Centre, Exeter, United Kingdom

^mDepartment of Geography, Ludwig-Maximilians-Universität, Munich, Germany

ⁿGeorg-August-University Göttingen, Tropical Plant Production and Agricultural Systems Modelling, Göttingen, Germany

^oDepartment of Geographical Sciences, University of Maryland, College Park, MD, USA

^pTexas AgriLife Research and Extension, Texas A&M University, Temple, TX, USA

^qDepartment of Statistics, University of Chicago, Chicago, IL, USA

^rEWAG, Swiss Federal Institute of Aquatic Science and Technology, Dübendorf, Switzerland

^sDepartment of Physical Geography and Ecosystem Science, Lund University, Lund, Sweden

^tEarth Institute Center for Climate Systems Research, Columbia University, New York, NY, USA

^uKarlsruhe Institute of Technology, IMK-IFU, 82467 Garmisch-Partenkirchen, Germany.

^vSchool of Geography, Earth and Environmental Science, University of Birmingham, Birmingham, UK.

Abstract

Concerns about food security under climate change have motivated efforts to better understand the future changes in yields by using detailed process-based models in agronomic sciences. Results of these models are often used to inform subsequent model-based analyses in agricultural economics and integrated assessment, but the computational requirements of process-based models sometimes hamper the ability to utilize these models in existing impact assessment frameworks at high resolutions globally. Conducting a large simulation set with perturbations in atmospheric CO₂ concentrations, temperature, precipitation, and nitrogen inputs, Phase II of the Global Gridded Crop Model Intercomparison (GGCMI), an activity of the Agricultural Model Intercomparison and Improvement Project (AgMIP), constitutes an unprecedentedly data-rich basis of projected yield changes across 12 models and five crops (maize, soy, rice, spring wheat, and winter wheat) using global gridded simulations. Results from Phase II of the GGCMI effort, a targeted experiment aimed at understanding the interaction between multiple climate variables (as well as management) are presented first. Then the construction of an “emulator or statistical representation of the simulated 30-year mean climatological output in each location is outlined. The emulated response surfaces capture the details of the process-based models in a lightweight, computationally tractable form that facilitates model comparison as well as potential applications in subsequent modeling efforts such as integrated assessment.

Keywords: climate change, food security, model emulation, AgMIP, crop model

1. Introduction

2 Projecting crop yield response to a changing climate is of
3 great importance, especially as the global food production sys-
4 tem will face pressure from increased demand over the next
5 century. Climate-related reductions in supply could therefore
6 have severe socioeconomic consequences. Multiple studies
7 with different crop or climate models predict sharp reduction in
8 yields on currently cultivated cropland under business-as-usual
9 climate scenarios, although their yield projections show con-
10 siderable spread (e.g. Porter et al. (IPCC), 2014, Rosenzweig
11 et al., 2014, Schaubberger et al., 2017, and references therein).
12 Model differences are unsurprising because crop responses in
13 models can be complex, with crop growth a function of com-
14 plex interactions between climate inputs and management prac-
15 tices.

16 Computational Models have been used to project crop yields
17 since the 1950's, beginning with statistical models (Heady,
18 1957, Heady & Dillon, 1961) that attempt to capture the rela-
19 tionship between input factors and resultant yields. These sta-
20 tistical models were typically developed on a small scale for lo-
21 cations with extensive histories of yield data. The emergence of
22 computers allowed development of numerical models that sim-
23 ulate the process of photosynthesis and the biology and phe-
24 nology of individual crops (first proposed by de Wit (1957),
25 Duncan et al. (1967) and attempted by Duncan (1972)). His-
26 torical mapping of crop model development can be found in
27 the appendix/supplementary of Rosenzweig et al. (2014). A
28 half-century of improvement in both models and computing re-
29 sources means that researchers can now run crop simulation
30 models for many years at high spatial resolution on the global
31 scale.

32 Both types of models continue to be used, and compara-

33 tive studies have concluded that when done carefully, both ap-
34 proaches can provide similar yield estimates (e.g. Lobell &
35 Burke, 2010, Moore et al., 2017, Roberts et al., 2017, Zhao
36 et al., 2017). Models tend to agree broadly in major response
37 patterns, including a reasonable representation of the spatial
38 pattern in historical yields of major crops (e.g. Elliott et al.,
39 2015, Müller et al., 2017) and projections of decreases in yield
40 under future climate scenarios.

41 Process models do continue to struggle with some important
42 details, including reproducing historical year-to-year variability
43 (e.g. Müller et al., 2017), reproducing historical yields when
44 driven by reanalysis weather (e.g. Glotter et al., 2014), and low
45 sensitivity to extreme events (e.g. Glotter et al., 2015). These
46 issues are driven in part by the diversity of new cultivars and
47 genetic variants, which outstrips the ability of academic mod-
48 eling groups to capture them (e.g. Jones et al., 2017). Mod-
49 els do not simulate many additional factors affecting produc-
50 tion, including pests/diseases/weeds. For these reasons, indi-
51 vidual studies must generally re-calibrate models to ensure that
52 short-term predictions reflect current cultivar mixes, and long-
53 term projections retain considerable uncertainty (Wolf & Oijen,
54 2002, Jagtap & Jones, 2002, Angulo et al., 2013, Asseng et al.,
55 2013, 2015). Inter-model discrepancies can also be high in ar-
56 eas not yet cultivated (e.g. Challinor et al., 2014, White et al.,
57 2011). Finally, process-based models present additional diffi-
58 culties for high-resolution global studies because of their com-
59 plexity and computational requirements. For economic impacts
60 assessments, it is often impossible to integrate a set of process-
61 based crop models directly into an integrated assessment model
62 to estimate the potential cost of climate change to the agricul-
63 tural sector.

64 Nevertheless, process-based models are necessary for under-
65 standing the global future yield impacts of climate change for
66 many reasons. First, cultivation may shift to new areas, where

*Corresponding author at: 4734 S Ellis, Chicago, IL 60637, United States.
email: jfranke@uchicago.edu

67 no yield data are currently available and therefore statistical
 68 models cannot apply. Yield data are also often limited in the de-
 69 veloping world, where future climate impacts may be the most
 70 critical. Second, only process-based models can capture the
 71 growth response to elevated CO₂, novel conditions that are not
 72 represented in historical data (e.g. Pugh et al., 2016, Roberts
 73 et al., 2017). Similarly, only process-based models can rep-
 74 resent novel changes in management practices (e.g. fertilizer
 75 input) that may ameliorate climate-induced damages.

76 Statistical emulation of crop simulations offers the possibility
 77 of combining some advantageous features of both statistical and
 78 process-based models. The statistical representation of compli-
 79 cated numerical simulation (e.g. O’Hagan, 2006, Conti et al.,
 80 2009), in which simulation output acts as the training data for a
 81 statistical model, has been of increasing interest with the growth
 82 of simulation complexity and volume of output. Such emula-
 83 tors or “surrogate models” have been used in a variety of fields
 84 including hydrology (Razavi et al., 2012), engineering (Storlie
 85 et al., 2009), environmental sciences (Ratto et al., 2012), and
 86 climate (Castruccio et al., 2014). For agricultural impacts stud-
 87 ies, emulation of process-based models allows exploring crop
 88 yields in regions outside ranges of current cultivation and with
 89 input variables outside historical precedents, in a lightweight,
 90 flexible form that is compatible with economic studies.

91 Crop yield emulators have been proposed and implemented
 92 by many studies (e.g. Howden & Crimp, 2005, Räisänen &
 93 Ruokolainen, 2006, Lobell & Burke, 2010, Iizumi et al., 2010,
 94 Ferrise et al., 2011, Holzkämper et al., 2012, Ruane et al., 2013,
 95 Makowski et al., 2015), and in the last several years multiple₁₀₁
 96 studies have developed emulators based on a variety of sim-₁₀₂
 97 ulation model outputs. Several studies analyzed a single crop₁₀₃
 98 model run on a RCP climate scenario set (e.g. Oyebamiji et al.,₁₀₄
 99 2015). Multiple groups (e.g. Blanc & Sultan, 2015, Blanc,₁₀₅
 100 2017, Ostberg et al., 2018), constructed emulators for a 5-model₁₀₆

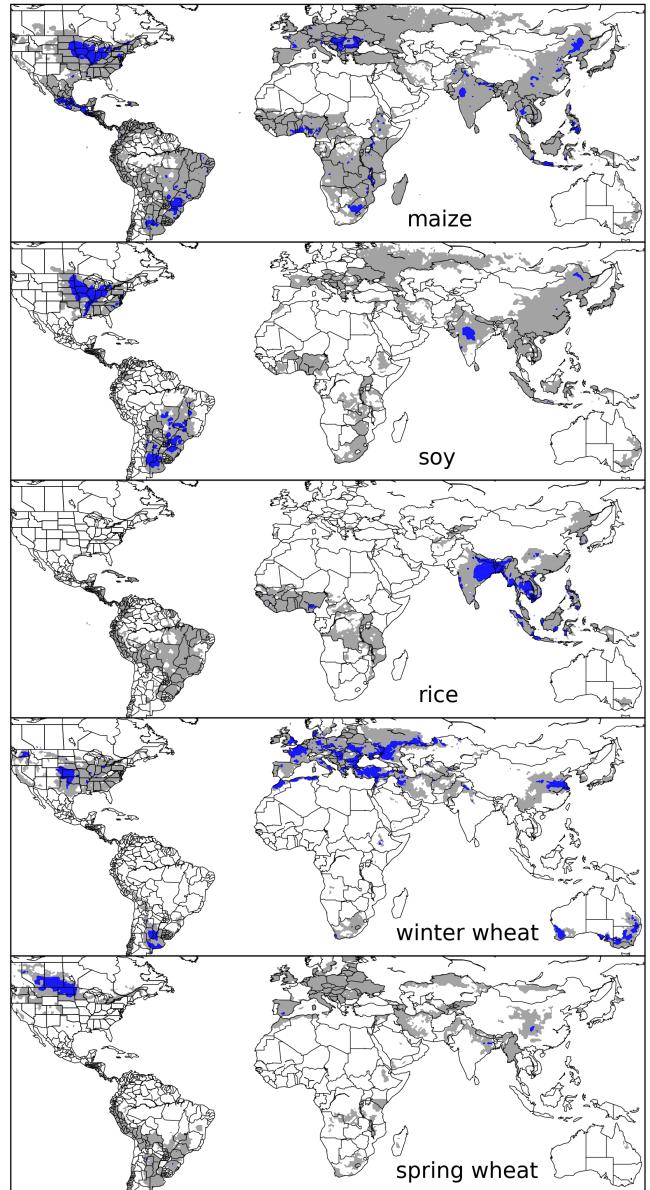


Figure 1: Presently cultivated area for rain-fed crops in the real world. Blue contour area indicates grid-cells with more than 20,000 hectares (approx. 10% of the land in a grid cell near the equator for example) of crop cultivated. Gray contour shows area with more than 10 hectares cultivated. Cultivated areas for maize, rice, and soy are taken from the MIRCA2000 (“monthly irrigated and rain-fed crop areas around the year 2000”) dataset (Portmann et al., 2010). Areas for winter and spring wheat areas are adapted from MIRCA2000 data and sorted by growing season. For analogous figure of irrigated crops, see Figure ??.

intercomparison exercise performed as part of ISIMIP (Warsza-
 wski et al., 2014), the Inter-Sectoral Impacts Model Intercom-
 parison Project and evaluated several different climate scenar-
 ios (over multiple climate model runs). Several other studies
 (e.g. Moore et al., 2017, Mistry et al., 2017) utilize a hybrid
 simulation output and real-world data approach to develop and

107 emulator or damage function. Additional recent studies have₁₃₅
 108 explored an impact response surface (aka. emulator when us-₁₃₆
 109 ing simulated data) over an explicit multivariate input simulation₁₃₇
 110 space (as opposed to specific RCP climate model runs), with a₁₃₈
 111 site-based approach (as opposed to a globally gridded model)₁₃₉
 112 across temperature, water, and CO₂ sampling (Snyder et al.,₁₄₀
 113 2018), or with models for wheat across water and temperature₁₄₁
 114 dimensions for different sites in Europe (Fronzek et al., 2018).₁₄₂

115 The Global Gridded Crop Model Intercomparison (GGCMI)₁₄₃
 116 Phase II experiment is an attempt to expand upon previous₁₄₄
 117 process-based crop modeling studies by running globally grid-

118 ded crop models over a set of uniform input dimensions as op-₁₄₅
 119 posed to RCP climate scenarios in order to test the sensitivity
 120 to yield drivers within and across models. GGCMI is a multi-¹⁴⁶
 121 model exercise conducted as part of the Agricultural Model In-₁₄₇
 122 tercomparison and Improvement Project (AgMIP, (Rosenzweig¹⁴⁸
 123 et al., 2013, 2014)), which brings together major global crop¹⁴⁹
 124 simulation models from different research organizations around¹⁵⁰
 125 the world under a framework similar to the Climate Model In-¹⁵¹
 126 tercomparison Project (CMIP, Taylor et al., 2012, Eyring et al.,¹⁵²
 127 2016). The GGCMI analysis framework builds on the Ag-¹⁵³
 128 MIP Coordinated Climate-Crop Modeling Project (C3MP, Ru-¹⁵⁴
 129 ane et al., 2014, McDermid et al., 2015), and will contribute¹⁵⁵
 130 to the AgMIP Coordinated Global and Regional Assessments¹⁵⁶
 131 (CGRA, Ruane et al., 2018, Rosenzweig et al., 2018).¹⁵⁷

132 The GGCMI Phase II project develops global simulations₁₅₈
 133 of yields of major crops under scenarios that sample a uni-₁₅₉
 134 form parameter space. Overall goals include understanding₁₆₀

where highest-yield regions may shift under climate change,
 exploring future adaptive management strategies, understanding
 how interacting parameters affect crop yields, quantifying
 uncertainties, and testing strategies for producing lightweight
 statistical emulations of the more detailed process-based mod-
 els. In the remainder of this paper, we describe the GGCMI
 Phase II experiments, present initial overall results, and release
 the simulation output dataset for public use. We also present
 a climatological-mean yield emulator as a distillation of the
 dataset and as a potential tool for impact assessments.

2. Materials and Methods

2.1. GGCMI Phase II: experiment design

GGCMI Phase II is the continuation of a multi-model com-
 parison exercise begun in 2014. The initial Phase I compared
 harmonized yields of 21 models for 19 crops over a historical
 (1980-2010) scenario with a primary goal of model evaluation
 (Elliott et al., 2015, Müller et al., 2017). Phase II compares sim-
 ulations of 12 models for 5 crops (maize, rice, soybean, spring
 wheat, and winter wheat) over hundreds of scenarios in which
 individual climate or management inputs are adjusted from
 their historical values. The reduced set of crops includes the
 three major global cereals and the major legume and accounts
 for over 50% of human calories (in 2016, nearly 3.5 billion tons
 or 32% of total global crop production by weight (Food and
 Agriculture Organization of the United Nations, 2018).

The major goals of GGCMI Phase II are to:

Input variable	Abbr.	Tested range	Unit
CO ₂	C	360, 510, 660, 810	ppm
Temperature	T	-1, 0, 1, 2, 3, 4, 5*, 6	°C
Precipitation	W	-50, -30, -20, -10, 0, 10, 20, 30, (and W _{inf})	%
Applied nitrogen	N	10, 60, 200	kg ha ⁻¹

Table 1: Phase II input variable test levels. Temperature and precipitation values indicate the perturbations from the historical, climatology. * Only simulated by one model. W-percentage does not apply to the irrigated (W_{inf}) simulations.

Model (Key Citations)	Maize	Soy	Rice	Winter Wheat	Spring Wheat	N Dim.	Simulations per Crop
APSIM-UGOE , Keating et al. (2003), Holzworth et al. (2014)	X	X	X	-	X	Yes	37
CARAIB , Dury et al. (2011), Pirttioja et al. (2015)	X	X	X	X	X	No	224
EPIC-IIASA , Balkovi et al. (2014)	X	X	X	X	X	Yes	35
EPIC-TAMU , Izaurrealde et al. (2006)	X	X	X	X	X	Yes	672
JULES* , Osborne et al. (2015), Williams & Falloon (2015), Williams et al. (2017)	X	X	X	-	X	No	224
GEPIC , Liu et al. (2007), Folberth et al. (2012)	X	X	X	X	X	Yes	384
LPJ-GUESS , Lindeskog et al. (2013), Olin et al. (2015)	X	-	-	X	X	Yes	672
LPJmL , von Bloh et al. (2018)	X	X	X	X	X	Yes	672
ORCHIDEE-crop , Valade et al. (2014)	X	-	X	-	X	Yes	33
pDSSAT , Elliott et al. (2014), Jones et al. (2003)	X	X	X	X	X	Yes	672
PEPIC , Liu et al. (2016a,b)	X	X	X	X	X	Yes	130
PROMET* , Mauser & Bach (2015), Hank et al. (2015), Mauser et al. (2009)	X	X	X	X	X	Yes†	239
Totals	12	10	11	9	12	-	3993 (maize)

Table 2: Models included in the GGCMI Phase II and the number of C, T, W, and N simulations performed for rain-fed crops (“Sims per Crop”), with 672 as the maximum. “N-Dim.” indicates if simulations include varying nitrogen levels; two models omit this dimension. All models provided the same set of simulations across all modeled crops, but some omitted individual crops in some cases. (For example, APSIM did not simulate winter wheat.) Irrigated simulations are provided at the level of the other covariates for each model (for an additional 84 simulations for the fully-sampled models). Geographic extent of simulation varies to some extent within a certain model for different scenarios (672 rain-fed simulations does not necessarily equal 672 climatological yields in all areas). This geographic variance only applies for areas far outside the area of currently cultivated crops. Two models (marked with *) use non-AgMERRA climate inputs. For further details on models, see Elliott et al. (2015). †PROMET provided simulations at only two nitrogen levels so is not emulated across the nitrogen dimension.

- Enhance understanding of how models work by characterizing their sensitivity to input climate and nitrogen drivers.¹⁷⁸
 - Study the interactions between climate variables and nitrogen inputs in driving modeled yield impacts.¹⁸⁰¹⁸¹
 - Explore differences in crop response to warming across the Earth's climate regions.¹⁸²¹⁸³¹⁸⁴
 - Provide a dataset that allows statistical emulation of crop model responses for downstream modelers.¹⁸⁵
 - Illustrate differences in potential adaptation via growing season changes.¹⁸⁶¹⁸⁷

(1980-2010) used in Phase I. In most cases, historical daily climate inputs are taken from the 0.5 degree NASA AgMERRA daily gridded re-analysis product specifically designed for agricultural modeling, with satellite-corrected precipitation (Ruane et al., 2015). Two models require sub-daily input data and use alternative sources. See Elliott et al. (2015) for additional details.

The experimental protocol consists of 9 levels for precipitation perturbations, 7 for temperature, 4 for CO₂, and 3 for applied nitrogen, for a total of 672 simulations for rain-fed agri-

The guiding scientific rationale of GGCMI Phase II is to pro-¹⁸⁹
duce a comprehensive, systematic evaluation of the response¹⁹⁰
of process-based crop models to different values for carbon¹⁹¹
oxide, temperature, water, and applied nitrogen (collectively¹⁹²
known as “CTWN”). Phase II of the GGCMI project consists¹⁹³
of a series of simulations, each with one or more of the CTWN¹⁹⁴
dimensions perturbed over the 31-year historical time series¹⁹⁵

(1980-2010) used in Phase I. In most cases, historical daily climate inputs are taken from the 0.5 degree NASA AgMERRA daily gridded re-analysis product specifically designed for agricultural modeling, with satellite-corrected precipitation (Ruane et al., 2015). Two models require sub-daily input data and use alternative sources. See Elliott et al. (2015) for additional details.

ified as discrete values applied uniformly over all grid cells.²³⁰
Note that CO₂ changes are applied independently of changes²³¹
in climate variables, so that higher CO₂ is not associated with²³²
higher temperatures. An additional, identical set of scenarios²³³
(at the same C, T, W, and N levels) simulate adaptive agron-²³⁴
omy under climate change by varying the growing season for²³⁵
crop production. (These adaptation simulations are not shown²³⁶
or analyzed here.) The resulting GGCMI data set captures a²³⁷
distribution of crop responses over the potential space of future²³⁸
climate conditions.²³⁹

The 12 models included in GGCMI Phase II are all mecha-²⁴⁰
nistic process-based crop models that are widely used in im-²⁴¹
pacts assessments (Table 2). Although some of the models²⁴²
shares a common base (e.g. LPJmL and LPJ-GUESS and the²⁴³
EPIC models), they have developed independently from this²⁴⁴
shared base, for more details on the genealogy of the mod-²⁴⁵
els see Figure S1 in Rosenzweig et al. (2014). Differences in²⁴⁶
model structure does mean that several key factors are not stan-²⁴⁷
dardized across the experiment, including secondary soil nutri-²⁴⁸
ents, carry over effects across growing years including residue²⁴⁹
management and soil moisture, and extent of simulated area for²⁵⁰
different crops. Growing seasons are identical across models,²⁵¹
but vary by crop and by location on the globe. All stresses²⁵²
except factors related to nitrogen, temperature, and water (e.g.²⁵³
alkalinity, salinity) are disabled. No additional nitrogen inputs,²⁵⁴
such as atmospheric deposition, are considered, but some mod-²⁵⁵
els have individual assumptions on soil organic matter that may²⁵⁶
release additional nitrogen through mineralization. See Rosen-²⁵⁷
zweig et al. (2014), Elliott et al. (2015) and Müller et al. (2017)²⁵⁸
for further details on models and underlying assumptions.²⁵⁹

Each model is run at 0.5 degree spatial resolution and covers²⁶⁰
all currently cultivated areas and much of the uncultivated land²⁶¹
area. Coverage extends considerably outside currently culti-²⁶²
vated areas because cultivation will likely shift under climate²⁶³

change. See Figure 1 for the present-day cultivated area of
rain-fed crops, and Figure ?? in the supplemental material for
irrigated crops. Some areas such as Greenland, far-northern
Canada, Siberia, Antarctica, the Gobi and Sahara deserts, and
central Australia are not simulated as they are assumed to re-
main non-arable even under an extreme climate change.

The participating modeling groups provide simulations at
any of four initially specified levels of participation, so the num-
ber of simulations varies by model, with some sampling only a
part of the experiment variable space. Most modeling groups
simulate all five crops in the protocol, but some omitted one
or more. Table 2 provides details of coverage for each model.
Note that the three models that provide less than 50 simulations
are excluded from the emulator analysis.

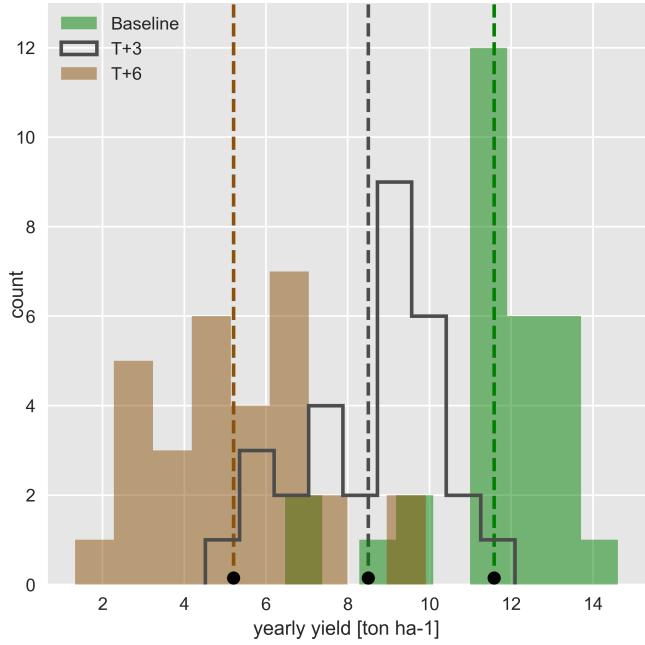
All models produce as output, crop yields (tons ha⁻¹ year⁻¹)
for each 0.5 degree grid cell. Because both yields and yield
changes vary substantially across models and across grid-cells,
we primarily analyze relative change from a baseline. We take
as the baseline the scenario with historical climatology (i.e. T
and P changes of 0), C of 360 ppm, and applied N at 200 kg
ha⁻¹. We show absolute yields in some cases to illustrate geo-
graphic differences in yields for a single model.

2.2. *Simulation model validation approach*

Simulation model validation for GGCMI phase II builds on
the validation efforts presented in Müller et al. (2017) for the
first phase. In this case however, the models are not run on the
best approximation of management levels (namely nitrogen ap-
plication level) by country as with phase I. As the goals of this
phase of the project are focused on understanding the sensitiv-
ity in *change* in yield to changes in input drivers –and not to
simulate historical yields as accurately as possible– no direct
comparison to historical yield data can be made. Additionally,
some models are not calibrated as they were in phase I of the
project.

264 We evaluate the models here based on the response to year-₂₈₁
 265 to-year temperature and precipitation variability in the histori-₂₈₂
 266 cal record. If the models can (somewhat) faithfully represent₂₈₃
 267 the the historical variability in yields (which, once detrended₂₈₄
 268 to account for changing management levels must be driven by₂₈₅
 269 differences in weather), then the models may provide some util-₂₈₆
 270 ity in understanding the impact on mean climatological shifts in₂₈₇
 271 temperature and precipitation. Specifically, we calculate a Pear-₂₈₈
 272 son correlation coefficient between the detrended time series of₂₈₉
 273 simulations and FAO data for the period 1981-2009. Validating₂₉₀
 274 the response to CO₂ and Nitrogen applications is more difficult₂₉₁
 275 because real world data is not available outside of small green-₂₉₂
 276 house and field level trials.₂₉₂

277 2.3. Climatological-mean yield emulator design



298 Figure 2: Example showing both climatological mean yields and distribution
 299 of yearly yields for three 30-year scenarios. Figure shows rain-fed maize for a₃₀₀
 300 grid cell in northern Iowa (a representative high-yield region) from the pDSSAT
 301 model, for the baseline climatology (1981-2010) and for scenarios with tem-₃₀₂
 302 perature shifted by (T) +3 and (T) +6 °C, with other variables held at baseline
 303 values. Dashed vertical lines and black dots indicate the climatological mean₃₀₄
 304 yield.₃₀₅

305 in the year-to-year variability in yields, but instead on the broad
 306 mean changes over the multi-decadal timescale. Emulation in-
 307 volves fitting individual regression models for each crop, simu-
 308 lation model, and 0.5 degree geographic pixel from the GGCMI
 309 Phase II data set. The regressors are the applied constant pertur-
 310 bations in temperature, water, nitrogen and CO₂, we aggregate
 311 the simulation outputs in the time dimension, and regress on the
 312 30-year mean yields. (See Figure 2 for illustration.) The regres-
 313 sion therefore omits information about yield responses to year-
 314 to-year climate perturbations, which are more complex. Emu-
 315 lating inter-annual yield variations would likely require con-
 316 sidering statistical details of the historical climate time series,
 317 including changes in marginal distribution and temporal depen-
 318 dencies. (Future work should explore this.) The climatological
 319 emulation indirectly includes any yield response to geographi-
 320 cally distributed factors such as soil type, insolation, and the
 321 baseline climate itself, because we construct separate emulators
 322 for each grid cell.₃₂₃

324 We regress climatological-mean yields against a third-order
 325 polynomial in C, T, W, and N with interaction terms. The
 326 higher-order terms are necessary to capture any nonlinear re-
 327 sponses, which are well-documented in observations for tem-
 328 perature and water perturbations (e.g. Schlenker & Roberts
 329 (2009) for T and He et al. (2016) for W). We include inter-
 330 action terms (both linear and higher-order) because past stud-
 331 ies have shown them to be significant effects. For example,
 332 Lobell & Field (2007) and Tebaldi & Lobell (2008) showed
 333 that in real-world yields, the joint distribution in T and W is
 334 needed to explain observed yield variance (C and N are fixed
 335 in these data). Other observation-based studies have shown the
 336 importance of the interaction between water and nitrogen (e.g.
 337 Aulakh & Malhi, 2005), and between nitrogen and carbon diox-
 338 ide (Osaki et al., 1992, Nakamura et al., 1997). We do not focus
 339 on comparing different model specifications in this study, and
 340

341 The decision to first construct a climatological-mean yield₃₄₂
 342 emulator is driven by the target application for this analysis₃₄₃
 343 tool. Many impact modelers are not focused on the changes₃₄₄

315 instead stick to a relatively simple parameterized specification³³² all emulators.
 316 that allows for some, albeit limited, coefficient interpretation.

317 The limited GGCMI variable sample space means that use
 318 of the full polynomial expression described above, which has
 319 34 terms for the rain-fed case (12 for irrigated), can be prob-³³³
 320 lematic, and can lead to over-fitting and unstable parameter es-³³⁴
 321 timations. We therefore reduce the number of terms through a³³⁵
 322 feature selection cross-validation process in which terms in the³³⁶
 323 polynomial are tested for importance. In this procedure higher-³³⁷
 324 order and interaction terms are added successively to the model;³³⁸
 325 we then follow the reduction of the the aggregate mean squared³³⁹
 326 error with increasing terms and eliminate those terms that do³⁴⁰
 327 not contribute significant reductions. See supplemental docu-³⁴¹
 328 ments for more details. We select terms by applying the feature³⁴²
 329 selection process to the three models that provided the com-³⁴³
 330 plete set of 672 rain-fed simulations (pDSSAT, EPIC-TAMU,³⁴⁴
 331 and LPJmL); the resulting choice of terms is then applied for³⁴⁵

Feature importance is remarkably consistent across all three models and across all crops (see Figure ?? in the supplemental material). The feature selection process results in a final polynomial in 23 terms, with 11 terms eliminated. We omit the N^3 term, which cannot be fitted because we sample only three nitrogen levels. We eliminate many of the C terms: the cubic, the CT, CTN, and CWN interaction terms, and all higher order interaction terms in C. Finally, we eliminate two 2nd-order interaction terms in T and one in W. Implication of this choice include that nitrogen interactions are complex and important, and that water interaction effects are more nonlinear than those in temperature. The resulting statistical model (Equation 1) is used for all grid cells, models, and crops:

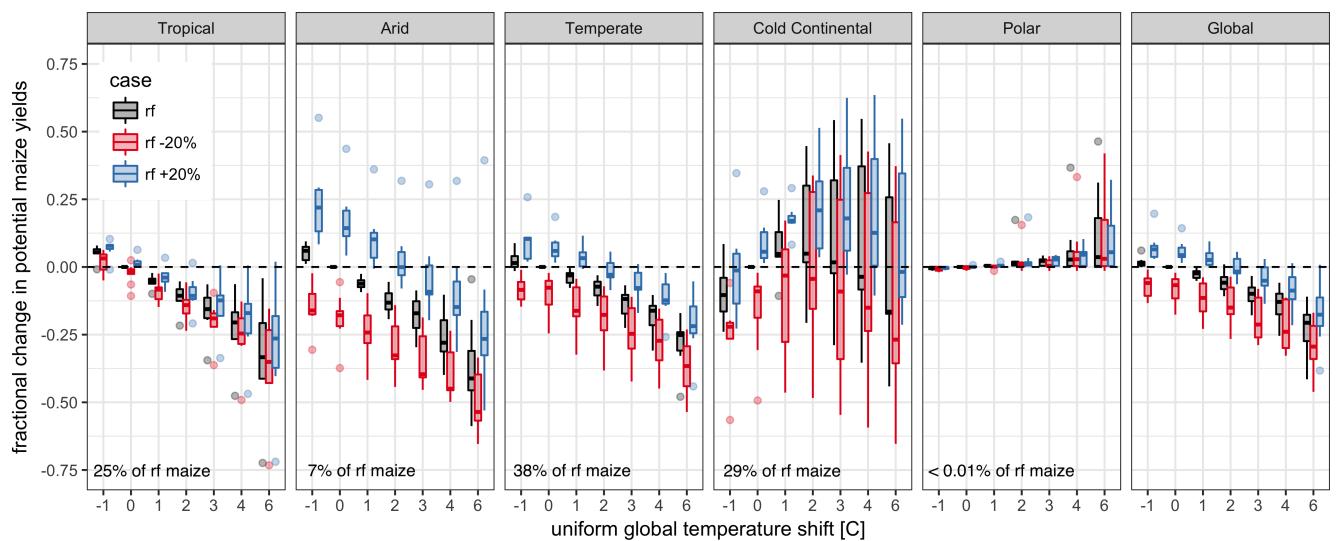


Figure 3: Illustration of the distribution of regional yield changes across the multi-model ensemble, split by Köppen-Geiger climate regions (Rubel & Kottek (2010)). We show responses of a single crop (rain-fed maize) to applied uniform temperature perturbations, for three discrete precipitation perturbation levels (rain-fed (rf) -20%, rain-fed (0), and rain-fed +20%), with CO₂ and nitrogen held constant at baseline values (360 ppm and 200 kg ha⁻¹ yr⁻¹). Y-axis is fractional change in the regional average climatological potential yield relative to the baseline. The figure shows all modeled land area; see Figure ?? in the supplemental material for only currently-cultivated land. Panel text gives the percentage of rain-fed maize presently cultivated in each climate zone (Portmann et al., 2010). Box-and-whiskers plots show distribution across models, with median marked. Box edges are first and third quartiles, i.e. box height is the interquartile range (IQR). Whiskers extend to maximum and minimum of simulations but are limited at 1.5-IQR; otherwise the outlier is shown. Models generally agree in most climate regions (other than cold continental), with projected changes larger than inter-model variance. Outliers in the tropics (strong negative impact of temperature increases) are the pDSSAT model; outliers in the high-rainfall case (strong positive impact of precipitation increases) are the JULES model. Inter-model variance increases in the case where precipitation is reduced, suggesting uncertainty in model response to water limitation. The right panel with global changes shows yield responses to an globally uniform temperature shift; note that these results are not directly comparable to simulations of more realistic climate scenarios with the same global mean change.

$$\begin{aligned}
Y &= K_1 \\
&+ K_2 C + K_3 T + K_4 W + K_5 N \\
&+ K_6 C^2 + K_7 T^2 + K_8 W^2 + K_9 N^2 \\
&+ K_{10} C W + K_{11} C N + K_{12} T W + K_{13} T N + K_{14} W N \\
&+ K_{15} T^3 + K_{16} W^3 + K_{17} T W N \\
&+ K_{18} T^2 W + K_{19} W^2 T + K_{20} W^2 N \\
&+ K_{21} N^2 C + K_{22} N^2 T + K_{23} N^2 W
\end{aligned} \tag{1}$$

346 To fit the parameters K , we use a Bayesian Ridge probabilis-
 347 tic estimator (MacKay, 1991), which reduces volatility in pa-
 348 rameter estimates when the sampling is sparse, by weighting
 349 parameter estimates towards zero. The Bayesian Ridge method
 350 is necessary to maintain a consistent functional form across all
 351 models, and locations as the linear least squares fails to pro-
 352 vide a stable result in many cases. In the GGCMI Phase II₃₇₉
 353 experiment, the most problematic fits are those for models that₃₈₀
 354 provided a limited number of cases or for low-yield geographic₃₈₁
 355 regions where some modeling groups did not run all scenarios.₃₈₂
 356 Because we do not attempt to emulate models that provided₃₈₃
 357 less than 50 simulations, the lowest number of simulations em-₃₈₄
 358 ulted across the full parameter space is 130 (for the PEPIC₃₈₅
 359 model). We use the implementation of the Bayesian Ridge esti-₃₈₆
 360 mator from the scikit-learn package in Python (Pedregosa et al.,₃₈₇
 361 2011).

362 The resulting parameter matrices for all crop models are₃₉₀
 363 available on request, as are the raw simulation data and a Python₃₉₁
 364 application to emulate yields. The yield output for a single₃₉₂
 365 GGCMI model that simulates all scenarios and all five crops₃₉₃
 366 is ~12.5 GB; the emulator is ~100 MB, a reduction by over₃₉₄
 367 two orders of magnitude.

368 Because no general criteria exist for defining an acceptable
 369 model emulator, we develop a metric of emulator performance
 370 specific to GGCMI. For a multi-model comparison exercise like
 371 GGCMI, a reasonable criterion is what we term the “normalized
 372 error”, which compares the fidelity of an emulator for a given
 373 model and scenario to the inter-model uncertainty. We define
 374 the normalized error e for each scenario as the difference be-
 375 tween the fractional yield change from the emulator and that in
 376 the original simulation, divided by the standard deviation of the
 377 multi-model spread (Equations 2 and 3):

$$F_{scn.} = \frac{Y_{scn.} - Y_{baseline}}{Y_{baseline}} \tag{2}$$

$$e_{scn.} = \frac{F_{em, scn.} - F_{sim, scn.}}{\sigma_{sim, scn.}} \tag{3}$$

378 Here $F_{scn.}$ is the fractional change in a model’s mean emu-
 379 lated or simulated yield from a defined baseline, in some sce-
 380 nario (scn.) in C, T, W, and N space; $Y_{scn.}$ and $Y_{baseline}$ are the
 381 absolute emulated or simulated mean yields. The normalized
 382 error e is the difference between the emulated fractional change
 383 in yield and that actually simulated, normalized by σ_{sim} , the
 384 standard deviation in simulated fractional yields $F_{sim, scn.}$ across
 385 all models. The emulator is fit across all available simulation
 386 outputs, and then the error is calculated across the simulation
 387 scenarios provided by all nine models (Figure 9 and Figures ??
 388 and Figures ?? in supplemental documents). Note that the nor-
 389 malized error e for a model depends not only on the fidelity of
 390 its emulator in reproducing a given simulation but on the partic-
 391 ular suite of models considered in the intercomparison exercise.
 392 The rationale for this choice is to relate the fidelity of the em-
 393 ultation to an estimate of true uncertainty, which we take as the
 394 multi-model spread.

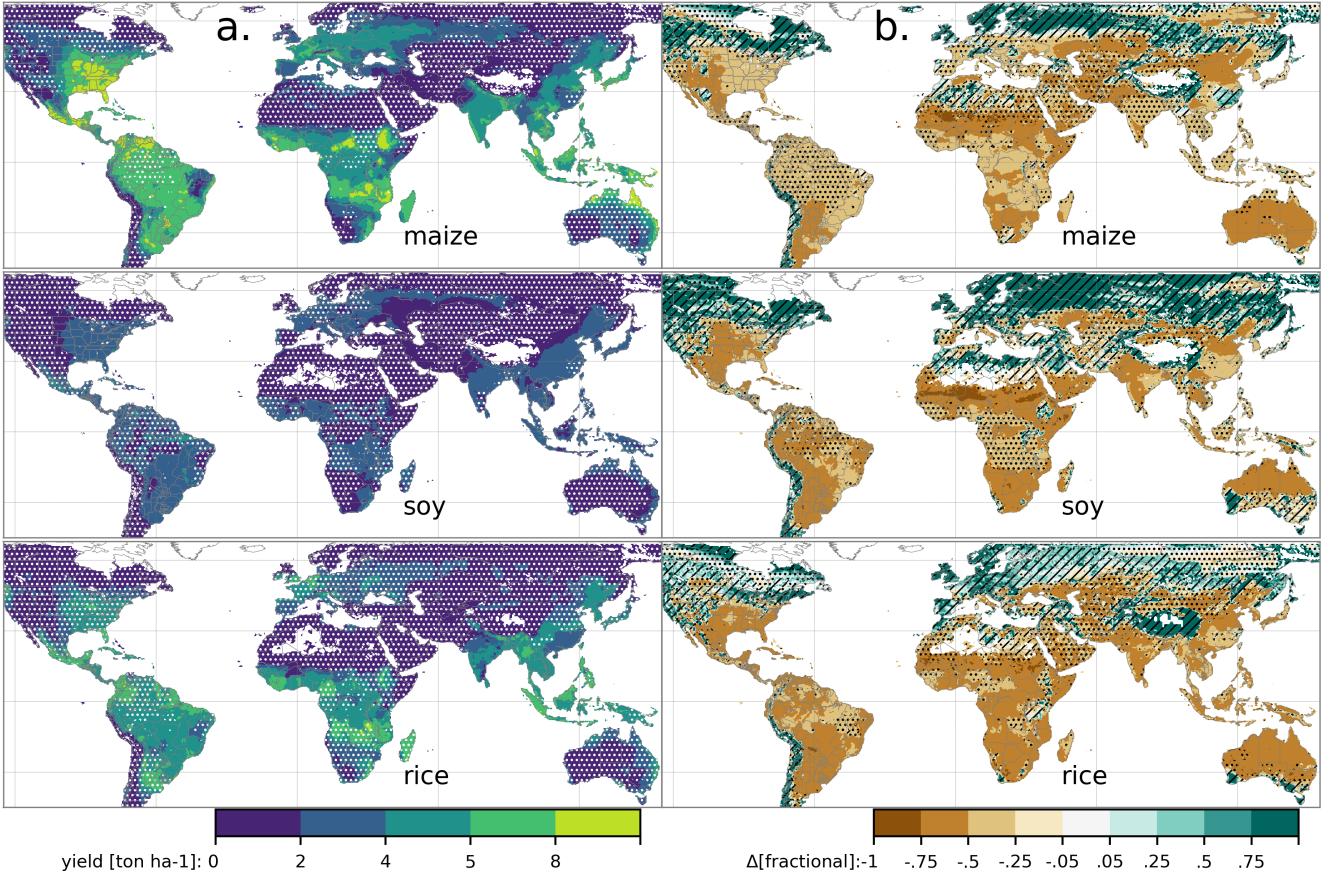


Figure 4: Illustration of the spatial pattern of potential yields and potential yield changes in the GGCMI Phase II ensemble, for three major crops. Left column (a) shows multi-model mean climatological yields for the baseline scenario for (top-bottom) rain-fed maize, soy, and rice. (For wheat see Figure ?? in the supplemental material.) White stippling indicates areas where these crops are not currently cultivated. Absence of cultivation aligns well with the lowest yield contour ($0\text{-}2 \text{ ton ha}^{-1}$). Right column (b) shows the multi-model mean fractional yield change in the extreme $T + 4^\circ\text{C}$ scenario (with other inputs at baseline values). Areas without hatching or stippling are those where confidence in projections is high: the multi-model mean fractional change exceeds two standard deviations of the ensemble. ($\Delta > 2\sigma$). Hatching indicates areas of low confidence ($\Delta < 1\sigma$), and stippling areas of medium confidence ($1\sigma < \Delta < 2\sigma$). Crop model results in cold areas, where yield impacts are on average positive, also have the highest uncertainty.

3. Results

3.1. Simulation results

Crop models in the GGCMI ensemble show a broadly consistent responses to climate and management perturbations in most regions, with a strong negative impact of increased temperature in all but the coldest regions. We illustrate this result for rain-fed maize in Figure 3, which shows yields for the primary Köppen-Geiger climate regions (Rubel & Kottek, 2010).

In warming scenarios, models show decreases in maize yield in the temperate, tropical, and arid regions that account for nearly three-quarters of global maize production. These impacts are robust for even moderate climate perturbations. In the temperate zone, even a 1 degree temperature rise with other variables

held fixed leads to a median yield reduction that outweighs the variance across models. A 6 degree temperature rise results in median loss of $\sim 25\%$ of yields with a signal to noise of nearly three. A notable exception is the cold continental region, where models disagree strongly, extending even to the sign of impacts. Model simulations of other crops produce similar responses to warming, with robust yield losses in warmer locations and high inter-model variance in the cold continental regions (Figures ??).

The effects of rainfall changes on maize yields are also as expected and are consistent across models. Increased rainfall mitigates the negative effect of higher temperatures, most strongly in arid regions. Decreased rainfall amplifies yield losses and

also increases inter-model variance more strongly, suggesting
that models have difficulty representing crop response to water
stress. We show only rain-fed maize here; see Figure ?? for the
irrigated case. As expected, irrigated crops are more resilient to
temperature increases in all regions, especially so where water
is limiting.

Mapping the distribution of baseline yields and yield changes
shows the geographic dependencies that underlie these results.
Figure 4 shows baseline and changes in the T+4 scenario for
rain-fed maize, soy, and rice in the multi-model ensemble mean,
with locations of model agreement marked. Absolute yield po-
tentials are have strong spatial variation, with much of the
Earth's surface area unsuitable for any given crop. In general,
models agree most on yield response in regions where yield
potentials are currently high and therefore where crops are cur-
rently grown. Models show robust decreases in yields at low
latitudes, and highly uncertain median increases at most high
latitudes. For wheat crops see Figure ??; wheat projections are
both more uncertain and show fewer areas of increased yield in
the inter-model mean.

3.2. Simulation model validation results

Figure 7 shows the time series correlation between the simu-
lation model yield and FAO yield data. The results are mixed,
with many regions for rice and wheat being difficult to model.
No single model is dominant, with each model providing near
best-in-class performance in at least one location-crop combi-
nation. The presence of no vertical dark green color bars clearly
illustrates the power of a multi-model intercomparison project
like the one presented here. The ensemble mean yield is cal-
culated across all 'high' nitrogen application level model sim-
ulations and correlated with the FAO data (not the mean of the
correlations). The ensemble mean does not beat the best model
in each case, but shows positive correlation in over 75% of the
cases presented here.

Soy is qualitatively the easiest crop to represent (except in
Argentina), which is likely due to the invariance of the re-
sponse to nitrogen application (soy fixes atmospheric nitrogen
very efficiently). Comparison to the FAO data is therefore eas-
ier than the other crops because the nitrogen application levels
do not matter. US maize has the best performance across mod-
els, with nearly every model representing the historical vari-
ability to some extent. Especially good example years for US
maize are 1983, 1988, and 2004 (top left panel), where every
model gets the direction of the anomaly compared to surround-
ing years correct. 1983 and 1988 are famously bad years for
US maize along with 2012 (not shown). US maize is (prob-
ably) both the most uniformly industrialized (in terms of man-
agement) crop and the one with the best data collection in the
historical period of all the cases presented here.

FAO data is at least one level of abstraction from ground truth
in many cases, especially in developing countries. The fail-
ure of models to represent the year-to-year variability in rice in
some countries in southeast Asia is likely partly due to model
failure and partly due to lack of data. Partitioning of these con-
tributions is impossible at this stage. Additionally, there is less
year-to-year variability in rice yields (partially due to the frac-
tion of irrigated cultivation). Since the Pearson r metric is scale
invariant, it will tend to score the rice models more poorly than
maize and soy. The pDSSAT model shows very poor perfor-
mance for rice in India (top right panel).

*One might suspect that the difference in performance be-
tween Pakistan (no successful models) and India (many suc-
cessful models) for rice may lie in the FAO data and not the
models themselves. What would be so different about rice pro-
duction across these two countries that could explain this dif-
ference??*

Figure 8 shows the distribution across historical maize yields
for some high producing countries. The discrepancy between

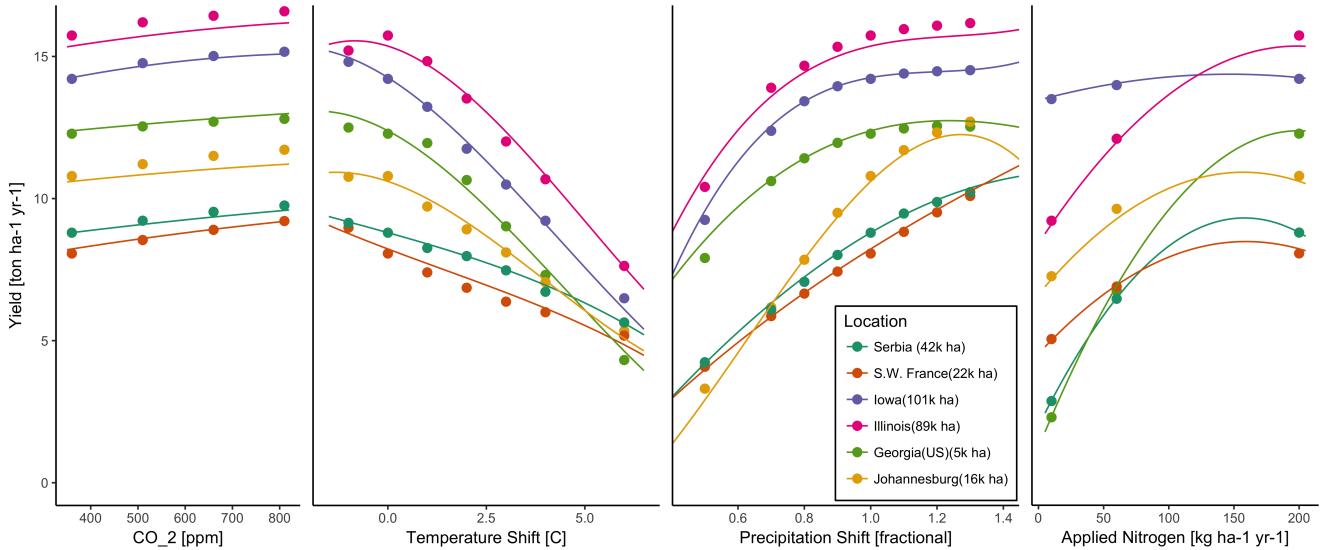


Figure 5: Example illustrating spatial variations in yield response and emulation ability. We show rain-fed maize in the pDSSAT model in six example locations selected to represent high-cultivation areas around the globe. Legend includes hectares cultivated in each selected grid cell. Each panel shows variation along a single variable, with others held at baseline values. Dots show climatological mean yield, solid lines a simple polynomial fit across this 1D variation, and dashed lines the results of the full emulator of Equation 1. The climatological response is sufficiently smooth to be represented by a simple polynomial. Because precipitation changes are imposed as multiplicative factors rather than additive offsets, locations with higher baseline precipitation have a larger absolute spread in inputs sampled than do drier locations (not visible here).

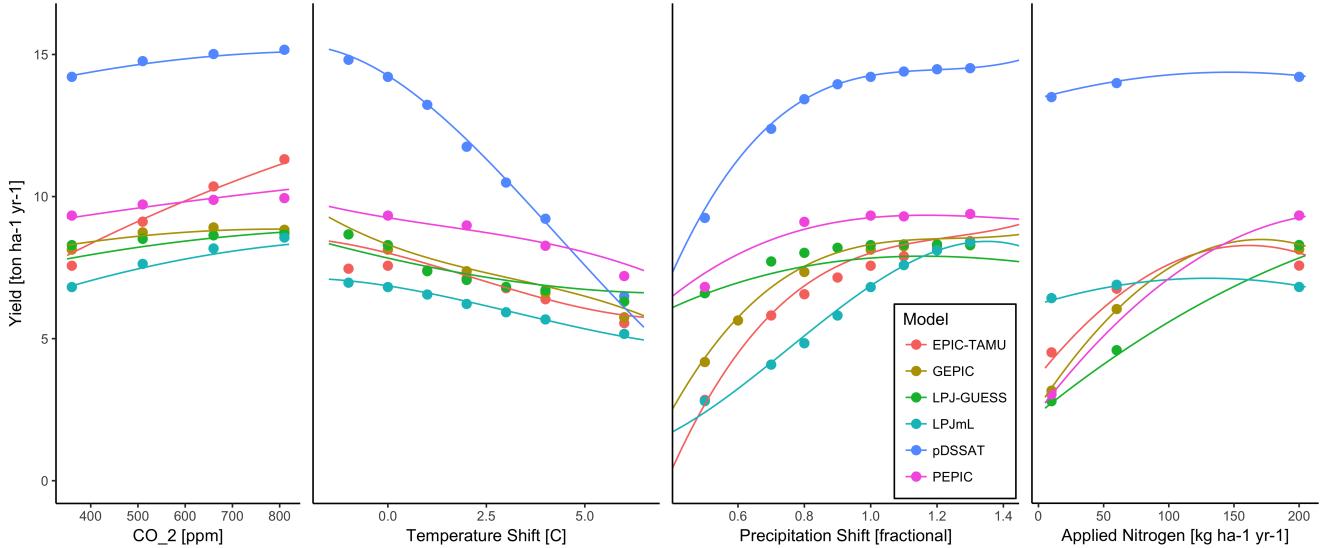


Figure 6: Example illustrating across-model variations in yield response. We show simulations and emulations from six models for rain-fed maize in the same Iowa location shown in Figure 5, with the same plot conventions. Models that did not simulate the nitrogen dimension are omitted for clarity. The inter-model standard deviation is larger for the perturbations in CO₂ and nitrogen than for those in temperature or precipitation illustrating that the sensitivity to weather is better constrained than to management at elevated CO₂. While most model responses can readily be emulated with a simple polynomial, some response surfaces are more complicated and lead to emulation error.

490 the simulations and FAO data is most evident in developing na-494 **3.3. Emulator performance**

491 tions, where nitrogen application levels are far below the 200

492 kg ha⁻¹ applied in the simulations shown here (though the dis-495 tributions are similar in those nations otherwise).

496 Emulation provides not only a computational tool but a
497 means of understanding and interpreting crop yield response
498 across the parameter space. Emulation is only possible, how-
ever, when crop yield responses are sufficiently smooth and



Agfromet_validation.png

Figure 7: Time series correlation coefficients between simulated crop yield and FAO data at the country level. The top panels indicate two example cases: US maize (a good case), and rice in India (mixed case), both for the high nitrogen application case. The heatmaps illustrate the Pearson r correlation between the detrended simulation mean yield at the country level compared to the detrended FAO yield data for the top producing countries for each crop with continuous FAO data over the 1980-2010 period. Models that provided different nitrogen application levels are shown with low, med, and high label (models that did not simulate different nitrogen levels are analogous to a high nitrogen application level). The ensemble mean yield is also correlated with the FAO data.

499 continuous to allow fitting with a relatively simple functional₅₀₀
 500 form. In the GGCMI simulations, this condition largely but₅₀₁
 501 not always holds. Responses are quite diverse across locations,₅₀₂
 502 crops, and models, but in most cases local responses are reg-₅₀₃
 503 ular enough to permit emulation. Figure 5 illustrates the ge-₅₀₄
 504 ographic diversity of responses even in high-yield areas for a₅₀₅
 505 single crop and model (rain-fed maize in pDSSAT for various₅₀₆
 506 high-cultivation areas). This heterogeneity validates the choice₅₀₇
 507 of emulating at the grid cell level.

Each panel in Figure 5 shows model yield output from scenarios varying only along a single dimension (CO_2 , temperature, precipitation, or nitrogen addition), with other inputs held fixed at baseline levels; in all cases yields evolve smoothly across the space sampled. For reference we show the results of the full emulation fitted across the parameter space. The polynomial fit readily captures the climatological response to perturbations.

516 Crop yield responses generally follow similar functional



phase_II_em_val.png

Figure 8: Distribution in historical yields (1981-2009) for maize for eight example high producing countries. FAO, simulation (high nitrogen), and emulation. Emulated values are calculated based on the additive temperature anomaly or percentage precipitation anomaly from the 1980-2010 period in each year. Note: the emulator is designed to provide the mean change in yield under climatological mean shift in temperature (or precipitation). Applying it at the year to year level should be interpreted with caution.

517 forms across models, though with a spread in magnitude. Fig-₅₂₇ 3 and ??.) For this location and crop, CO₂ fertilization effects
518 ure 6 illustrates the inter-model diversity of yield responses₅₂₈ can range from ~5–50%, and nitrogen responses from nearly
519 to the same perturbations, even for a single crop and location₅₂₉ flat to a 60% drop in the lowest-application simulation.
520 (rain-fed maize in northern Iowa, the same location shown in₅₃₀
521 the Figure 5). The differences make it important to construct₅₃₁ While the nitrogen dimension is important and uncertain, it
522 emulators separately for each individual model, and the fidelity₅₃₂ is also the most problematic to emulate in this work because
523 of emulation can also differ across models. This figure illus-₅₃₃ of its limited sampling. The GGCMI protocol specified only
524 trates a common phenomenon, that models differ more in re-₅₃₄ three nitrogen levels (10, 100 and 200 kg N y⁻¹ ha⁻¹), so a
525 sponse to perturbations in CO₂ and nitrogen perturbations than₅₃₅ third-order fit would be over-determined but a second-order fit
526 to those in temperature or precipitation. (Compare also Figures₅₃₆ can result in potentially unphysical results. Steep and nonlinear
declines in yield with lower nitrogen levels means that some re-

gressions imply a peak in yield between the 100 and 200 kg N y^{-1} ha $^{-1}$ levels. While there may be some reason to believe over-application of nitrogen at the wrong time in the growing season could lead to reduced yields, these features are almost certainly an artifact of under sampling. In addition, the polynomial fit cannot capture the well-documented saturation effect of nitrogen application (e.g. Ingestad, 1977) as accurately as would be possible with a non-parametric model.

To assess the ability of the polynomial emulation to capture the behavior of complex process-based models, we evaluate the normalized emulator error. That is, for each grid cell, model, and scenario we evaluate the difference between the model yield and its emulation, normalized by the inter-model standard deviation in yield projections. This metric implies that emulation is generally satisfactory, with several distinct exceptions. Almost all model-crop combination emulators have normalized errors less than one over nearly all currently cultivated hectares (Figure 9), but some individual model-crop combinations are problematic (e.g. PROMET for rice and soy, JULES for soy and winter wheat, Figures ??–??). Normalized errors for soy are somewhat higher across all models not because emulator fidelity is worse but because models agree more closely on yield changes for soy than for other crops (see Figure ??, lowering the denominator). Emulator performance often degrades in geographic locations where crops are not currently cultivated. Figure 10 shows a CARAIB case as an example, where emulator performance is satisfactory over cultivated areas for all crops other than soy, but uncultivated regions show some problematic areas.

It should be noted that this assessment metric is relatively forgiving. First, each emulation is evaluated against the simulation actually used to train the emulator. Had we used a spline interpolation the error would necessarily be zero. Second, the performance metric scales emulator fidelity not by the magni-

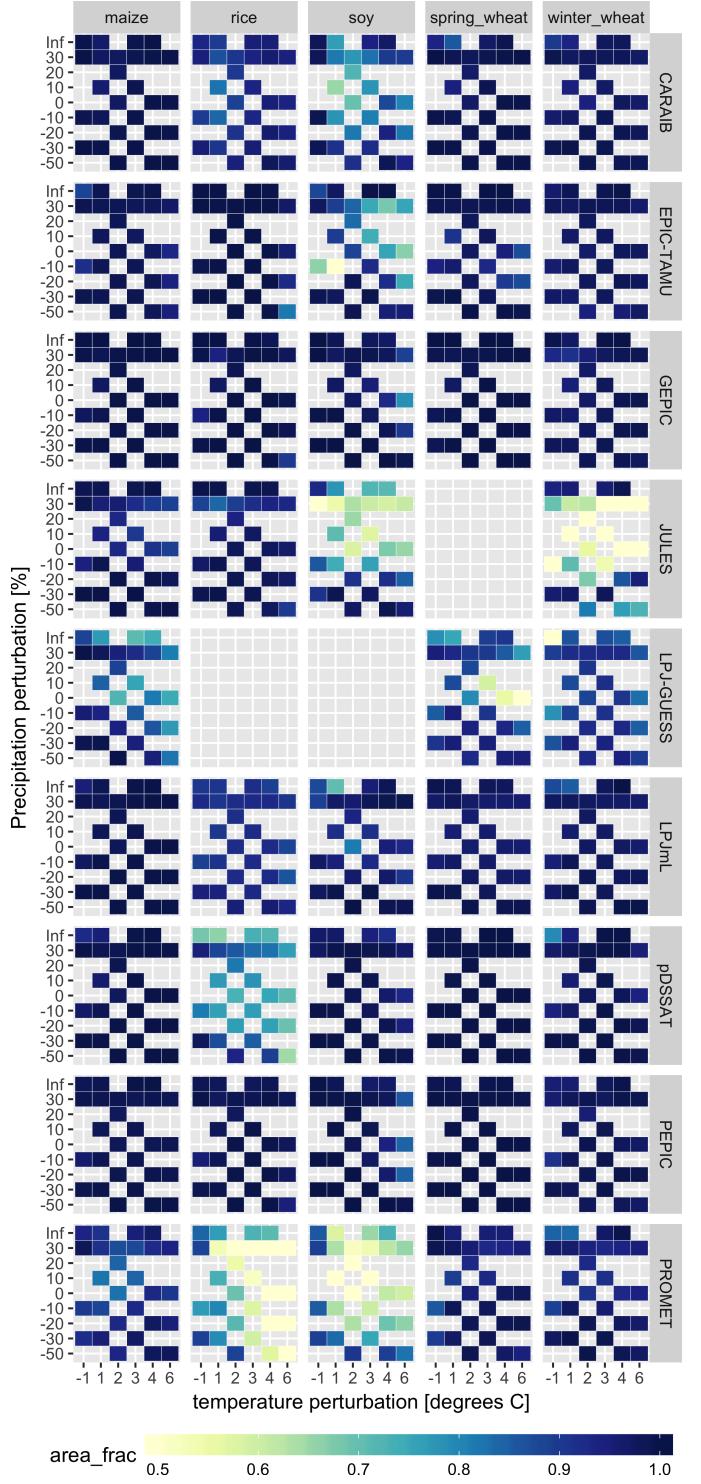


Figure 9: Assessment of emulator performance over currently cultivated areas based on normalized error (Equations 3, 2). We show performance of all 9 models emulated, over all crops and all sampled T and P inputs, but with CO₂ and nitrogen held fixed at baseline values. Large columns are crops and large rows models; squares within are T,P scenario pairs. Colors denote the fraction of currently cultivated hectares with $e < 1$. Of the 756 scenarios with these CO₂ and N values, we consider only those for which all 9 models submitted data. JULES did not simulate spring wheat and LPJ-GUESS did not simulate rice and soy. Emulator performance is generally satisfactory, with some exceptions. Emulator failures (significant areas of poor performance) occur for individual crop-model combinations, with performance generally degrading for hotter and wetter scenarios.

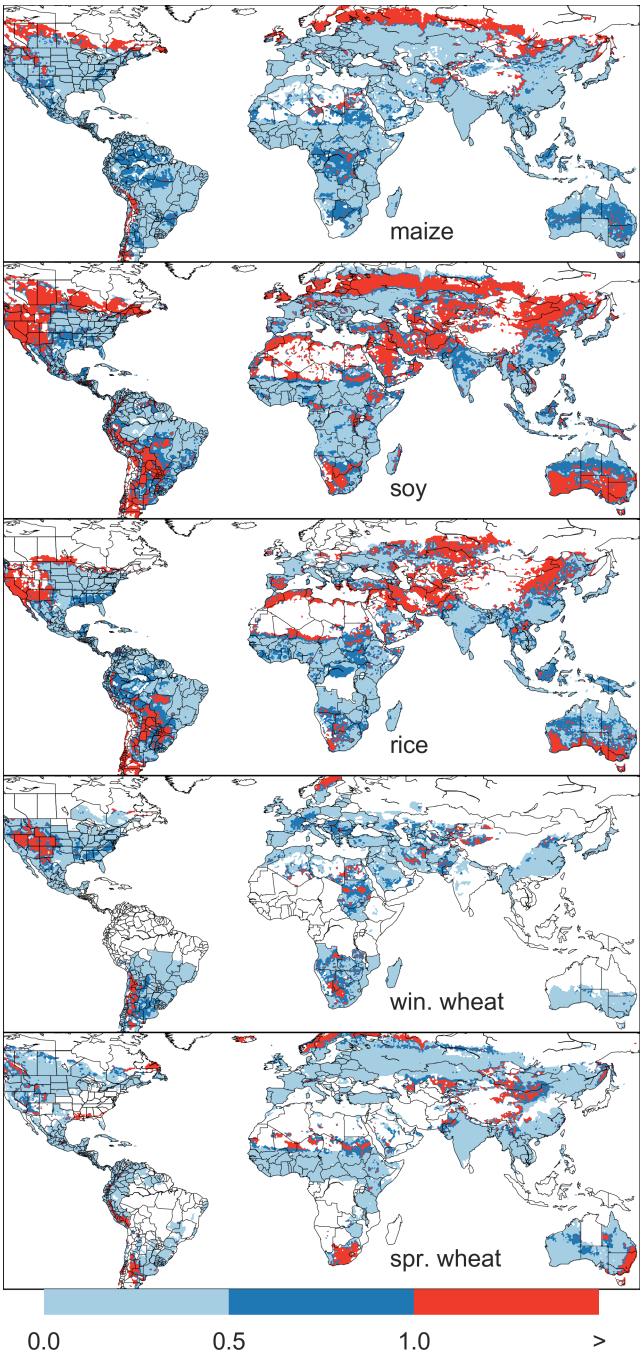


Figure 10: Illustration of our test of emulator performance, applied to the CARAIB model for the T+4 scenario for rain-fed crops. Contour colors indicate the normalized emulator error e , where $e > 1$ means that emulator error exceeds the multi-model standard deviation. White areas are those where crops are not simulated by this model. Models differ in their areas omitted, meaning the number of samples used to calculate the multi-model standard deviation is not spatially consistent in all locations. Emulator performance is generally good relative to model spread in areas where crops are currently cultivated (compare to Figure 1) and in temperate zones in general; emulation issues occur primarily in marginal areas with low yield potentials. For CARAIB, emulation of soy is more problematic, as was also shown in Figure 9.

tude of yield changes but by the inter-model spread in those changes. Where models differ more widely, the standard for emulators becomes less stringent. Because models disagree on the magnitude of CO₂ fertilization, this effect is readily seen when comparing assessments of emulator performance in simulations at baseline CO₂ (Figure 9) with those at higher CO₂ levels (Figure ??). Widening the inter-model spread leads to an apparent increase in emulator skill.

3.4. Emulator applications

Because the emulator or “surrogate model” transforms the discrete simulation sample space into a continuous response surface at any geographic scale, it can be used for a variety of applications. Emulators provide an easy way to compare a ensembles of climate or impacts projections. They also provide a means for generating continuous damage functions. As an example, we show a damage function constructed from 4D emulations for aggregated yield at the global scale, for maize on currently cultivated land, with simulated values shown for comparison. (Figure 11; see Figures ??- ?? in the supplemental material for other crops and dimensions.) The emulated values closely match simulations even at this aggregation level. Note that these functions are presented only as examples and do not represent true global projections, because they are developed from simulation data with a uniform temperature shift while increases in global mean temperature should manifest non-uniformly. The global coverage of the GGCMI simulations allows impacts modelers to apply arbitrary geographically-varying climate projections, as well as arbitrary aggregation mask, to develop damage functions for any climate scenario and any geopolitical or geographic level.

4. Conclusions and discussion

The GGCMI Phase II experiment assess sensitivities of process-based crop yield models to changing climate and man-

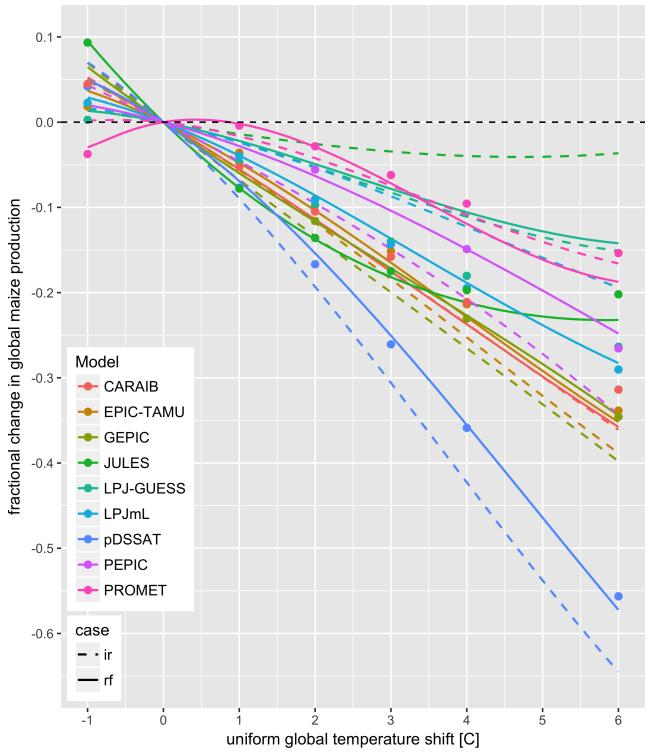


Figure 11: Global emulated damages for maize on currently cultivated lands⁶³¹ for the GGCMI models emulated, for uniform temperature shifts with other⁶³² inputs held at baseline. (The damage function is created from aggregating up⁶³³ emulated values at the grid-cell level, not from a regression of global mean⁶³⁴ yields.) Lines are emulations for rain-fed (solid) and irrigated (dashed) crops;⁶³⁵ for comparison, dots are the simulated values for the rain-fed case. For most⁶³⁶ models, irrigated crops show a sharper reduction than do rain-fed because of the⁶³⁷ locations of cultivated areas: irrigated crops tend to be grown in warmer areas⁶³⁸ where impacts are more severe for a given temperature shift. (The exceptions⁶³⁹ are PROMET, JULES, and LPJmL.) For other crops and scenarios see Figures⁶⁴⁰ ??- ?? in the supplemental material.

agement inputs, and was designed to allow not only comparison⁶³⁸ across models but evaluation of complex interactions between⁶³⁹ driving factors (CO₂, temperature, precipitation, and applied⁶⁴⁰ nitrogen) and identification of geographic shifts in high yield⁶⁴¹ potential locations. While the richness of the dataset invites⁶⁴² further analysis, we show only a selection of insights derived⁶⁴³ from the simulations. Across the major crops, inter-model un-⁶⁴⁴ certainty is greatest for wheat and least for soy. Across factors⁶⁴⁵ impacting yields, inter-model-uncertainty is largest for CO₂ fer-⁶⁴⁶ tilization and nitrogen response effects. Across geographic re-⁶⁴⁷ gions, inter-model uncertainty is largest in the high latitudes⁶⁴⁸ where yields may increase, and model projections are most ro-⁶⁴⁹ bust in low latitudes where yield impacts are largest.

Model performance when compared to historical data is mixed, with models performing better for maize and soy than for rice and wheat. The value of utilizing multiple models is illustrated by the distribution in performance skill across different countries and crops. An end-user of the simulation outputs or emulator tool may pick and choose models based on historical skill to provide the most faithful temperature and precipitation response depending on their application. The nitrogen and CO₂ responses were not validated in this work.

One counterintuitive result is that irrigated maize shows steeper yield reductions under warming than does rain-fed maize when considered only over currently cultivated land. The effect is the result of geographic differences in cultivated area. In any given location, irrigation increases crop resiliency to temperature increase, but irrigated maize is grown in warmer locations where the impacts of warming are more severe (Figures ??-??). The same behavior holds for rice and winter wheat, but not for soy or spring wheat (Figures ??-??). Irrigated wheat and maize are also more sensitive to nitrogen fertilization levels, presumably because growth in rain-fed crops is also water-limited (Figure ??). (Soy as a nitrogen-fixer is relatively insensitive to nitrogen, and rice is not generally grown in water-limited conditions.)

We show that emulation of the output of these complex responses is possible even with a relatively simple reduced-form statistical model and a limited library of simulations. Emulation therefore offers the opportunity of producing rapid assessments of agricultural impacts for arbitrary climate scenarios in a computationally non-intensive way. The resulting tool should aid in impacts assessment, economic studies, and uncertainty analyses. Emulator parameter values also provide a useful way to compare sensitivities across models to different climate and management inputs, and the terms in the polynomial fits offer the possibility of physical interpretation of these dependencies

651 to some degree.

652 We open up this simulation output dataset for further analysis⁶⁸⁶
653 by the community as we have only scratched the surface with⁶⁸⁷
654 this work, and all simulation output data are readily available.⁶⁸⁸
655 Each simulation run includes year to year variability in yields⁶⁸⁹
656 under different climate and management regimes. Some of the⁶⁹⁰
657 precipitation and temperature space has been lost due to the ag-⁶⁹¹
658 gregation in the time dimension (i.e. the + 6 C simulation in⁶⁹²
659 the hottest year of the historical period compared to the coldest⁶⁹³
660 historical year, or precipitation perturbations in the driest his-⁶⁹⁴
661 torical year etc.) Development of a year-to-year emulator, or
662 an emulator at different spatial scales may provide useful for⁶⁹⁵
663 some IAM applications. More exhaustive analysis of differ-⁶⁹⁶
664 ent statistical model specification for emulation may likely pro-⁶⁹⁷
665 vide additional predictive skill over the specification provided⁶⁹⁸
666 here. The potentially richest area for analysis is the interactions⁶⁹⁹
667 space between input variable especially the Nitrogen and CO₂⁷⁰⁰
668 interactions with weather and with each other. Adaptation via⁷⁰¹
669 growing season changes were also simulated and are available⁷⁰²
670 in the database, though this dimension was not presented or an-⁷⁰³
671 alized here.

672 The emulation approach presented here has some limitations.⁷⁰⁵
673 Because the GGCMI simulations apply uniform perturbations⁷⁰⁶
674 to historical climate inputs, they do not sample changes in⁷⁰⁷
675 higher order moments. The emulation therefore does not ad-⁷⁰⁸
676 dress the crop yield impacts of potential changes in climate⁷⁰⁹
677 variability. While some information could be extracted from⁷¹⁰
678 consideration of year-over-year variability, more detailed sim-⁷¹¹
679 ulations and analysis are likely necessary to diagnose the im-⁷¹²
680 pact of changes in variance and sub-growing-season tempo-⁷¹³
681 ral effects. Additionally, the emulator is intended to provide⁷¹⁴
682 the change in yield from a historical mean baseline value and⁷¹⁵
683 should be used in conjunction with historical data (or data prod-⁷¹⁶
684 ucts) or a historical mean emulator (not presented here).

685 The future of food security is one of the larger challenges
facing humanity at present. The development (and emulation)
of multi-model ensembles such as GGCMI Phase II provides
a way to begin to quantify uncertainties in crop responses to
a range of potential climate inputs and explore the potential
benefits of adaptive responses. Emulation also allow making
state-of-the-art simulation results available to a wide research
community as simple, computationally tractable tools that can
be used by downstream modelers to understand the socioeco-
nomic impacts of crop response to climate change.

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718 6. References

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