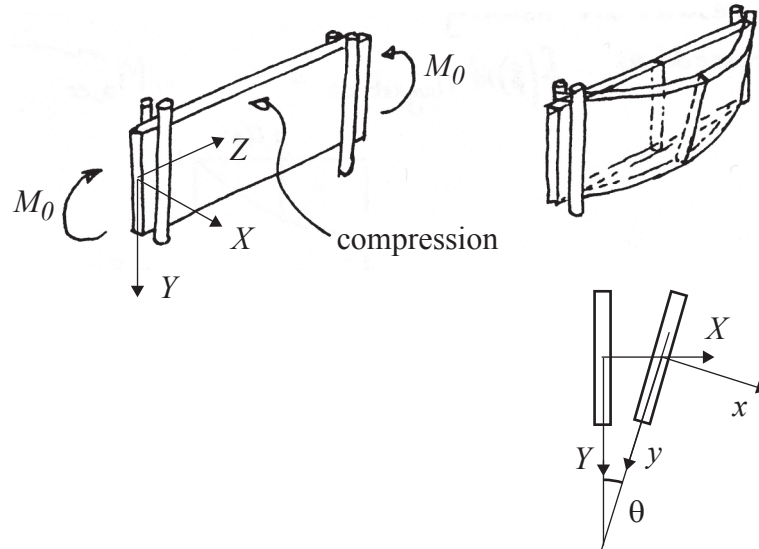


3.6.1 Rectangular section (no warping)

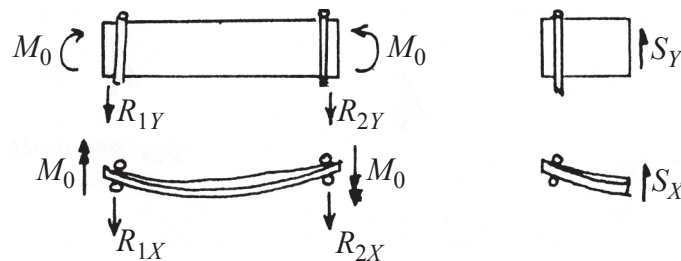
Consider a “simply supported” rectangular section (thin plank) beam loaded by equal and opposite in-plane bending couples, and supported in such a way that the ends are prevented from torsional rotation.



Note that X, Y, Z is a *global coordinate system* that is fixed; while x, y, z is a *local coordinate system* that moves with the cross-section.

Assume $I_{xx} \gg I_{yy}$, and hence there are negligibly small vertical deflections prior to buckling. Consider equilibrium *in the deformed shape*.

Force equilibrium:



Reaction forces:

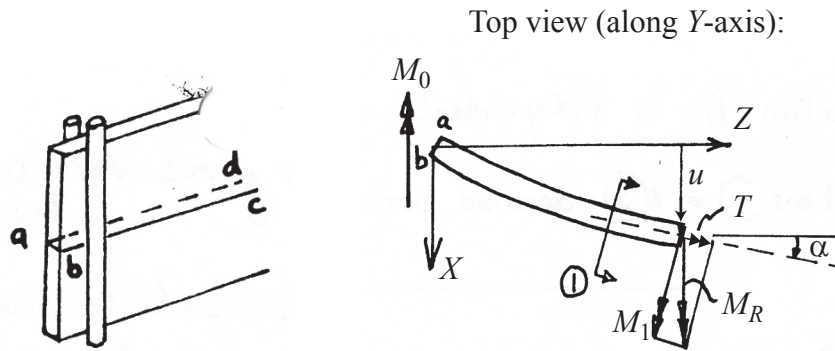
$$R_{1Y} = R_{2Y} = 0$$

$$R_{1X} = R_{2X} = 0$$

Shear forces:

$$S_X = S_Y = 0$$

Moment equilibrium:



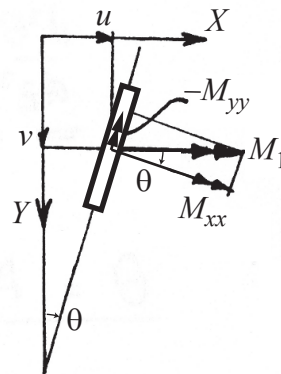
$$M_R = M_0$$

$$M_1 = M_R \cos \alpha \approx M_0$$

$$T = M_R \sin \alpha \approx M_0 \alpha$$

where $\alpha = \frac{du}{dz}$

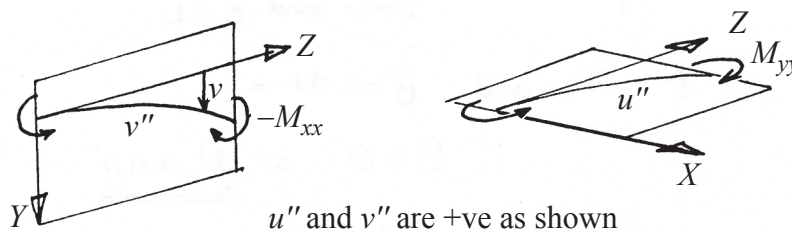
View along direction 1:



$$M_{xx} = M_1 \cos \theta \approx M_0$$

$$M_{yy} = -M_1 \sin \theta \approx -M_0 \theta$$

Material law and compatibility:



Consider the beam centroid plotted in the YZ and ZX planes. We have bending relationships (with particular +ve and -ve signs because of our right-handed coordinate set)

$$M_{xx} = -EI_{xx}v''$$

$$M_{yy} = +EI_{yy}u''$$

We also have a torsional relationship

$$T = GJ \frac{d\theta}{dz}$$

Combining equilibrium, compatibility and the material law: we obtain *one independent* equation relating to vertical bending:

$$M_0 = M_{xx} = -EI_{xx}v''$$

and *two coupled equations* relating to the combined lateral-torsional behaviour of the beam

$$-M_0\theta = M_{yy} = EI_{yy}u'' \quad (*)$$

$$M_0u' = T = GJ \frac{d\theta}{dz} \quad (\dagger)$$

Governing differential equation for lateral-torsional behaviour:

Differentiate (\dagger) by Z (equivalently, z) and substitute u'' from $(*)$ gives

$$\frac{d^2\theta}{dz^2} + \left(\frac{M_0^2}{GJEI_{yy}} \right) \theta = 0$$

General solution:

$$\theta = A \cos \beta Z + B \sin \beta Z$$

where $\beta = \frac{M_0}{\sqrt{GJEI_{yy}}}$.

The boundary conditions are:

$$\theta = 0 \quad \text{at } Z = 0 \text{ and } Z = L$$

hence

$$A = 0 \quad \text{and} \quad B \sin \beta L = 0$$

and so

$$B = 0 \quad \text{or} \quad \beta L = n\pi$$

The lowest critical moment has $n = 1$, and hence

$$M_{0,cr} = \frac{\pi}{L} \sqrt{GJEI_{yy}}$$

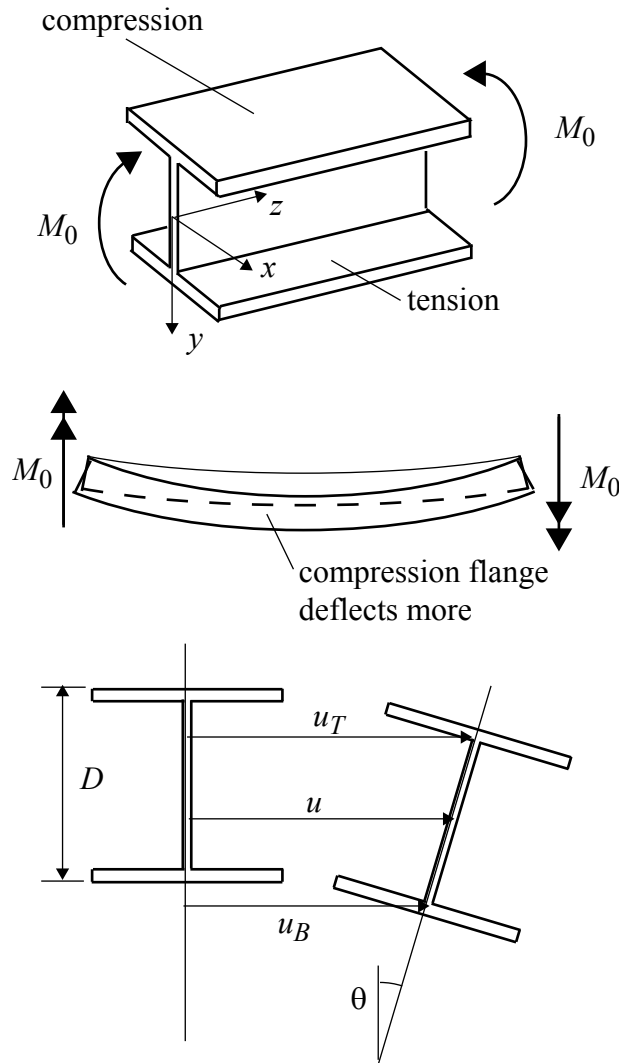
Note that:

- $M_{0,cr}$ depends on both the torsional rigidity GJ and the minor axis flexural rigidity EI_{yy}
- $M_{0,cr} \propto \frac{1}{L}$ whereas $P_E \propto \frac{1}{L^2}$

Try Question 6, Examples Paper 4

3.6.2 I-beam (including warping)

A pure bending moment M_0 about the major axis can cause lateral-torsional buckling about the minor axis of bending of the beam.



It was shown in the first half of 3D4 that the torque carried by the beam, T , is related to the section rotation θ by

$$T = GJ\theta' - E\Gamma\theta'''$$

where Γ is the *restrained warping torsion constant*.

Following through all of the previous lateral-torsional buckling analysis gives

$$E\Gamma \frac{d^4\theta}{dz^4} - GJ \frac{d^2\theta}{dz^2} - \frac{M_0^2}{EI_{yy}} \theta = 0$$

giving a **Governing Differential Equation:**

$$\theta'''' - 2\alpha\theta'' - \beta\theta = 0$$

where α is a structural parameter, and β is a measure of the load,

$$\alpha = \frac{GJ}{2E\Gamma} \quad \text{and} \quad \beta = \frac{M_0^2}{E^2 I_{yy} \Gamma}$$

The **General Solution** is

$$\theta = A \cos k_1 z + B \sin k_1 z + C \cosh k_2 z + D \sinh k_2 z$$

where

$$k_1^2 = -\alpha + \sqrt{\alpha^2 + \beta}$$

$$k_2^2 = +\alpha + \sqrt{\alpha^2 + \beta}$$

Imposing the boundary conditions ($\theta = 0$, $\theta'' = 0$ at $x = 0$, $x = L$), we find that all terms vanish except $B \sin k_1 z$. Thus, either $B = 0$ (trivial solution) or $k_1 L = n\pi$, which gives the critical buckling condition for the case $n = 1$. Hence,

$$\sqrt{\alpha^2 + \beta} - \alpha = \frac{\pi^2}{L^2} (= k_1^2)$$

from which we obtain

$$\beta = 2\alpha \frac{\pi^2}{L^2} + \frac{\pi^4}{L^4}$$

or

$$M_{0,cr}^2 = \left(\frac{\pi}{L} \sqrt{GJ E I_{yy}} \right)^2 + \left(\frac{\pi^2}{L^2} E \sqrt{I_{yy} \Gamma} \right)^2$$

$$M_{0,cr} = \frac{\pi}{L} \sqrt{GJ E I_{yy}} \sqrt{1 + \frac{\pi^2 E \Gamma}{L^2 GJ}}$$

The last term is a factor that allows for warping, and typically has a value of about 1.25 for $L/D \approx 20$ for an I-section. For long spans, the additional warping term is of less importance.

For an I-beam the restrained warping term comes from the requirement to bend the flanges about their major axis, and is given by

$$\Gamma = \frac{I_f D^2}{2} \approx \frac{I_y D^2}{4}$$

where I_f is the second moment of area of a single flange about its major axis. Because the web is thin and at the neutral axis for lateral bending, we approximate $I_f \approx I_y/2$.

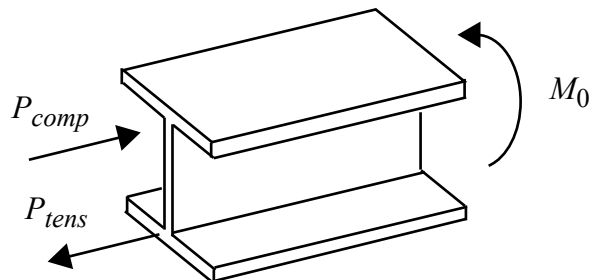
For short spans, the warping correction can dominate. In that case,

$$M_{0,cr} = \frac{\pi}{L} \sqrt{GJ} \sqrt{E I_{yy}} \left(\frac{\pi \sqrt{E \Gamma}}{L \sqrt{GJ}} \right) = \frac{\pi^2}{L^2} E \sqrt{I_{yy} \Gamma}$$

Substituting $\Gamma = I_{yy} D^2/4 = I_f D^2/2$

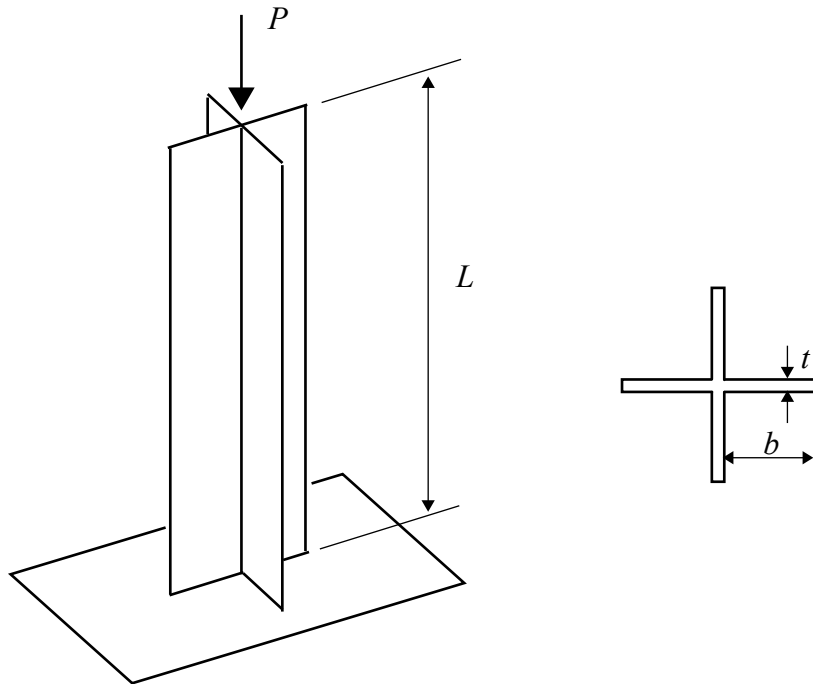
$$\frac{M_{0,cr}}{D} = \frac{\pi^2}{L^2} E I_f$$

Note: Force in compression flange is $P_{comp} = M_0/D$, and in this case the equation reduces to the Euler buckling of the compression flange.



3.6.3 Axial-torsional buckling

Consider a cruciform column, fixed at the base and free at the top.



This has an open section and hence low torsional stiffness

$$J = 4 \times \frac{1}{3}bt^3$$

Consider a mode of buckling in which the top end rotates through an angle θ relative to the bottom end, with the entire column in a state of uniform shear. An analysis of this buckling mode leads to the following expression for the *critical stress for torsional buckling*:

$$\sigma_{cr,T} = G \left(\frac{t}{b} \right)^2$$

Note that this does not depend on the length L .

Try Question 7, Examples Paper 4