

# Privacy, Data Privacy, and Differential Privacy

James Bailie, Robin Gong, and Xiao-Li Meng

December 13, 2023

# HARVARD LAW REVIEW.

---

VOL. IV.

DECEMBER 15, 1890.

NO. 5.

---

## THE RIGHT TO PRIVACY.

"It could be done only on principles of private justice, moral fitness,  
and public convenience, which, when applied to a new subject, make

*The right to be  
let alone.*



Samuel D. Warren II



Louis Brandeis

# Privacy – Can you define it?

- Law: **Privacy is the right to be let alone.**

Warren & Brandeis (1890). The Right to Privacy. *Harvard Law Review*.

# Privacy – Can you define it?

- Law: **Privacy is the right to be let alone.**

Warren & Brandeis (1890). The Right to Privacy. *Harvard Law Review*.

- Economics: **Privacy is the price of divulging information.**

Acquisti et al. (2016) The Economics of Privacy.  
*Journal of Economic Literature*.

# Privacy – Can you define it?

- Law: **Privacy is the right to be let alone.**

Warren & Brandeis (1890). The Right to Privacy. *Harvard Law Review*.

- Economics: **Privacy is the price of divulging information.**

Acquisti et al. (2016) The Economics of Privacy.  
*Journal of Economic Literature*.

- Political Science: **The boundaries of power over the individual ascribe the rights of the individual to privacy.**

Raab (2019). Political Science and Privacy. In *The Handbook of Privacy Studies: An Interdisciplinary Introduction*. Amsterdam University Press.

# Privacy – Can you define it?

- Law: **Privacy is the right to be let alone.**

Warren & Brandeis (1890). The Right to Privacy. *Harvard Law Review*.

- Economics: **Privacy is the price of divulging information.**

Acquisti et al. (2016) The Economics of Privacy.  
*Journal of Economic Literature*.

- Political Science: **The boundaries of power over the individual ascribe the rights of the individual to privacy.**

Raab (2019). Political Science and Privacy. In *The Handbook of Privacy Studies: An Interdisciplinary Introduction*. Amsterdam University Press.

- Philosophy: **“Privacy . . . is a concept in disarray. ...** Currently privacy is a sweeping concept. . . . Philosophers . . . have frequently lamented the great difficulty in reaching a satisfying conception of privacy.”

Solove (2008) *Understanding Privacy*. Harvard University Press.

# Data Privacy — What does that mean?

# Data Privacy — What does that mean?

## Data Content Privacy

Protect information that can be revealed by the recorded data values.



# Data Privacy — What does that mean?

## Data Content Privacy

Protect information that can be revealed by the recorded data values.

## Metadata Privacy

Protect the identities of the sender and the receiver, time of communication, etc.

# Data Privacy — What does that mean?

## Data Content Privacy

Protect information that can be revealed by the recorded data values.

## Metadata Privacy

Protect the identities of the sender and the receiver, time of communication, etc.

## Right To Be Forgotten

Right to have personal data erased.

- But how do we operationalize *erasure*? Do we erasure all copies? All consequences?

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  
 $R = 1$  if head, and  $R = 0$  if tail.

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  $R = 1$  if head, and  $R = 0$  if tail.
- Report  $Y = 1$  if  $X = R$ , and otherwise report  $Y = 0$ .

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  $R = 1$  if head, and  $R = 0$  if tail.
- Report  $Y = 1$  if  $X = R$ , and otherwise report  $Y = 0$ .
- At the individual level,  $Y_i = 1$  can mean a cheater or not a cheater.

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  $R = 1$  if head, and  $R = 0$  if tail.
- Report  $Y = 1$  if  $X = R$ , and otherwise report  $Y = 0$ .
- At the individual level,  $Y_i = 1$  can mean a cheater or not a cheater.
- But in aggregation:

$$p_Y = \Pr(R = X) = p \times p_{\text{cheat}} + (1 - p) \times (1 - p_{\text{cheat}})$$

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  
 $R = 1$  if head, and  $R = 0$  if tail.
- Report  $Y = 1$  if  $X = R$ , and otherwise report  $Y = 0$ .
- At the individual level,  $Y_i = 1$  can mean a cheater or not a cheater.
- But in aggregation:

$$p_Y = \Pr(R = X) = p \times p_{\text{cheat}} + (1 - p) \times (1 - p_{\text{cheat}})$$

Recovering  $p_{\text{cheat}}$ :

$$p_{\text{cheat}} = \frac{p_Y + p - 1}{2p - 1}$$



## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  $R = 1$  if head, and  $R = 0$  if tail.
- Report  $Y = 1$  if  $X = R$ , and otherwise report  $Y = 0$ .
- At the individual level,  $Y_i = 1$  can mean a cheater or not a cheater.
- But in aggregation:

$$p_Y = \Pr(R = X) = p \times p_{\text{cheat}} + (1 - p) \times (1 - p_{\text{cheat}})$$

Recovering  $p_{\text{cheat}}$ :

$$p_{\text{cheat}} = \frac{p_Y + p - 1}{2p - 1}$$

Estimate

$$\hat{p}_{\text{cheat}} = \frac{\bar{Y}_n + p - 1}{2p - 1}$$

## Protecting Privacy via Randomized Response (Warner, 1965)

- Estimating exam cheating rate  $p_{\text{cheat}}$ .  $X = 1$ : cheated;  $X = 0$ , not cheated.
- Each student tosses a biased coin (with  $p > 0.5$ ) secretly before answering.  $R = 1$  if head, and  $R = 0$  if tail.
- Report  $Y = 1$  if  $X = R$ , and otherwise report  $Y = 0$ .
- At the individual level,  $Y_i = 1$  can mean a cheater or not a cheater.
- But in aggregation:

$$p_Y = \Pr(R = X) = p \times p_{\text{cheat}} + (1 - p) \times (1 - p_{\text{cheat}})$$

Recovering  $p_{\text{cheat}}$ :

$$p_{\text{cheat}} = \frac{p_Y + p - 1}{2p - 1}$$

Estimate

$$\hat{p}_{\text{cheat}} = \frac{\bar{Y}_n + p - 1}{2p - 1}$$

Ex:  $\bar{Y}_n = 0.45$ ,  $p = 0.6$

$$\hat{p}_{\text{cheat}} = \frac{0.45 + 0.6 - 1}{2 \times 0.6 - 1} = 0.25$$

# What is the loss of information or the gain in privacy?

## Increased Variance

$$\text{Var}(\hat{p}_{\text{cheat}}) = \frac{1}{n} \frac{p_Y(1-p_Y)}{(2p-1)^2} \leq \frac{1}{16n} \frac{1}{(p-0.5)^2}$$

# What is the loss of information or the gain in privacy?

## Increased Variance

$$\text{Var}(\hat{p}_{\text{cheat}}) = \frac{1}{n} \frac{p_Y(1-p_Y)}{(2p-1)^2} \leq \frac{1}{16n} \frac{1}{(p-0.5)^2}$$

## Control Relative Risk via Controlling Likelihood Ratio

$$\frac{\Pr(X_i = 1|Y_i)}{\Pr(X_i = 0|Y_i)} = \frac{\Pr(Y_i|X_i = 1) \Pr(X_i = 1)}{\Pr(Y_i|X_i = 0) \Pr(X_i = 0)}$$

# What is the loss of information or the gain in privacy?

## Increased Variance

$$\text{Var}(\hat{p}_{\text{cheat}}) = \frac{1}{n} \frac{p_Y(1-p_Y)}{(2p-1)^2} \leq \frac{1}{16n} \frac{1}{(p-0.5)^2}$$

## Control Relative Risk via Controlling Likelihood Ratio

$$\frac{\Pr(X_i = 1 | Y_i)}{\Pr(X_i = 0 | Y_i)} = \frac{\Pr(Y_i | X_i = 1) \Pr(X_i = 1)}{\Pr(Y_i | X_i = 0) \Pr(X_i = 0)}$$

## The “first” example of *differential privacy*

$$\frac{\Pr(Y_i = 1 | X_i = 1)}{\Pr(Y_i = 1 | X_i = 0)} = \frac{p}{1-p} = e^\epsilon, \quad \text{with } \epsilon = \text{logit}(p)$$

# What is the loss of information or the gain in privacy?

## Increased Variance

$$\text{Var}(\hat{p}_{\text{cheat}}) = \frac{1}{n} \frac{p_Y(1-p_Y)}{(2p-1)^2} \leq \frac{1}{16n} \frac{1}{(p-0.5)^2}$$

## Control Relative Risk via Controlling Likelihood Ratio

$$\frac{\Pr(X_i = 1 | Y_i)}{\Pr(X_i = 0 | Y_i)} = \frac{\Pr(Y_i | X_i = 1) \Pr(X_i = 1)}{\Pr(Y_i | X_i = 0) \Pr(X_i = 0)}$$

## The “first” example of *differential privacy*

$$\frac{\Pr(Y_i = 1 | X_i = 1)}{\Pr(Y_i = 1 | X_i = 0)} = \frac{p}{1-p} = e^\epsilon, \quad \text{with } \epsilon = \text{logit}(p)$$

$$\frac{\Pr(Y_i = 0 | X_i = 1)}{\Pr(Y_i = 0 | X_i = 0)} = \frac{1-p}{p} = e^{-\epsilon}$$

# What is the loss of information or the gain in privacy?

## Increased Variance

$$\text{Var}(\hat{p}_{\text{cheat}}) = \frac{1}{n} \frac{p_Y(1-p_Y)}{(2p-1)^2} \leq \frac{1}{16n} \frac{1}{(p-0.5)^2}$$

## Control Relative Risk via Controlling Likelihood Ratio

$$\frac{\Pr(X_i = 1 | Y_i)}{\Pr(X_i = 0 | Y_i)} = \frac{\Pr(Y_i | X_i = 1) \Pr(X_i = 1)}{\Pr(Y_i | X_i = 0) \Pr(X_i = 0)}$$

## The “first” example of *differential privacy*

$$\frac{\Pr(Y_i = 1 | X_i = 1)}{\Pr(Y_i = 1 | X_i = 0)} = \frac{p}{1-p} = e^\epsilon, \quad \text{with } \epsilon = \text{logit}(p)$$

$$\frac{\Pr(Y_i = 0 | X_i = 1)}{\Pr(Y_i = 0 | X_i = 0)} = \frac{1-p}{p} = e^{-\epsilon}$$

$$e^{-\epsilon} \leq \frac{\Pr(Y_i = y | X_i = 1)}{\Pr(Y_i = y | X_i = 0)} \leq e^\epsilon, \quad \text{for } y = 0, 1$$

# What is the loss of information or the gain in privacy?

## Increased Variance

$$\text{Var}(\hat{p}_{\text{cheat}}) = \frac{1}{n} \frac{p_Y(1-p_Y)}{(2p-1)^2} \leq \frac{1}{16n} \frac{1}{(p-0.5)^2}$$

## Control Relative Risk via Controlling Likelihood Ratio

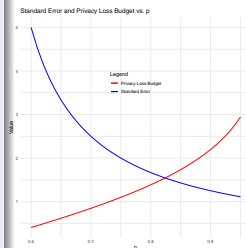
$$\frac{\Pr(X_i = 1 | Y_i)}{\Pr(X_i = 0 | Y_i)} = \frac{\Pr(Y_i | X_i = 1) \Pr(X_i = 1)}{\Pr(Y_i | X_i = 0) \Pr(X_i = 0)}$$

## The “first” example of *differential privacy*

$$\frac{\Pr(Y_i = 1 | X_i = 1)}{\Pr(Y_i = 1 | X_i = 0)} = \frac{p}{1-p} = e^\epsilon, \quad \text{with } \epsilon = \text{logit}(p)$$

$$\frac{\Pr(Y_i = 0 | X_i = 1)}{\Pr(Y_i = 0 | X_i = 0)} = \frac{1-p}{p} = e^{-\epsilon}$$

$$e^{-\epsilon} \leq \frac{\Pr(Y_i = y | X_i = 1)}{\Pr(Y_i = y | X_i = 0)} \leq e^\epsilon, \quad \text{for } y = 0, 1$$





## Define *Pure* DP: Dwork et al. (2006) vs Dwork et al. (2016)

Let the database  $\mathbf{X} = \{x_1, \dots, x_n\}$  be a vector of  $n$  entries from some domain  $D$ , typically of the form  $\{0, 1\}^d$  or  $\mathbb{R}^d$ . Let  $T_{\mathcal{A}}$  be a random mechanism (map) from  $D^n$  to a state space  $\mathcal{T}$ , corresponding to a query from an adversary  $\mathcal{A}$ .

## Define *Pure* DP: Dwork et al. (2006) vs Dwork et al. (2016)

Let the database  $\mathbf{X} = \{x_1, \dots, x_n\}$  be a vector of  $n$  entries from some domain  $D$ , typically of the form  $\{0, 1\}^d$  or  $\mathbb{R}^d$ . Let  $T_{\mathcal{A}}$  be a random mechanism (map) from  $D^n$  to a state space  $\mathcal{T}$ , corresponding to a query from an adversary  $\mathcal{A}$ .

### Definition 1 of Dwork, McSherry, et al. (2006)

A mechanism is  $\epsilon$ -indistinguishable if for all pairs  $\mathbf{X}, \mathbf{X}' \in D^n$  which differ in only one entry, for all adversaries  $\mathcal{A}$ , and for all transcripts  $t$ :

$$\left| \ln \frac{\Pr(T_{\mathcal{A}}(\mathbf{X}) = t)}{\Pr(T_{\mathcal{A}}(\mathbf{X}') = t)} \right| \leq \epsilon.$$

## Define *Pure* DP: Dwork et al. (2006) vs Dwork et al. (2016)

Let the database  $\mathbf{X} = \{x_1, \dots, x_n\}$  be a vector of  $n$  entries from some domain  $D$ , typically of the form  $\{0, 1\}^d$  or  $\mathbb{R}^d$ . Let  $T_{\mathcal{A}}$  be a random mechanism (map) from  $D^n$  to a state space  $\mathcal{T}$ , corresponding to a query from an adversary  $\mathcal{A}$ .

### Definition 1 of Dwork, McSherry, et al. (2006)

A mechanism is  $\epsilon$ -indistinguishable if for all pairs  $\mathbf{X}, \mathbf{X}' \in D^n$  which differ in only one entry, for all adversaries  $\mathcal{A}$ , and for all transcripts  $t$ :

$$\left| \ln \frac{\Pr(T_{\mathcal{A}}(\mathbf{X}) = t)}{\Pr(T_{\mathcal{A}}(\mathbf{X}') = t)} \right| \leq \epsilon.$$

## Define *Pure* DP: Dwork et al. (2006) vs Dwork et al. (2016)

Let the database  $\mathbf{X} = \{x_1, \dots, x_n\}$  be a vector of  $n$  entries from some domain  $D$ , typically of the form  $\{0, 1\}^d$  or  $\mathbb{R}^d$ . Let  $T_{\mathcal{A}}$  be a random mechanism (map) from  $D^n$  to a state space  $\mathcal{T}$ , corresponding to a query from an adversary  $\mathcal{A}$ .

### Definition 1 of Dwork, McSherry, et al. (2006)

A mechanism is  $\epsilon$ -indistinguishable if for all pairs  $\mathbf{X}, \mathbf{X}' \in D^n$  which differ in only one entry, for all adversaries  $\mathcal{A}$ , and for all transcripts  $t$ :

$$\left| \ln \frac{\Pr(T_{\mathcal{A}}(\mathbf{X}) = t)}{\Pr(T_{\mathcal{A}}(\mathbf{X}') = t)} \right| \leq \epsilon.$$

### Definition 2.1 of Dwork et al. (2016)

A noninteractive mechanism  $\mathcal{M}$  is  $\epsilon$ -differentially private (with respect to a given distance measure) if for all neighboring datasets  $\mathbf{X}, \mathbf{X}' \in \mathbb{N}^{|D|}$ , and for all events (measurable sets)  $S$  in the space of outputs of  $\mathcal{M}$ :

$$\Pr(\mathcal{M}(\mathbf{X}) \in S) \leq e^\epsilon \Pr(\mathcal{M}(\mathbf{X}') \in S).$$

The probabilities are over the coin flips of  $\mathcal{M}$ .

# Differential Privacy for the 2020 U.S. Census: Can We Make Data Both Private and Useful?

Special Issue 2

## FROM THE EDITORS



### Harnessing the Known Unknowns: Differential Privacy and the 2020 Census

by Ruobin Gong, Erica L. Groshen, and Saill Vadhav

Published: Jun 24, 2022

Special Issue 2: Differential Privacy for the 2020 U.S. Census

## CENSUS: IMPORTANCE, HISTORY, AND TECHNICAL CHANGES



### Coming to Our Census: How Social Statistics Underpin Our Democracy (and Republic)

by Teresa A. Sullivan

Published: Jan 31, 2020

#### CONNECTIONS

Commentary: Bill Mann, I. Sanderson, & Thomas



### Disclosure Protection in the Context of Statistical Agency Operations: Data Quality and Related Constraints

by John L. Eltinge

Published: Jun 24, 2022

Implementing Differential

## Does DP control the posterior-to-prior ratio ?

Revisit the Random Response Mechanism:  $Y_i = 1_{\{X_i=R_i\}}$ .

Suppose an adversary's prior for  $X_1$  is  $\Pr(X_1 = 1) = \pi$ .

$$\begin{aligned} C_\pi(y) &\equiv \frac{\Pr(X_1 = 1 | Y_1 = y)}{\Pr(X_1 = 1)} = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y)} \\ &= \frac{LR(y)}{LR(y)\pi + (1 - \pi)}, \quad \text{where } LR(y) = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y | X_1 = 0)} \end{aligned}$$

## Does DP control the posterior-to-prior ratio ?

Revisit the Random Response Mechanism:  $Y_i = 1_{\{X_i=R_i\}}$ .

Suppose an adversary's prior for  $X_1$  is  $\Pr(X_1 = 1) = \pi$ .

$$\begin{aligned} C_\pi(y) &\equiv \frac{\Pr(X_1 = 1 | Y_1 = y)}{\Pr(X_1 = 1)} = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y)} \\ &= \frac{LR(y)}{LR(y)\pi + (1 - \pi)}, \quad \text{where } LR(y) = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y | X_1 = 0)} \end{aligned}$$

$$LR(y) \geq 1 \Rightarrow 1 \leq C_\pi(y) \leq LR(y)$$

$$\max_{\pi} C_\pi(y) = C_0(y) = LR(y)$$

$$\min_{\pi} C_\pi(y) = C_1(y) = 1$$

## Does DP control the posterior-to-prior ratio ?

Revisit the Random Response Mechanism:  $Y_i = 1_{\{X_i=R_i\}}$ .

Suppose an adversary's prior for  $X_1$  is  $\Pr(X_1 = 1) = \pi$ .

$$\begin{aligned} C_\pi(y) &\equiv \frac{\Pr(X_1 = 1 | Y_1 = y)}{\Pr(X_1 = 1)} = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y)} \\ &= \frac{LR(y)}{LR(y)\pi + (1 - \pi)}, \quad \text{where } LR(y) = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y | X_1 = 0)} \end{aligned}$$

$$LR(y) \geq 1 \Rightarrow 1 \leq C_\pi(y) \leq LR(y)$$

$$\max_{\pi} C_\pi(y) = C_0(y) = LR(y)$$

$$\min_{\pi} C_\pi(y) = C_1(y) = 1$$

$$LR(y) \leq 1 \Rightarrow LR(y) \leq C_\pi(y) \leq 1$$

$$\max_{\pi} C_\pi(y) = C_1(y) = 1$$

$$\min_{\pi} C_\pi(y) = C_0(y) = LR(y)$$



## Does DP control the posterior-to-prior ratio ?

Revisit the Random Response Mechanism:  $Y_i = 1_{\{X_i=R_i\}}$ .

Suppose an adversary's prior for  $X_1$  is  $\Pr(X_1 = 1) = \pi$ .

$$\begin{aligned} C_\pi(y) &\equiv \frac{\Pr(X_1 = 1 | Y_1 = y)}{\Pr(X_1 = 1)} = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y)} \\ &= \frac{LR(y)}{LR(y)\pi + (1 - \pi)}, \quad \text{where } LR(y) = \frac{\Pr(Y_1 = y | X_1 = 1)}{\Pr(Y_1 = y | X_1 = 0)} \end{aligned}$$

$$LR(y) \geq 1 \Rightarrow 1 \leq C_\pi(y) \leq LR(y)$$

$$\max_{\pi} C_\pi(y) = C_0(y) = LR(y)$$

$$\min_{\pi} C_\pi(y) = C_1(y) = 1$$

$$LR(y) \leq 1 \Rightarrow LR(y) \leq C_\pi(y) \leq 1$$

$$\max_{\pi} C_\pi(y) = C_1(y) = 1$$

$$\min_{\pi} C_\pi(y) = C_0(y) = LR(y)$$

The prior-to-posterior semantic for differential privacy:

$$e^{-\epsilon} \leq C_\pi(y) \leq e^\epsilon \quad \text{for all } \pi \text{ if and only if } e^{-\epsilon} \leq LR(y) \leq e^\epsilon$$

However, what if  $X_1$  and  $X_2$  are *a priori* dependent?

Suppose our prior for  $(X_1, X_2)$  is  $\Pr(X_1 = a, X_2 = b) = \pi_{ab}$ . Let

$$C_\pi(y_1, y_2) \equiv \frac{\Pr(X_1 = 1 | Y_1 = y_1, Y_2 = y_2)}{\Pr(X_1 = 1)} = \frac{\Pr(Y_1 = y_1, Y_2 = y_2 | X_1 = 1)}{\Pr(Y_1 = y_1, Y_2 = y_2)}$$

Transferring the bound on likelihood ratio to posterior-to-prior ratio

$$C_\pi(y_1, y_2) = \frac{LR(y_1, y_2)}{LR(y_1, y_2)\pi_{1\cdot} + (1 - \pi_{1\cdot})}, \quad \pi_{1\cdot} = \Pr(X_1 = 1) = \pi_{11} + \pi_{10}$$

$$LR(y_1, y_2) = \frac{\Pr(Y_1 = y_1, Y_2 = y_2 | X_1 = 1)}{\Pr(Y_1 = y_1, Y_2 = y_2 | X_1 = 0)}.$$

However, what if  $X_1$  and  $X_2$  are *a priori* dependent?

Suppose our prior for  $(X_1, X_2)$  is  $\Pr(X_1 = a, X_2 = b) = \pi_{ab}$ . Let

$$C_\pi(y_1, y_2) \equiv \frac{\Pr(X_1 = 1 | Y_1 = y_1, Y_2 = y_2)}{\Pr(X_1 = 1)} = \frac{\Pr(Y_1 = y_1, Y_2 = y_2 | X_1 = 1)}{\Pr(Y_1 = y_1, Y_2 = y_2)}$$

Transferring the bound on likelihood ratio to posterior-to-prior ratio

$$C_\pi(y_1, y_2) = \frac{LR(y_1, y_2)}{LR(y_1, y_2)\pi_{1\cdot} + (1 - \pi_{1\cdot})}, \quad \pi_{1\cdot} = \Pr(X_1 = 1) = \pi_{11} + \pi_{10}$$

$$LR(y_1, y_2) = \frac{\Pr(Y_1 = y_1, Y_2 = y_2 | X_1 = 1)}{\Pr(Y_1 = y_1, Y_2 = y_2 | X_1 = 0)}.$$

Consider the case  $y_1 = 1, y_2 = 1$ , and recall  $e^\epsilon = p/(1 - p)$

$$LR(1, 1) = \frac{e^\epsilon \frac{\pi_{11}}{\pi_{1\cdot}} + \frac{\pi_{10}}{\pi_{1\cdot}}}{\frac{\pi_{01}}{\pi_{0\cdot}} + e^{-\epsilon} \frac{\pi_{00}}{\pi_{0\cdot}}}$$

## The dependence is a big trouble maker

This means that when  $\pi_{10} = \pi_{01} = 0$ ,  $LR(1, 1) = e^{2\epsilon} > e^\epsilon$ .

- But  $\pi_{10} = \pi_{01} = 0$  means that  $X_2 = X_1$ , hence  $X_1$  can be learned from the information for  $X_2$ . Consequently, the “individual information unit” for  $X_1$  should be the pair  $\{X_1, X_2\}$ , not merely  $X_1$ .

# The dependence is a big trouble maker

This means that when  $\pi_{10} = \pi_{01} = 0$ ,  $LR(1, 1) = e^{2\epsilon} > e^\epsilon$ .

- But  $\pi_{10} = \pi_{01} = 0$  means that  $X_2 = X_1$ , hence  $X_1$  can be learned from the information for  $X_2$ . Consequently, the “individual information unit” for  $X_1$  should be the pair  $\{X_1, X_2\}$ , not merely  $X_1$ .
- In fact as soon as  $\text{Cov}(X_1, X_2) > 0$ ,  $LR(1, 1) > e^\epsilon$ . This is because

$$LR(1, 1) > e^\epsilon \iff \Pr(X_2 = 1|X_1 = 1) > \Pr(X_2 = 1|X_1 = 0)$$

But

$$\begin{aligned}\text{Cov}(X_1, X_2) &= \Pr(X_1 = 1, X_2 = 1) - \Pr(X_1 = 1)\Pr(X_2 = 1) \\ &= [\Pr(X_2 = 1|X_1 = 1) - \Pr(X_2 = 1|X_1 = 0)]\Pr(X_1 = 0)\Pr(X_1 = 1).\end{aligned}$$

Data are *accidental* representation, not *essential* information itself

Manipulating data values without considering their interdependence is not a legitimate information operation in general

## In general, what does DP actual guarantee?

An attacker  $A$  is interested in learning about  $\mathbf{X}_A = \{x_i, i \in I_A\}$  in a database  $\mathbf{X} = \{X_i, i \in I\}$ , where  $I_A$  could contain a single individual or everyone in  $I$ . Suppose the attacker has prior knowledge about the entire  $\mathbf{X}$  in the form of  $\pi(\mathbf{X})$ .

## In general, what does DP actual guarantee?

An attacker  $A$  is interested in learning about  $\mathbf{X}_A = \{x_i, i \in I_A\}$  in a database  $\mathbf{X} = \{X_i, i \in I\}$ , where  $I_A$  could contain a single individual or everyone in  $I$ . Suppose the attacker has prior knowledge about the entire  $\mathbf{X}$  in the form of  $\pi(\mathbf{X})$ .

Let  $\pi_A(X_i)$  be the marginal prior, and  $\pi_A(X_i|\mathbf{X}_{-i})$  be the conditional prior, conditioning on  $\mathbf{X}_{-i} = \{X_j, j \neq i\}$ . Upon learning  $M = m$ ,

- Does  $\epsilon$ -DP guarantees the marginal posterior-to-prior ratio

$$e^{-\epsilon} \leq \frac{P_A(X_i = x|M = m)}{\pi_A(X_i = x)} \leq e^{\epsilon}, \quad \forall x \in \mathcal{X}_i? \quad \text{No, not in general}$$

(Kifer & Machanavajjhala, 2011a, 2012; Tschantz et al., 2020)

## In general, what does DP actual guarantee?

An attacker  $A$  is interested in learning about  $\mathbf{X}_A = \{x_i, i \in I_A\}$  in a database  $\mathbf{X} = \{X_i, i \in I\}$ , where  $I_A$  could contain a single individual or everyone in  $I$ . Suppose the attacker has prior knowledge about the entire  $\mathbf{X}$  in the form of  $\pi(\mathbf{X})$ .

Let  $\pi_A(X_i)$  be the marginal prior, and  $\pi_A(X_i|\mathbf{X}_{-i})$  be the conditional prior, conditioning on  $\mathbf{X}_{-i} = \{X_j, j \neq i\}$ . Upon learning  $M = m$ ,

- Does  $\epsilon$ -DP guarantees the marginal posterior-to-prior ratio

$$e^{-\epsilon} \leq \frac{P_A(X_i = x|M = m)}{\pi_A(X_i = x)} \leq e^{\epsilon}, \quad \forall x \in \mathcal{X}_i? \quad \text{No, not in general}$$

(Kifer & Machanavajjhala, 2011a, 2012; Tschantz et al., 2020)

- Does  $\epsilon$ -DP guarantees the conditional posterior-to-prior ratio

$$e^{-\epsilon} \leq \frac{P_A(X_i = x|M = m, \mathbf{X}_{-i})}{\pi_A(X_i = x|\mathbf{X}_{-i})} \leq e^{\epsilon}? \quad \forall x \in \mathcal{X}_i? \quad \text{Yes}$$



# In general, what does DP actual guarantee?

An attacker  $A$  is interested in learning about  $\mathbf{X}_A = \{x_i, i \in I_A\}$  in a database  $\mathbf{X} = \{X_i, i \in I\}$ , where  $I_A$  could contain a single individual or everyone in  $I$ . Suppose the attacker has prior knowledge about the entire  $\mathbf{X}$  in the form of  $\pi(\mathbf{X})$ .

Let  $\pi_A(X_i)$  be the marginal prior, and  $\pi_A(X_i|\mathbf{X}_{-i})$  be the conditional prior, conditioning on  $\mathbf{X}_{-i} = \{X_j, j \neq i\}$ . Upon learning  $M = m$ ,

- Does  $\epsilon$ -DP guarantees the marginal posterior-to-prior ratio

$$e^{-\epsilon} \leq \frac{P_A(X_i = x|M = m)}{\pi_A(X_i = x)} \leq e^{\epsilon}, \quad \forall x \in \mathcal{X}_i? \quad \text{No, not in general}$$

(Kifer & Machanavajjhala, 2011a, 2012; Tschantz et al., 2020)

- Does  $\epsilon$ -DP guarantees the conditional posterior-to-prior ratio

$$e^{-\epsilon} \leq \frac{P_A(X_i = x|M = m, \mathbf{X}_{-i})}{\pi_A(X_i = x|\mathbf{X}_{-i})} \leq e^{\epsilon}? \quad \forall x \in \mathcal{X}_i? \quad \text{Yes}$$

- Thus the guaranteed limit  $e^{\epsilon}$  is only for the **unique individual information**: variations unexplained by anyone else in the database or by knowledge on (and beyond) the database population.

## Theorem (Bailie, Gong & Meng, 2023)

A random map  $M$  delivers  $\epsilon$ -DP under Hamming distance if and only if for every prior  $\pi$  on  $\mathcal{D}$ , every sub- $\sigma$  field  $\mathcal{F}$  of the corresponding full  $\sigma$ -field  $\sigma_\pi(\mathcal{X})$ , every  $B \in \mathcal{B}(\mathbb{R}^d)$ , every  $i$ , and every  $A \in \mathcal{B}(\Theta_i)$ , where  $\Theta_i$  is the state space of  $x_i$ , we have

$$e^{-c_i \epsilon} \pi(X_i \in A \mid \mathcal{F}) \leq \Pr(X_i \in A \mid M \in B; \mathcal{F}) \leq e^{c_i \epsilon} \pi(x_i \in A \mid \mathcal{F}), \quad (1)$$

where  $\pi(x_i \mid \mathcal{F})$  is the marginal prior for  $X_i$  (conditional on  $\mathcal{F}$ ),  $\Pr$  is the marginal posterior for  $X_i$ , and  $c_i$  is the size of the minimal information chamber (MIC) for  $X_i$ .

## Theorem (Bailie, Gong & Meng, 2023)

A random map  $M$  delivers  $\epsilon$ -DP under Hamming distance if and only if for every prior  $\pi$  on  $\mathcal{D}$ , every sub- $\sigma$  field  $\mathcal{F}$  of the corresponding full  $\sigma$ -field  $\sigma_\pi(\mathcal{X})$ , every  $B \in \mathcal{B}(\mathbb{R}^d)$ , every  $i$ , and every  $A \in \mathcal{B}(\Theta_i)$ , where  $\Theta_i$  is the state space of  $x_i$ , we have

$$e^{-c_i \epsilon} \pi(X_i \in A \mid \mathcal{F}) \leq \Pr(X_i \in A \mid M \in B; \mathcal{F}) \leq e^{c_i \epsilon} \pi(x_i \in A \mid \mathcal{F}), \quad (1)$$

where  $\pi(x_i \mid \mathcal{F})$  is the marginal prior for  $X_i$  (conditional on  $\mathcal{F}$ ),  $\Pr$  is the marginal posterior for  $X_i$ , and  $c_i$  is the size of the minimal information chamber (MIC) for  $X_i$ .

- $MIC = C_{-i} \cup \{X_i\}$ :  $C_{-i} \subset \mathbf{X}_{-i}$  is the Markov boundary for  $X_i$ , that is, the smallest subset of  $\mathbf{X}_{-i}$  such that

$$\pi(X_i \mid \mathbf{X}_{-i}, \mathcal{F}) = \pi(X_i \mid C_{-i}, \mathcal{F}).$$

- MIC is the  $X_i$ 's "information family" – knowing any one of them will provide information about  $X_i$ , in addition to public knowledge coded into  $\mathcal{F}$ .

## Theorem (Bailie, Gong & Meng, 2023)

A random map  $M$  delivers  $\epsilon$ -DP under Hamming distance if and only if for every prior  $\pi$  on  $\mathcal{D}$ , every sub- $\sigma$  field  $\mathcal{F}$  of the corresponding full  $\sigma$ -field  $\sigma_\pi(\mathcal{X})$ , every  $B \in \mathcal{B}(\mathbb{R}^d)$ , every  $i$ , and every  $A \in \mathcal{B}(\Theta_i)$ , where  $\Theta_i$  is the state space of  $x_i$ , we have

$$e^{-c_i \epsilon} \pi(X_i \in A \mid \mathcal{F}) \leq \Pr(X_i \in A \mid M \in B; \mathcal{F}) \leq e^{c_i \epsilon} \pi(x_i \in A \mid \mathcal{F}), \quad (1)$$

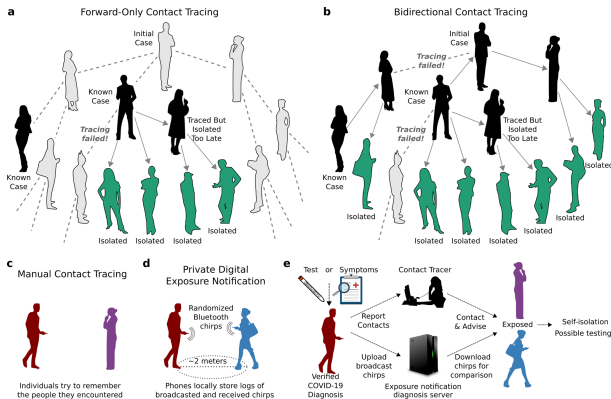
where  $\pi(x_i \mid \mathcal{F})$  is the marginal prior for  $X_i$  (conditional on  $\mathcal{F}$ ),  $\Pr$  is the marginal posterior for  $X_i$ , and  $c_i$  is the size of the minimal information chamber (MIC) for  $X_i$ .

- $MIC = C_{-i} \cup \{X_i\}$ :  $C_{-i} \subset \mathbf{X}_{-i}$  is the Markov boundary for  $X_i$ , that is, the smallest subset of  $\mathbf{X}_{-i}$  such that

$$\pi(X_i \mid \mathbf{X}_{-i}, \mathcal{F}) = \pi(X_i \mid C_{-i}, \mathcal{F}).$$

- MIC is the  $X_i$ 's "information family" – knowing any one of them will provide information about  $X_i$ , in addition to public knowledge coded into  $\mathcal{F}$ .
- Protecting *relative* risk against "strong adversary" is the easiest — **the more the adversary's prior information, the less left for protection.**

Information spreads like a virus — we need to quarantine not only the infected individual but also everyone they've come into contact with.



## Why is it called “Differential Privacy”?

Let the probability space for  $M(\mathbf{X})$  be  $\{\mathcal{M}, \mathcal{F}, P_{\mathbf{X}}\}$  (with  $P_{\mathbf{X}}(S) = \Pr(M(\mathbf{X}) \in S | \mathbf{X})$ )

# Why is it called “Differential Privacy”?

Let the probability space for  $M(\mathbf{X})$  be  $\{\mathcal{M}, \mathcal{F}, P_{\mathbf{X}}\}$  (with  $P_{\mathbf{X}}(S) = \Pr(M(\mathbf{X}) \in S | \mathbf{X})$ )

“Differential” comes from “derivative”, essential for studying *changes*

For log-likelihood  $\ell(\mathbf{X}|S) = \ln \Pr(M(\mathbf{X}) \in S | \mathbf{X})$ , pure DP is equivalent to requiring

$$\frac{\sup_{S \in \mathcal{F}} |\ell(\mathbf{X}|S) - \ell(\mathbf{X}'|S)|}{d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}')} \leq \epsilon, \quad \text{for all } \mathbf{X}, \mathbf{X}',$$

because “divergence”  $d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}') = 1$  for “neighboring” pair  $\{\mathbf{X}, \mathbf{X}'\}$ .

# Why is it called “Differential Privacy”?

Let the probability space for  $M(\mathbf{X})$  be  $\{\mathcal{M}, \mathcal{F}, P_{\mathbf{X}}\}$  (with  $P_{\mathbf{X}}(S) = \Pr(M(\mathbf{X}) \in S | \mathbf{X})$ )

“Differential” comes from “derivative”, essential for studying *changes*

For log-likelihood  $\ell(\mathbf{X}|S) = \ln \Pr(M(\mathbf{X}) \in S | \mathbf{X})$ , pure DP is equivalent to requiring

$$\frac{\sup_{S \in \mathcal{F}} |\ell(\mathbf{X}|S) - \ell(\mathbf{X}'|S)|}{d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}')} \leq \epsilon, \quad \text{for all } \mathbf{X}, \mathbf{X}',$$

because “divergence”  $d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}') = 1$  for “neighboring” pair  $\{\mathbf{X}, \mathbf{X}'\}$ .

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*

$(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{\text{Pr}}, \epsilon_{\mathcal{D}})$  if

$$d_{\text{Pr}}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (2)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .



# Five Building Blocks

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*  $(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{\mathcal{P}}, \epsilon_{\mathcal{D}})$  if

$$d_{\mathcal{P}}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (3)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .

# Five Building Blocks

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*  $(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{\mathcal{P}}, \epsilon_{\mathcal{D}})$  if

$$d_{\mathcal{P}}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (3)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .

- The **protection domain** (*what can be protected?*): dataset space  $\mathcal{X}$ ;

# Five Building Blocks

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*  $(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{\mathcal{P}}, \epsilon_{\mathcal{D}})$  if

$$d_{\mathcal{P}}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (3)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .

- The **protection domain** (*what can be protected?*): dataset space  $\mathcal{X}$ ;
- The **scope of protection** (*to where does the protection extend?*): data multiverse  $\mathcal{D}$  (*essential*), a collection of data universes  $\mathcal{D} \subset \mathcal{X}$  (*accidental*);

# Five Building Blocks

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*  $(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{Pr}, \epsilon_{\mathcal{D}})$  if

$$d_{Pr}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (3)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .

- The **protection domain** (*what can be protected?*): dataset space  $\mathcal{X}$ ;
- The **scope of protection** (*to where does the protection extend?*): data multiverse  $\mathcal{D}$  (*essential*), a collection of data universes  $\mathcal{D} \subset \mathcal{X}$  (*accidental*);
- The **protection units** (*who are the units of protection*): the input divergence  $d_{\mathcal{X}}$  on  $\mathcal{X}$ ;

# Five Building Blocks

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*  $(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{\mathcal{P}}, \epsilon_{\mathcal{D}})$  if

$$d_{\mathcal{P}}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (3)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .

- The **protection domain** (*what can be protected?*): dataset space  $\mathcal{X}$ ;
- The **scope of protection** (*to where does the protection extend?*): data multiverse  $\mathcal{D}$  (*essential*), a collection of data universes  $\mathcal{D} \subset \mathcal{X}$  (*accidental*);
- The **protection units** (*who are the units of protection*): the input divergence  $d_{\mathcal{X}}$  on  $\mathcal{X}$ ;
- The **standard of protection** (*how to measure protection*): the divergence  $d_{\mathcal{P}}$  on probabilities;

# Five Building Blocks

## A general DP Specification (Bailie et al., 2024)

A data-release mechanism  $M : \mathcal{X} \rightarrow \mathcal{M}$  satisfies a *DP specification*  $(\mathcal{X}, \mathcal{D}, d_{\mathcal{X}}, d_{\mathcal{P}}, \epsilon_{\mathcal{D}})$  if

$$d_{\mathcal{P}}[P_{\mathbf{X}}, P_{\mathbf{X}'}] \leq \epsilon_{\mathcal{D}} d_{\mathcal{X}}(\mathbf{X}, \mathbf{X}'), \quad (3)$$

for all  $\mathbf{X}, \mathbf{X}'$  in every data universe  $\mathcal{D}$  in the data multiverse  $\mathcal{D}$ .

- The **protection domain** (*what can be protected?*): dataset space  $\mathcal{X}$ ;
- The **scope of protection** (*to where does the protection extend?*): data multiverse  $\mathcal{D}$  (*essential*), a collection of data universes  $\mathcal{D} \subset \mathcal{X}$  (*accidental*);
- The **protection units** (*who are the units of protection*): the input divergence  $d_{\mathcal{X}}$  on  $\mathcal{X}$ ;
- The **standard of protection** (*how to measure protection*): the divergence  $d_{\mathcal{P}}$  on probabilities;
- The **intensity of protection** (*how much protection is afforded*): privacy loss budget  $\epsilon_{\mathcal{D}} \in \mathbb{R}^{\geq 0}$ , for each data universe  $\mathcal{D}$ .

## Examples in the Literature

4.  $d_{Pr}$ :  $(\epsilon, \delta)$ -approximate DP (Dwork, Kenthapadi, et al., 2006) Rényi DP (Mironov, 2017)  
concentrated DP (Bun & Steinke, 2016)  $f$ -divergence privacy (Barber & Duchi, 2014; Barthe & Olmedo, 2013)  $f$ -DP (including Gaussian DP) (Dong et al., 2022).

# Examples in the Literature

4.  $d_{Pr}$ :  $(\epsilon, \delta)$ -approximate DP (Dwork, Kenthapadi, et al., 2006) Rényi DP (Mironov, 2017) concentrated DP (Bun & Steinke, 2016)  $f$ -divergence privacy (Barber & Duchi, 2014; Barthe & Olmedo, 2013)  $f$ -DP (including Gaussian DP) (Dong et al., 2022).
3.  $d_{\mathcal{X}}$ :  $(\mathcal{R}, \epsilon)$ -generic DP (Kifer & Machanavajjhala, 2011b) edge vs node privacy (Hay et al., 2009; McSherry & Mahajan, 2010)  $d$ -metric DP (Chatzikokolakis et al., 2013) Blowfish privacy (He et al., 2014) element level DP (Asi et al., 2022) distributional privacy (Zhou et al., 2009) event-level vs user-level DP (Dwork et al., 2010).



# Examples in the Literature

4.  $d_{Pr}$ :  $(\epsilon, \delta)$ -approximate DP (Dwork, Kenthapadi, et al., 2006) Rényi DP (Mironov, 2017) concentrated DP (Bun & Steinke, 2016)  $f$ -divergence privacy (Barber & Duchi, 2014; Barthe & Olmedo, 2013)  $f$ -DP (including Gaussian DP) (Dong et al., 2022).
3.  $d_{\mathcal{X}}$ :  $(\mathcal{R}, \epsilon)$ -generic DP (Kifer & Machanavajjhala, 2011b) edge vs node privacy (Hay et al., 2009; McSherry & Mahajan, 2010)  $d$ -metric DP (Chatzikokolakis et al., 2013) Blowfish privacy (He et al., 2014) element level DP (Asi et al., 2022) distributional privacy (Zhou et al., 2009) event-level vs user-level DP (Dwork et al., 2010).
2.  $\mathcal{D}$ : privacy under invariants (Ashmead et al., 2019; Gong & Meng, 2020; Gao et al., 2022; Dharangutte et al., 2023) conditioned or empirical DP (J. M. Abowd et al., 2013; Charest & Hou, 2016) personalized DP (Ebadi et al., 2015; Jorgensen et al., 2015) individual DP (Soria-Comas et al., 2017; Feldman & Zrnic, 2022) bootstrap DP (O’Keefe & Charest, 2019) stratified DP (Bun et al., 2022) per-record DP (Seeman et al., 2023+) per-instance DP (Wang, 2018; Redberg & Wang, 2021).

# Examples in the Literature

4.  $d_{Pr}$ :  $(\epsilon, \delta)$ -approximate DP (Dwork, Kenthapadi, et al., 2006) Rényi DP (Mironov, 2017) concentrated DP (Bun & Steinke, 2016)  $f$ -divergence privacy (Barber & Duchi, 2014; Barthe & Olmedo, 2013)  $f$ -DP (including Gaussian DP) (Dong et al., 2022).

3.  $d_{\mathcal{X}}$ :  $(\mathcal{R}, \epsilon)$ -generic DP (Kifer & Machanavajjhala, 2011b) edge vs node privacy (Hay et al., 2009; McSherry & Mahajan, 2010)  $d$ -metric DP (Chatzikokolakis et al., 2013) Blowfish privacy (He et al., 2014) element level DP (Asi et al., 2022) distributional privacy (Zhou et al., 2009) event-level vs user-level DP (Dwork et al., 2010).

2.  $\mathcal{D}$ : privacy under invariants (Ashmead et al., 2019; Gong & Meng, 2020; Gao et al., 2022; Dharangutte et al., 2023) conditioned or empirical DP (J. M. Abowd et al., 2013; Charest & Hou, 2016) personalized DP (Ebadi et al., 2015; Jorgensen et al., 2015) individual DP (Soria-Comas et al., 2017; Feldman & Zrnic, 2022) bootstrap DP (O'Keefe & Charest, 2019) stratified DP (Bun et al., 2022) per-record DP (Seeman et al., 2023+) per-instance DP (Wang, 2018; Redberg & Wang, 2021).

1.  $\mathcal{X}$ : DP for network data (Hay et al., 2009) for geospatial data (Andrés et al., 2013) Pufferfish DP (Kifer & Machanavajjhala, 2014) noiseless privacy (Bhaskar et al., 2011) privacy under partial knowledge (Seeman et al., 2022) privacy amplification (Beimel et al., 2010; Balle et al., 2020; Bun et al., 2022).

# Examples from the US Decennial Censuses

	$d_{Pr}$	$d_{\mathcal{X}}$ (Unit)	Invariants	Privacy Loss Budget
TopDown*	$D_{nor}$	$d_{Ham}^p$ (person)	Population (state) Total housing units (block) Occupied group quarters (block) Structural zeros	PL & DHC: $\rho^2 = 15.29$ $\epsilon = 52.83$ ( $\delta = 10^{-10}$ )
SafeTab**	$D_{nor}$	$d_{Ham}^p$ (person)	None	DDHC-A: $\rho^2 = 19.776$ DDHC-B & S-DHC: <i>TBD</i> .
Swapping	MULT	$d_{Ham}^h$ (household)	Varies but greater than TDA	$\epsilon$ between 9.37-19.38

\* (J. Abowd et al., 2022)

\*\* (Tumult Labs, 2022)

- $\mathcal{X}$  is always the space of possible Census Edited Files,  $\mathcal{X}_{CEF}$ .
- $D_{nor}(P, Q) = \sup_{\alpha > 1} \frac{1}{\sqrt{\alpha}} \max \left[ \sqrt{D_{\alpha}(P||Q)}, \sqrt{D_{\alpha}(Q||P)} \right]$  is the normalised Rényi metric [zero concentrated DP] (with  $D_{\alpha}$  the Rényi divergence of order);
- $MULT(P, Q) = \sup_{S \in \mathcal{F}} \left| \ln \frac{P(S)}{Q(S)} \right|$  is the multiplicative distance (pure DP); and
- $d_{Ham}^u$  is the Hamming distance (on units  $u$ ).

# Swapping Satisfies DP, Subject to its Invariants

## Permutation Swapping

Input: a dataset  $\mathbf{x}$ .

Define strata as groups of records which match on the swap key  $\mathbf{V}_{\text{Stratify}}$ .

Within each stratum:

- 1 Select each record independently with probability  $p$  (the swap rate).
- 2 Randomly derange swapping variable  $\mathbf{V}_{\text{Swap}}$  of selected records.

Output: the *swapped* dataset  $\mathbf{w}$ .

# Swapping Satisfies DP, Subject to its Invariants

## Permutation Swapping

Input: a dataset  $\mathbf{x}$ .

Define strata as groups of records which match on the swap key  $\mathbf{V}_{\text{Stratify}}$ .

Within each stratum:

- 1 Select each record independently with probability  $p$  (the swap rate).
- 2 Randomly derange swapping variable  $\mathbf{V}_{\text{Swap}}$  of selected records.

Output: the *swapped* dataset  $\mathbf{w}$ .

*Permutation Swapping* is DP subject to its invariants, with input divergence

$d_{\mathcal{X}} = d_{\text{Ham}}^u$ , output divergence  $d_{\text{Pr}} = \text{MULT}$  and budget

$$\epsilon = \begin{cases} \ln(b+1) - \ln o & \text{if } 0 < p \leq 0.5, \\ \max \{ \ln o, \ln(b+1) - \ln o \} & \text{if } 0.5 < p < 1, \end{cases}$$

where  $o = p/(1-p)$  and  $b$  is the maximum stratum size.

# The TopDown Algorithm (TDA) (J. Abowd et al., 2022)

Two-step procedure:

- 1 Start with a Census edited file  $\mathbf{x} \in \mathcal{X}_{\text{CEF}}$ .

# The TopDown Algorithm (TDA) (J. Abowd et al., 2022)

Two-step procedure:

- 1 Start with a Census edited file  $\mathbf{x} \in \mathcal{X}_{\text{CEF}}$ .
- 2 Add Gaussian noise to cells:

$$\mathbf{T}(\mathbf{x}) = \mathbf{q}(\mathbf{x}) + \mathbf{W},$$

where  $\mathbf{W} \sim \mathcal{N}_{\mathbb{Z}}(0, \Sigma)$ , so that  $\mathbf{T}$  satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \{\mathcal{X}_{\text{CEF}}\}, d_{\text{Ham}}^p, D_{\text{nor}})$  with budget  $\rho_{\text{TDA}}$  (Canonne et al., 2022).

# The TopDown Algorithm (TDA) (J. Abowd et al., 2022)

Two-step procedure:

- 1 Start with a Census edited file  $\mathbf{x} \in \mathcal{X}_{\text{CEF}}$ .
- 2 Add Gaussian noise to cells:

$$\mathbf{T}(\mathbf{x}) = \mathbf{q}(\mathbf{x}) + \mathbf{W},$$

where  $\mathbf{W} \sim \mathcal{N}_{\mathbb{Z}}(\mathbf{0}, \mathbf{\Sigma})$ , so that  $\mathbf{T}$  satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \{\mathcal{X}_{\text{CEF}}\}, d_{\text{Ham}}^p, D_{\text{nor}})$  with budget  $\rho_{\text{TDA}}$  (Canonne et al., 2022).

- 2 “Post-process”: find dataset  $\mathbf{z}$  with  $\mathbf{q}(\mathbf{z})$  close to  $\mathbf{T}(\mathbf{x})$  such that  $\mathbf{c}_{\text{TDA}}(\mathbf{z}) = \mathbf{c}_{\text{TDA}}(\mathbf{x})$ .



# The TopDown Algorithm (TDA) (J. Abowd et al., 2022)

Two-step procedure:

- 1 Start with a Census edited file  $\mathbf{x} \in \mathcal{X}_{\text{CEF}}$ .
- 2 Add Gaussian noise to cells:

$$\mathbf{T}(\mathbf{x}) = \mathbf{q}(\mathbf{x}) + \mathbf{W},$$

where  $\mathbf{W} \sim \mathcal{N}_{\mathbb{Z}}(\mathbf{0}, \mathbf{\Sigma})$ , so that  $\mathbf{T}$  satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \{\mathcal{X}_{\text{CEF}}\}, d_{\text{Ham}}^p, D_{\text{nor}})$  with budget  $\rho_{\text{TDA}}$  (Canonne et al., 2022).

- 2 “Post-process”: find dataset  $\mathbf{z}$  with  $\mathbf{q}(\mathbf{z})$  close to  $\mathbf{T}(\mathbf{x})$  such that  $\mathbf{c}_{\text{TDA}}(\mathbf{z}) = \mathbf{c}_{\text{TDA}}(\mathbf{x})$ .

# The TopDown Algorithm (TDA) (J. Abowd et al., 2022)

Two-step procedure:

- 1 Start with a Census edited file  $\mathbf{x} \in \mathcal{X}_{\text{CEF}}$ .
- 2 Add Gaussian noise to cells:

$$\mathbf{T}(\mathbf{x}) = \mathbf{q}(\mathbf{x}) + \mathbf{W},$$

where  $\mathbf{W} \sim \mathcal{N}_{\mathbb{Z}}(\mathbf{0}, \mathbf{\Sigma})$ , so that  $\mathbf{T}$  satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \{\mathcal{X}_{\text{CEF}}\}, d_{\text{Ham}}^p, D_{\text{nor}})$  with budget  $\rho_{\text{TDA}}$  (Canonne et al., 2022).

- 2 “Post-process”: find dataset  $\mathbf{z}$  with  $\mathbf{q}(\mathbf{z})$  close to  $\mathbf{T}(\mathbf{x})$  such that  $\mathbf{c}_{\text{TDA}}(\mathbf{z}) = \mathbf{c}_{\text{TDA}}(\mathbf{x})$ .

TDA satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \mathcal{D}_{\mathbf{c}_{\text{TDA}}}, d_{\text{Ham}}^p, D_{\text{nor}})$  with budget  $\rho_{\text{TDA}}$ .

## Theorem: TDA Satisfies DP, Subject to its Invariants

Let  $\mathbf{c}_{\text{TDA}} : \mathcal{X}_{\text{CEF}} \rightarrow \mathbb{R}^l$  be the invariants of TDA and let  $\mathcal{D}_{\mathbf{c}_{\text{TDA}}}$  be the induced data multiverse:

$$\mathcal{D}_{\mathbf{c}_{\text{TDA}}} = \{\mathcal{D} \subset \mathcal{X}_{\text{CEF}} \mid \mathbf{c}_{\text{TDA}}(\mathbf{x}) = \mathbf{c}_{\text{TDA}}(\mathbf{x}') \forall \mathbf{x}, \mathbf{x}' \in \mathcal{D}\}.$$

## Theorem: TDA Satisfies DP, Subject to its Invariants

Let  $\mathbf{c}_{\text{TDA}} : \mathcal{X}_{\text{CEF}} \rightarrow \mathbb{R}^l$  be the invariants of TDA and let  $\mathcal{D}_{\mathbf{c}_{\text{TDA}}}$  be the induced data multiverse:

$$\mathcal{D}_{\mathbf{c}_{\text{TDA}}} = \{\mathcal{D} \subset \mathcal{X}_{\text{CEF}} \mid \mathbf{c}_{\text{TDA}}(\mathbf{x}) = \mathbf{c}_{\text{TDA}}(\mathbf{x}') \forall \mathbf{x}, \mathbf{x}' \in \mathcal{D}\}.$$

- TDA satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \mathcal{D}_{\mathbf{c}_{\text{TDA}}}, d_{\text{Ham}}^p, D_{\text{nor}})$  with privacy budget  $\rho_{\text{TDA}} = 2.63$  (for the PL Redistricting File) and  $\rho_{\text{TDA}} = 15.29$  (for the DHC).

# Theorem: TDA Satisfies DP, Subject to its Invariants

Let  $\mathbf{c}_{\text{TDA}} : \mathcal{X}_{\text{CEF}} \rightarrow \mathbb{R}^l$  be the invariants of TDA and let  $\mathcal{D}_{\mathbf{c}_{\text{TDA}}}$  be the induced data multiverse:

$$\mathcal{D}_{\mathbf{c}_{\text{TDA}}} = \{\mathcal{D} \subset \mathcal{X}_{\text{CEF}} \mid \mathbf{c}_{\text{TDA}}(\mathbf{x}) = \mathbf{c}_{\text{TDA}}(\mathbf{x}') \forall \mathbf{x}, \mathbf{x}' \in \mathcal{D}\}.$$

- TDA satisfies  $\text{DP}(\mathcal{X}_{\text{CEF}}, \mathcal{D}_{\mathbf{c}_{\text{TDA}}}, d_{\text{Ham}}^p, D_{\text{nor}})$  with privacy budget  $\rho_{\text{TDA}} = 2.63$  (for the PL Redistricting File) and  $\rho_{\text{TDA}} = 15.29$  (for the DHC).
- Let  $\mathbf{c}'$  be any proper subset of TDA's invariants. TDA does not satisfy  $\text{DP}(\mathcal{X}_{\text{CEF}}, \mathcal{D}_{\mathbf{c}'}, d_{\mathcal{X}}, D_{\text{nor}})$  with any finite budget  $\rho$ .

# References I

- Abowd, J., Ashmead, R., Cumings-Menon, R., Garfinkel, S., Heineck, M., Heiss, C., ... Zhuravlev, P. (2022, June). The 2020 Census disclosure avoidance system TopDown algorithm. *Harvard Data Science Review*(Special Issue 2). doi: 10.1162/99608f92.529e3cb9
- Abowd, J. M., Schneider, M. J., & Vilhuber, L. (2013). Differential privacy applications to Bayesian and linear mixed model estimation. *Journal of Privacy and Confidentiality*, 5(1).
- Acquisti, A., Taylor, C., & Wagman, L. (2016). The economics of privacy. *Journal of Economic Literature*, 54(2), 442–92.
- Andrés, M. E., Bordenabe, N. E., Chatzikokolakis, K., & Palamidessi, C. (2013, November). Geo-indistinguishability: Differential privacy for location-based systems. In *Proceedings of the 2013 ACM SIGSAC conference on Computer & communications security* (pp. 901–914). New York, NY, USA: Association for Computing Machinery. doi: 10.1145/2508859.2516735

## References II

- Ashmead, R., Kifer, D., Leclerc, P., Machanavajjhala, A., & Sexton, W. (2019). *Effective privacy after adjusting for invariants with applications to the 2020 Census* (Tech. Rep.). [https://github.com/uscensusbureau/census2020-das-e2e/blob/master/doc/20190711\\_0941\\_Effective\\_Privacy\\_after\\_Adjusting\\_for\\_Constraints\\_With\\_applications\\_to\\_the\\_2020\\_Census.pdf](https://github.com/uscensusbureau/census2020-das-e2e/blob/master/doc/20190711_0941_Effective_Privacy_after_Adjusting_for_Constraints_With_applications_to_the_2020_Census.pdf).
- Asi, H., Duchi, J. C., & Javidbakht, O. (2022). Element level differential privacy: The right granularity of privacy. In *AAAI Workshop on Privacy-Preserving Artificial Intelligence*. Association for the Advancement of Artificial Intelligence.
- Bailie, J., Gong, R., & Meng, X.-L. (2024). A refreshment stirred, not shaken (i): Five building blocks of differential privacy. *In preparation for Journal of Royal Statistical Society B*.

## References III

- Balle, B., Barthe, G., & Gaboardi, M. (2020, January). Privacy profiles and amplification by subsampling. *Journal of Privacy and Confidentiality*, 10(1). doi: 10.29012/jpc.726
- Barber, R. F., & Duchi, J. C. (2014, December). *Privacy and statistical risk: Formalisms and minimax bounds* (No. arXiv:1412.4451).  
<http://arxiv.org/abs/1412.4451>. arXiv. doi: 10.48550/arXiv.1412.4451
- Barthe, G., & Olmedo, F. (2013). Beyond differential privacy: Composition theorems and relational logic for f-divergences between probabilistic programs. In F. V. Fomin, R. Freivalds, M. Kwiatkowska, & D. Peleg (Eds.), *Automata, languages, and programming* (pp. 49–60). Berlin, Heidelberg: Springer. doi: 10.1007/978-3-642-39212-2\_8



## References IV

- Beimel, A., Kasiviswanathan, S. P., & Nissim, K. (2010, February). Bounds on the sample complexity for private learning and private data release. In D. Micciancio (Ed.), *Proceedings of the 7th theory of cryptography conference, TCC 2010, Zurich, Switzerland* (pp. 437–454). Berlin, Heidelberg: Springer. doi: 10.1007/978-3-642-11799-2\_26
- Bhaskar, R., Bhowmick, A., Goyal, V., Laxman, S., & Thakurta, A. (2011). Noiseless database privacy. In D. H. Lee & X. Wang (Eds.), *Advances in cryptology – ASIACRYPT 2011* (pp. 215–232). Berlin, Heidelberg: Springer. doi: 10.1007/978-3-642-25385-0\_12
- Bun, M., Drechsler, J., Gaboardi, M., McMillan, A., & Sarathy, J. (2022, June). Controlling privacy loss in sampling schemes: An analysis of stratified and cluster sampling. In *Foundations of Responsible Computing (FORC 2022)* (p. 24).

# References V

- Bun, M., & Steinke, T. (2016). Concentrated differential privacy: Simplifications, extensions, and lower bounds. In M. Hirt & A. Smith (Eds.), *Theory of cryptography* (pp. 635–658). Berlin, Heidelberg: Springer. doi: 10.1007/978-3-662-53641-4\_24
- Canonne, C., Kamath, G., & Steinke, T. (2022, July). The discrete Gaussian for differential privacy. *Journal of Privacy and Confidentiality*, 12(1). doi: 10.29012/jpc.784
- Charest, A.-S., & Hou, Y. (2016). On the meaning and limits of empirical differential privacy. *Journal of Privacy and Confidentiality*, 7(3), 53–66.
- Chatzikokolakis, K., Andrés, M. E., Bordenabe, N. E., & Palamidessi, C. (2013). Broadening the Scope of Differential Privacy Using Metrics. In E. De Cristofaro & M. Wright (Eds.), *Privacy Enhancing Technologies* (pp. 82–102). Berlin, Heidelberg: Springer. doi: 10.1007/978-3-642-39077-7\_5

## References VI

- Dharangutte, P., Gao, J., Gong, R., & Yu, F.-Y. (2023). Integer subspace differential privacy. In *Proceedings of the aaai conference on artificial intelligence (aaai-23)*.
- Dong, J., Roth, A., & Su, W. J. (2022). Gaussian differential privacy. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, 84(1), 3–37. doi: 10.1111/rssb.12454
- Dwork, C., Kenthapadi, K., McSherry, F., Mironov, I., & Naor, M. (2006). Our data, ourselves: Privacy via distributed noise generation. In S. Vaudenay (Ed.), *Advances in cryptology - EUROCRYPT 2006* (pp. 486–503). Berlin, Heidelberg: Springer. doi: 10.1007/11761679\_29
- Dwork, C., McSherry, F., Nissim, K., & Smith, A. (2006). Calibrating noise to sensitivity in private data analysis. In *Theory of cryptography conference* (pp. 265–284).

## References VII

- Dwork, C., McSherry, F., Nissim, K., & Smith, A. (2016). Calibrating noise to sensitivity in private data analysis. *Journal of Privacy and Confidentiality*, 7(3), 17–51.
- Dwork, C., Naor, M., Pitassi, T., & Rothblum, G. N. (2010, June). Differential privacy under continual observation. In *Proceedings of the forty-second ACM symposium on Theory of computing* (pp. 715–724). New York, NY, USA: Association for Computing Machinery.  
(<https://dl.acm.org/doi/10.1145/1806689.1806787>) doi: 10.1145/1806689.1806787
- Ebadi, H., Sands, D., & Schneider, G. (2015, January). Differential Privacy: Now it's Getting Personal. *ACM SIGPLAN Notices*, 50(1), 69–81. doi: 10.1145/2775051.2677005

## References VIII

- Feldman, V., & Zrnic, T. (2022, January). *Individual privacy accounting via a Rényi filter* (No. arXiv:2008.11193). <http://arxiv.org/abs/2008.11193>. arXiv.
- Gao, J., Gong, R., & Yu, F.-Y. (2022, June). Subspace differential privacy. In *Proceedings of the aaai conference on artificial intelligence* (Vol. 36, pp. 3986–3995). doi: 10.1609/aaai.v36i4.20315
- Gong, R., & Meng, X.-L. (2020). Congenial differential privacy under mandated disclosure. In *Proceedings of the 2020 acm-ims on foundations of data science conference* (pp. 59–70).
- Hay, M., Li, C., Miklau, G., & Jensen, D. (2009, December). Accurate estimation of the degree distribution of private networks. In *2009 Ninth IEEE International Conference on Data Mining* (pp. 169–178). doi: 10.1109/ICDM.2009.11

## References IX

- He, X., Machanavajjhala, A., & Ding, B. (2014). Blowfish privacy: Tuning privacy-utility trade-offs using policies. In *Proceedings of the 2014 acm sigmod international conference on management of data* (pp. 1447–1458).
- Jorgensen, Z., Yu, T., & Cormode, G. (2015, April). Conservative or liberal? Personalized differential privacy. In *2015 IEEE 31st International Conference on Data Engineering* (pp. 1023–1034).  
(<https://ieeexplore.ieee.org/document/7113353>) doi: 10.1109/ICDE.2015.7113353
- Kifer, D., & Machanavajjhala, A. (2011a). No free lunch in data privacy. In *Proceedings of the 2011 acm sigmod international conference on management of data* (pp. 193–204).
- Kifer, D., & Machanavajjhala, A. (2011b). No free lunch in data privacy. In *Proceedings of the 2011 international conference on Management of data - SIGMOD '11* (pp. 193–204). Athens, Greece: ACM Press. doi: 10.1145/1989323.1989345

## References X

- Kifer, D., & Machanavajjhala, A. (2012). A rigorous and customizable framework for privacy. In *Proceedings of the 31st acm sigmod-sigact-sigai symposium on principles of database systems* (pp. 77–88).
- Kifer, D., & Machanavajjhala, A. (2014). Pufferfish: A framework for mathematical privacy definitions. *ACM Transactions on Database Systems (TODS)*, 39(1), 1–36.
- McSherry, F., & Mahajan, R. (2010, August). Differentially-private network trace analysis. In *Proceedings of the ACM SIGCOMM 2010 conference* (pp. 123–134). New York, NY, USA: Association for Computing Machinery. doi: 10.1145/1851182.1851199
- Mironov, I. (2017, August). Rényi differential privacy. *2017 IEEE 30th Computer Security Foundations Symposium (CSF)*, 263–275. doi: 10.1109/CSF.2017.11
- O’Keefe, C. M., & Charest, A.-S. (2019). Bootstrap differential privacy. *Transactions on Data Privacy*, 12, 1–28.

## References XI

- Raab, C. (2019). Political science and privacy. *The handbook of privacy studies: An interdisciplinary introduction*, 257.
- Redberg, R., & Wang, Y.-X. (2021). Privately publishable per-instance privacy. In *Advances in Neural Information Processing Systems* (Vol. 34, pp. 17335–17346). Curran Associates, Inc.
- Seeman, J., Reimherr, M., & Slavkovic, A. (2022, May). *Formal privacy for partially private data* (No. arXiv:2204.01102).  
<http://arxiv.org/abs/2204.01102>. arXiv.
- Seeman, J., Sexton, W., Pujol, D., & Machanavajjhala, A. (2023+). Per-record differential privacy: Modeling dependence between individual privacy loss and confidential records.
- Solove, D. J. (2008). *Understanding Privacy*. Cambridge, MA: Harvard University Press.



## References XII

- Soria-Comas, J., Domingo-Ferrer, J., Sánchez, D., & Megías, D. (2017, June). Individual differential privacy: A utility-preserving formulation of differential privacy guarantees. *IEEE Transactions on Information Forensics and Security*, 12(6), 1418–1429. doi: 10.1109/TIFS.2017.2663337
- Tschantz, M. C., Sen, S., & Datta, A. (2020). SoK: Differential privacy as a causal property. In *2020 IEEE Symposium on Security and Privacy (SP)* (pp. 354–371).
- Tumult Labs. (2022, March). *SafeTab: DP algorithms for 2020 Census Detailed DHC Race & Ethnicity* (Tech. Rep.).  
<https://www2.census.gov/about/partners/cac/sac/meetings/2022-03/dhc-attachment-1-safetab-dp-algorithms.pdf>.
- Wang, Y.-X. (2018, November). *Per-instance Differential Privacy* (No. arXiv:1707.07708). <http://arxiv.org/abs/1707.07708>. arXiv.
- Warner, S. L. (1965). Randomized response: A survey technique for eliminating evasive answer bias. *Journal of the American Statistical Association*, 60(309), 63–69.

## References XIII

- Warren, S., & Brandeis, L. (1890). The right to privacy. *Harvard Law Review*, 4(5), 193–220.
- Zhou, S., Ligett, K., & Wasserman, L. (2009, June). Differential privacy with compression. In *Proceedings of the 2009 IEEE international conference on Symposium on Information Theory - Volume 4* (pp. 2718–2722). Coex, Seoul, Korea: IEEE Press.