

An Introduction to Separation Logic

(2/2)

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+ Overview

First part (Last time) – Introduction

- Motivation
- In the beginning...
- The Logic
- Some examples

Second part (Today) – Harder stuff

- Modularity
- Concurrency
- ~~Decidability~~

Modularity

Frame rule allows modular proofs!

- Frame rule provides modularity in proofs
- Specifications are open to extension of new state.

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Two works in separation logic on adding modular procedure/function rules

- Static Modularity: Hypothetical Frame Rule [O'Hearn, Reynold and Yang, POPL 2004]
- Dynamic Modularity: Abstract Predicates [Parkinson and Bierman, POPL 2005]

+ Background: Procedures

We will use judgements of the form:

$$\Gamma \vdash \{P\}C\{Q\}$$

where

$$\Gamma ::= \{P\}\kappa\{Q\}, \Gamma \mid \epsilon$$


Procedure call

$$\Gamma, \{P\}\kappa\{Q\} \vdash \{P\}\kappa\{Q\}$$

Procedure definition

$$\frac{\Gamma, \{P_1\}\kappa_1\{Q_1\} \vdash \{P\}C\{Q\} \quad \Gamma \vdash \{P_1\}C_1\{Q_1\}}{\Gamma \vdash \{P\}let \ \kappa_1 = C_1 \ in \ C \ end\{Q\}}$$

Will sometimes have parameters, or modifies clauses:

$$\Gamma ::= \{P\}\kappa(x)\{Q\}[X], \Gamma \mid \epsilon$$


Procedures with a hidden data-structure, e.g. Memory Manager with a free list.

Procedures with client specifications:

- $\{empty\}alloc\{x \mapsto _, _ \}[x]$
- $\{x \mapsto _, _ \}dealloc\{empty\}[]$

Expect to implement it using specifications involving free list:

- $\{list(f)\}alloc\{list(f) * x \mapsto _, _ \}[x, f]$
- $\{x \mapsto _, _ * list(f)\}dealloc\{list(f)\}[f]$

Key Idea: verify procedures with additional state that client cannot use or depend on.

+ Modular procedure proof rule

We want a rule of the following form

$$\frac{\Gamma, \{P_1\}\kappa_1\{Q_1\}[X_1], \dots \vdash \{P\}C\{Q\} \quad \Gamma \vdash \{P_1 * R\}C_1\{Q_1 * R\} \quad \dots}{\Gamma \vdash \{P * R\} \text{ let } \kappa_1 = C_1, \dots \text{ in } C\{Q * R\}}$$

where

- C does not modify free variables in R except using procedures $\kappa_1, \dots, \kappa_n$.
- C_i only modifies X_i and Y
- Y is disjoint from P , Q and C .

+ Simple memory manager

Returning to the motivating example:

$$\frac{\begin{array}{l} \Gamma, \{emp\} malloc \{x \mapsto _, _ \}[x], \dots \vdash \{P\} C \{Q\} \\ \Gamma \vdash \{emp * list(f)\} C_1 \{(x \mapsto _, _) * list(f)\} \\ \Gamma \vdash \{(x \mapsto _, _) * list(f)\} C_2 \{emp * list(f)\} \end{array}}{\Gamma \vdash \{P * list(f)\} \text{ let } malloc = C_1, free = C_2 \text{ in } C \{Q * list(f)\}}$$

+ Dynamic modularity

So far:

- “Ownership transfer”
- Static modularity: single instance of hidden data structure

Cannot instantiate several memory managers, e.g. connection pooling.

$$\begin{aligned} &\{empty\} \text{ consPool } (db) \{cpool(ret, db)\} \\ &\{cpool(x, db)\} \text{ getConn } (x) \{cpool(x, db) * conn(ret, db)\} \\ &\{cpool(x, db) * conn(y, db)\} \text{ freeConn } (x, y) \{cpool(x, db)\} \end{aligned}$$

+ Abstract Predicates

Need to scope predicate definitions to support ADTs

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1. Define judgements

$$\Lambda; \Gamma \vdash \{P\}C\{Q\}$$

where Λ is an abstract predicate environment.

e.g.

$$\Lambda := (\alpha_1(\overline{x_1}) \stackrel{\text{def}}{=} P_1), \dots, (\alpha_n(\overline{x_n}) \stackrel{\text{def}}{=} P_n)$$

A mapping from predicate name, α , to formula, P .

Need to scope predicate definitions to support ADTs

1. Define judgements

$$\Lambda; \Gamma \vdash \{P\}C\{Q\}$$

2. The predicate definitions are used with the rule of consequence

$$\frac{\Lambda \models P \Rightarrow P' \quad \Lambda; \Gamma \vdash \{P'\}C\{Q'\} \quad \Lambda \models Q' \Rightarrow Q}{\Lambda; \Gamma \vdash \{P\}C\{Q\}}$$

with two axioms: **open** and **close**

$$(\alpha(\overline{x}) \stackrel{\text{def}}{=} P), \Lambda \models \alpha(\overline{E}) \Rightarrow P[\overline{E}/\overline{x}]$$

$$(\alpha(\overline{x}) \stackrel{\text{def}}{=} P), \Lambda \models P[\overline{E}/\overline{x}] \Rightarrow \alpha(\overline{E})$$

Intuitively, **open** and **close** can be seen as pack and unpack for abstract data types.

3. Provide rule to allow predicates to be introduced and scoped

$$\frac{\Lambda'; \Gamma, \{P_1\}k_1(\overline{x_1})\{Q_1\}, \dots \vdash \{P\}C\{Q\} \quad \Lambda, \Lambda'; \Gamma \vdash \{P_1\}C_1\{Q_1\} \quad \dots}{\Lambda'; \Gamma \vdash \{P\}\text{let } k_1(\overline{x_1}) = C_1, \dots \text{ in } C\{Q\}}$$

C is verified without knowing the definitions in Λ hence it can not modify things defined in it except through $\{k_1, \dots\}$.

+ Example: Connection Pool

We define two abstract predicates for the connection pool module: *cpool* and *clist*.

$$cpool(x, db) \stackrel{\text{def}}{=} \exists i. x \mapsto i, db * clist(i, db)$$

$$clist(x, db) \stackrel{\text{def}}{=} x \doteq null \vee (\exists i. j. x \mapsto i, j * conn(i, db) * clist(j, db))$$

where $E \doteq E'$ is a shorthand for $E = E' \wedge empty$.

+ Connection pool

```
let
  consPool db :=
    (newvar p; p=cons(null,db); return p)

  getConn x := (newvar n,c,l,p; l=[x];
    if (l == null) then
      p=[x+1]; c=consConn(p)
    else (c=[l]; n=[l+1]; dispose(l);
      dispose(l+1); [x]=n);
    return c)

  freeConn x y :=
    (newvar t,n; t=[x]; n=cons(y,t); [x]=n)
in
  C
```


+ Constructor verification

Let us verify the constructor

$\{empty\}$
 $\{empty\}$
 $p = cons(null, db); return p;$
 $\{ret \mapsto null, db\}$
 $\{Pool(ret, db)\}$

Here we must prove

$$\Lambda \models (ret \mapsto null, db) \Rightarrow Pool(this, db)$$

From the definition of *ConnList* and *Pool* we know

$$\Lambda \models empty \Rightarrow ConnList(null, db)$$

$$\Lambda \models (ret \mapsto null, db) * ConnList(null, db) \Rightarrow Pool(this, db)$$

+ Client Example

$\{empty\}$

$x = consPool(db);$

$y = getConn(x);$

$UseConn(y);$

$freeConn(x, y);$

$UseConn(y)$

$\{true\}$

+ Client Example

$\{empty\}$

$x = consPool(db);$

$\{Pool(x, db)\}$

$y = getConn(x);$

$UseConn(y);$

$freeConn(x, y);$

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$\{Pool(x, db)\}$

$UseConn(y)$

$\{true\}$

X

Now let us consider specifying C-style **malloc** and **free**

$$\{empty\} \mathbf{malloc}(n) \{ (ret \mapsto _) * \dots * (ret + n - 1 \mapsto _) \}$$
$$\{ (x \mapsto _) * \dots * (x + n - 1 \mapsto _) \} \mathbf{free}(x) \{empty\}$$

but what is n in **free**'s specification? We don't want to write **free(x,n)** as that isn't how the code is written.

Now let us consider specifying C-style **malloc** and **free**

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but what is n in **free**'s specification? We don't want to write **free(x,n)** as that isn't how the code is written.

Write specifications using APs:

$$\{empty\} \mathbf{malloc}(n) \{ Block(ret, n) * ret \mapsto _ * \dots * ret + n - 1 \mapsto _ \}$$

$$\{ Block(x, n) * x \mapsto _ * \dots * x + n - 1 \mapsto _ \} \mathbf{free}(x) \{empty\}$$

Here *Block* is not known to the client and can be defined as

$$Block(x, n) \stackrel{\text{def}}{=} x - 1 \mapsto n$$

Concurrency

+ Separation Logic: concurrency

- Read sharing

$$E \mapsto_z E' * E \mapsto_{z'} E' \Leftrightarrow E \mapsto_{z+z'} E'$$

- Parallel rule

$$\frac{\{P_1\}C_1\{Q_1\} \quad \{P_2\}C_2\{Q_2\}}{\{P_1 * P_2\}C_1 || C_2\{Q_1 * Q_2\}}$$

- Resource rule

$$\frac{\{P\}C\{Q\}}{\{P * I_r\} \text{resource } r \text{ in } C\{Q * I_r\}}$$

- CCR rule

$$\frac{\{P * I_r \wedge B\}C\{Q * I_r\}}{\{P\} \text{with } r \text{ when } B \text{ in } C\{Q\}}$$

Some side-conditions but we can ignore them in this talk

+ Example: simple lock (1/3)

$\{emp\}$

lock() {

 local status = false;

 while (!status)

 status = CAS(LOCK, 0, 1);

}

$\{P\}$

$\{P\}$

unlock() {

 LOCK=0;

}

$\{emp\}$

+ Example: simple lock (1/3)

$\{emp\}$

lock() {

 local status = false;

 while (!status)

 with r do{

 status = CAS(LOCK,0,1);

 }

 }

$\{P\}$

$\{P\}$

unlock() {

 with r do{ LOCK=0; }

}

$\{emp\}$

- $I_r \stackrel{def}{=} (\text{LOCK} = 0 \wedge P) \vee (\text{LOCK} = 1 \wedge emp)$
- $P * P \Rightarrow false$

+ Example: simple lock (2/3)

$$\frac{\{I_r\} \text{status} = \text{CAS}(\text{LOCK}, 0, 1); \{I_r * (\text{status} \dot{\Rightarrow} P)\}}{\{emp\} \text{with } r \text{ do } \{ \text{status} = \text{CAS}(\text{LOCK}, 0, 1); \} \{(\text{status} \dot{\Rightarrow} P)\}}$$

$$\frac{\{(\text{LOCK} = 1 \wedge emp) * P\} \text{LOCK} = 0; \{(\text{LOCK} = 0 \wedge P) * emp\}}{\frac{\{I_r * P\} \text{LOCK} = 0; \{I_r\}}{\{P\} \text{with } r \text{ do } \{\text{LOCK} = 0; \} \{emp\}}}$$

- $I_r \stackrel{def}{=} (\text{LOCK} = 0 \wedge P) \vee (\text{LOCK} = 1 \wedge emp)$
- Proof requires $P * P \Rightarrow false$
- $I_r * P \Rightarrow \text{LOCK} = 1 \wedge P$

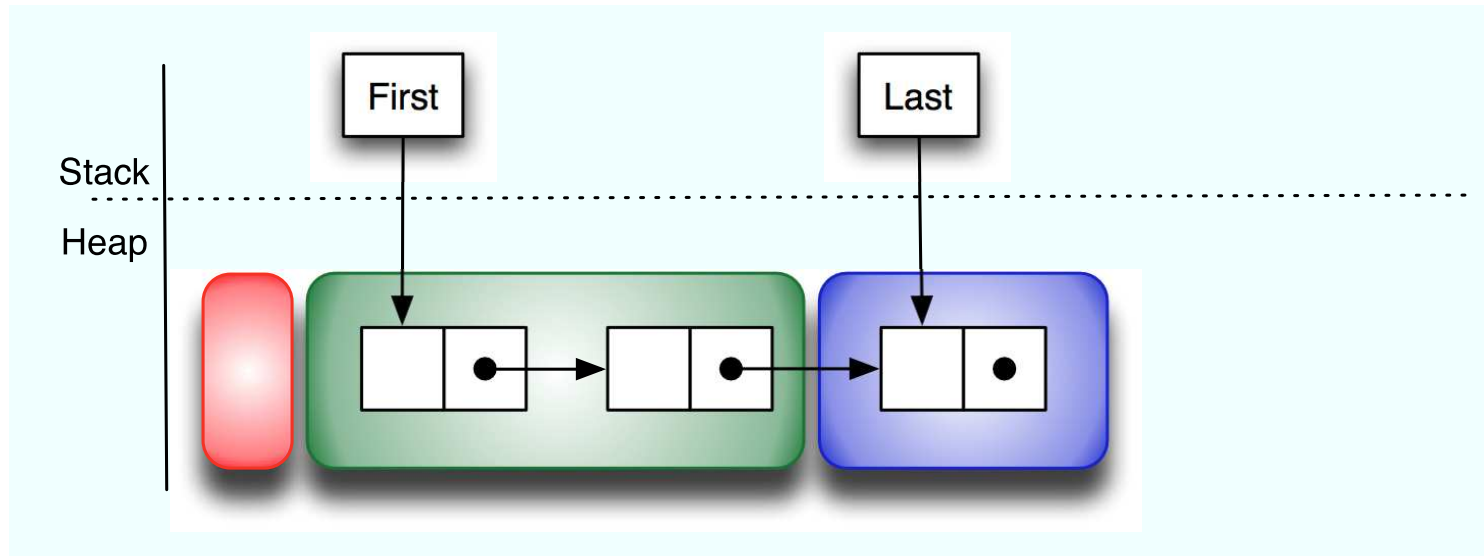
+ Example: simple lock (3/3)

```
{emp}  
lock ();  
{10 ↦ _}  
t = [10] + 1;  
{10 ↦ t - 1}  
[10] = t;  
{10 ↦ t}  
unlock ();  
{emp}
```

where $P = 10 \mapsto _$

Note: we have not had to worry at all about interference.

+ Example: Queue



semaphore number= 0;

P (number);

t = first

first = [first+1]

dispose(t);

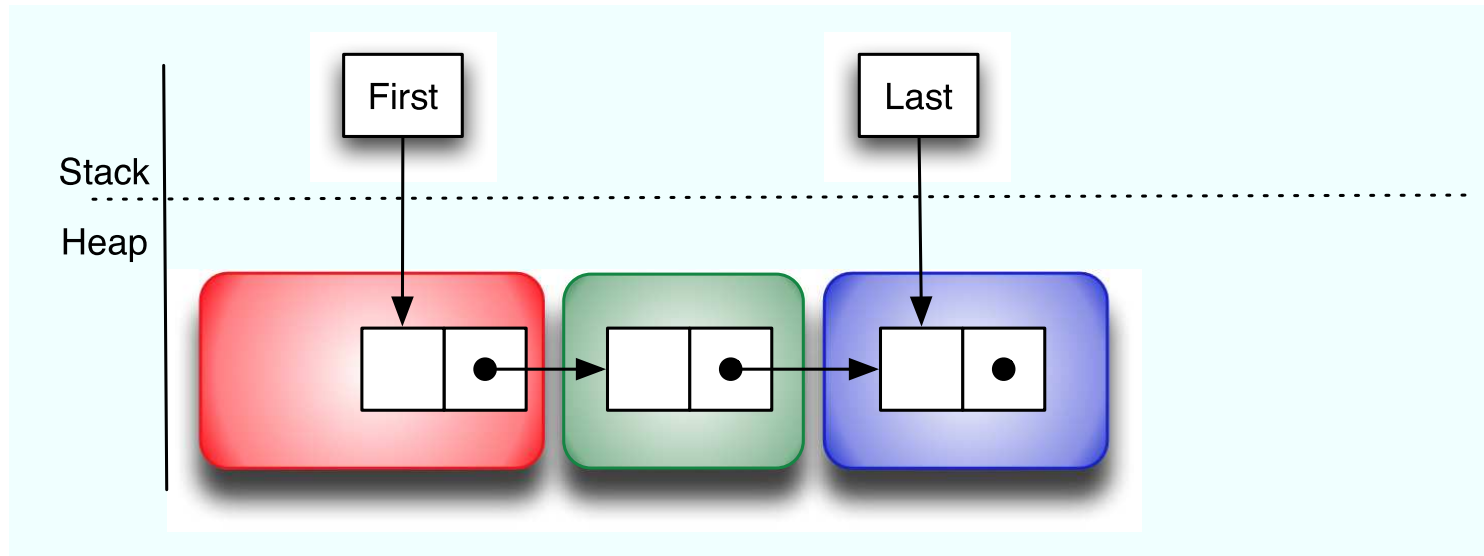
x = cons(*,*)

[last+1] = x;

last = [last+1]

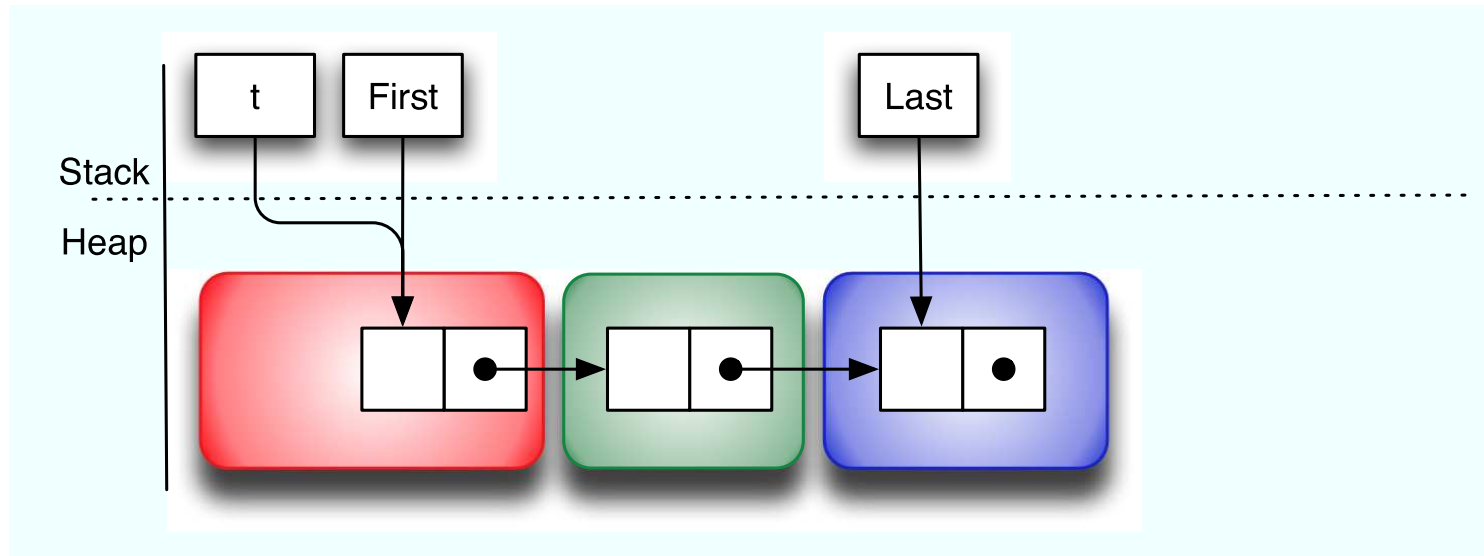
V(number);

+ Example: Queue



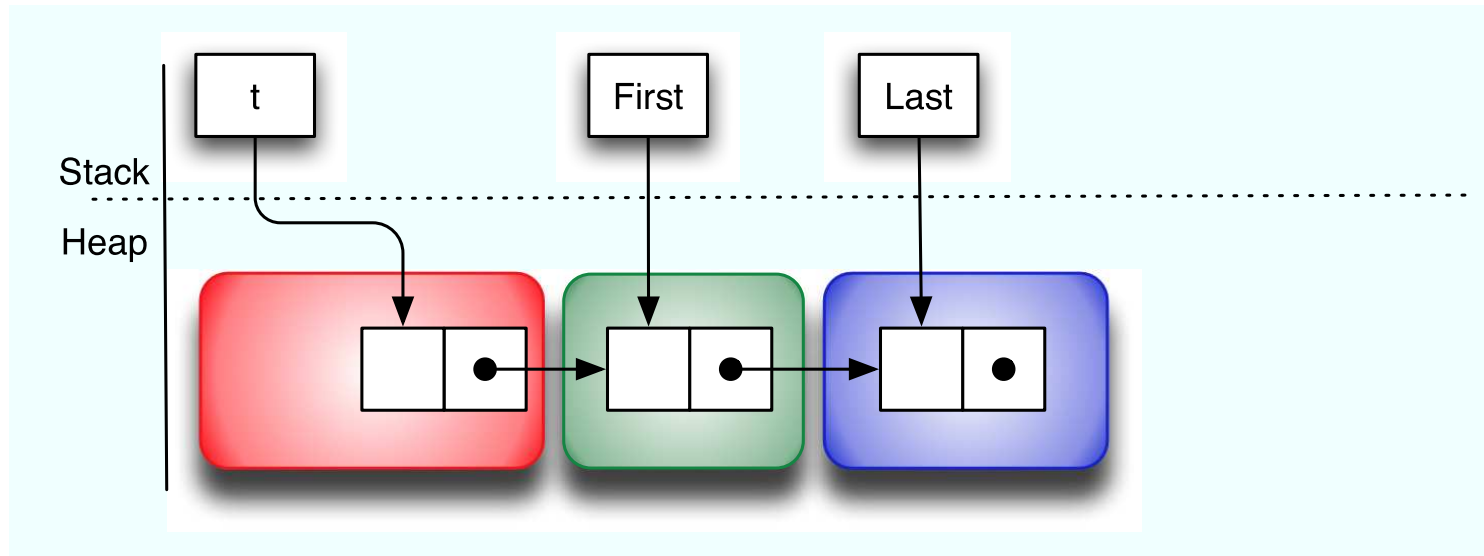
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semaphore number= 0;  
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t = first  
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+ Example: Queue



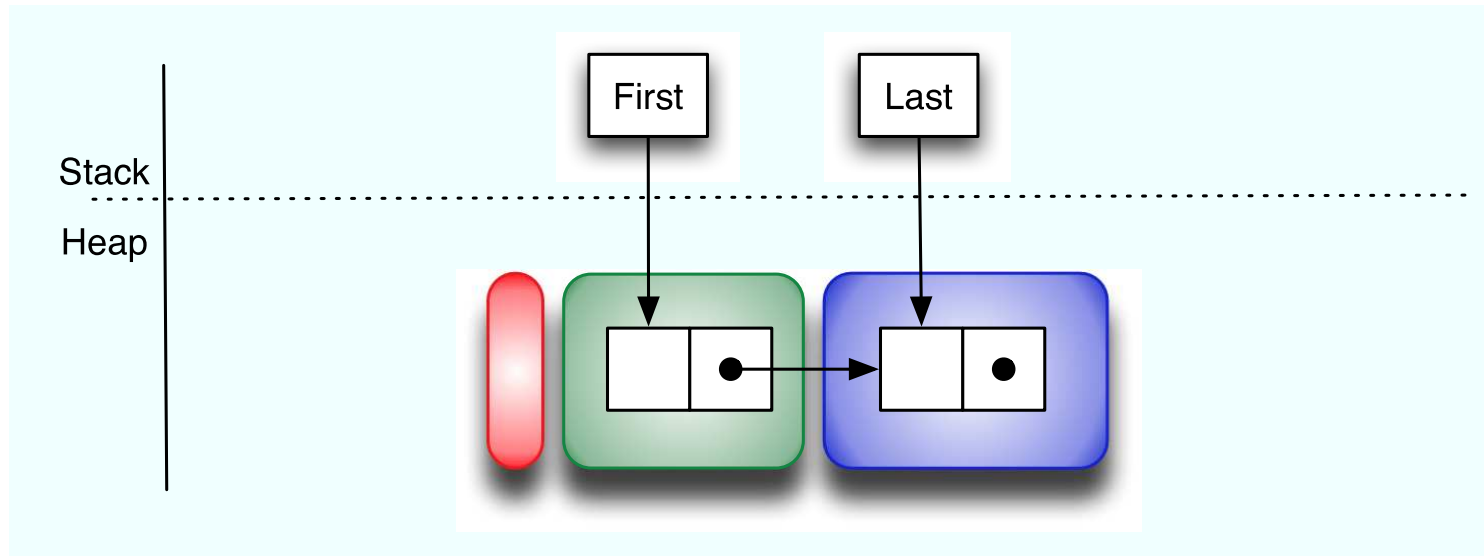
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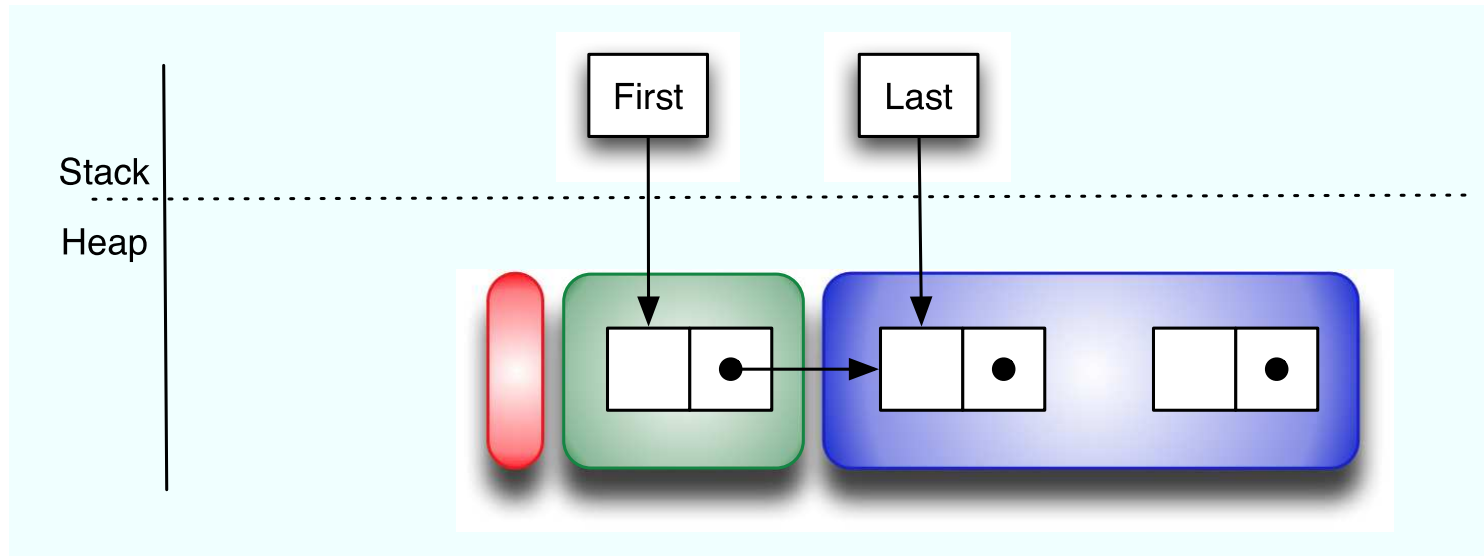
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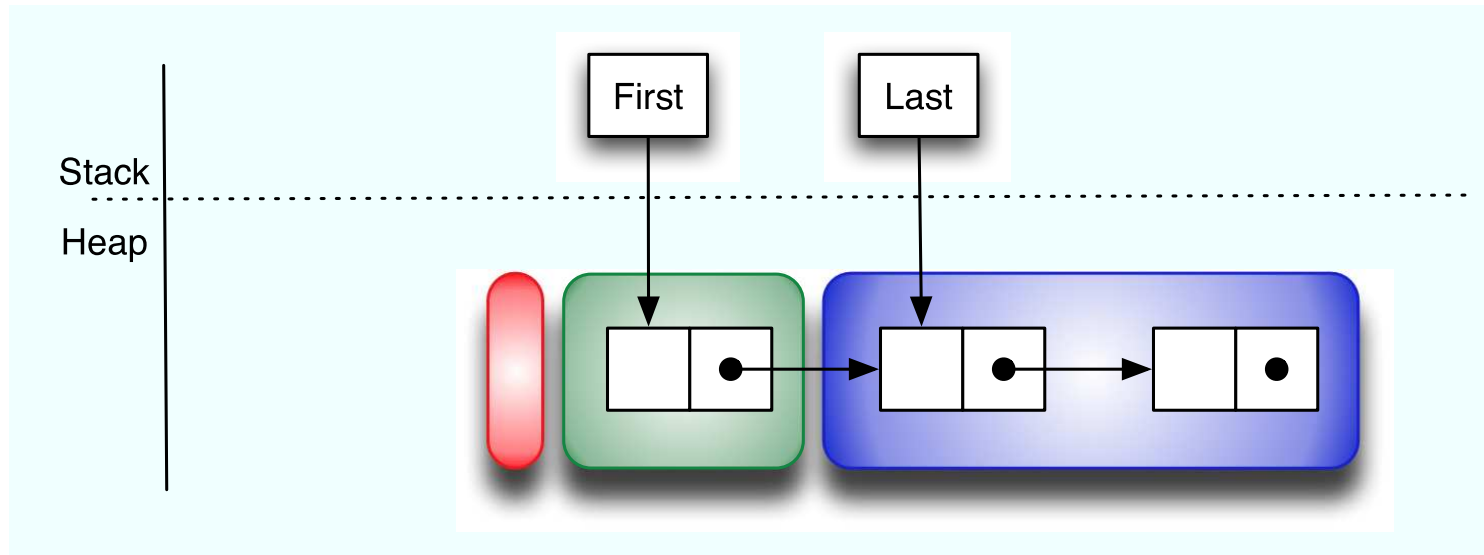
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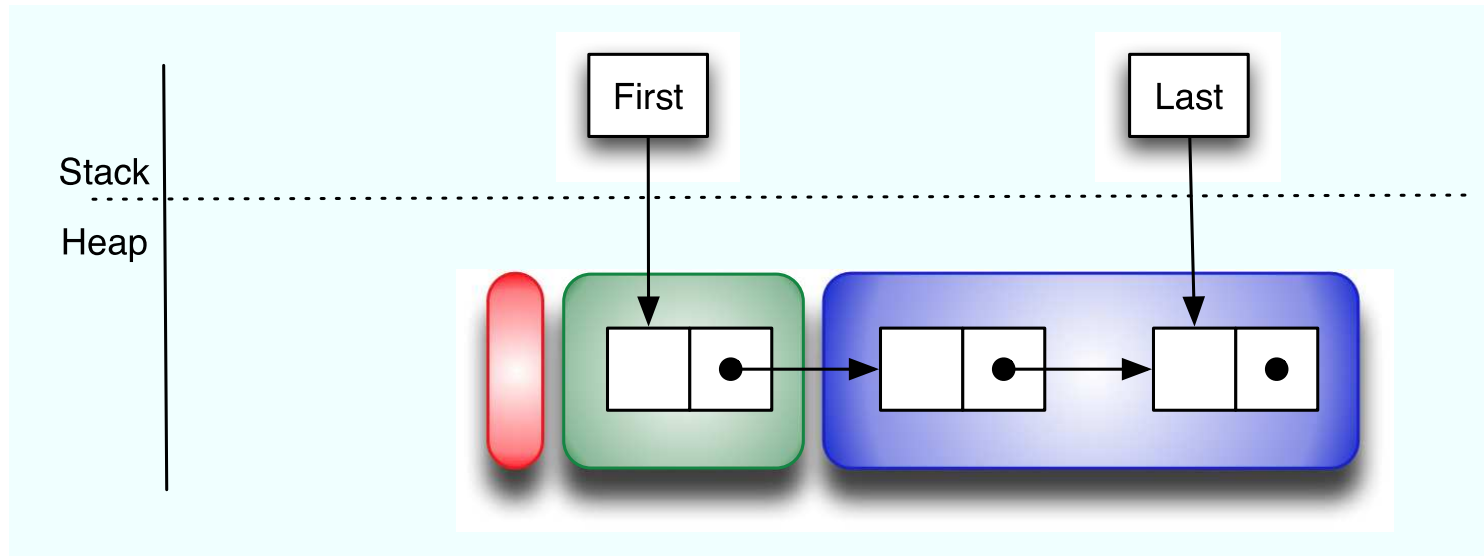
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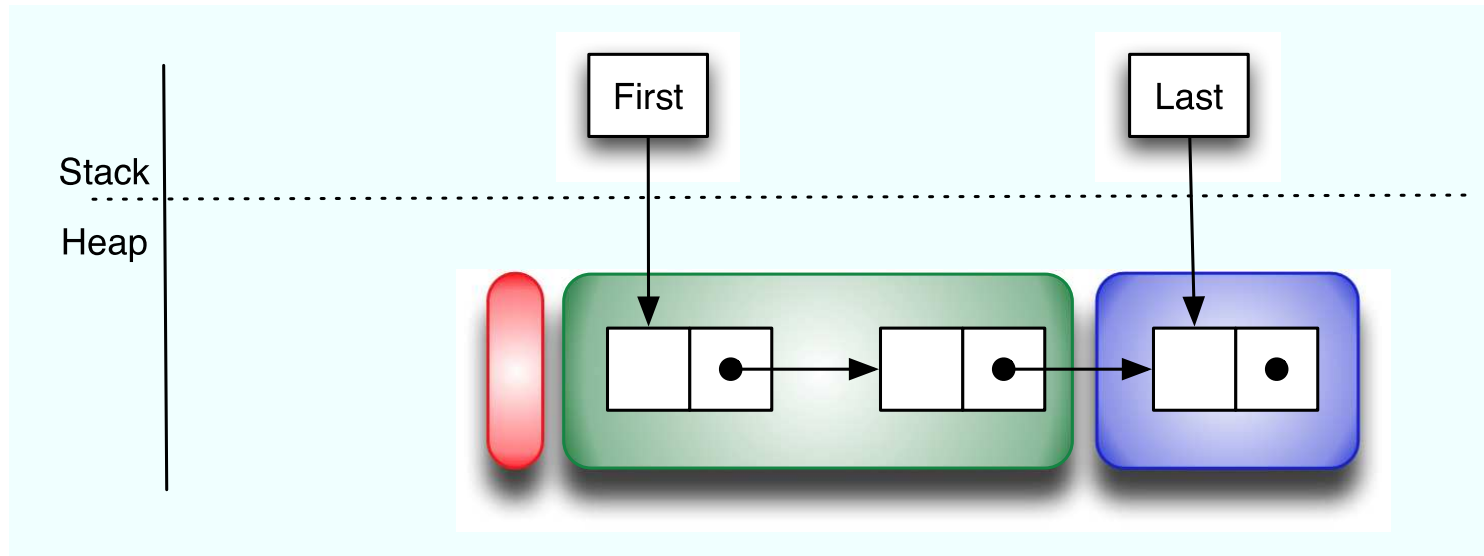
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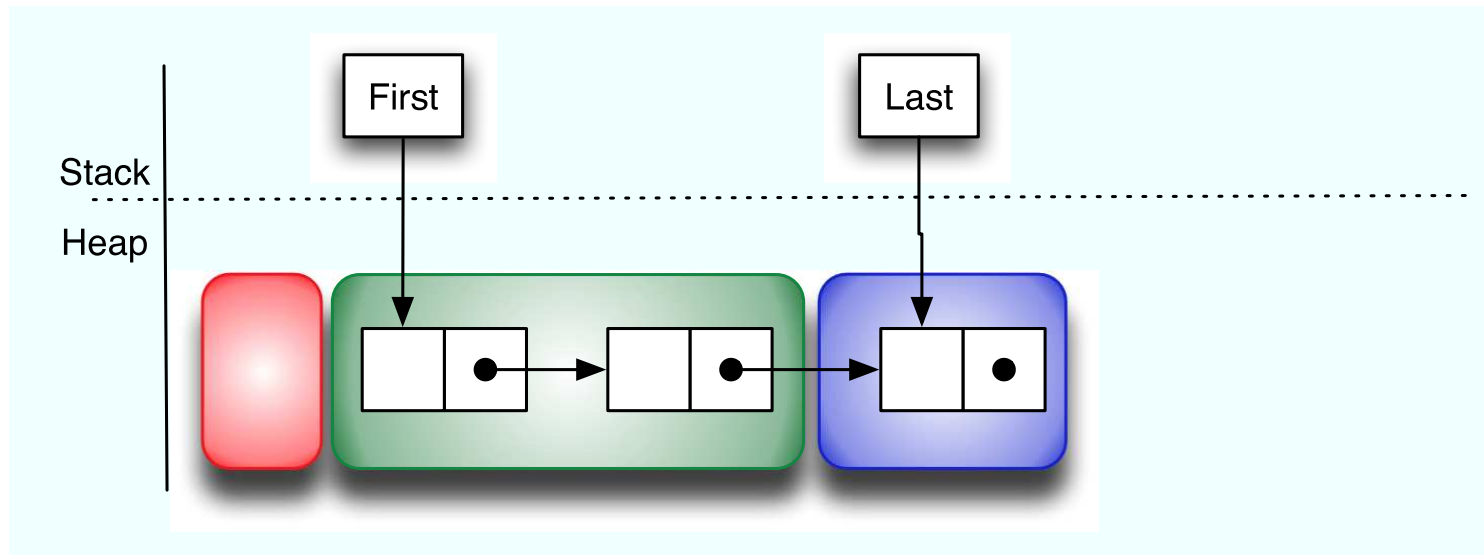

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first = [first+1] |  
dispose(t );     |  
                  |  
x = cons(*,*)     |  
[last+1] = x;      |  
last = [last+1]   |  
V(number);        |
```

+ Auxiliary variables

What is the green box?

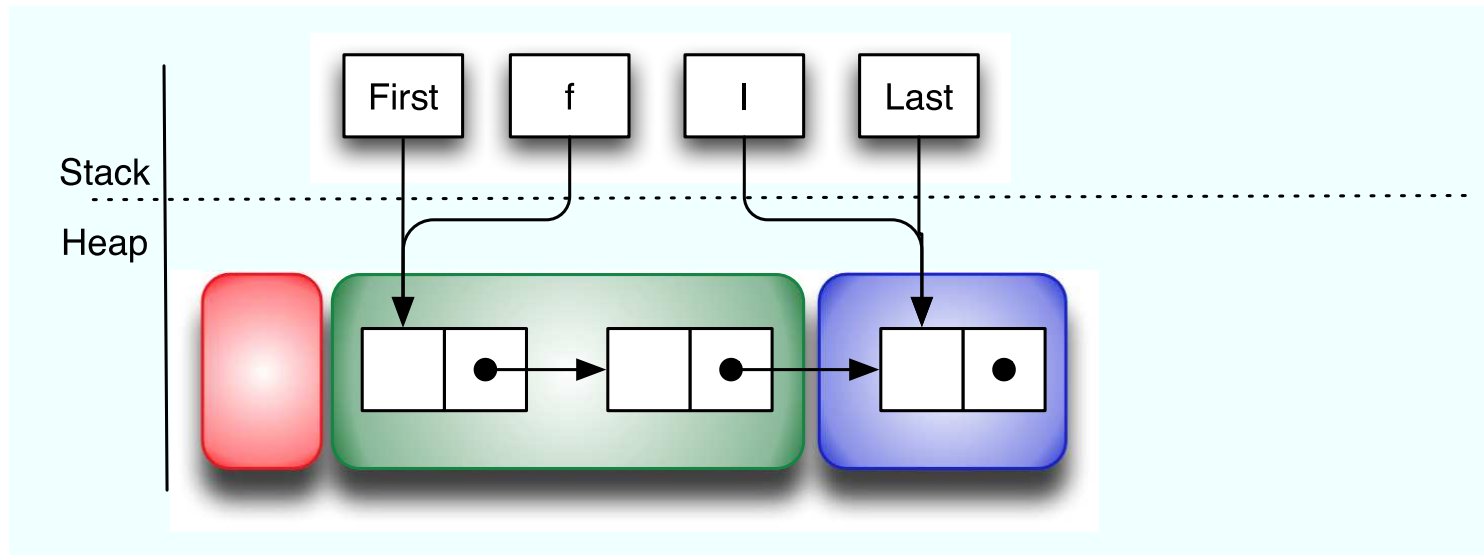


$P(n)$ = with n when $n > 0$ do $f = [first+1]$; $n--$

$V(n)$ = with n when do $l = last$; $n++$

+ Auxiliary variables

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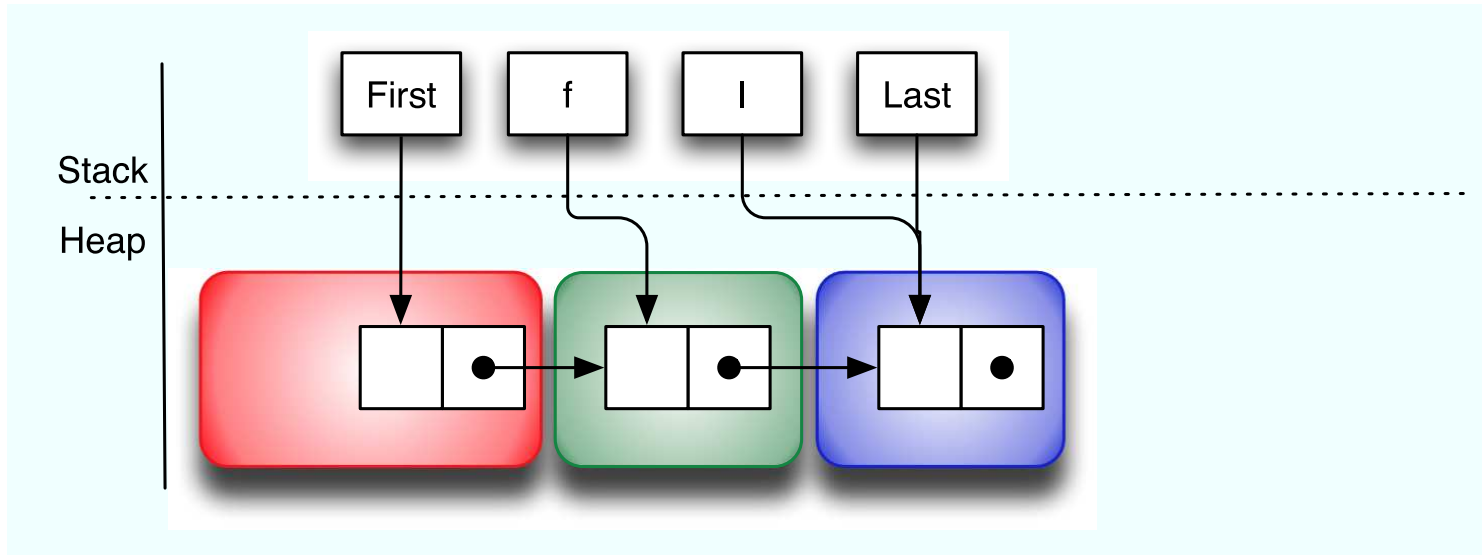


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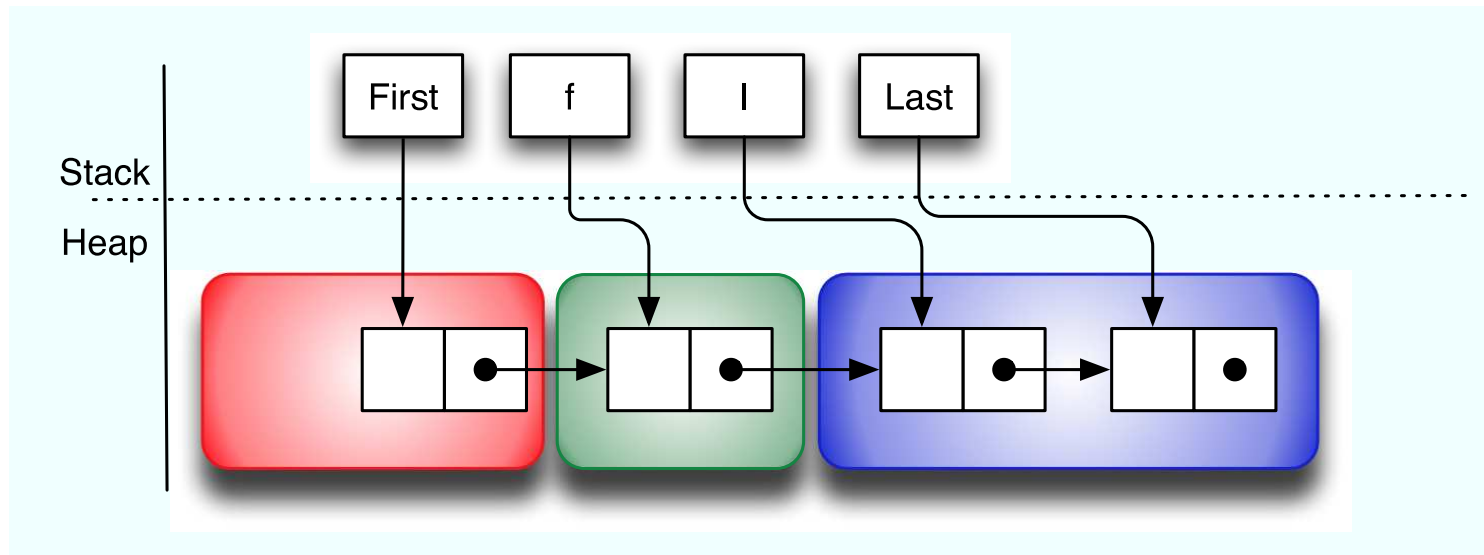


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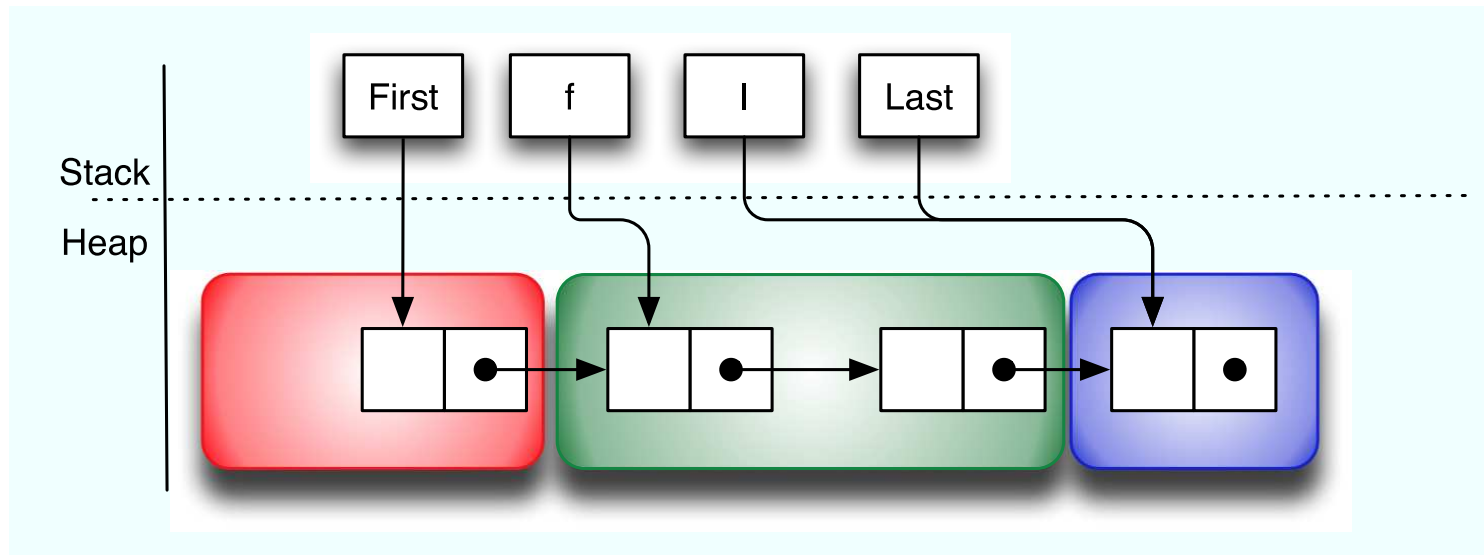


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$\{f = first \wedge emp\}$ P (number); $\{first \mapsto _, f\}$ t = first $\{first \mapsto _, f \wedge t = first\}$ first = [first+1] $\{t \mapsto _, f \wedge f = first\}$ dispose(t); $\{f = first\}$ Invariant = ls(f number l) where $ls\ x\ n\ z = (x = z \wedge n = 0 \wedge emp)$ $\vee (x \neq z \wedge n > 0 \wedge \exists y. x \mapsto _, y * ls\ y\ (n - 1)\ z)$	$\{l = last \wedge last \mapsto _, _ \}$ x = cons(*,*) $\{l = last \wedge last \mapsto _, _ * x \mapsto _, _ \}$ [last+1] = x; $\{l = last \wedge last \mapsto _, x * x \mapsto _, _ \}$ last = [last+1] $\{l \mapsto _, last * last \mapsto _, _ \}$ V(number); $\{last \mapsto _, _ \wedge l = last\}$
--	--

+ Conclusions +

- Can handle modularity
 - static: single instance of hidden datastructure
 - dynamic: abstract datatypes and classes
- Can handle concurrency
 - No interference flooding

+ What's next? —

- Tool support – Berdine, Calcagno, O'Hearn
- Inference – Distefano, Berdine, Cook, O'Hearn
- Code Pointers – Thielecke
- Racy Concurrency – Parkinson, Bornat
- Java – Parkinson
- Dynamic Allocation of Semaphores – ?

+ References +

The references for this part of the course can all be found on:

<http://www.dcs.qmw.ac.uk/~ohearn/localreasoning.html>