

# Topic 1

December 30, 2021

## 1 Topic 1 - Some basic operations in Python for scientific computing

1.0.1 1. Program to accept two numbers from the user to add, subtract, multiply and divide it and print the results.

```
[59]: n1=int(input('Enter a number: '))
      n2=int(input('Enter a number: '))
      a=n1+n2;
      s=n1-n2;
      p=n1*n2;
      d=n1/n2;
      print('The sum of the two numbers = ',a)
      print('The difference of the two numbers = ',s)
      print('The product of the two numbers = ',p)
      print('The quotient of the two numbers = ',d)
```

```
Enter a number: 5
Enter a number: 8
The sum of the two numbers = 13
The difference of the two numbers = -3
The product of the two numbers = 40
The quotient of the two numbers = 0.625
```

1.0.2 2. Program to check if a number is even or odd.

```
[60]: a= int(input('Enter a number: '))
      if(a%2==0):
          print(a, ' is an even number')
      else:
          print(a, ' is an odd number')
```

```
Enter a number: 674
674 is an even number
```

### 1.0.3 3. Program to check whether a given integer is positive or negative.

```
[96]: b= int(input('Enter an integer: '))
      if(b>0):
          print(b, ' is positive')
      elif(b<0):
          print(b, ' is negative')
      else:
          print("zero")
```

```
Enter an integer: 7
7 is positive
```

### 1.0.4 4. Program to check the biggest of three numbers entered by the user.

```
[62]: a1=int(input('Enter a number: '))
      a2=int(input('Enter a number: '))
      a3=int(input('Enter a number: '))
      if(a1>=a2) and (a1>=a3):
          largest=a1
      elif(a2>=a1) and (a2>=a3):
          largest=a2
      else:
          largest=a3

      print("")
      print('The largest of the three numbers is',largest)
```

```
Enter a number: 5
Enter a number: 8
Enter a number: 3
```

```
The largest of the three numbers is 8
```

### 1.0.5 5. Write a program to compute the factorial of a number.

```
[63]: fact=1;
      f=int(input('Enter the number: '))
      while(f>0):
          fact=fact*f
          f=f-1
      print('The factorial is ',fact)
```

```
Enter the number: 7
The factorial is 5040
```

### 1.0.6 6. Program to generate the multiplication table of a number (from 1 to 10)

```
[64]: x=int(input('Enter the number: '))
      for i in range(1,11):
          print(x,' x ',i,' = ',x*i)
```

Enter the number: 7

```
7 x 1 = 7
7 x 2 = 14
7 x 3 = 21
7 x 4 = 28
7 x 5 = 35
7 x 6 = 42
7 x 7 = 49
7 x 8 = 56
7 x 9 = 63
7 x 10 = 70
```

### 1.0.7 7. Lists

```
[65]: list=[]    #empty list

#Adding numbers to the list
nm=int(input('How many elements are to be added to the list: '))
while(nm>0):
    m=int(input('Enter the element to be added: '))
    list.append(m)
    nm=nm-1
print("")
print('Updated list: ')
print(list)
```

How many numbers are to be added to the list: 5

Enter the element to be added: 6

Enter the element to be added: 8

Enter the element to be added: 3

Enter the element to be added: 5

Enter the element to be added: 9

Updated list:

[6, 8, 3, 5, 9]

```
[66]: print('First element in the list: ', list[0])    #accessing an element from the
      ↪list using index number
      print('Third element in the list: ', list[2])
```

First element in the list: 6

Third element in the list: 3

```
[67]: list.remove(8)      #removing an element from the list
      print('Updated list: ',list)
```

Updated list: [6, 3, 5, 9]

### 1.0.8 Arrays

```
[93]: from numpy import *
      ar=array([[1,2,3],[4,5,6],[7,8,9]])
      print(ar)
```

```
[[1 2 3]
 [4 5 6]
 [7 8 9]]
```

```
[69]: ab=array([[1,2],[3,4]],dtype=float)
      print(ab)
```

```
[[1. 2.]
 [3. 4.]]
```

```
[70]: print(zeros(5))
```

```
[0. 0. 0. 0. 0.]
```

```
[71]: print(ones(5))
```

```
[1. 1. 1. 1. 1.]
```

```
[72]: print(identity(5))
```

```
[[1. 0. 0. 0. 0.]
 [0. 1. 0. 0. 0.]
 [0. 0. 1. 0. 0.]
 [0. 0. 0. 1. 0.]
 [0. 0. 0. 0. 1.]]
```

```
[73]: # arange (from,to,stepsize)
      # linspace(from,to,no.of points)

      print(arange(2,20,3))
      print("")
      print(linspace(2,10,5))
```

```
[ 2  5  8 11 14 17]
```

```
[ 2.  4.  6.  8. 10.]
```

### 1.0.9 Matrices

```
[74]: matrix1=array([[1,2,3],[4,5,6],[7,8,9]])  
      print(matrix1)
```

```
[[1 2 3]  
 [4 5 6]  
 [7 8 9]]
```

```
[94]: matrix1[1]
```

```
[94]: array([4, 5, 6])
```

```
[98]: matrix1[:,0]  #printing first column
```

```
[98]: array([1, 4, 7])
```

```
[77]: matrix1[1,2]  #accessing an element
```

```
[77]: 6
```

```
[95]: print(sin(matrix1))
```

```
[[ 0.84147098  0.90929743  0.14112001]  
 [-0.7568025  -0.95892427 -0.2794155 ]  
 [ 0.6569866   0.98935825  0.41211849]]
```

```
[79]: # Adding - Subtracting - Multiplying - Dividing matrices (element wise)
```

```
m1=array([[1,1,3],[2,3,5],[3,4,2]])  
m2=array([[2,8,4],[7,1,3],[0,7,3]])  
print('The two matrices are: ')  
print("")  
print(m1, ' and ')  
print("")  
print(m2)
```

The two matrices are:

```
[[1 1 3]  
 [2 3 5]  
 [3 4 2]]  and
```

```
[[2 8 4]  
 [7 1 3]  
 [0 7 3]]
```

```
[80]: print(m1+m2)  #Adding
```

```
[[ 3  9  7]
 [ 9  4  8]
 [ 3 11  5]]
```

```
[81]: print(m1-m2)    #difference
```

```
[[ -1 -7 -1]
 [-5  2  2]
 [ 3 -3 -1]]
```

```
[82]: print(m1*m2)    #product
```

```
[[ 2  8 12]
 [14  3 15]
 [ 0 28  6]]
```

```
[83]: print(m2/m1)    #quotient
```

```
[[2.         8.         1.33333333]
 [3.5        0.33333333 0.6        ]
 [0.         1.75        1.5        ]]
```

### 1.0.10 Solving a system of linear equations.

The system of linear equations can be solved using the function *numpy.linalg.solve()*.

#### 1.0.11 1. Solve the system of equations:

**1.0.12**  $4x + 3y = 20$  and  $-5x + 9y = 26$

```
[2]: from numpy import *
A=matrix([[4,3],[-5,9]])
B=matrix([[20],[26]])
print(A)
print('=')
print(B)
```

```
[[ 4  3]
 [-5  9]]
=
[[20]
 [26]]
```

```
[2]: print(linalg.solve(A,B))
```

```
[[2.]
 [4.]]
```

**1.0.13 2. Solve the system of equations:**

**1.0.14**  $2x - 3y + 5z = 11$

**1.0.15**  $5x + 2y - 7z = -12$

**1.0.16**  $-4x + 3y + z = 5$

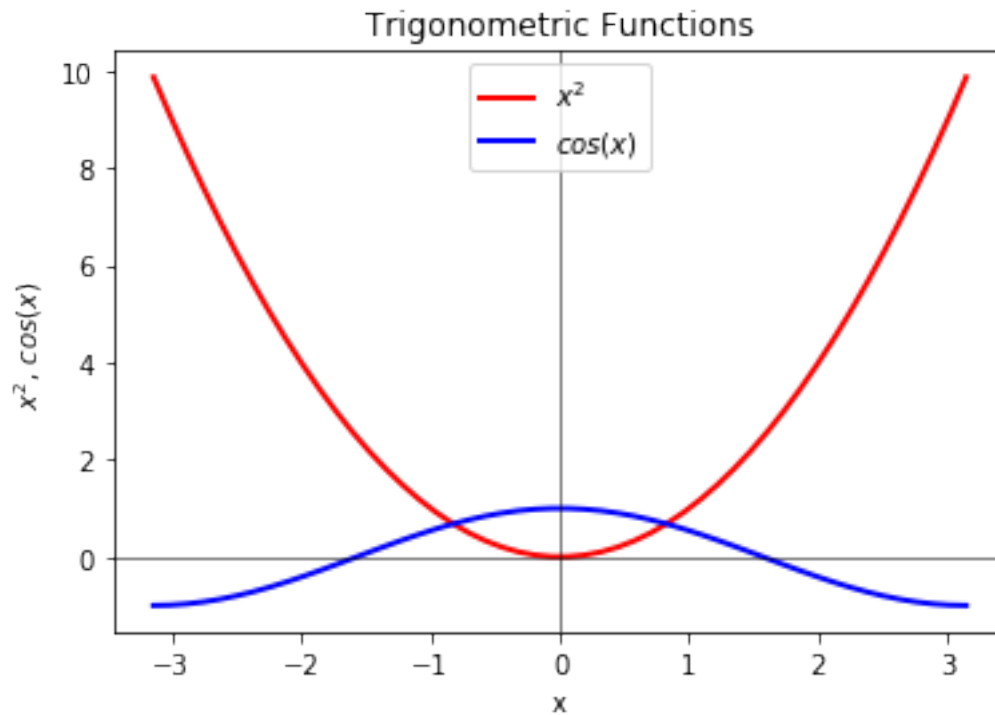
```
[68]: A1=matrix([[2,-3,5],[5,2,-7],[-4,3,1]])  
      B1=matrix([[11],[-12],[5]])  
      print(linalg.solve(A1,B1))
```

```
[[1.]  
 [2.]  
 [3.]]
```

**1.0.17 Scalar and Vector Plotting**

Q1. Plot the graphs of the functions  $x^2$  and  $\cos(x)$  in a single plot.

```
[2]: import numpy as np  
      import matplotlib.pyplot as plt  
  
      X = np.linspace(-np.pi, np.pi)  
      Y1 = X**2  
      Y2 = np.cos(X)  
  
      plt.plot(X, Y1, lw=2, color='red',label='$x^2$')  
      plt.plot(X, Y2, lw=2, color='blue',label='$\cos(x)$')  
  
      plt.title('Trigonometric Functions')  
      plt.xlabel('x')  
      plt.ylabel('$x^2$, $\cos(x)$')  
      plt.axhline(0, lw=0.5, color='black')  
      plt.axvline(0, lw=0.5, color='black')  
      plt.legend()  
      None
```



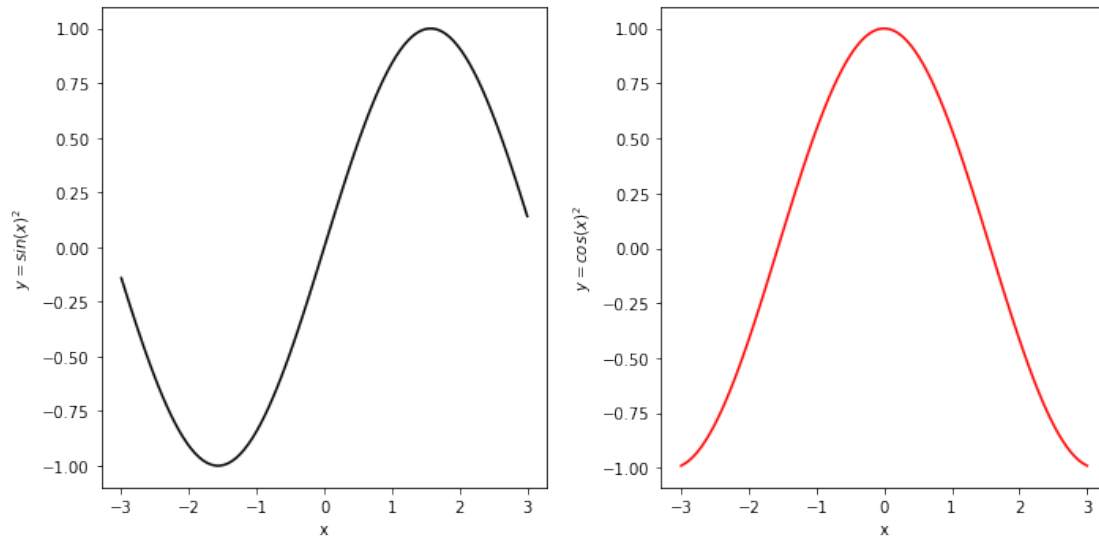
Q2. Plot the graphs of the trigonometric functions  $\sin(x)$  and  $\cos(x)$  in as subplots.

```
[46]: plt.figure(figsize=(10,5))
xvalues = linspace(-3, 3, 100)

plt.subplot(1, 2, 1)
yvalues = sin(xvalues)
plt.plot(xvalues, yvalues, color='black')
plt.xlabel('x')
plt.ylabel('$y=\sin(x)^2$')

plt.subplot(1, 2, 2)
yvalues = cos(xvalues)
plt.plot(xvalues, yvalues, color='red')
plt.xlabel('x')
plt.ylabel('$y=\cos(x)^2$')
plt.tight_layout()
```

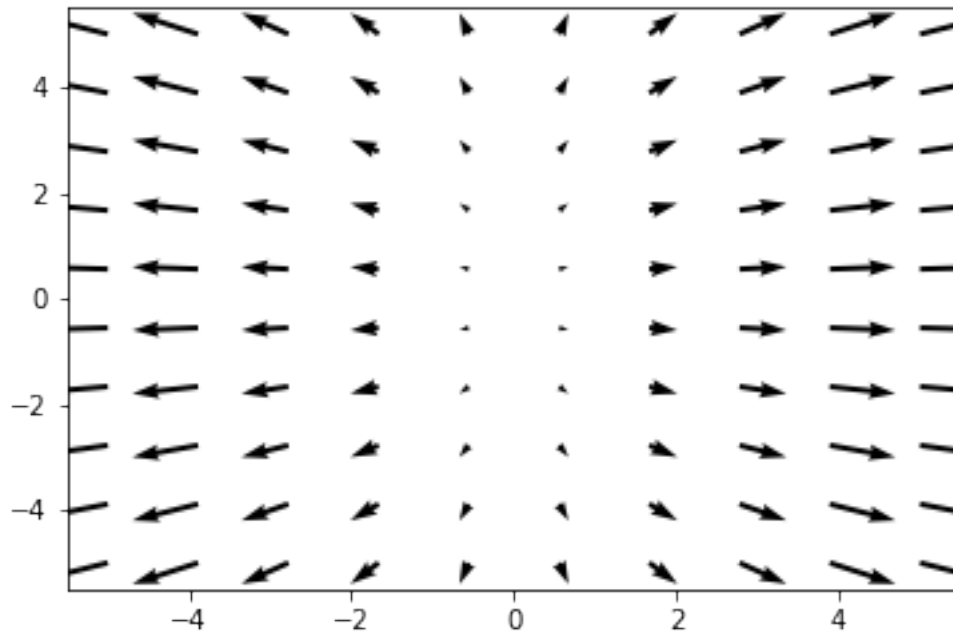




### 1.0.18 Vector Plot

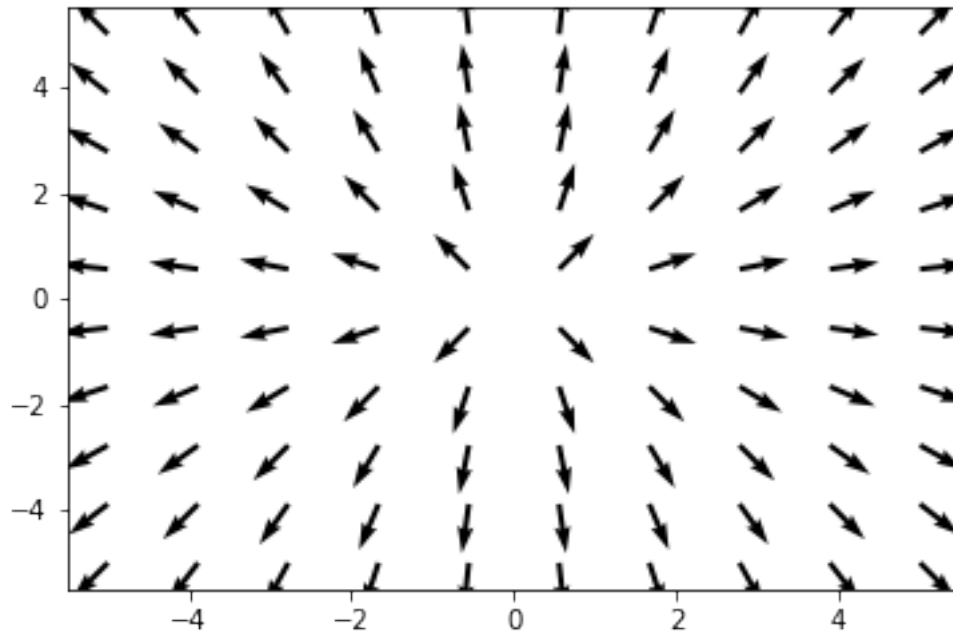
**Q1.** Plot the vector field for  $f(x, y) = 2xi + \frac{y}{2}j$

```
[44]: # Vector Plot of  $f(x, y) = 2xi + (y/2)j$ 
import numpy as np
import matplotlib.pyplot as plt
x, y = np.meshgrid(np.linspace(-5, 5, 10), np.linspace(-5, 5, 10))
u = 2 * x
v = y / 2
plt.quiver(x, y, u, v)
plt.show()
```



**Q2.** Plot the vector field for  $f(x,y) = \frac{x}{\sqrt{x^2+y^2}}i + \frac{y}{\sqrt{x^2+y^2}}j$

```
[14]: import numpy as np
import matplotlib.pyplot as plt
x,y=np.meshgrid(np.linspace(-5,5,10),np.linspace(-5,5,10))
u=x/np.sqrt(x**2+y**2)
v=y/np.sqrt(x**2+y**2)
plt.quiver(x,y,u,v)
plt.show()
```



### 1.0.19 Solution of initial value problems

1. Solve the IVP  $\frac{dy}{dx} = -0.3y, y(0) = 5$

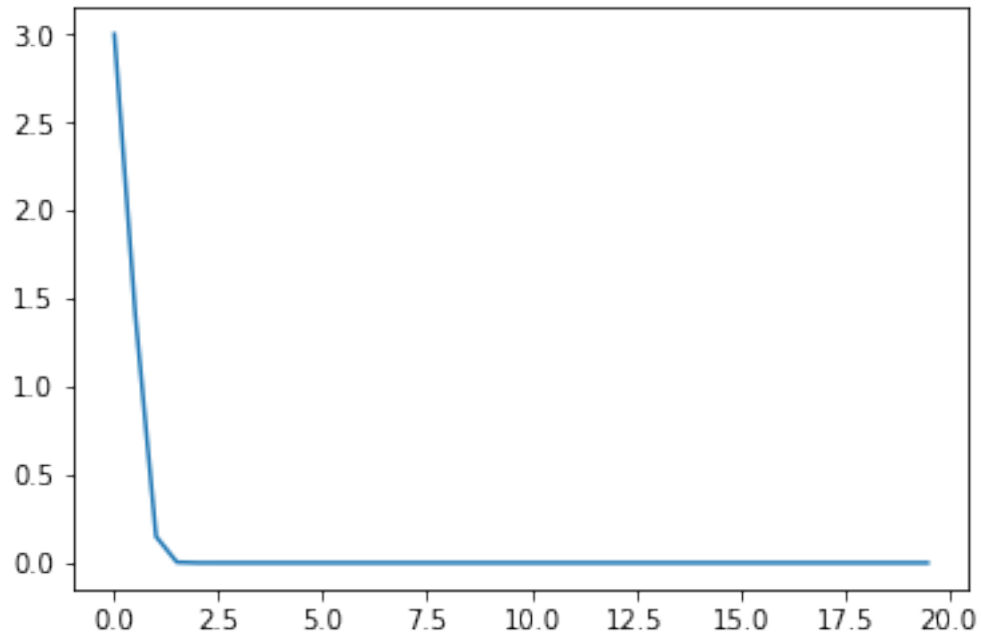
```
[64]: from numpy import *
      from scipy.integrate import odeint
      import matplotlib.pyplot as plt

      def model(y,x):          # define a function that returns dy/dx
          dydx=-0.3*y
          return dydx

      y0=5                      # intial condition
      x=arange(0,20,0.5)       # timepoints

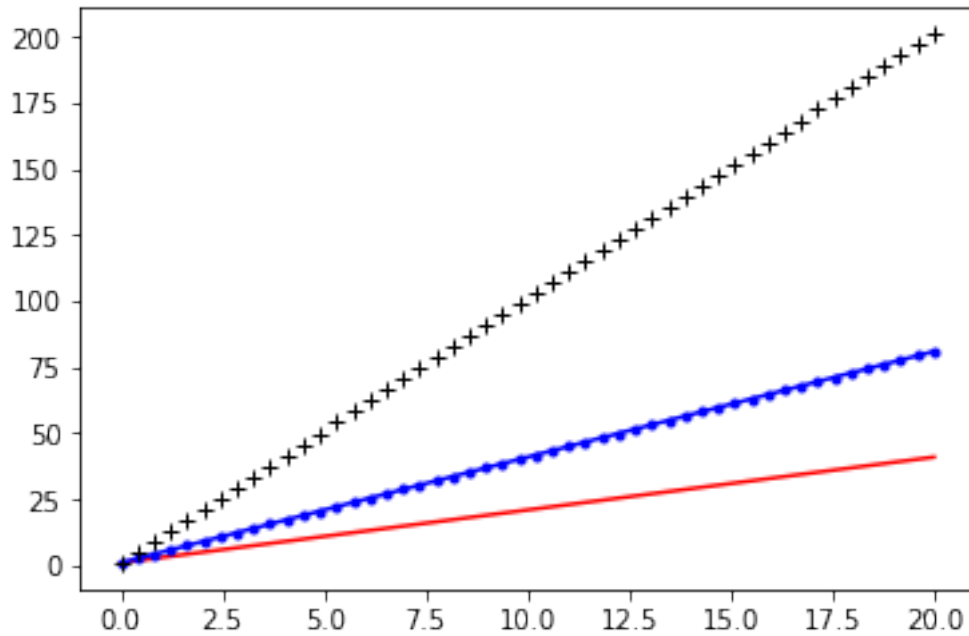
      y1=odeint(model,y0,x) # solve ODE

      plt.plot(x,y1)
      plt.show()
```



2. Solve the IVP  $\frac{dy}{dx} = 2k, y(0) = 1$

```
[57]: def model(y,t,k):          # define a function that returns dy/dx
        dydx=2*k
        return dydx
y0=1          # intial condition
t=linspace(0,20,50)  # timepoints
# solve ODE
k=1
yk1=odeint(model,y0,t,args=(k,))
k=2
yk2=odeint(model,y0,t,args=(k,))
k=5
yk3=odeint(model,y0,t,args=(k,))
plt.plot(t,yk1,'r')
plt.plot(t,yk2,'b.-')
plt.plot(t,yk3,'k+')
plt.show()
```



3. Solve the IVP  $\frac{dy}{dx} = 1 - y, y(0) = 0$

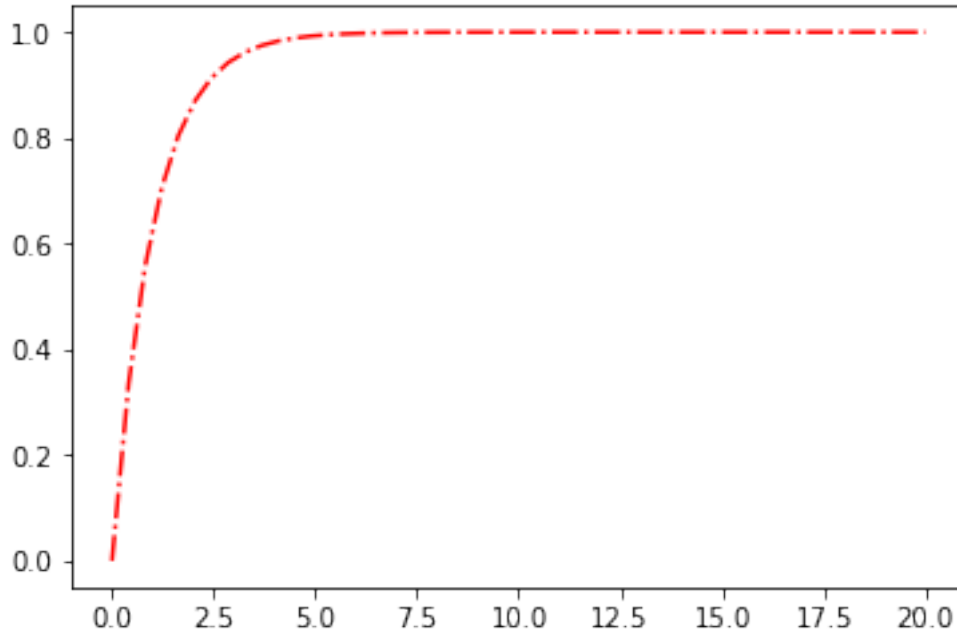
```
[27]: from numpy import *
from scipy.integrate import odeint
import matplotlib.pyplot as plt

def model(y,x):          # define a function that returns dy/dx
    dydx=1-y
    return dydx

y0=0                      # intial condition
x=linspace(0,20)         # timepoints

yx=odeint(model,y0,x)    # solve ODE

plt.plot(x,yx,'r-.')
plt.show()
```



### 1.0.20 Solving higher order differential equations

To solve higher order differential equations, we have to convert it to a system of first order differential equations using the following method and then solve by using *odeint*. **Example:** Solve  $y'' + 2y' + y = 0$  ; \_\_\_\_\_ (1) with initial conditions  $[y(0) = 5, y'(0) = 3]$

Here, take  $y' = t$  \_\_\_\_\_ (2) Substitute (2) in (1), we get  $t' + 2t + y = 0$   
i.e.  $t' = -2t - y$  \_\_\_\_\_(3)

Equations (2) and (3) constitute the system of first order differential equations.

Now, let  $u$  be a vector,  $u = [y, t]$ . This implies  $u[0] = y$  and  $u[1] = t$ . Then, (2) and (3) can be written as:  $y' = u[1]$   $t' = -2u[1] - u[0]$  \_\_\_\_\_

**Step 1 :** Define a function which returns the system of differential equations. **Step 2 :** Assign the initial conditions and define a range for independent variable  $x$ . **Step 3 :** Using in built function *odeint* solve the D.Eqns. Syntax -  $us = \text{odeint}(\text{func}, IC, x)$  **Step 4 :** The solution  $us$  will be an array with 2 columns. First column for  $u[0] = y$  and second column for  $u[1] = t$ . (With number of rows depending on the number of values defined for  $x$ ). Therefore,  $Sol = us[:, 0]$  will extract the values obtained for  $y$  from  $us$ . **Step 5 :** Plot the solution for  $Sol$ .

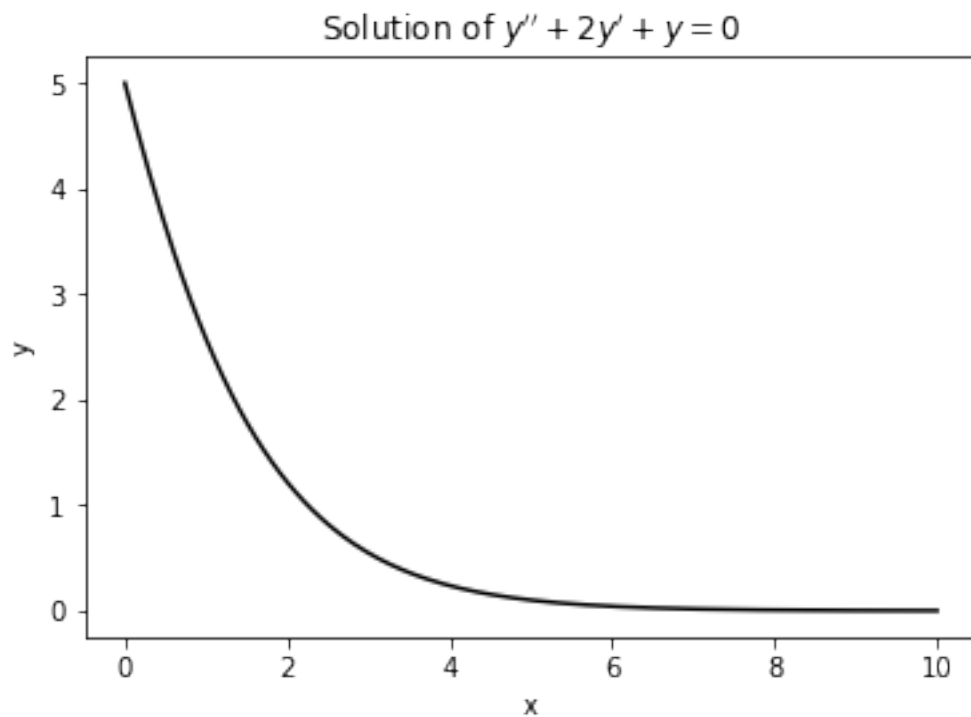
**1. Solve the differential equation  $y'' + 2y' + y = 0$  with the initial conditions,  $y(0) = 5, y'(0) = -3$ .**

```
[2]: from numpy import *
      from scipy.integrate import odeint
      import matplotlib.pyplot as plt
      def du_dx(u,x):
```

```

    return [u[1], -2*u[1]-u[0]]
u0=[5,-3]
xs=linspace(0,10,200)
us=odeint(du_dx,u0,xs)
ys=us[:,0]
plt.plot(xs,ys,color="black")
plt.title("Solution of $y''+2y'+y=0$")
plt.xlabel("x")
plt.ylabel("y")
plt.show()

```

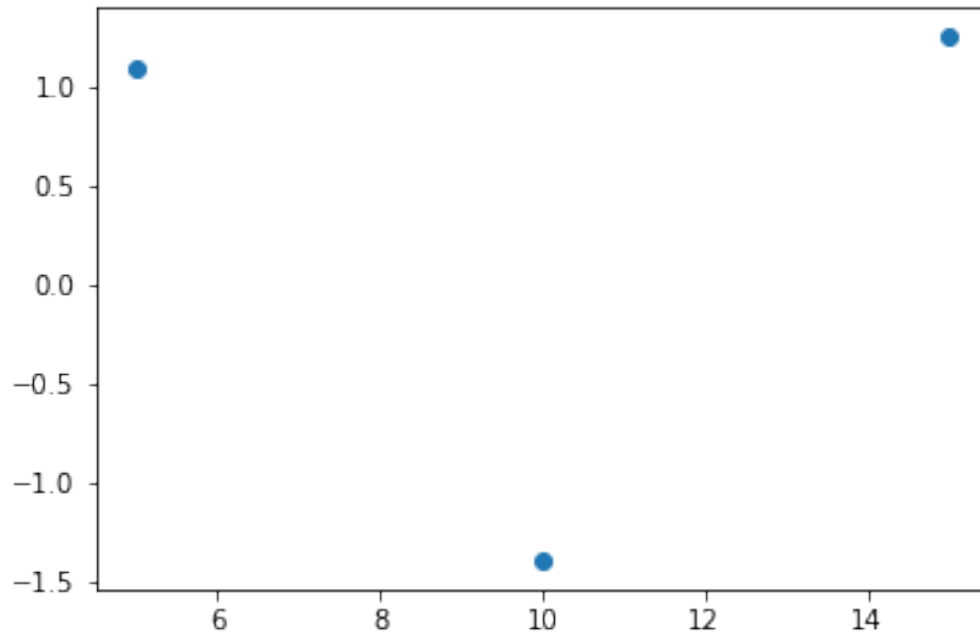


```

[4]: print(us[5,0],us[10,0],us[15,0])
x=[5,10,15]; y=[1.088,-1.391,1.249]
import matplotlib.pyplot as plt
plt.scatter(x, y)
plt.show()

```

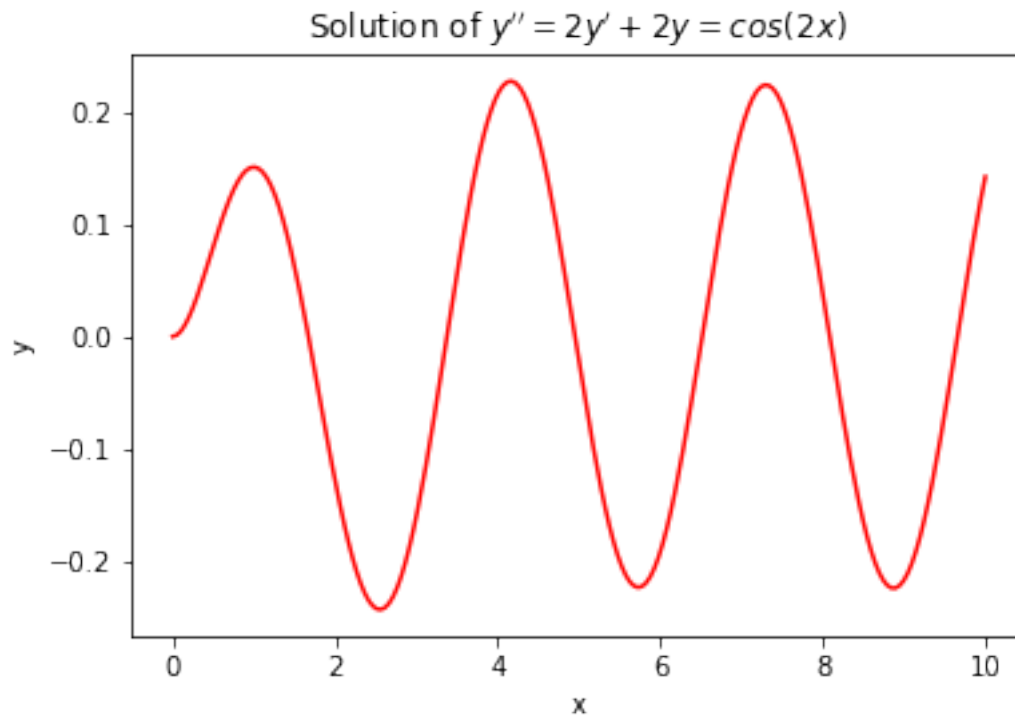
4.279980910683981 3.6330919852019443 3.0623797122019942



2. Solve the differential equation  $y'' + 2y' + 2y = \cos(2x)$  with the initial conditions,  $y(0) = 0, y'(0) = 0$ .

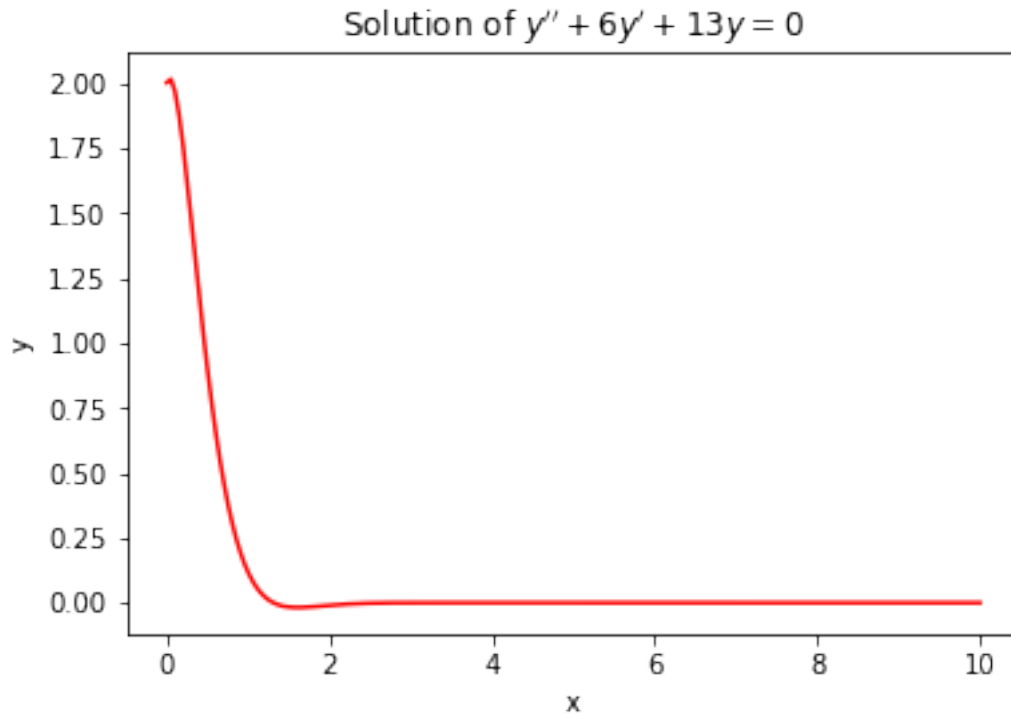
```
[29]: from numpy import *
from scipy.integrate import odeint
import matplotlib.pyplot as plt
def du_dx(u,x):
    return [u[1], -2*u[1]-2*u[0]+cos(2*x)]
u0=[0,0]
xs=linspace(0,10,200)
us=odeint(du_dx,u0,xs)
ys=us[:,0]
plt.plot(xs,ys,color="red")
plt.title("Solution of $y''=2y'+2y=\cos(2x)$")
plt.xlabel("x")
plt.ylabel("y")
plt.show()
```





3. Solve the differential equation  $y'' + 6y' + 13y = 0$  with the initial conditions,  $y(0) = 2, y'(0) = 1$ .

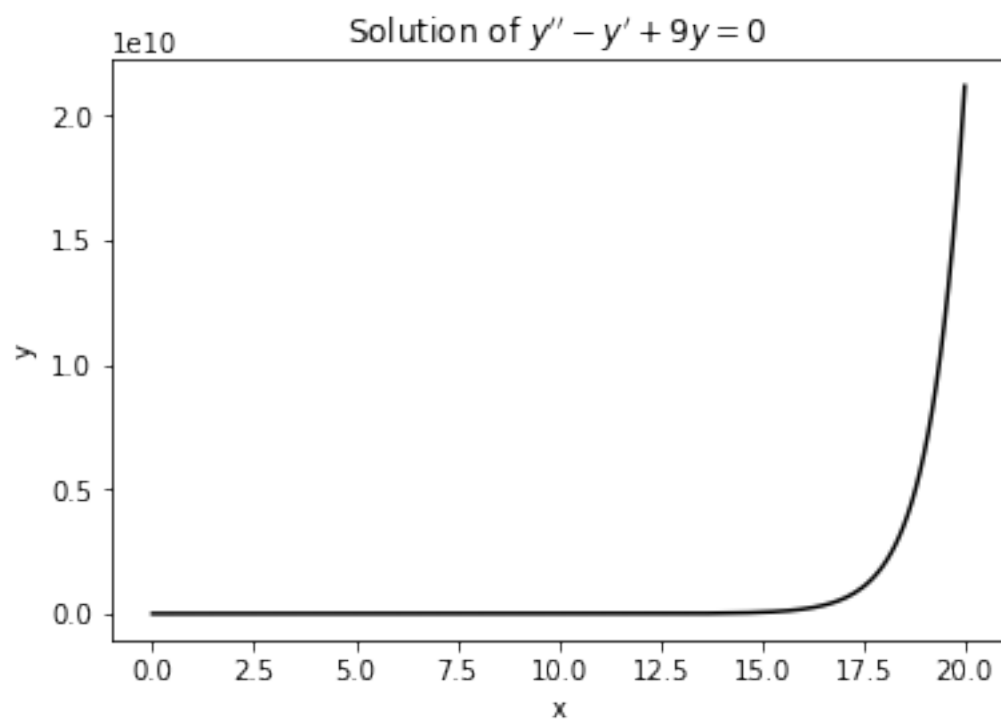
```
[90]: from numpy import *
      from scipy.integrate import odeint
      import matplotlib.pyplot as plt
      def du_dx(u,x):
          return [u[1], -6*u[1]-13*u[0]]
      u0=[2,1]
      xs=linspace(0,10,200)
      us=odeint(du_dx,u0,xs)
      ys=us[:,0]
      plt.plot(xs,ys,color="red")
      plt.title("Solution of $y''+6y'+13y=0$")
      plt.xlabel("x")
      plt.ylabel("y")
      plt.show()
```



4. Solve the differential equation  $y'' + 3y' - 5y = 0$  with the initial conditions,  $y(0) = 0, y'(0) = 5$ .

```
[19]: from numpy import *
from scipy.integrate import odeint
import matplotlib.pyplot as plt
def du_dx(u,x): # defining a function to return the differential equation
    return [u[1], -3*u[1]+5*u[0]]
u0=[0,5] # initial conditions
xs=linspace(0,20,200) #timepoints (x-axis)
us=odeint(du_dx,u0,xs) #solving the d.e to obtain solution array 'us'
# Array 'us' has two columns. The first column gives solution 'y'.
# Each row (r) contains value of y for a timepoint, t=r.
ys=us[:,0] #Extracting the first column (Solution set - y)
plt.plot(xs,ys,color="black") # Plotting the solution-set(yaxis) against
    ↳timepoints(xaxis)
plt.title("Solution of $y''-y'+9y=0$")
plt.xlabel("x")
plt.ylabel("y")
plt.show()
#####
print(us[5,0],us[10,0],us[15,0])
```

```
# To extract the solution y for a timepoint t=5(say), then you may use the code us[5,0].
```



```
1.5776655470660519 3.0645281101696122 5.603295179886854
```

```
[ ]:
```