MAST30025 Linear Statistical Models Assignment 3

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May 2023

(a)
$$r(A^c A) \le \min[r(A^c), \ r(A)] \le r(A)$$

$$r(A) = r(AA^c A) \le \min[r(A), \ r(A^c A)] \le r(A^c A)$$

$$\implies r(A^C A) = r(A)$$

(b)

$$(I - A(A^{T}A)^{c}A^{T})(I - A(A^{T}A)^{c}A^{T})$$

$$= I^{2} - IA(A^{T}A)^{c}A^{T} - A(A^{T}A)^{c}A^{T}I + A(A^{T}A)^{c}A^{T}A(A^{T}A)^{c}A^{T}$$

$$= I - 2(A(A^{T}A)^{c}A^{T}) + A(A^{T}A)^{c}A^{T}A(A^{T}A)^{c}A^{T}$$

$$= I - 2(A(A^{T}A)^{c}A^{T}) + [A(A^{T}A)^{c}A^{T}A] (A^{T}A)^{c}A^{T}$$

$$= I - 2(A(A^{T}A)^{c}A^{T}) + A(A^{T}A)^{c}A^{T}$$

$$= I - 2(A(A^{T}A)^{c}A^{T}) + A(A^{T}A)^{c}A^{T}$$

 $I-A(A^TA)^cA^T$ is idempotent, I and $A(A^TA)^cA^T$ are idempotent and symmetric

$$r(A(A^TA)^cA^T) \le min[r(A), r((A^TA)^c), r(A^T)] \le r(A)$$

$$r(A) = r(A(A^TA)^c A^T A) \le \min[r(A), r(A(A^TA)^c A^T)] \le r(A(A^TA)^c A^T)$$

$$\implies r(A(A^TA)^cA^T) = r(A)$$

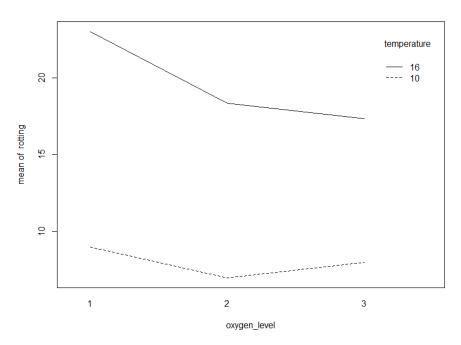
 $A(A^TA)^cA^T$ is $n \times n$ so I must be $n \times n$

$$\implies r(I) = n$$

As
$$I-A(A^TA)^cA^T$$
 is symmetric and $n\times n$, it is diagonalised by P , so $r(I-A(A^TA)^cA^T)=r(P^T(I-A(A^TA)^cA^T)P)=r(I-D)$

Since $A(A^TA)^cA^T$ is idempotent, it has $r(A(A^TA)^cA^T)=r(A)$ 1s on the diagonal of its diagonal matrix D

 $\implies r(I-D) = r(I) - r(D) = n - r(A)$ as the rank of a diagonal matrix = the number of non-zero entries on its diagonal



It may be reasonable to assume that there is no interaction due to the lines being relatively parallel despite the low sample size, although its hard to be certain.

```
(b)
[R \ code]
> y = rot_df\$rotting
> n = length(y)
> X = \mathbf{matrix}(\mathbf{c}(\mathbf{rep}(1, n), \mathbf{rep}(0, n*5)), n, 6)
> X[\mathbf{cbind}(1:n, \mathbf{as.numeric}(rot_\mathbf{df}soxygen_level)+1)] = 1
> X[cbind(1:n, as.numeric(rot_df$temperature)+4)] = 1
> library (Matrix)
> r = rankMatrix(X)[1]
> # find conditional inverse of XtX
> XtX = t(X) \% X
> M = XtX[2:5, 2:5]
> \det(M)
[1] 972
> XtXc = matrix(0, 6, 6)
> XtXc[2:5,2:5] = t(solve(M))
> XtXc = t(XtXc)
> all.equal(XtX %*% XtXc %*% XtX,XtX)
[1] TRUE
> b = XtXc \% \% t(X) \% \% y
> s2 = sum((y - X \% b)^2) / (n-r)
```

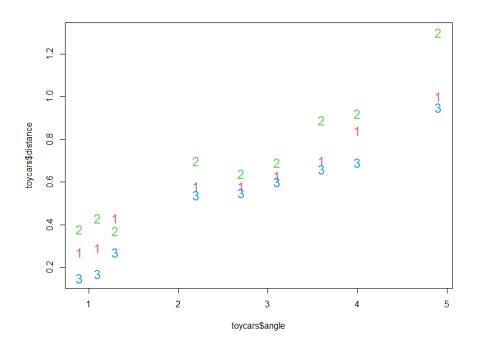
```
> X
       [1,]
                                       0
 [2,]
[3,]
          1
                1
                     0
                           0
                                 1
                                       0
          1
                1
                     0
                           0
                                       0
 [4,]
          1
                1
                     0
                           0
                                 0
                                       1
          1
 [5,]
                     0
                                       1
 [6,]
          1
                1
                     0
                           0
                                 0
                                       1
 [7,]
          1
                                       0
                0
                     1
 [8,]
          1
                0
                     1
                           0
                                 1
                                       0
 [9,]
          1
                                 1
                                       0
                0
                     1
                           0
[10,]
          1
                0
                     1
                           0
                                 0
                                       1
[11,]
          1
                     1
                           0
                                 0
                                       1
                0
[12,]
                     1
                                       1
          1
                0
                           0
          1
                     0
                                       0
[13,]
                0
                           1
                                 1
[14,]
          1
                0
                     0
                           1
                                 1
                                       0
[15,]
          1
                0
                     0
                           1
                                 1
                                       0
          1
                0
                     0
                           1
                                 0
                                       1
[16,]
[17,]
          1
                0
                     0
                           1
                                 0
                                       1
[18,]
                0
                     0
                           1
                                 0
                                       1
          1
>
> s2
[1] 26.12698
```

```
(c)
|R| code|
> tt = \mathbf{c}(0, 0, 0, 0, 1, -1) \# temp10mean - temp16mean
> ta = qt(0.975, n-r)
> halfwidth = ta * sqrt(s2 * t(tt) %*% XtXc %*% tt)
> tt \% \% b + c(-1, 1) * halfwidth
[1] -16.723555 -6.387556
95\% confidence interval for temp10effect-temp16effect:
 [-16.724, -6.388]
(d)
H_0: \tau_1 = \tau_2 = \tau_3 = 0
[R \ code]
> \mathbf{C} = \mathbf{matrix}(\mathbf{c}(0,0,1,1,-1,0,0,-1,0,0,0,0), 2, 6)
> all.equal(round(C %*% XtXc %*% t(X) %*% X, 3), C)
[1] TRUE
> numer = \mathbf{t}(\mathbf{C}\%\% b) \%\%\% solve(\mathbf{C}\%\%\% XtXc \%\%\% \mathbf{t}(\mathbf{C})) \%\%\% \mathbf{C}\%\%\%
> Fstat = (numer / 2) / s2
> \mathbf{pf}(Fstat, 2, n-r, lower=F)
              [,1]
[1,] 0.4481124
p-value = 0.448 \implies Cannot \ reject \ H_0 \ at \ 5\% \ significance \ level
```

This would be a complete block design study with oxygen level as the factor of interest and temperature as the blocking factor.

(e)

```
(a)
[R code]
toycars = read.csv("toycars.csv")
toycars$car = factor(toycars$car)
plot(toycars$angle, toycars$distance, pch=array(toycars$car),
col=as.numeric(toycars$car)+1, cex=1.5)
```



It seems that the distance travelled by the car increases as the angle increases. It would also seem that the type of car doesn't seem to have as much of an effect as the angle in this experiment, although we can still say that car 3 generally travels the least distance, while car 1 travels slightly further and car 2 travels the furthest.

(b) [R code] > imodel = lm(toycars\$distance ~ toycars\$car * toycars\$angle, data=toycars) > amodel = lm(toycars\$distance ~ toycars\$car + toycars\$angle, data=toycars) > anova(amodel, imodel) Analysis of Variance Table Model 1: toycars\$distance ~ toycars\$car + toycars\$angle Model 2: toycars\$distance ~ toycars\$car * toycars\$angle Res.Df RSS Df Sum of Sq F Pr(>F) 1 23 0.105657 2 21 0.093271 2 0.012386 1.3944 0.27

No significant interaction present between the type of toy car and the angle

```
(c)
|R \ code|
> fullmodel = imodel
> drop1(fullmodel, scope = ~ ., test="F")
Single term deletions
Model:
toycars $distance ~ toycars $car * toycars $angle
                             Df Sum of Sq
                                                          AIC F value
                                                RSS
Pr(>F)
<none>
                                            0.09327 -141.038
toycars $ car
                              2
                                  0.01979 \ 0.11307 \ -139.842
2.2284
          0.1325
toycars $ angle
                                  0.44593 \ 0.53920
                                                     -95.664 \ 100.4023 \ 1.87e-09
                              1
toycars $car: toycars $angle
                             2
                                  0.01239 \ 0.10566 \ -141.672
1.3944
          0.2700
<none>
toycars$car
toycars $ angle
toycars $car: toycars $angle
Signif. codes: 0
                               0.001
                                                0.01
                                                               0.05
                                                                             0.1
                       ***
                                         **
> backmodel2 = lm(toycars distance ~ toycars car + toycars angle, <math>data = toycars)
> drop1(backmodel2, scope = ~ ., test="F")
Single term deletions
Model:
toycars $distance ~ toycars $car + toycars $angle
               Df Sum of Sq
                                  RSS
                                            AIC F value
                                                             Pr(>F)
<none>
                              0.10566 -141.672
toycars$car
                     0.16945 \ \ 0.27511 \ \ -119.833 \ \ \ 18.444 \ \ 1.662 \, \mathrm{e}{-05} \ ***
                     1.65108 \ 1.75673
                                       -67.774 359.416 1.547e-15 ***
toycars $ angle
                1
Signif. codes: 0
                               0.001
                                                0.01
                                                               0.05
                                                                             0.1
                       ***
> # all tests are significant, we stop at backmodel2
```

```
(d)
H_0: \tau_1 - \tau_3 = 0.05
   [R \ code]
> linear Hypothesis (backmodel2, \mathbf{c}(0,0,-1,0), 0.05)
Linear hypothesis test
Hypothesis:
- toycars$car3 = 0.05
Model 1: restricted model
{\bf Model~2:~toy cars\$ distance~^{\tilde{}}~toy cars\$ car~+~toy cars\$ angle}
                RSS Df Sum of Sq
                                          F Pr(>F)
  Res. Df
1
       24 \ 0.11033
       23 \ 0.10566 \ 1 \ 0.0046722 \ 1.0171 \ 0.3237
Signif. codes: 0
                                  0.001
                                                     0.01
                                                                    0.05
                                                                                    0.1
                          ***
```

p-value = 0.3237 > 0.05, so we cannot reject H_0 at the 5% significance level

```
(e)
H_0:\tau_2=\tau_3
   [R \ code]
> linear Hypothesis (full model, \mathbf{c}(0,1,-1,0,0,0), 0)
Linear hypothesis test
Hypothesis:
toycars $car2 - toycars $car3 = 0
Model 1: restricted model
Model 2: toycars$distance ~ toycars$car * toycars$angle
                RSS Df Sum of Sq
                                          F Pr(>F)
  Res. Df
1
       22\  \  0.108767
                      1 \quad 0.015497 \ \ 3.4891 \ \ 0.07579 \ \ .
       21\  \  0.093271
Signif. codes: 0
                                 0.001
                                                   0.01
                                                                  0.05
                                                                                 0.1
                         ***
```

p-value = 0.0758 > 0.05, so we cannot reject H_0 at the 5% significance level

(a)

Mu can be regarded as a nuisance parameter since we are not interested in it specifically but it still accounts for some variation in our model $\frac{1}{2}$

(b)

$$X_1 = \begin{bmatrix} 1\\1\\1\\1\\1\\1\\1 \end{bmatrix}$$

$$X_2 = \begin{bmatrix} 1 & 0 & x_{11} \\ 1 & 0 & x_{12} \\ 1 & 0 & x_{13} \\ 0 & 1 & x_{21} \\ 0 & 1 & x_{22} \\ 0 & 1 & x_{23} \end{bmatrix}$$

(c)

 $[R \ code]$

$$> X1 = \mathbf{matrix}(\mathbf{c}(\mathbf{rep}(1, 6)), 6, 1) \\ > \\ > H1 = X1 \%\% \ \mathbf{ginv}(\mathbf{t}(X1) \%\% \ X1) \%\% \ \mathbf{t}(X1) \\ > \\ > \ \mathbf{fractions}(\mathbf{diag}(6) - \mathbf{H1}) \\ \quad [,1] \ [,2] \ [,3] \ [,4] \ [,5] \ [,6] \\ [1,] \ 5/6 -1/6 -1/6 -1/6 -1/6 -1/6 -1/6 \\ [2,] \ -1/6 \ 5/6 -1/6 -1/6 -1/6 -1/6 -1/6 \\ [3,] \ -1/6 -1/6 \ 5/6 -1/6 -1/6 -1/6 \\ [4,] \ -1/6 -1/6 \ -1/6 \ 5/6 -1/6 -1/6 \\ [5,] \ -1/6 \ -1/6 \ -1/6 \ -1/6 \ 5/6 -1/6 \\ [6,] \ -1/6 \ -1/6 \ -1/6 \ -1/6 \ -1/6 \ 5/6 \\ \end{cases}$$

$$X_{2|1} = [I - H_1]X_2 = \begin{bmatrix} \frac{5}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & \frac{5}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & -\frac{1}{6} & \frac{5}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & \frac{5}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} \\ -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & -\frac{1}{6} & \frac{5}{6} \end{bmatrix} \begin{bmatrix} 1 & 0 & x_{11} \\ 1 & 0 & x_{12} \\ 1 & 0 & x_{13} \\ 0 & 1 & x_{21} \\ 0 & 1 & x_{21} \\ 0 & 1 & x_{22} \\ 0 & 1 & x_{23} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} & x_{11} - \bar{x} \\ \frac{1}{2} & -\frac{1}{2} & x_{12} - \bar{x} \\ \frac{1}{2} & -\frac{1}{2} & x_{13} - \bar{x} \\ -\frac{1}{2} & \frac{1}{2} & x_{22} - \bar{x} \\ -\frac{1}{2} & \frac{1}{2} & x_{22} - \bar{x} \\ -\frac{1}{2} & \frac{1}{2} & x_{23} - \bar{x} \end{bmatrix}$$

```
(d)
\vec{b_2} = (X_{2|1}^T X_{2|1})^c X_{2|1}^T \vec{y}
[R \ code]
> xs = c(2,4,8,7,6,4)
> xs = c(2,4,6,7,6,4)
> y = c(4,2,10,8,8,12)
> xbar = mean(xs)
>\,\mathrm{X21}\,=\,\mathbf{matrix}\,(\,\mathbf{c}\,(\,0.5\,,0.5\,,0.5\,,-0.5\,,-0.5\,,-0.5\,,-0.5\,,-0.5\,,-0.5\,,0.5\,,0.5\,,0.5\,,
                 xs\left[1\right]-xbar\;,xs\left[2\right]-xbar\;,xs\left[3\right]-xbar\;,xs\left[4\right]-xbar\;,xs\left[5\right]-xbar\;,
                 xs[6] - xbar), 6,3)
> b2 = ginv(t(X21) %*% X21) %*% t(X21) %*% y > b2
                     [,1]
 [1,] -1.6857143
 [2,]
           1.6857143
 [3,]
           0.6285714
\vec{b_2} = \begin{bmatrix} -1.6857\\ 1.6857\\ 0.6286 \end{bmatrix}
```

```
(e)
\vec{b_1} = (X_1^T X_1)^c (X_1^T \vec{y} - X_1^T X_2 \vec{b_2})
[R \ code]
> \ b1 \ = \ ginv \left( \ \mathbf{t} \left( X1 \right) \ \%*\% \ X1 \right) \ \%*\% \ \left( \ \mathbf{t} \left( X1 \right) \ \%*\% \ y \ - \ \mathbf{t} \left( X1 \right) \ \%*\% \ X2 \ \%*\% \ b2 \right)
> b1
[1,1] [1,] [4.085714]
> X = \mathbf{cbind}(X1, X2)
> > b = rbind(b1, b2)
[ , 1 ]
[1,]
             44
[2,]
             16
[3,]
             28
[4,]
           248
> t(X) %*% y
         [,1]
[2,]
             16
             28
[3,]
[4,]
           248
\vec{b_1} = 4.0857
X^T X \vec{b} = X^T \vec{y}
```