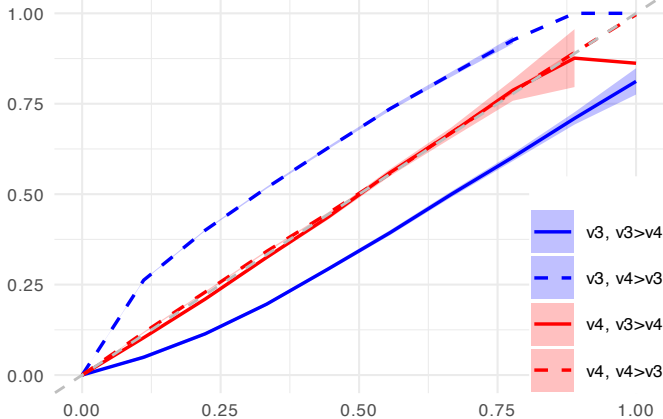


Observed

 Δ from calibrated