

# Outline

Model comparison

Further methods

Further packages

# 1. Model comparison

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## DIC and Bayes Factor

- **DIC** is a popular and useful method for comparing models; it can be calculated from MCMC samples
- **Bayes Factor** takes into account more information, but can be harder to calculate

$$\frac{\Pr(D|M_1)}{\Pr(D|M_2)} = \frac{\int \Pr(\theta_1|M_1) \Pr(D|\theta_1, M_1) d\theta_1}{\int \Pr(\theta_2|M_2) \Pr(D|\theta_2, M_2) d\theta_2}$$

- Harmonic mean estimator (HME): take the inverse of the mean of the inverse likelihood (using MCMC samples) – heavily criticised (google “worst Monte Carlo ever”), but some claim it works (Rasmussen et al., 2014).

## Reversible-jump MCMC

- extend MCMC to jump between **models** – take samples from

$$p(\text{Model } M | \text{Data}) \propto p(M)p(\text{Data} | M)$$

- First propose to jump between models, then jump between parameter spaces (possibly of different size)

## ABC

- similar; but: a summary statistic which is sufficient for parameter estimation is **not** necessarily sufficient for model selection (Didelot et al., 2011)

## 2. Further methods

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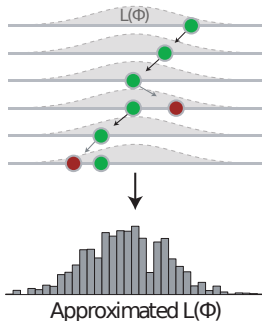
# Sampling from the posterior

Estimating the  
likelihood

	MCMC	SMC
SMC	PMCMC ✓	SMC <sup>2</sup>
ABC	ABC-MCMC ✓	ABC-SMC

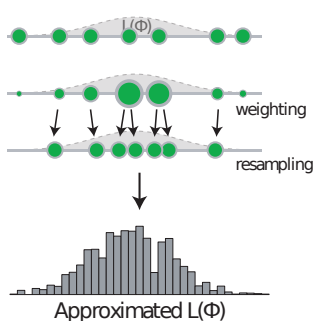
# SMC vs MCMC

MCMC Algorithm



- 1) Draw new parameter  $\Phi'$  close to the old  $\Phi$
- 2) Calculate  $L(\Phi')$
- 3) Jump proportional to  $L(\Phi')/L(\Phi)$

SMC Algorithm



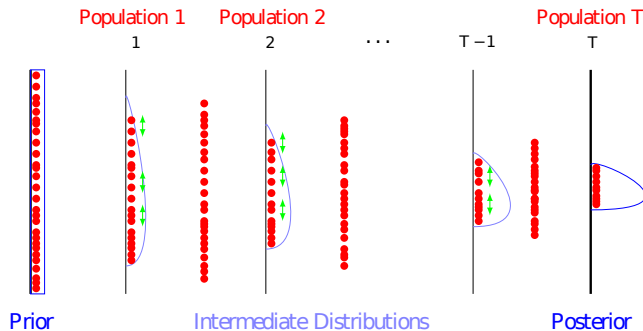
- 1) Last set of parameters  $\{\Phi_i\}$
- 2) Assign weight  $\omega_i$  proportional to  $L(\Phi_i)$
- 3) Draw new  $\{\Phi_i\}$  based on the  $\omega_i$

- Other forms of MCMC exist, e.g. Gibbs Sampler
- can use SMC for sampling from posterior, but must combat **particle depletion**

- use  $N_\theta$  particles for parameters, each with  $N_X$  particles for the trajectories
- each  $\theta$ -particle has its own particle filter
- **rejuvenation**: after every step, propose a Metropolis-Hastings step



# ABC-SMC



(Toni and Stumpf, 2009)

# Iterated Filtering

- similar: particles take a random walk
- multiple iterations of SMC; at each iteration, make random walk step size smaller
- King et al., 2008

# Gaussian Process Emulation

- Instead of defining an acceptance window (ABC), evaluate summary statistics at test points, and fit a **Gaussian process** to this
- can use this to define **implausibility regions**
- more later
- similar approach: Synthetic likelihoods (Wood, 2010)

### 3. Further packages

# MCMC

- `LaplacesDemon`
  - > 20 MCMC algorithms (including Metropolis-Hastings)
- `MHadaptive`
  - seems to incorrectly calculate DIC
- both are quite general, similar approach to our functions

# ABC

- EasyABC
  - implements various ABC methods, including
    - ABC-MCMC (as used here)
    - improved ABC-MCMC (Wegmann et al., 2009)
    - ABC-SMC (Toni, Welch, et al., 2009)
  - only uses Euclidean distance
- abc
  - package for analysing ABC output, similar to coda

- <http://libbi.org/>
- not an *R* package, written using a mixture of *C* and *perl*.
- very fast, very up-to-date; implements PMCMC and SMC<sup>2</sup>.
- uses its own syntax for model structure
- doesn't easily run on Windows

# SSM

- `https://github.com/standard-analytics/ssm`
- not an *R* package, written using a mixture of *C* and *python*.
- very fast, very up-to-date
- uses inference chains; start with simple methods, home in on parameter space of interest
- uses its own syntax for model structure
- doesn't easily run on Windows



# POMP

- R package

```
install.packages("pomp")
```

- implements many up-to-date methods
- interfaces with *C* for speed