Objective

```
In [1]: # CNNs w SIFT instead of pooling:
    # https://arxiv.org/ftp/arxiv/papers/1904/1904.00197.pdf
    # https://github.com/hmorimitsu/sift-flow-gpu
```

Colab Helpers (if needed)

```
In [2]: # from google.colab import drive
    # drive.mount("/content/gdrive")
    # # drive.mount("/content/gdrive", force_remount=True)

In [3]: # import os
    # os.chdir("/content/gdrive/My Drive/...pathtocode")

In [4]: # import torch
    # a = torch.Tensor([1]).cuda()
    # print(a)
```

Load Fashion-MNIST and Net

```
In [5]: import matplotlib.pyplot as plt
  import numpy as np
  import torch
  import time
  import copy
```

```
In [6]:
        from utils.data_process import get_FASHION_data
        TRAIN_IMAGES = 50000
        VAL IMAGES = 10000
        TEST_IMAGES = 10000
        data = get_FASHION_data(TRAIN_IMAGES, VAL_IMAGES, TEST_IMAGES)
        X_train, y_train = data['X_train'], data['y_train']
        X_val, y_val = data['X_val'], data['y_val']
        X_test, y_test = data['X_test'], data['y_test']
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
        # For auto-reloading external modules
        # See http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipy
        thon
        %load ext autoreload
        %autoreload 2
```

In [7]: # from models.neural_net_simple import NeuralNet
 from models.neural_net_traditional import NeuralNet
 # from models.neural_net_sift import NeuralNet

Init Net and Train

```
In [8]:
        # Hyperparameters
        input_size = 28 * 28
        num classes = 10
        epochs = 15 # 50 # 5 # 100
        batch size = 200
        learning_rate = 0.001
        # Initialize a new neural network model
        net = NeuralNet(learning rate,input size,num classes)
        # # extract output of layers
        # https://discuss.pytorch.org/t/how-can-i-extract-intermediate-layer-output-f
        rom-loaded-cnn-model/77301/3
        # https://discuss.pytorch.org/t/how-can-l-load-my-best-model-as-a-feature-ext
        ractor-evaluator/17254/6
        activation = {}
        def get activation(name):
            def hook(net, input, output):
                activation[name] = output.detach()
            return hook
        # net.Layers[2].register forward hook(get activation('pre fc')) # for net sim
        net.layers[3].register_forward_hook(get_activation('pre_fc')) # for net_simpl
        \# output = net(x)
        # activation['fc2']
```

Out[8]: <torch.utils.hooks.RemovableHandle at 0x7f44ff1d5e20>

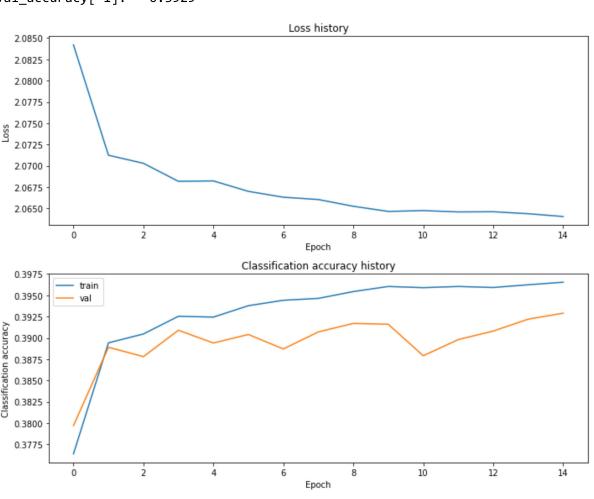
```
In [9]:
        TRAIN IMAGES = 50000
        VAL IMAGES = 10000
        TEST IMAGES = 10000
        data = get_FASHION_data(TRAIN_IMAGES, VAL_IMAGES, TEST_IMAGES)
        X_train, y_train = data['X_train'], data['y_train']
        X_val, y_val = data['X_val'], data['y_val']
        X_test, y_test = data['X_test'], data['y_test']
        # X_train = torch.tensor(X_train, dtype=torch.float32)
        # y train = torch.tensor(y train, dtype=torch.float32)
        # X_val = torch.tensor(X_val, dtype=torch.float32)
        # y val = torch.tensor(y val, dtype=torch.float32)
        X test = torch.tensor(X test, dtype=torch.float32)
        # y test = torch.tensor(y test, dtype=torch.float32)
        # Variables to store performance for each epoch
        train loss = np.zeros(epochs)
        train accuracy = np.zeros(epochs)
        val accuracy = np.zeros(epochs)
        start_time = time.time()
        print('Running ',epochs,' epochs')
        for epoch in range(epochs):
            print('epoch:', epoch)
            # Shuffle the dataset
            # data[['X','y']].sample(frac = 1)
            perm = np.random.permutation(X_train.shape[0])
            np.take(X_train,perm,axis=0,out=X_train)
            np.take(y_train,perm,axis=0,out=y_train)
            # Training
            # For each mini-batch...
            for batch in range(TRAIN IMAGES // batch size):
                # Create a mini-batch of training data and labels
                X batch = X train[batch*batch size : batch*batch size + batch size,
        :]
                y_batch = y_train[batch*batch_size : batch*batch_size + batch_size]
                X batch = torch.tensor(X batch, dtype=torch.float32)
                y_batch = torch.tensor(y_batch, dtype=torch.float32)
                # Run the forward pass of the model to get a prediction and compute t
        he accuracy
                forward out = net.forward(X batch).detach().numpy()
                pred labels = np.argmax(forward out,axis=1)
                train accuracy[epoch] += sum(pred labels == np.asarray(y batch)) / ba
        tch_size
                # Run the backward pass of the model to compute the loss, and update
         the weights
                y batch for L = y batch.type(torch.LongTensor)
                loss = net.backward(X batch,y batch for L)
```

```
train_loss[epoch] += loss
    # normalize
    train_accuracy[epoch] /= (TRAIN_IMAGES // batch_size)
    train loss[epoch] /= (TRAIN IMAGES // batch size)
    # Validation
    # No need to run the backward pass here, just run the forward pass to com
pute accuracy
    X val = torch.tensor(X val, dtype=torch.float32)
    val forward out = net.forward(X val).detach().numpy()
    val_pred_labels = np.argmax(val_forward_out,axis=1)
    val_accuracy[epoch] += sum(val_pred_labels == np.asarray(y_val)) / len(y_
val)
    net.epoch += 1
print('Done. Time:',time.time()-start time)
Running 15 epochs
epoch: 0
epoch: 1
<ipython-input-9-5650785be3ea>:61: UserWarning: To copy construct from a tens
or, it is recommended to use sourceTensor.clone().detach() or sourceTensor.cl
one().detach().requires_grad_(True), rather than torch.tensor(sourceTensor).
 X_val = torch.tensor(X_val, dtype=torch.float32)
epoch: 2
epoch: 3
epoch: 4
epoch: 5
epoch: 6
epoch: 7
epoch: 8
epoch: 9
epoch: 10
epoch: 11
epoch: 12
epoch: 13
epoch: 14
Done. Time: 2302.406450033188
```

Graph loss and train/val accuracies

```
In [22]:
         print('train_accuracy[-1]:',train_accuracy[-1])
         print('val_accuracy[-1]: ',val_accuracy[-1])
         # Plot the loss function and train / validation accuracies
         plt.subplot(2, 1, 1)
         plt.plot(train_loss)
         # plt.plot(train loss[:49])
         plt.title('Loss history')
         plt.xlabel('Epoch')
         plt.ylabel('Loss')
         plt.subplot(2, 1, 2)
         plt.plot(train_accuracy, label='train')
         plt.plot(val accuracy, label='val')
         # plt.plot(train accuracy[:49], label='train')
         # plt.plot(val_accuracy[:49], label='val')
         plt.title('Classification accuracy history')
         plt.xlabel('Epoch')
         plt.ylabel('Classification accuracy')
         plt.legend()
         plt.tight layout()
         # plt.savefig('loss acc trad 5epoch.jpg',dpi=1000)
         plt.show()
```

train_accuracy[-1]: 0.39654
val_accuracy[-1]: 0.3929



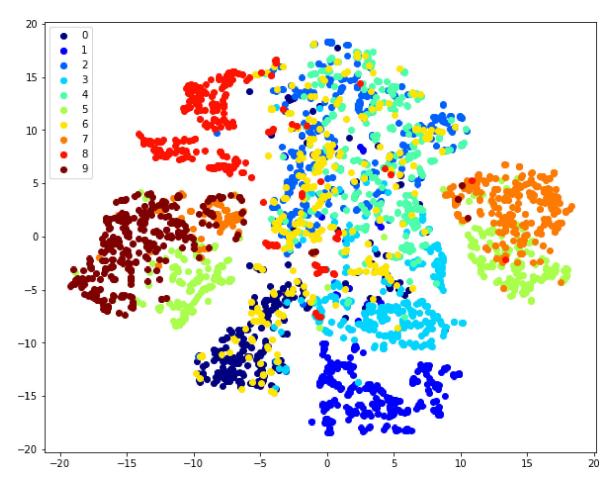
Run on Test Set, Visualize Features

```
In [24]:
         from sklearn.manifold import TSNE
         # # TSNE
In [25]:
         # https://www.jmlr.org/papers/volume9/vandermaaten08a/vandermaaten08a.pdf
         # https://builtin.com/data-science/tsne-python
In [26]:
         # run test set
         out = net(X test)
         pred = np.argmax(out.detach().numpy(),axis=1)
         print('Accuracy:', sum(pred == np.asarray(y_test)) / len(y_test) )
         # Look at output of layer
         data = activation['pre_fc']
         labels = y_test
         # np.save('data_prefc_trad_5epoch.npy',data)
         np.save('data_prefc_trad_15epoch.npy',data)
         print(data.shape)
         # print(data[0])
         Accuracy: 0.3946
         torch.Size([10000, 64, 12, 12])
In [15]:
         # choose random subset of points to visualize
         num data vis = 3000 # 50 #10
         np.random.seed(42) # For reproducability
         rndperm = np.random.permutation(data.shape[0])[:num data vis]
         data_sel = data[rndperm, :].reshape(num_data_vis,-1)
         labels sel = labels[rndperm]
         print(data_sel.shape, labels_sel.shape)
         torch.Size([3000, 9216]) (3000,)
```

```
In [16]:
         time start = time.time()
         # # could increase perplexity and n iter
         tsne = TSNE(n components=2, verbose=1, perplexity=15, n iter=300)
         tsne results = tsne.fit transform(data sel)
         print('tsne_results.shape',tsne_results.shape)
         print('t-SNE done. Time elapsed: {} seconds'.format(time.time()-time start))
         # Time:: 50: <1, 3000: 2.3sec
         /home/james/.local/lib/python3.8/site-packages/sklearn/manifold/_t_sne.py:80
         0: FutureWarning: The default initialization in TSNE will change from 'rando
         m' to 'pca' in 1.2.
           warnings.warn(
         /home/james/.local/lib/python3.8/site-packages/sklearn/manifold/ t sne.py:81
         0: FutureWarning: The default learning rate in TSNE will change from 200.0 to
         'auto' in 1.2.
           warnings.warn(
         [t-SNE] Computing 46 nearest neighbors...
         [t-SNE] Indexed 3000 samples in 0.012s...
         [t-SNE] Computed neighbors for 3000 samples in 3.373s...
         [t-SNE] Computed conditional probabilities for sample 1000 / 3000
         [t-SNE] Computed conditional probabilities for sample 2000 / 3000
         [t-SNE] Computed conditional probabilities for sample 3000 / 3000
         [t-SNE] Mean sigma: 227.572190
         [t-SNE] KL divergence after 250 iterations with early exaggeration: 76.364975
         [t-SNE] KL divergence after 300 iterations: 1.877447
         tsne results.shape (3000, 2)
         t-SNE done. Time elapsed: 5.886410713195801 seconds
```

```
In [17]:
         # display results
         x_plot = tsne_results[:,0]
         y_plot = tsne_results[:,1]
         # https://stackoverflow.com/questions/42056713/matplotlib-scatterplot-with-le
         gend
         unique = list(set(labels_sel))
         print(unique)
         colors = [plt.cm.jet(float(i)/max(unique)) for i in unique]
         for i, u in enumerate(unique):
             xi = [x_plot[j] for j in range(len(x_plot)) if labels_sel[j] == u]
             yi = [y_plot[j] for j in range(len(y_plot)) if labels_sel[j] == u]
             plt.scatter(xi, yi, color=colors[i], label=str(u))
         plt.legend()
         # plt.savefig('Simple_model_vis_fc2.jpg',dpi=1000)
         # plt.savefig('vis_trad_5epoch.jpg',dpi=1000)
         plt.savefig('vis_trad_15epoch.jpg',dpi=1000)
```

[0, 1, 2, 3, 4, 5, 6, 7, 8, 9]



Compare Reg Model and SIFT model

Create graphs to compare training loss and validation accuracy

```
In [18]:
         # # TODO
In [19]:
         # create new model
         # incorporate this sift descriptor written in pytorch
         # it is written on apu though so idk, to work out
         # https://github.com/hmorimitsu/sift-flow-gpu
In [20]:
         # train new model
         # test on test set
In [21]: # compare classifications
         # # Plot the loss function and train / validation accuracies
         # plt.subplot(2, 1, 1)
         # # print(train loss)
         # plt.plot(train loss, label='SGD')
         # plt.plot(train loss adam, label='Adam')
         # # plt.plot(train_loss[:49])
         # plt.title('Loss history')
         # plt.xlabel('Epoch')
         # plt.ylabel('Loss')
         # plt.legend()
         # plt.subplot(2, 1, 2)
         # plt.plot(train_accuracy, label='train SGD')
         # plt.plot(val accuracy, label='val SGD')
         # plt.plot(train accuracy adam, label='train Adam')
         # plt.plot(val_accuracy_adam, label='val Adam')
         # # plt.plot(train accuracy[:49], label='train')
         # # plt.plot(val_accuracy[:49], label='val')
         # plt.title('Classification accuracy history')
         # plt.xlabel('Epoch')
         # plt.ylabel('Classification accuracy')
         # plt.legend()
         # plt.tight_layout()
         # plt.show()
```