

CS2040S

Data Structures and Algorithms

(e-learning edition)

All about minimum spanning trees...

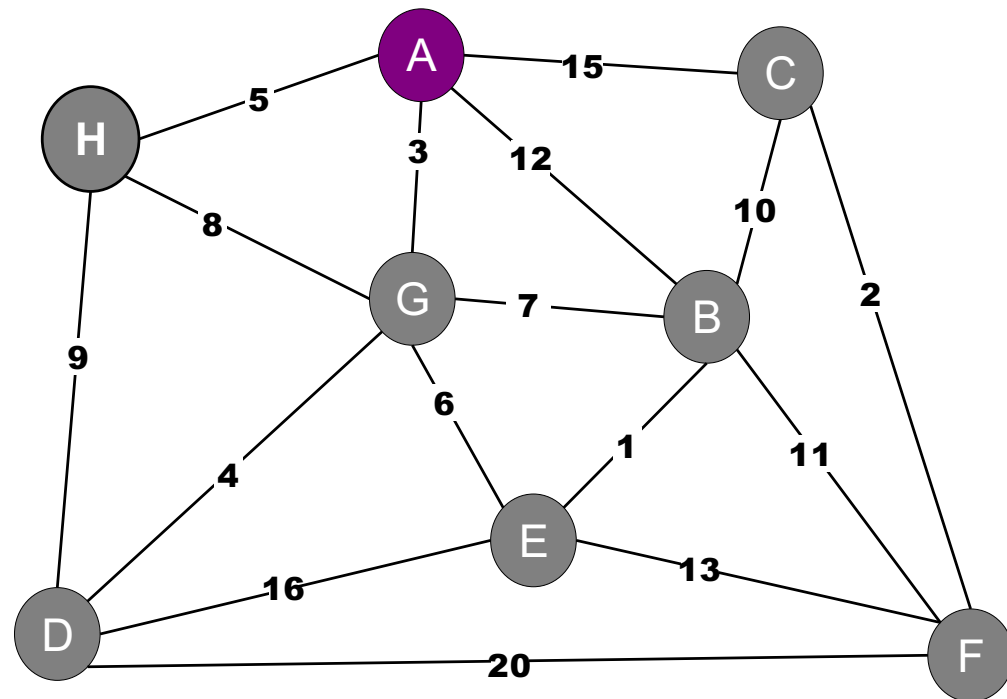
Roadmap

Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- **Prim's Algorithm**
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

Prim's Algorithm

Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)

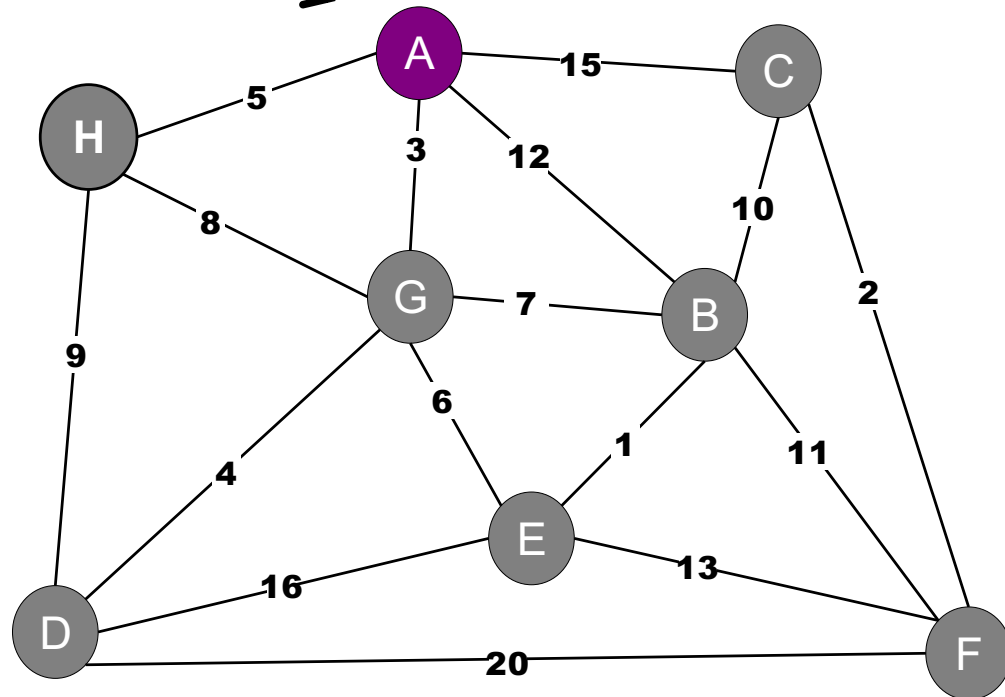


Prim's Algorithm

Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)

Basic idea:

- S : set of nodes connected by blue edges.
- Initially: $S = \{A\}$

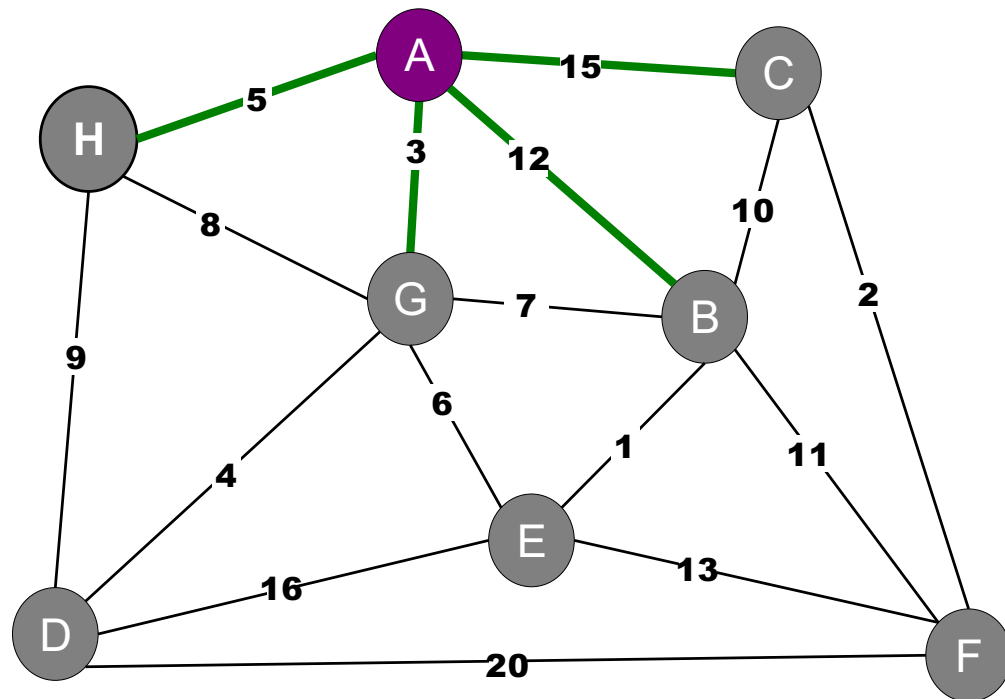


Prim's Algorithm

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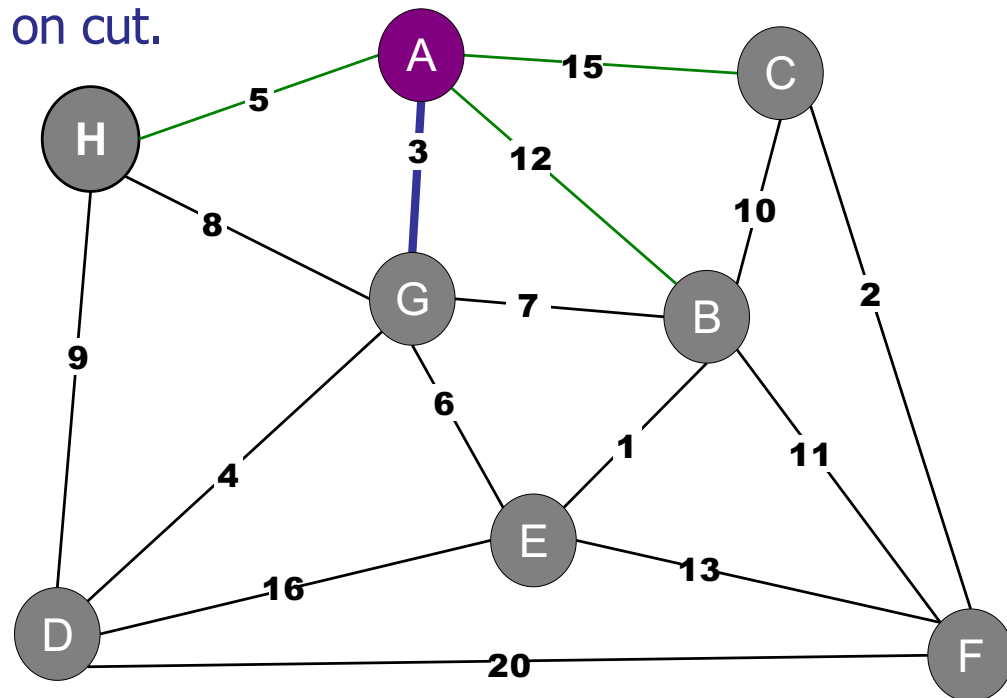


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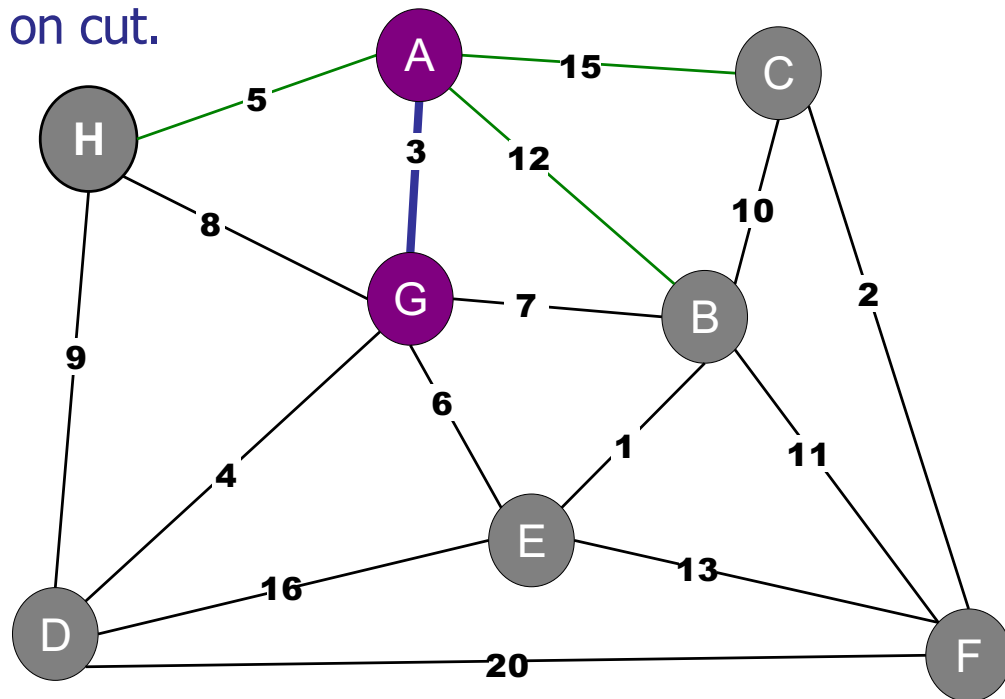


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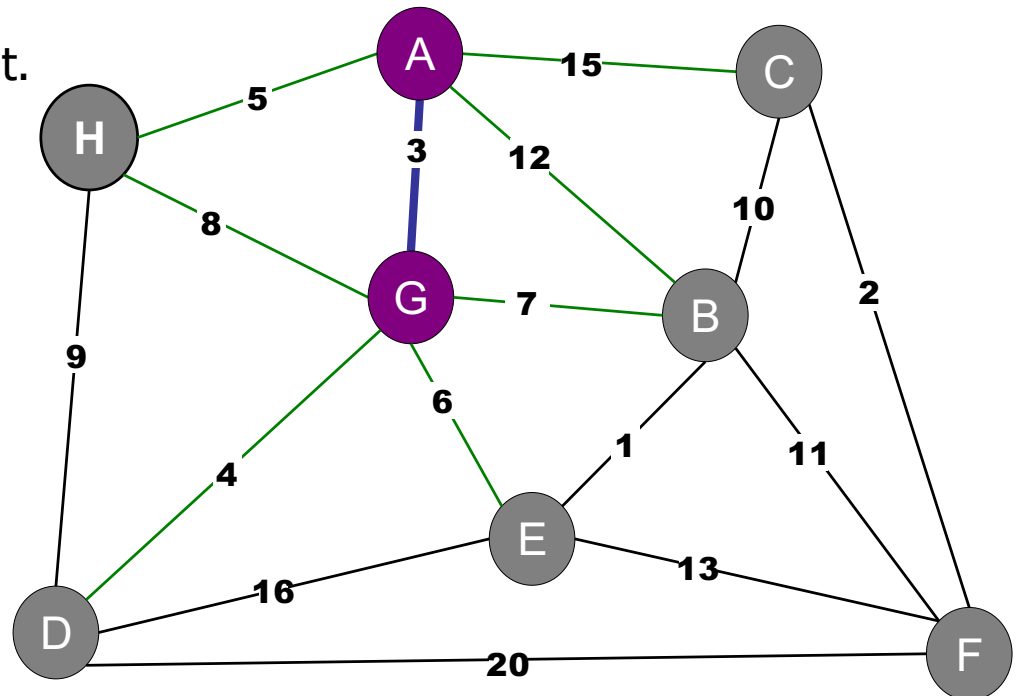


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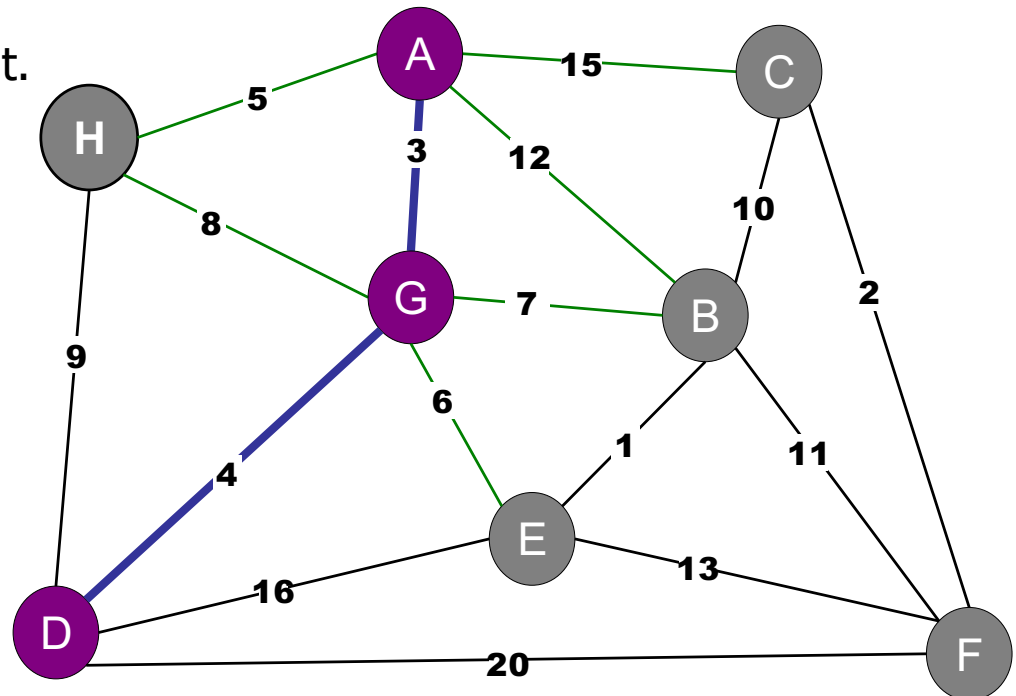


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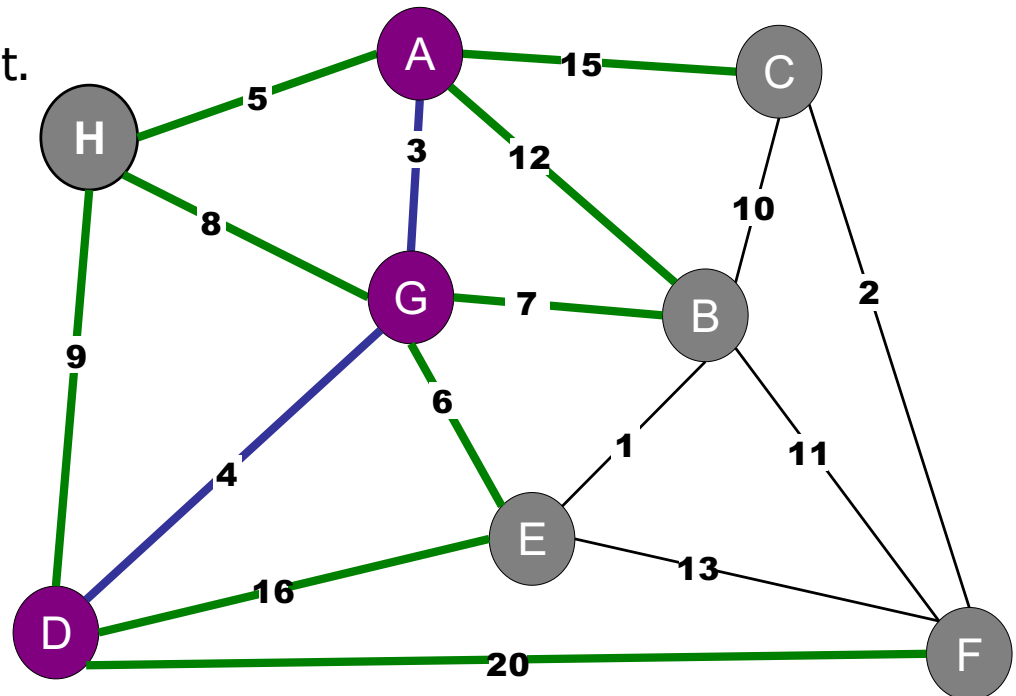


Prim's Algorithm

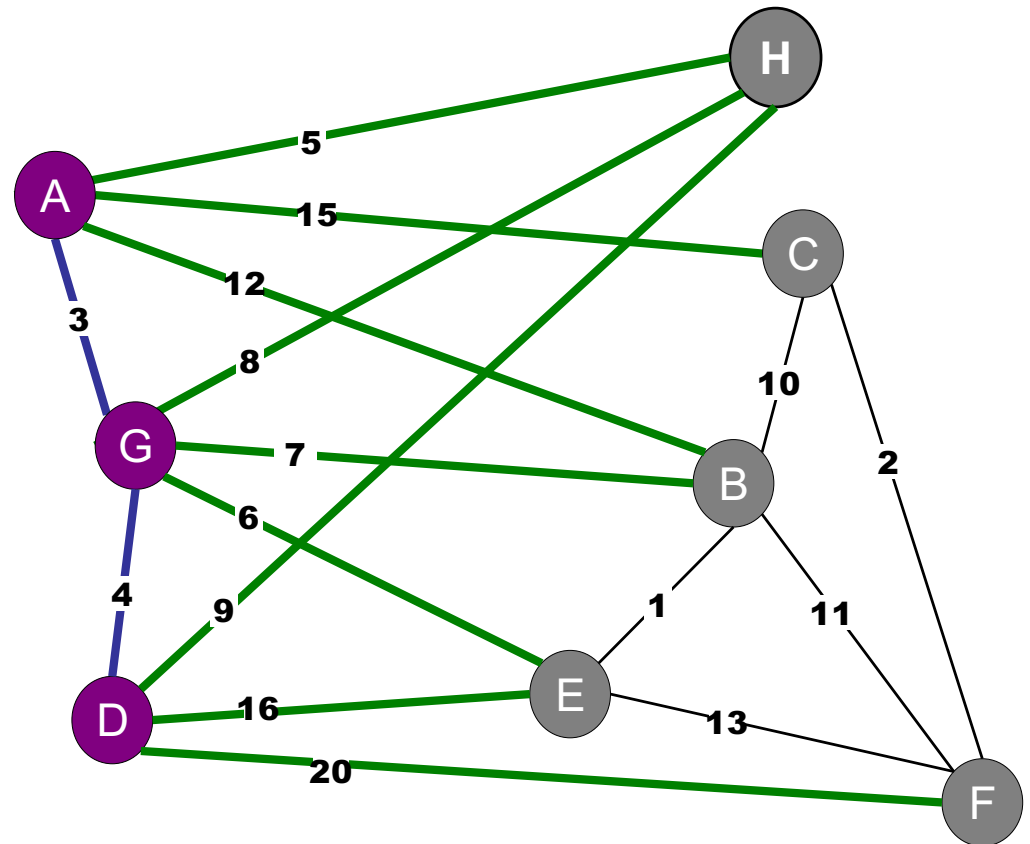
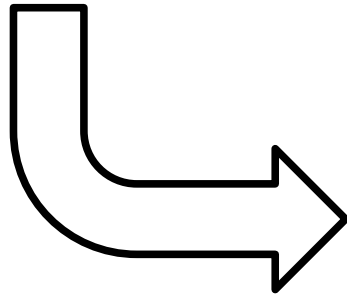
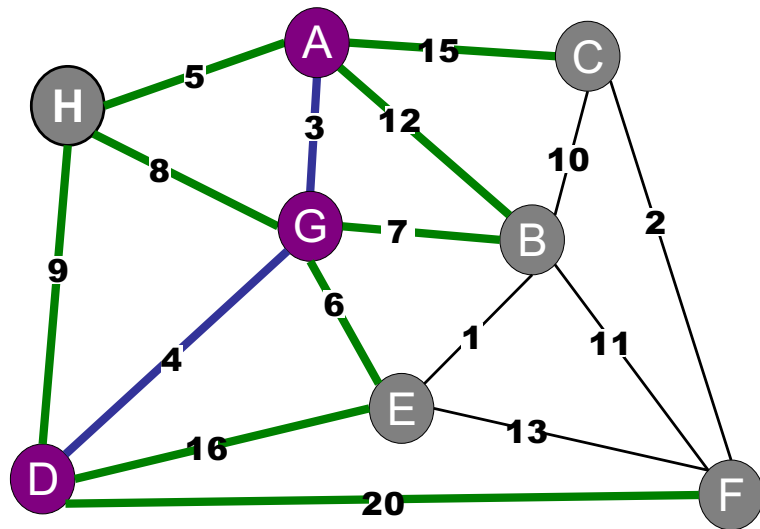
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Prim's Algorithm



How do we find the lightest edge on a cut?

- ✓ 1. Priority Queue
- 2. Union-Find
- 3. Max-flow / Min-cut
- 4. BFS
- 5. DFS

Prim's Algorithm: Initialization

// Initialize priority queue

```
PriorityQueue pq = new PriorityQueue();
```

```
for (Node v : G.V()) {  
    pq.insert(v, INFTY);  
}
```

```
pq.decreaseKey(start, 0);
```

// Initialize set S

```
HashSet<Node> S = new HashSet<Node>();
```

```
S.put(start);
```

// Initialize parent hash table

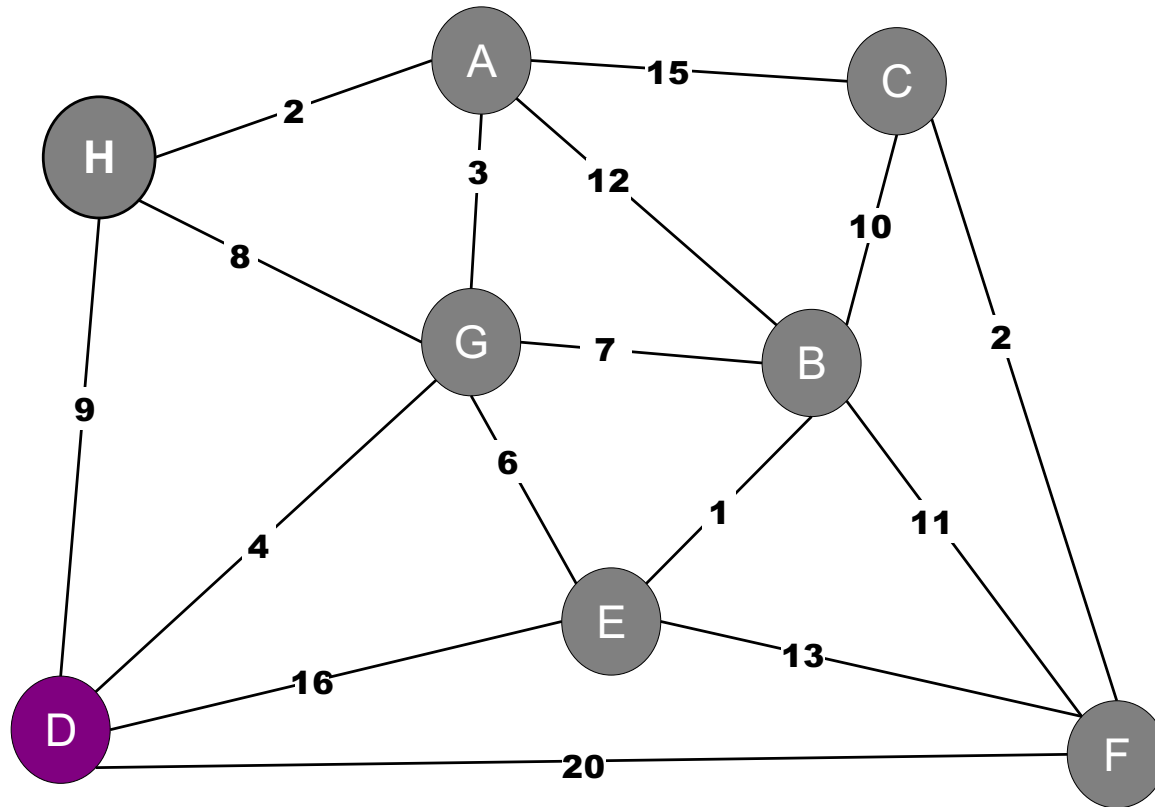
```
HashMap<Node, Node> parent = new HashMap<Node, Node>();
```

```
parent.put(start, null);
```

Prim's Algorithm

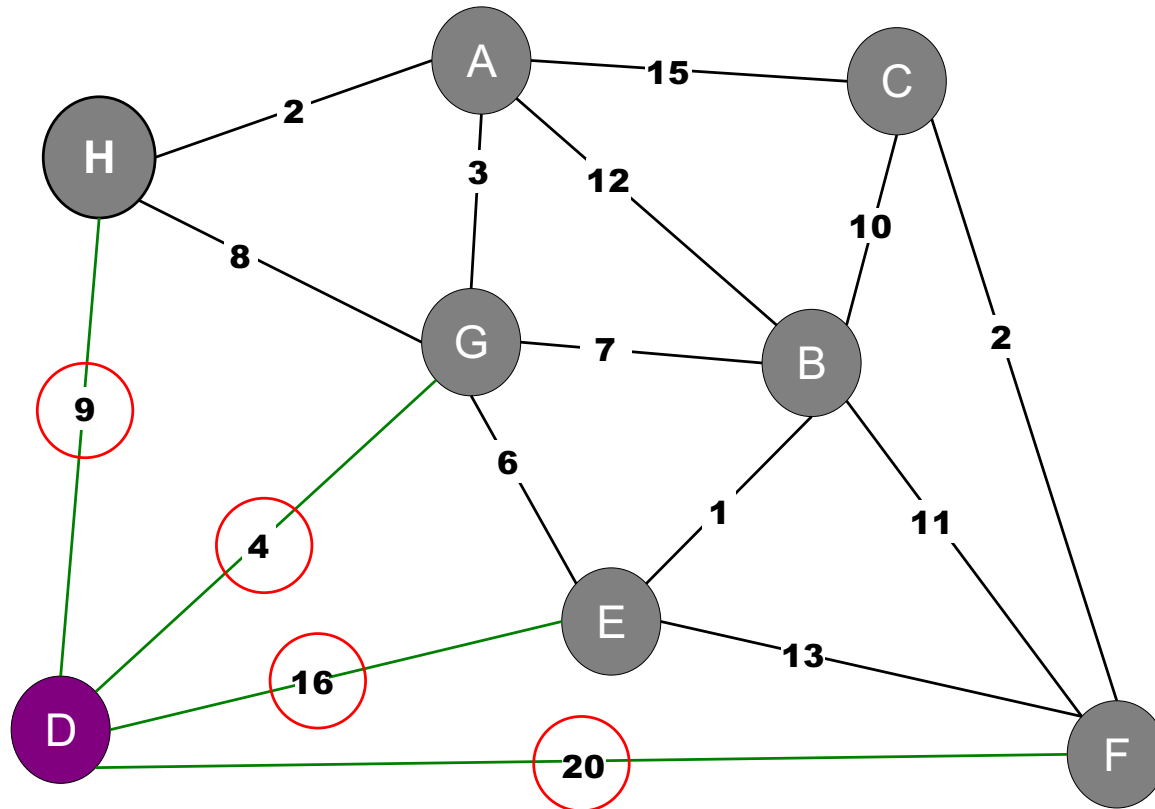
```
while (!pq.isEmpty()) {  
    Node v = pq.deleteMin();  
    S.put(v);  
    for each (Edge e : v.edgeList()) {  
        Node w = e.otherNode(v);  
        if (!S.get(w)) {  
            pq.decreaseKey(w, e.getWeight());  
            if wt parent.put(w, v);  
        } decreased  
    }  
}
```

Prim's Example



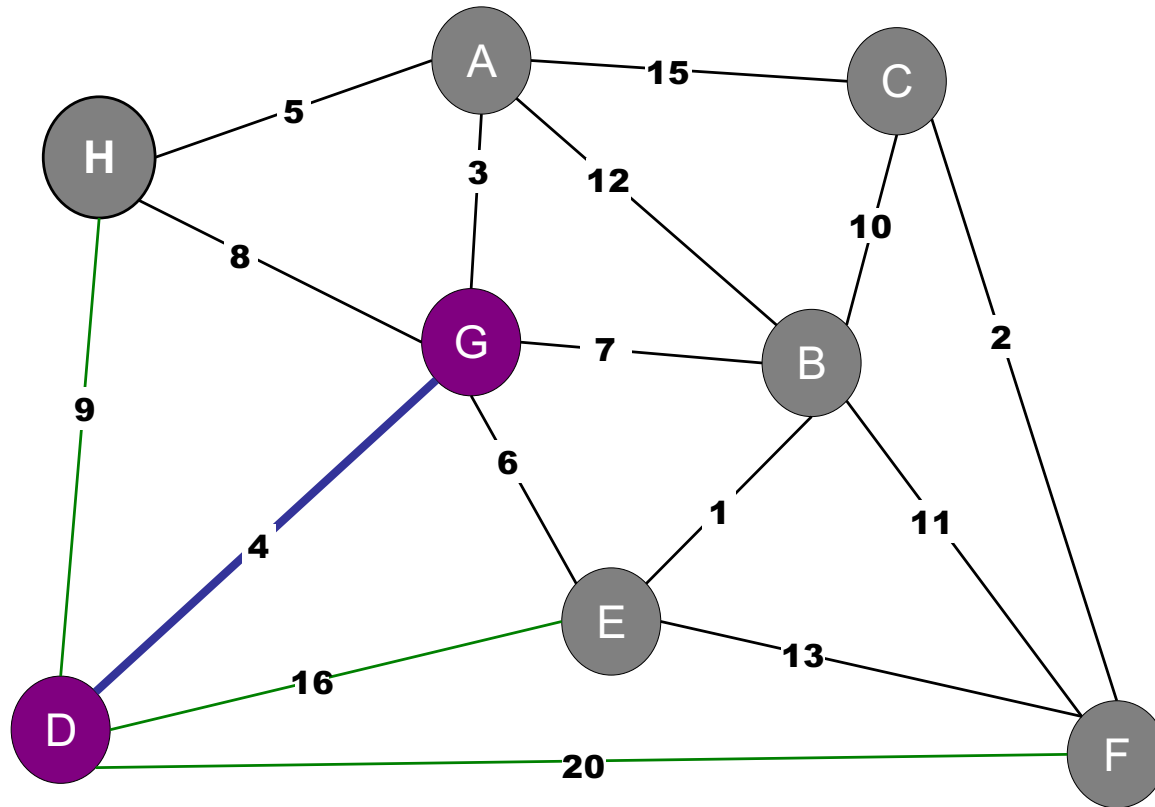
Vertex	Weight
D	0

Prim's Example



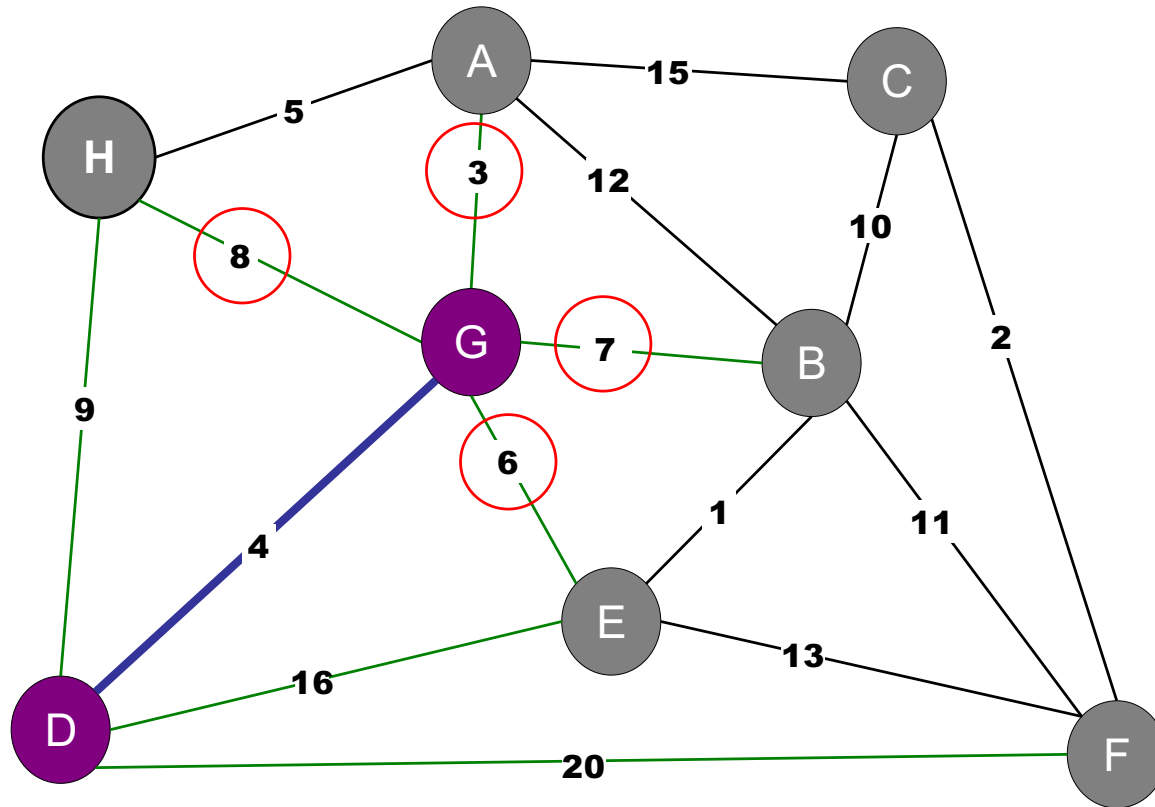
Vertex	Weight
G	4
H	9
E	16
F	20

Prim's Example



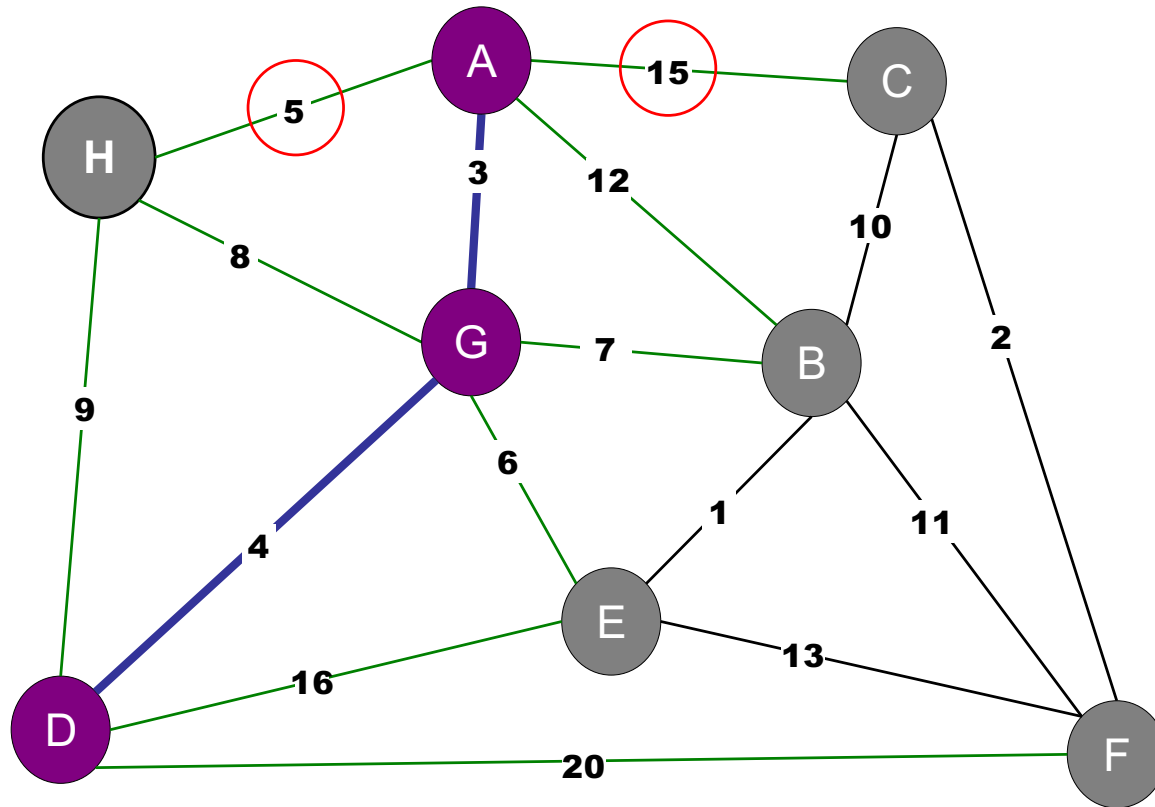
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Prim's Example



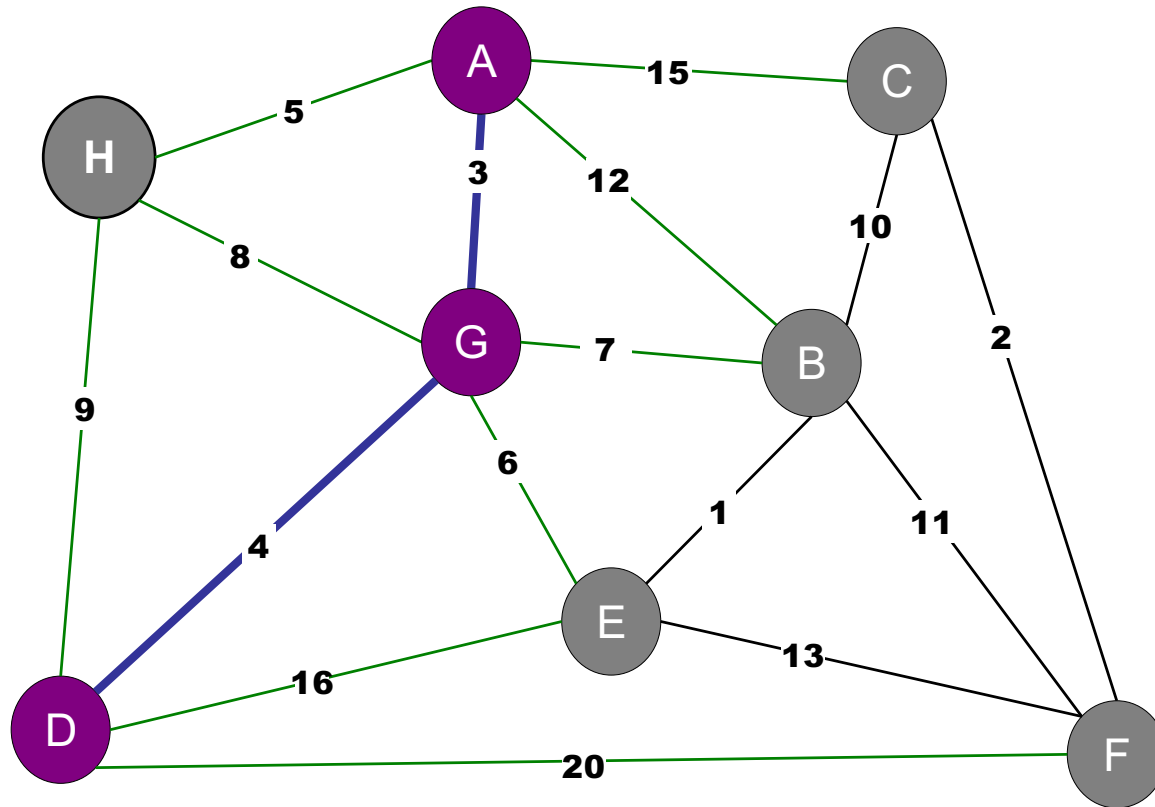
Vertex	Weight
A	3
E	16->6
B	7
H	9->8
F	20

Prim's Example



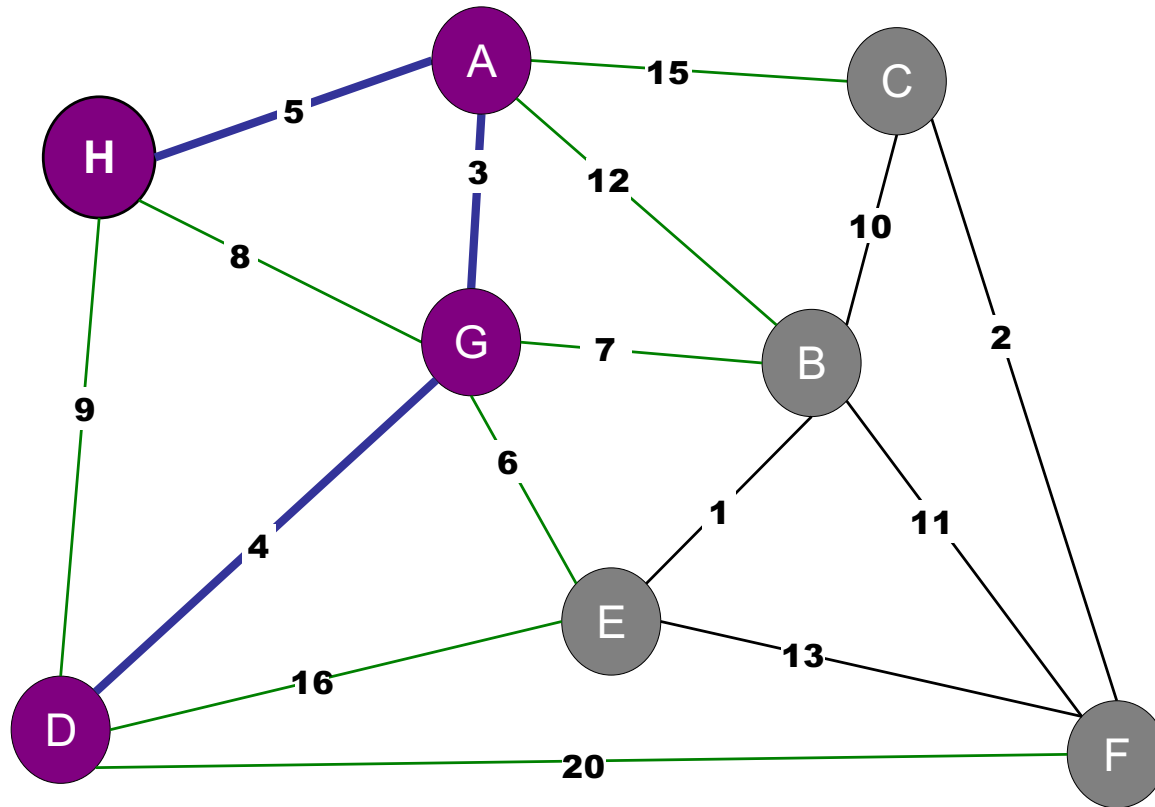
Vertex	Weight
H	8->5
E	6
B	7
C	15
F	20

Prim's Example



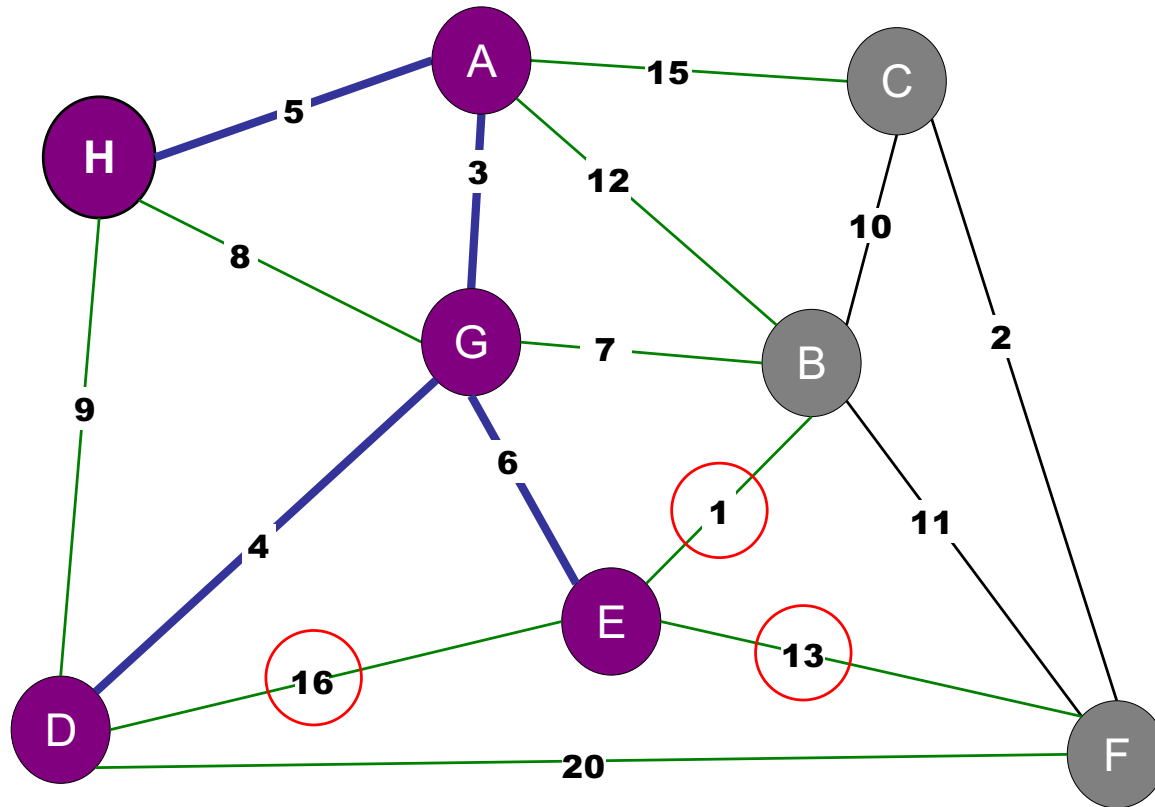
Vertex	Weight
H	5
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Prim's Example



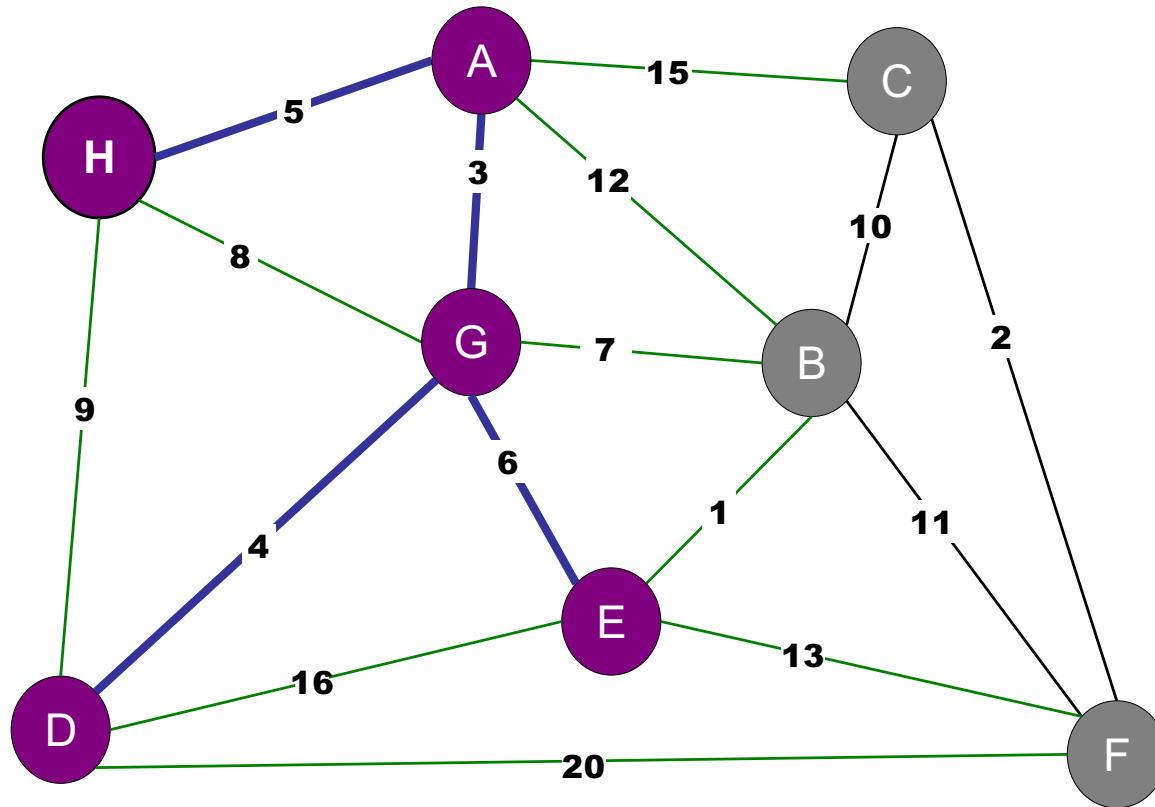
Vertex	Weight
E	6
B	7
C	15
F	20

Prim's Example



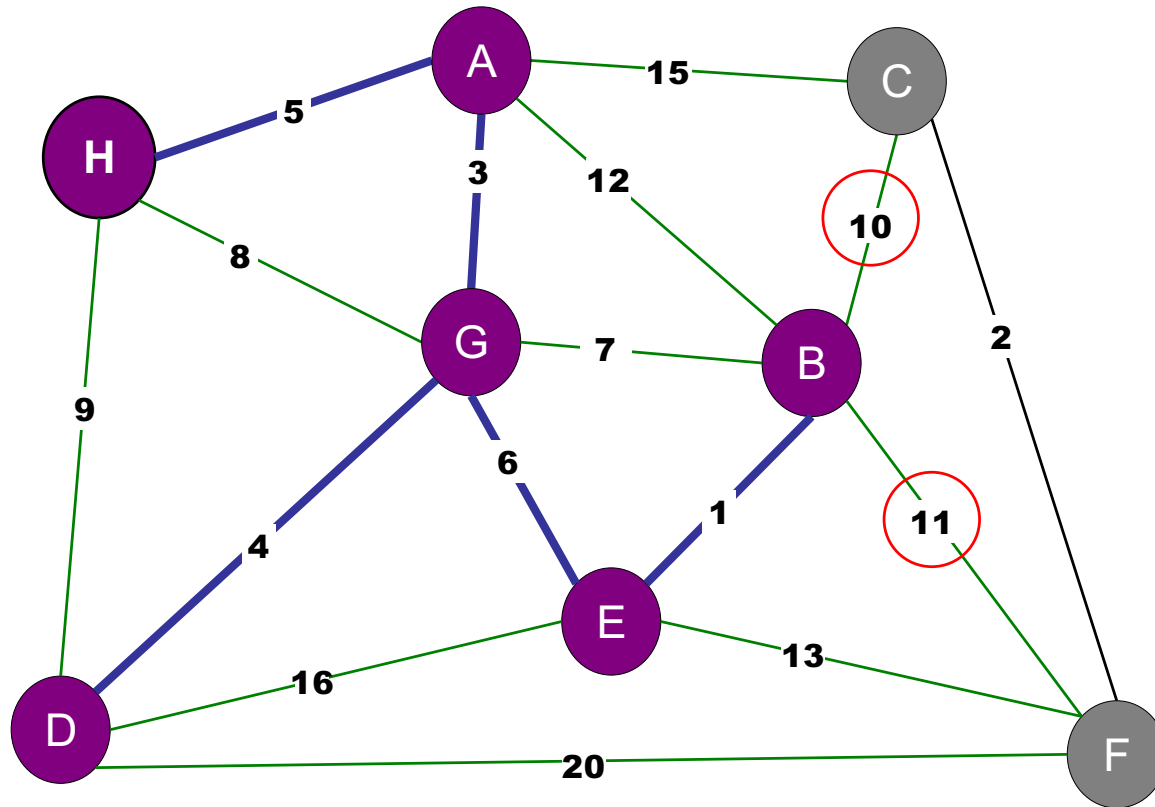
Vertex	Weight
B	7->1
C	15
F	20->13

Prim's Example



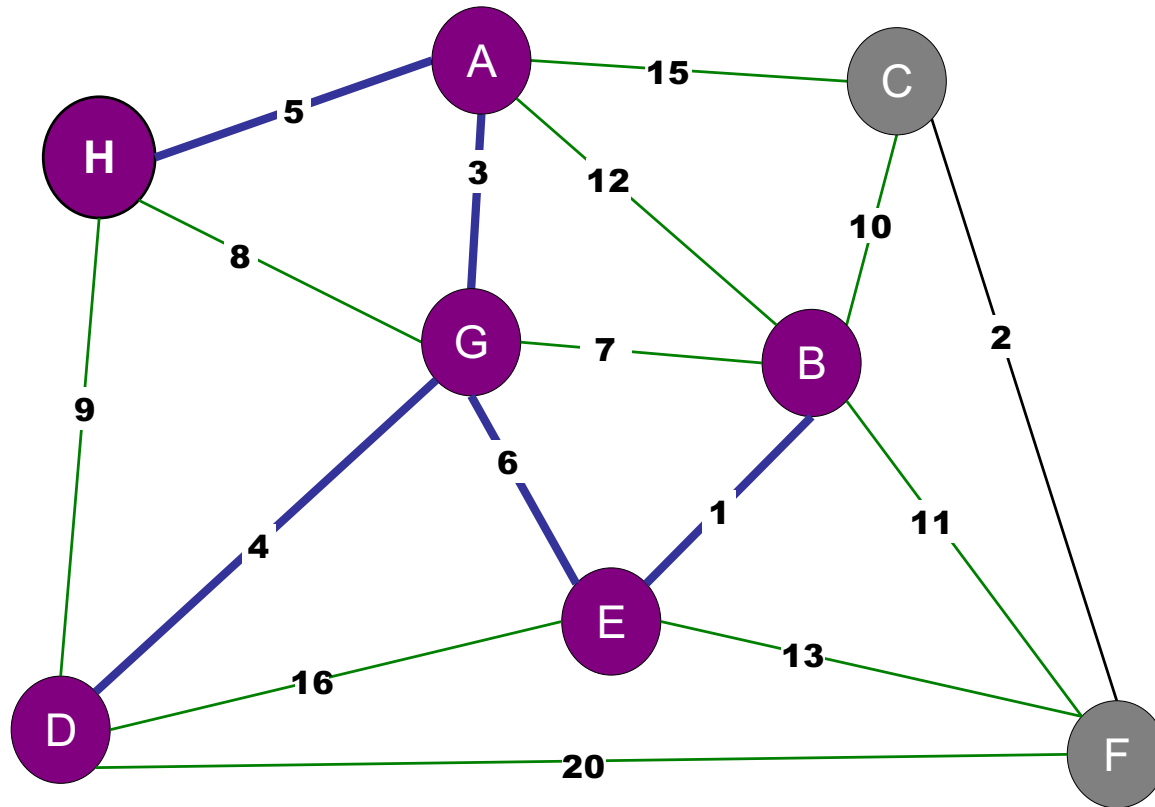
Vertex	Weight
B	1
C	15
F	13

Prim's Example



Vertex	Weight
C	15->10
F	13->11

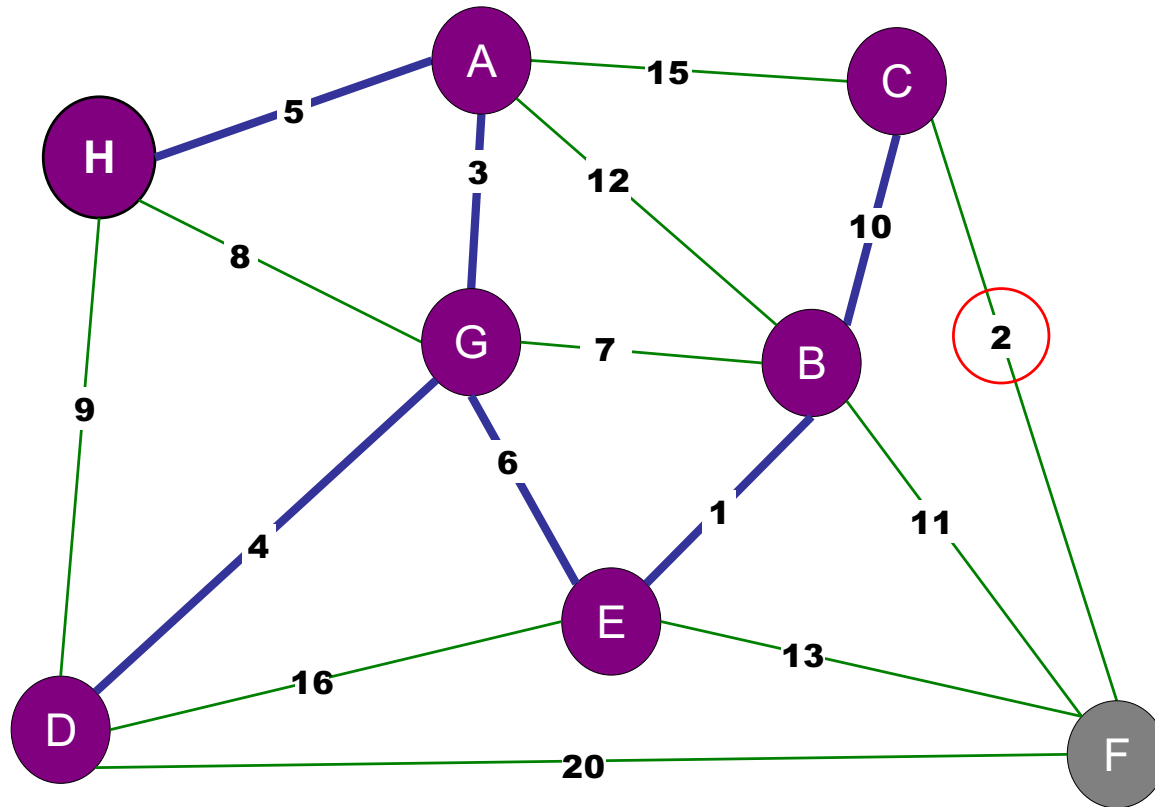
Prim's Example



Vertex	Weight
C	10
F	11

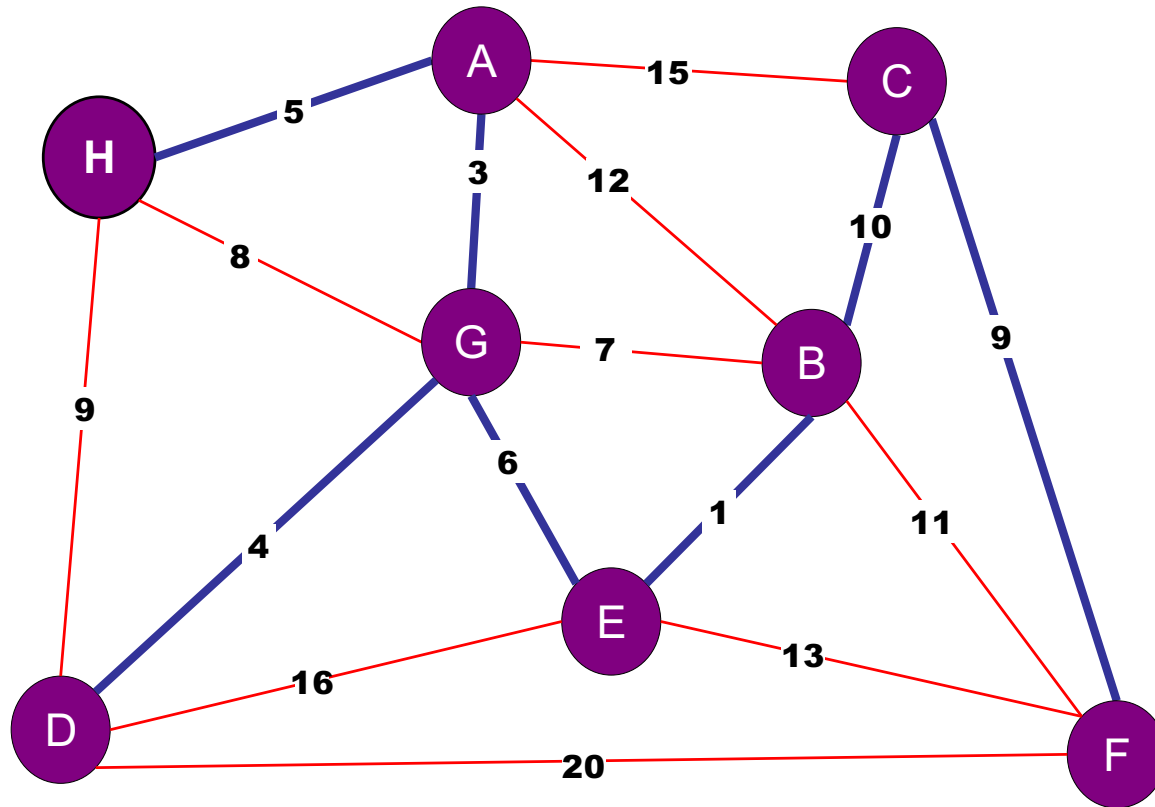
Prim's Example

Vertex	Weight
F	11->2

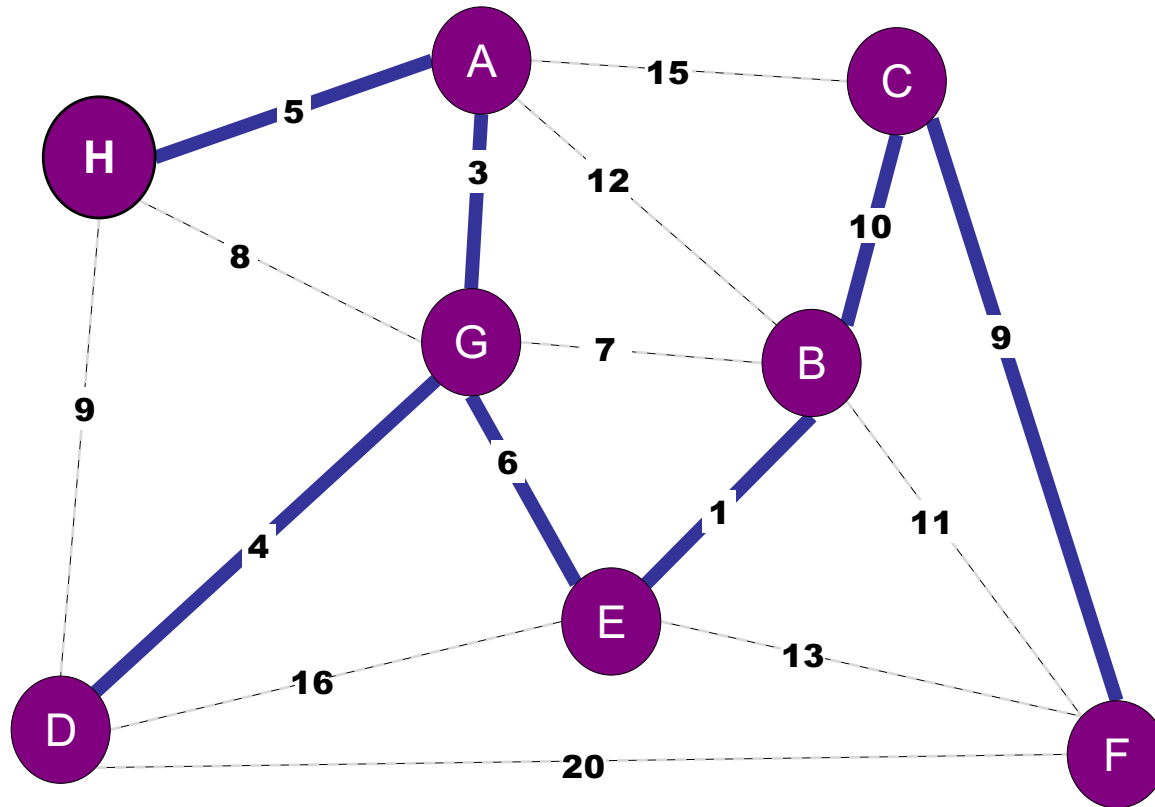


Prim's Example

Vertex	Weight



Vertex	Weight



Prim's Algorithm

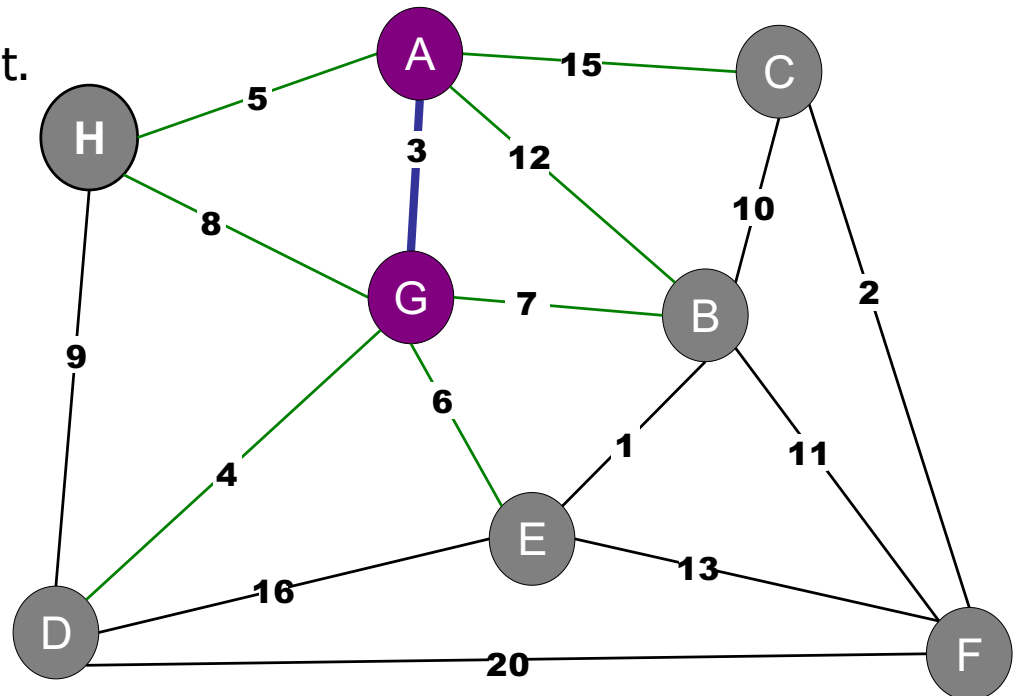
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- Repeat:
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 - Add new node to S .

Proof:

- Each added edge is the lightest on some cut.
- Hence each edge is in the MST.



What is the running time of Prim's Algorithm, using a binary heap?

1. $O(V)$
2. $O(E)$
-  3. $O(E \log V)$
4. $O(V \log E)$
5. $O(EV)$

Prim's Algorithm

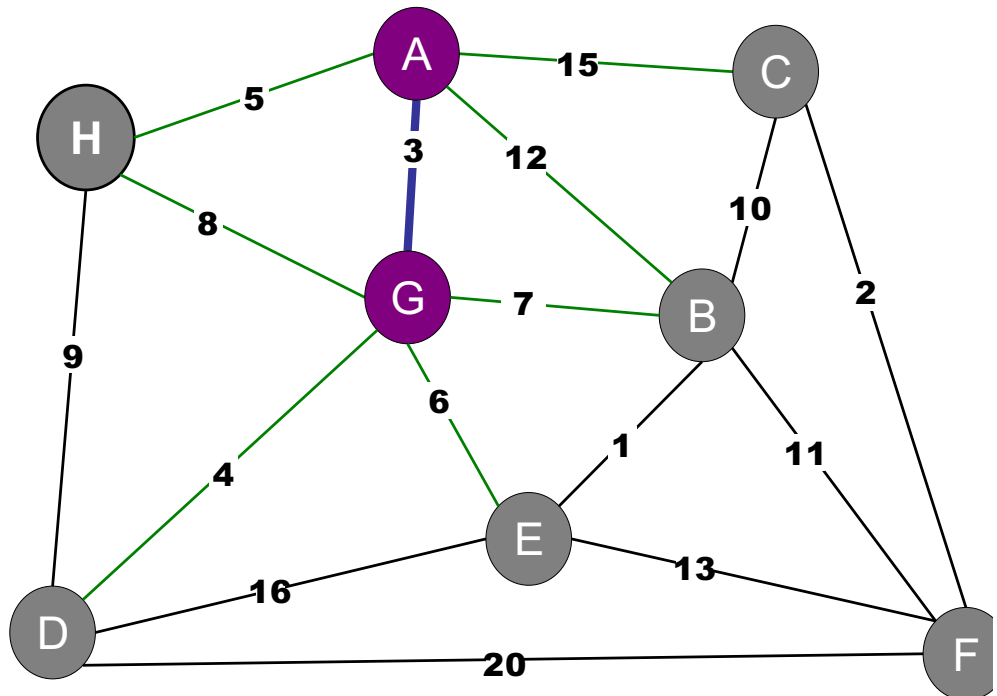
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Analysis:

- Each vertex added/removed once from the priority queue: $O(V \log V)$
- Each edge \Rightarrow one decreaseKey: $O(E \log V)$.



Two Algorithms

Prim's Algorithm.

Basic idea:

- Maintain a set of visited nodes.
- Greedily grow the set by adding node connected via the lightest edge.
- Use Priority Queue to order nodes by edge weight.

Dijkstra's Algorithm.

Basic idea:

- Maintain a set of visited nodes.
- Greedily grow the set by adding neighboring node that is closest to the source.
- Use Priority Queue to order nodes by distance.

Roadmap

Minimum Spanning Trees

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- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- **Kruskal's Algorithm**
- Boruvka's Algorithm
- Variations

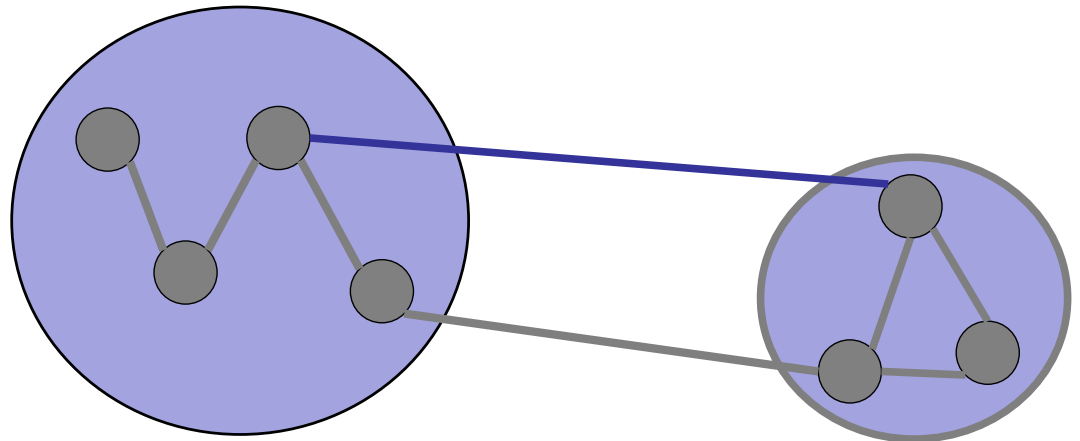
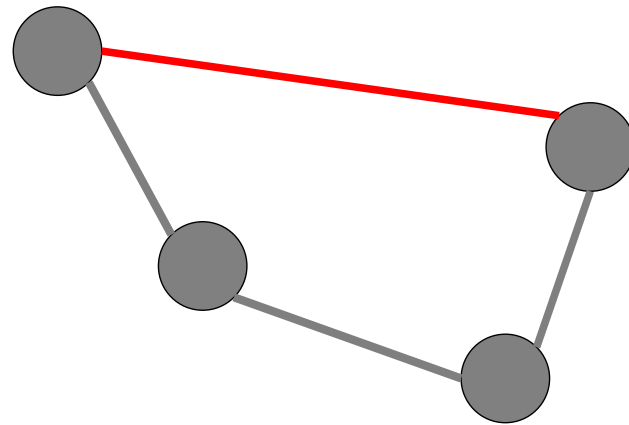
Generic MST Algorithm

Greedy Algorithm:

Repeat:

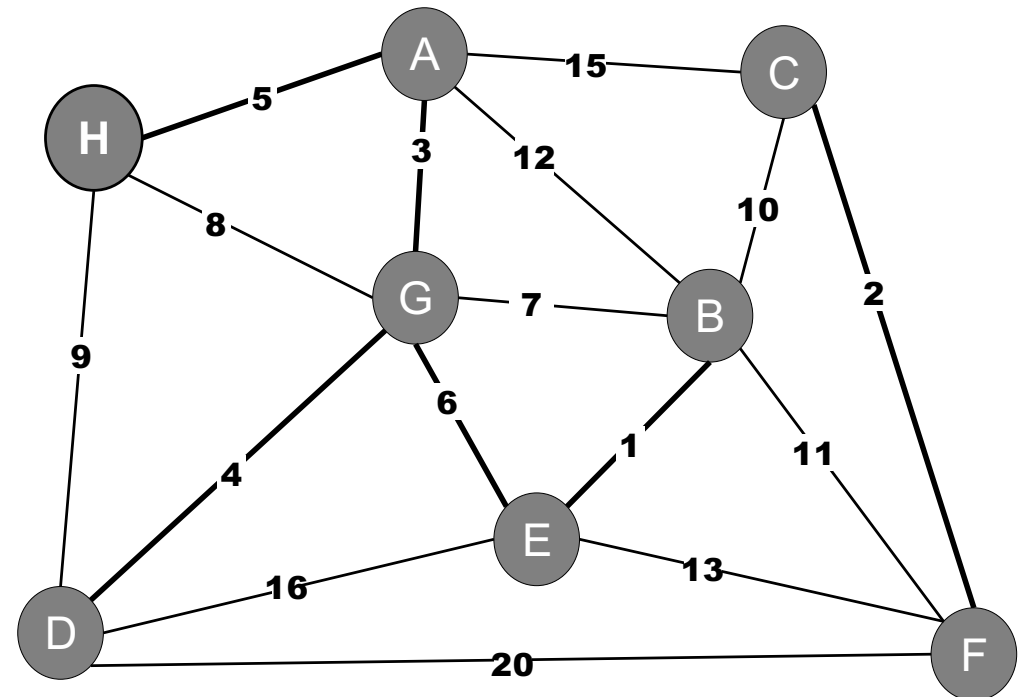
**Apply red rule or
blue rule to an
arbitrary edge.**

until no more edges
can be colored.



Kruskal's Algorithm

Kruskal's Algorithm. (Kruskal 1956)

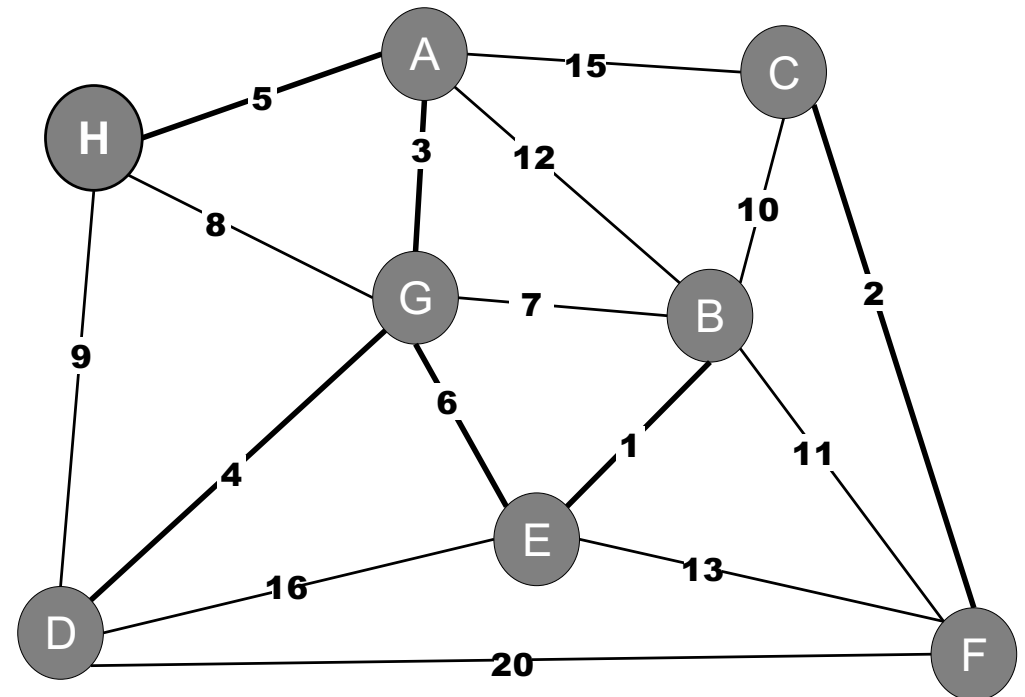


Kruskal's Algorithm

Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
 - If both endpoints are in the **same** blue tree, then color the edge red.
 - Otherwise, color the edge blue.

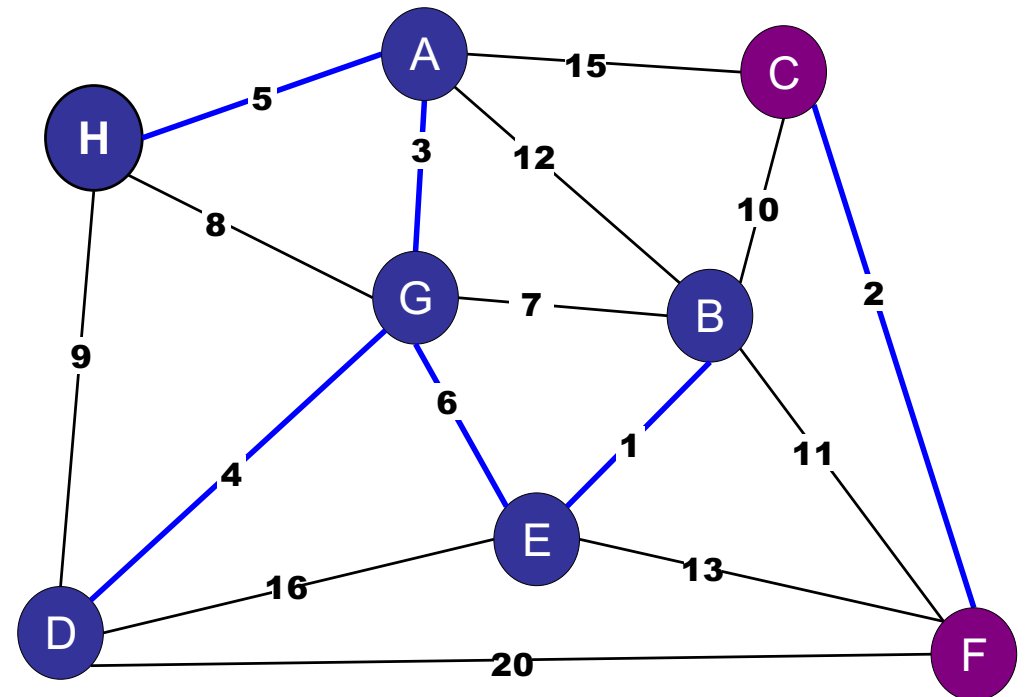


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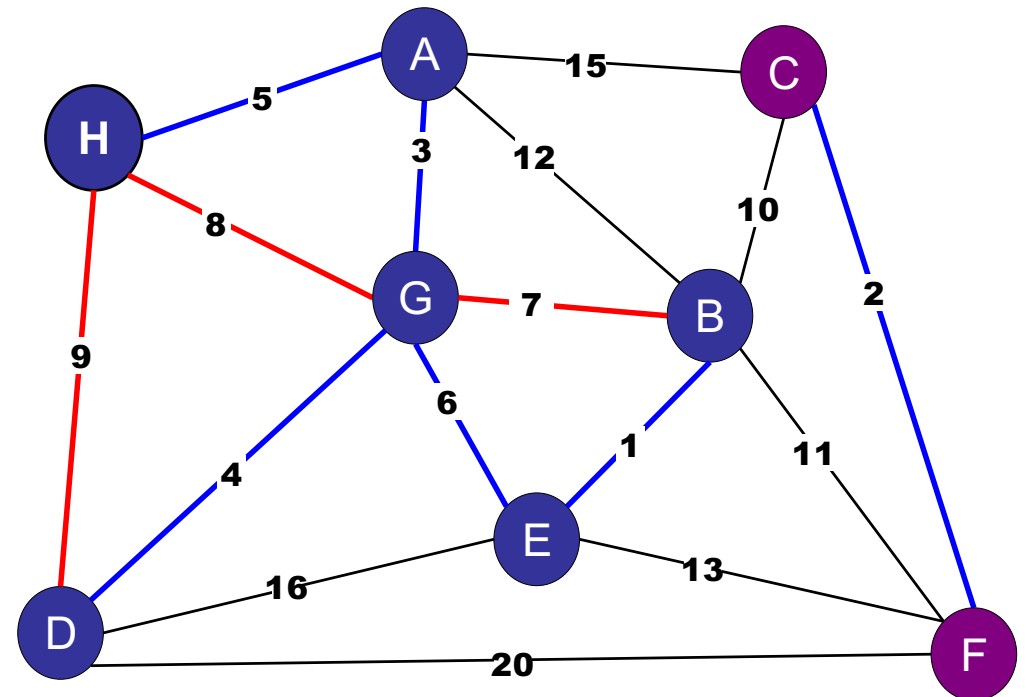


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Kruskal's Algorithm

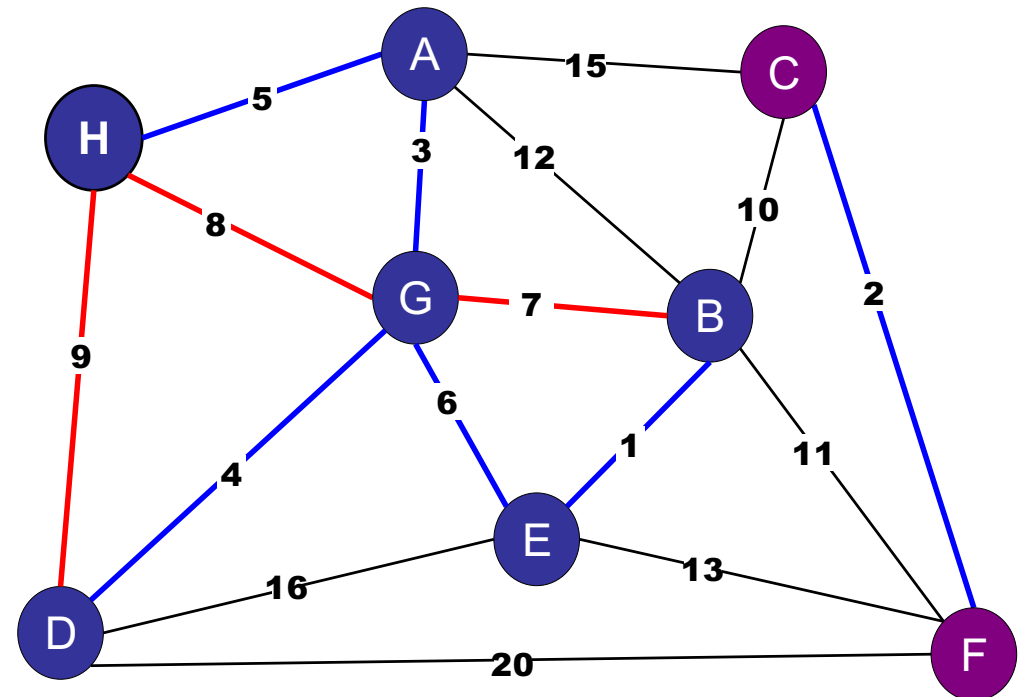
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Data structure:

- Union-Find
- Connect two nodes if they are in the same blue tree.



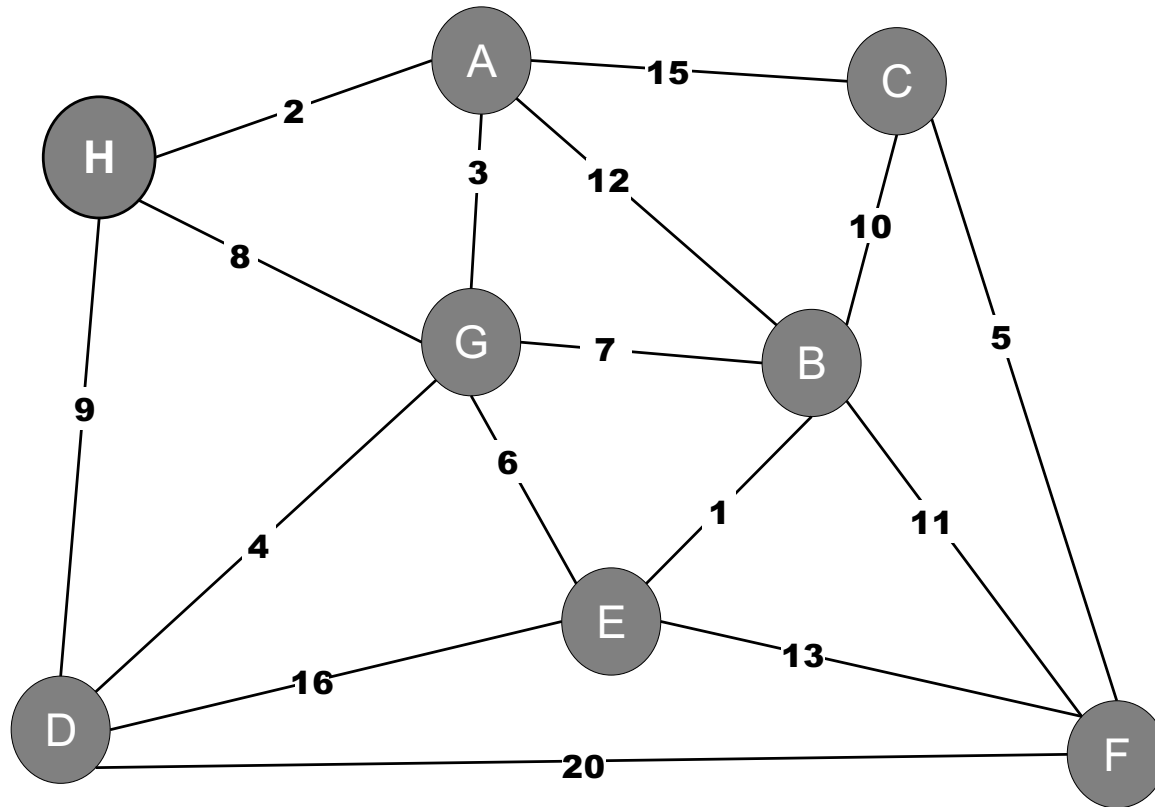
Kruskal's Algorithm

```
// Sort edges and initialize
Edge[] sortedEdges = sort(G.E());
ArrayList<Edge> mstEdges = new ArrayList<Edge>();
UnionFind uf = new UnionFind(G.V());

// Iterate through all the edges, in order
for (int i=0; i<sortedEdges.length; i++) {
    Edge e = sortedEdges[i]; // get edge
    Node v = e.one(); // get node endpoints
    Node w = e.two();

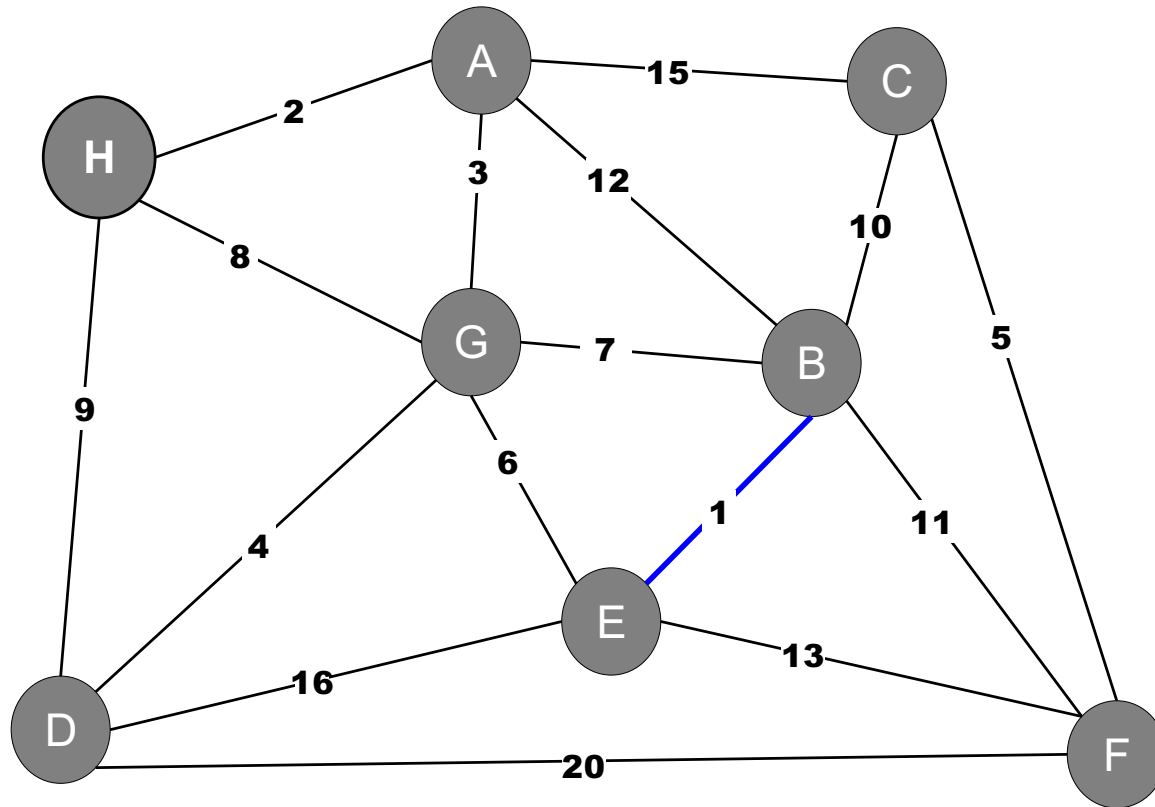
    if (!uf.find(v,w)) { // in the same tree?
        mstEdges.add(e); // save edge
        uf.union(v,w); // combine trees
    }
}
```


Kruskal's Example



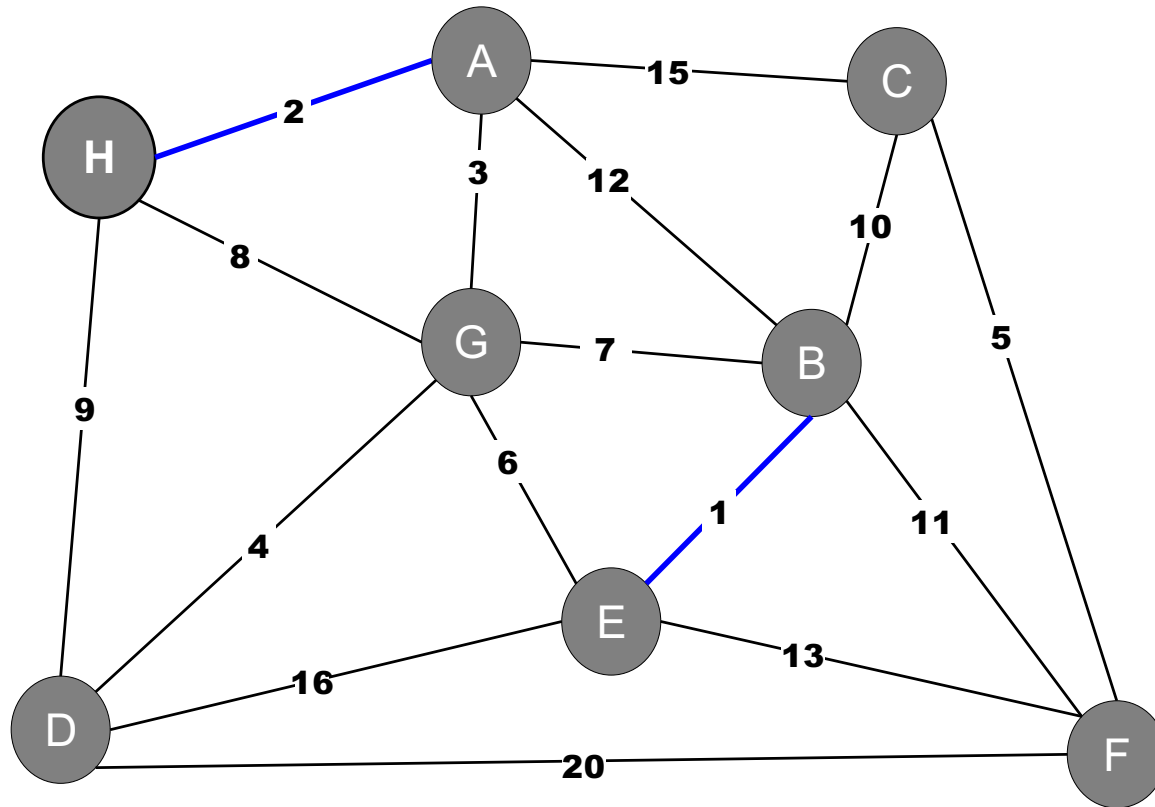
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
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Kruskal's Example



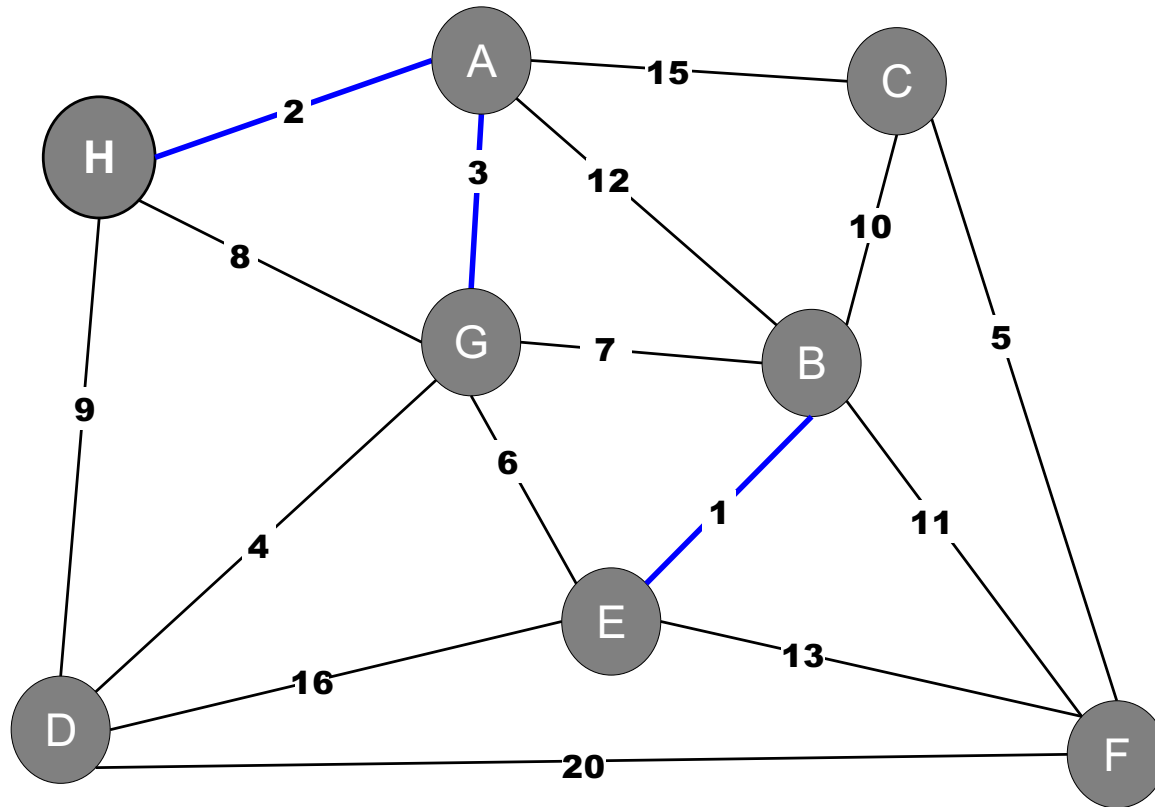
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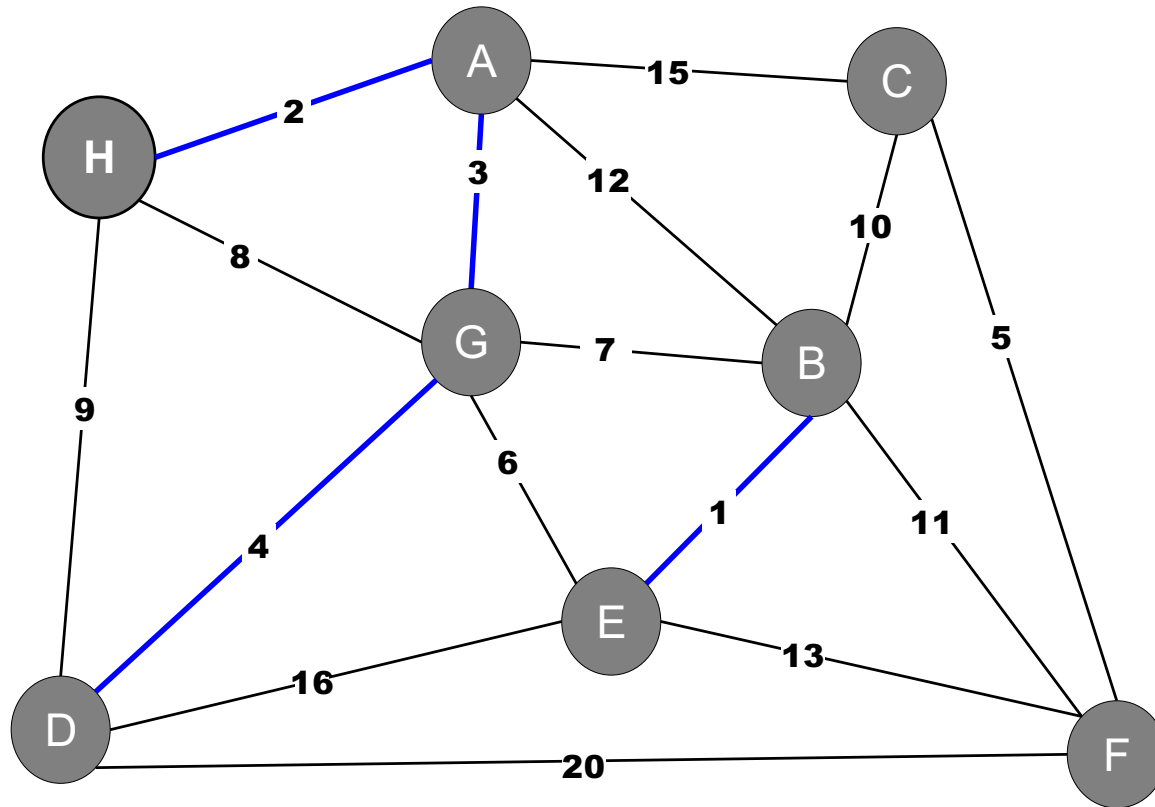
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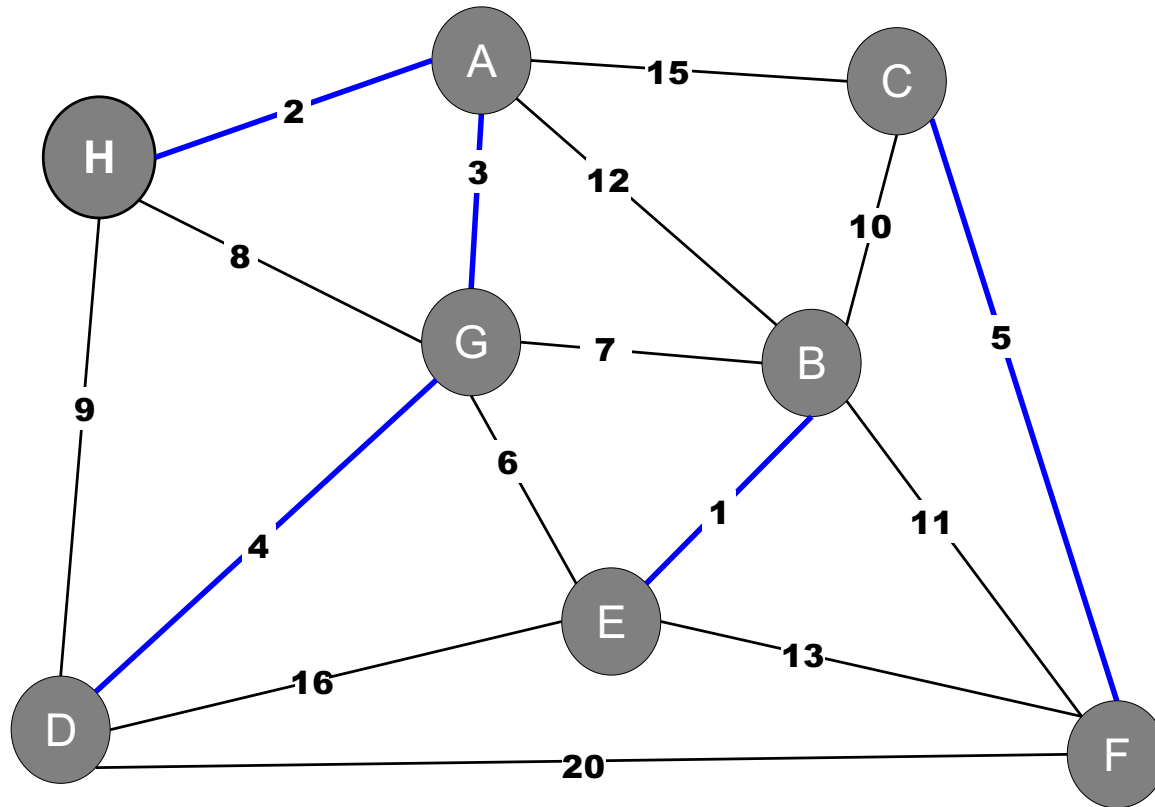
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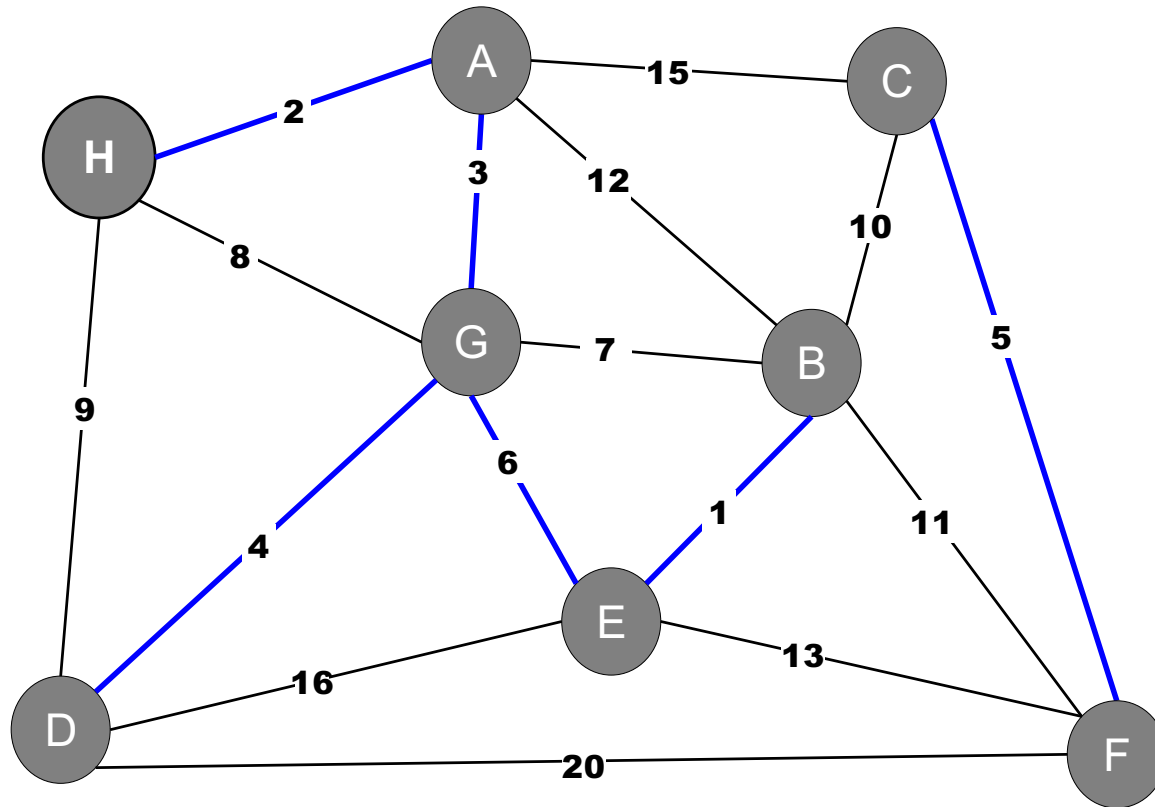
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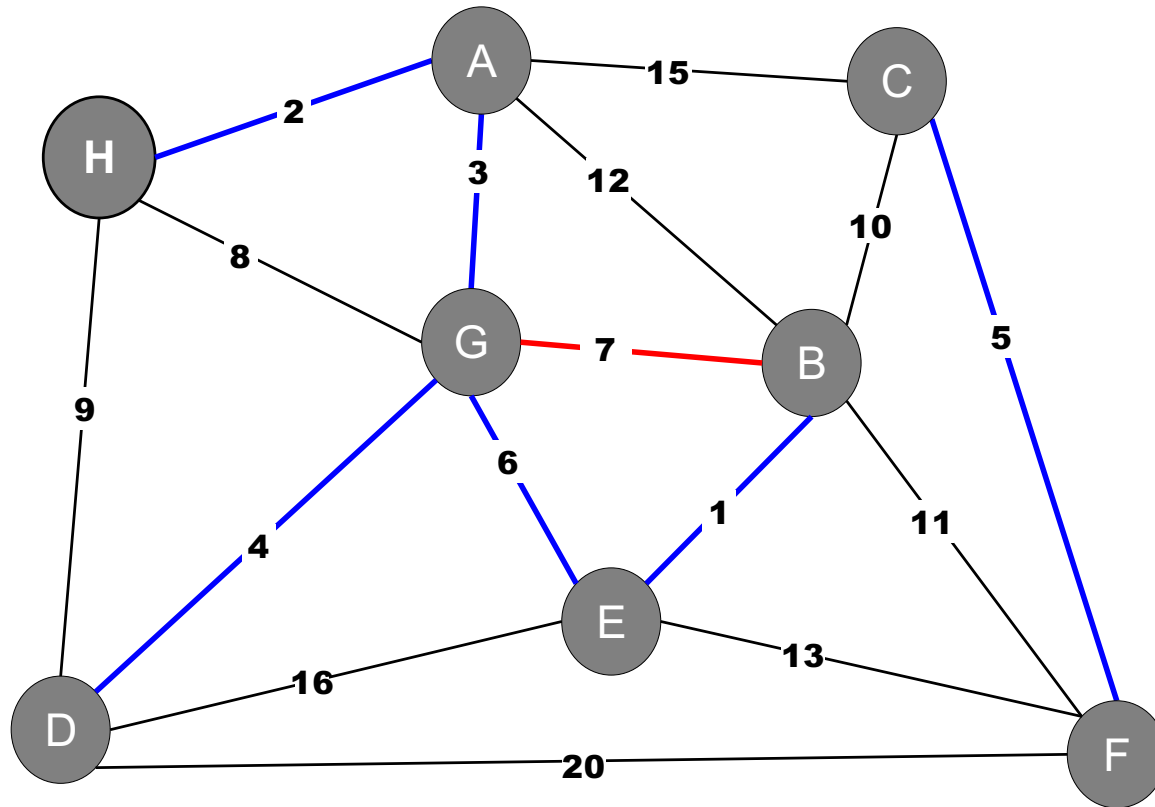
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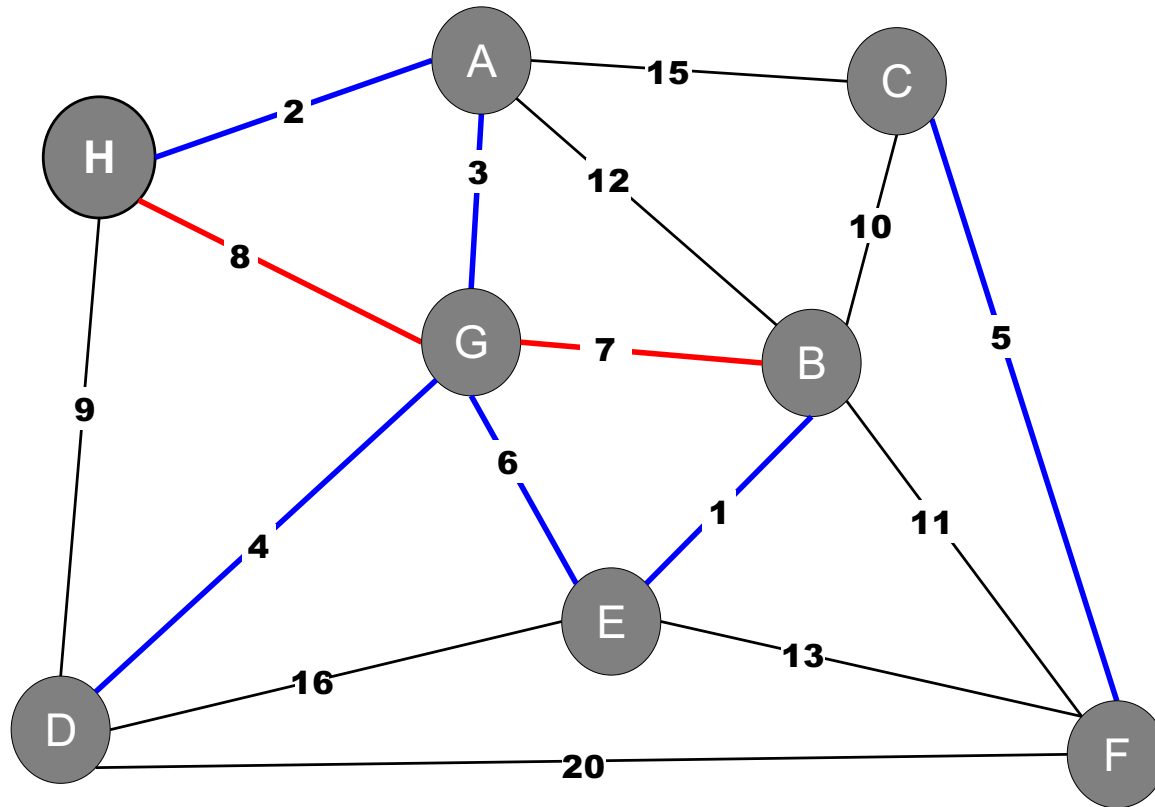
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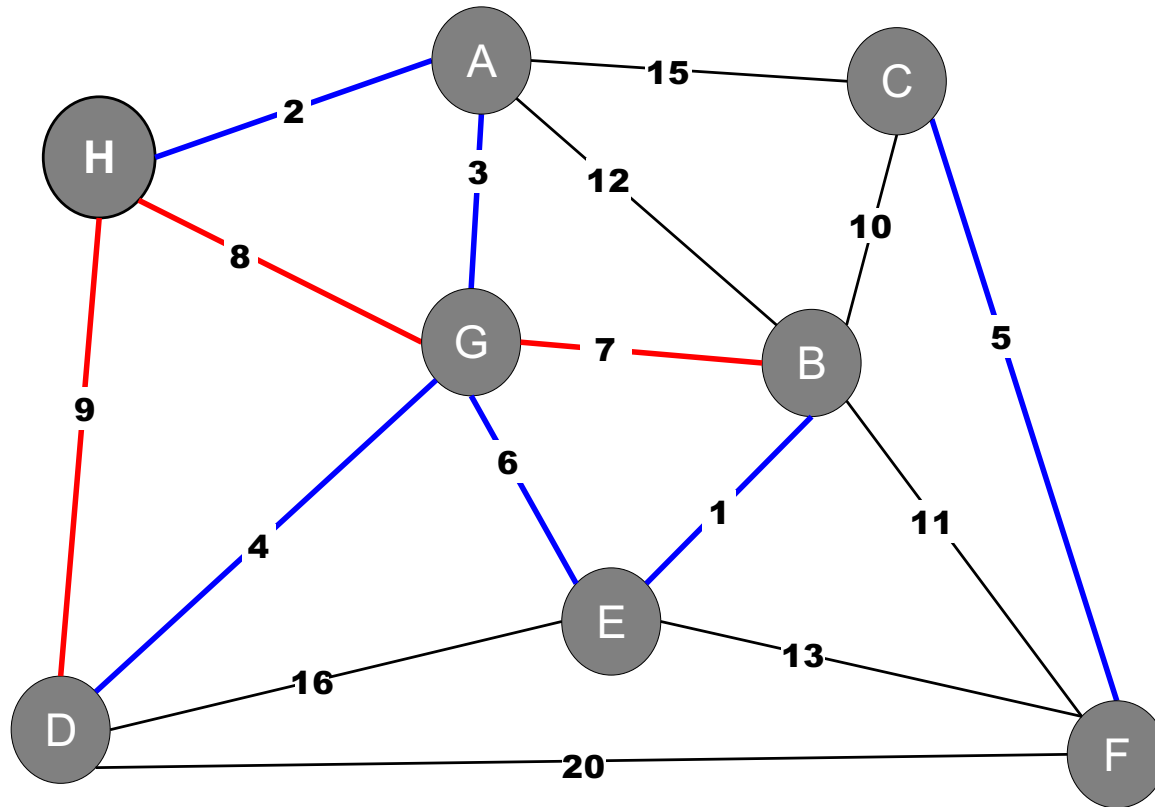
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Kruskal's Example



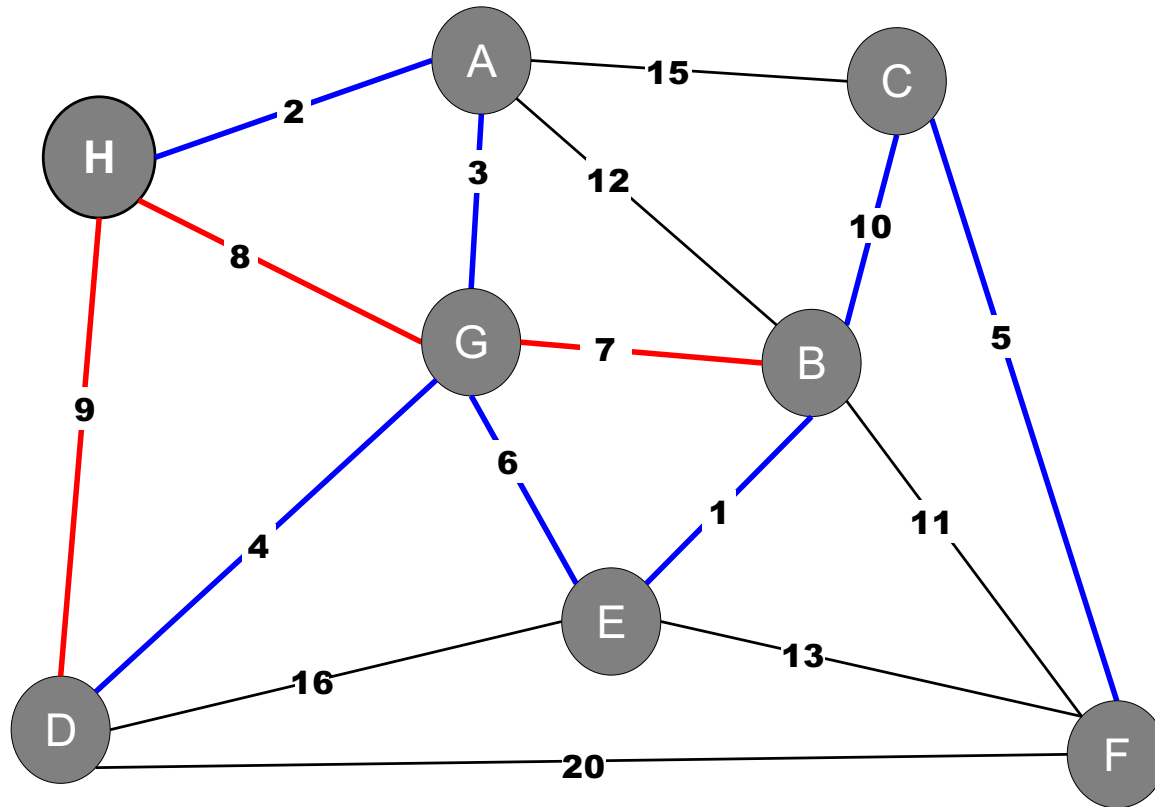
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Kruskal's Example



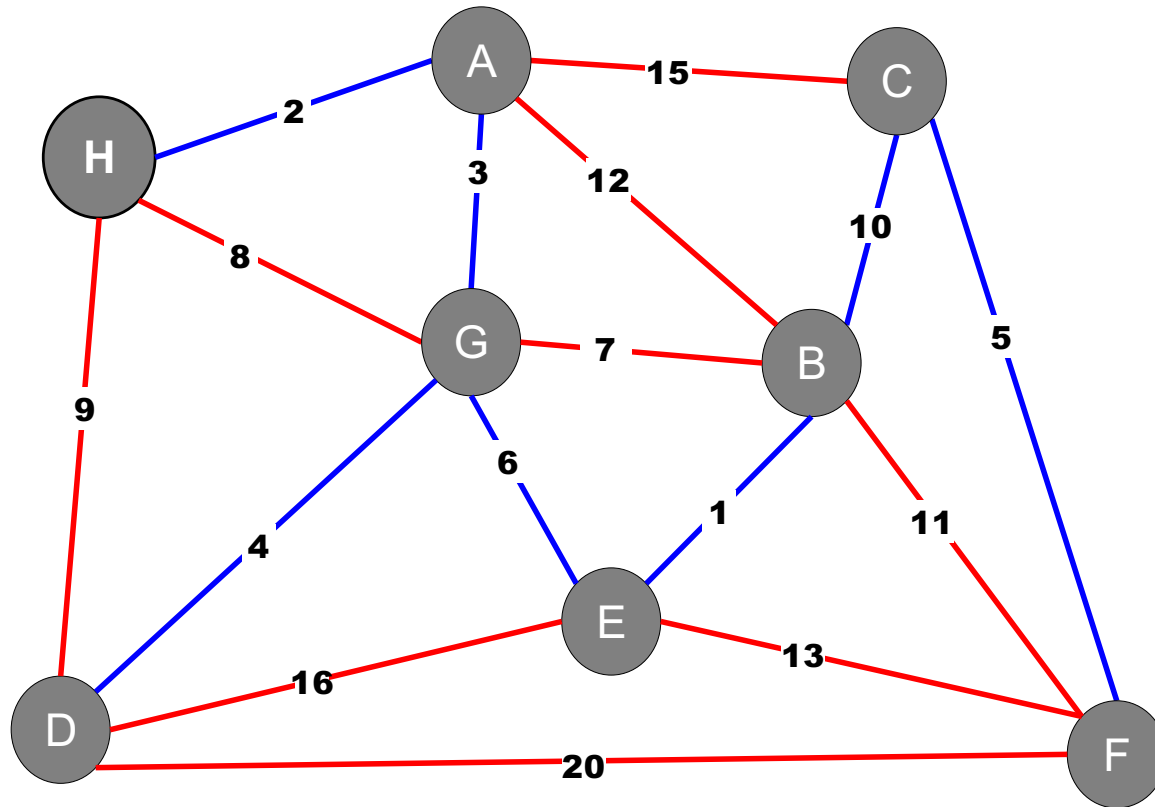
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13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

Kruskal's Algorithm

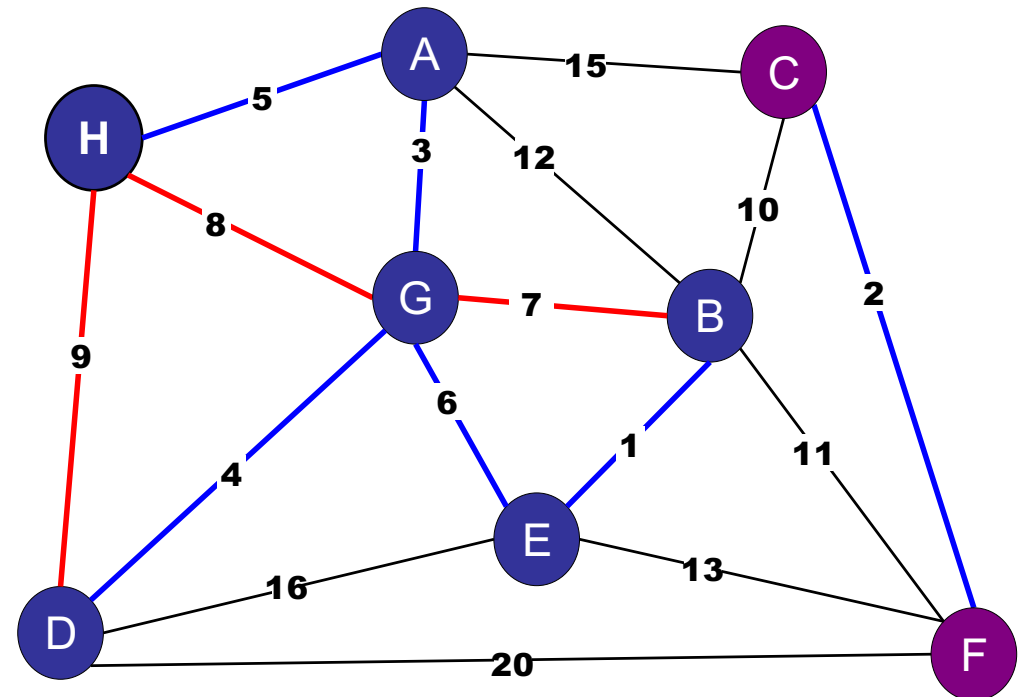
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
 - If both endpoints are in the **same** blue tree, then color the edge red.
 - Otherwise, color the edge blue.

Proof:

- Each added edge crosses a cut.
- Each edge is the lightest edge across the cut: all other lighter edges across the cut have already been considered.



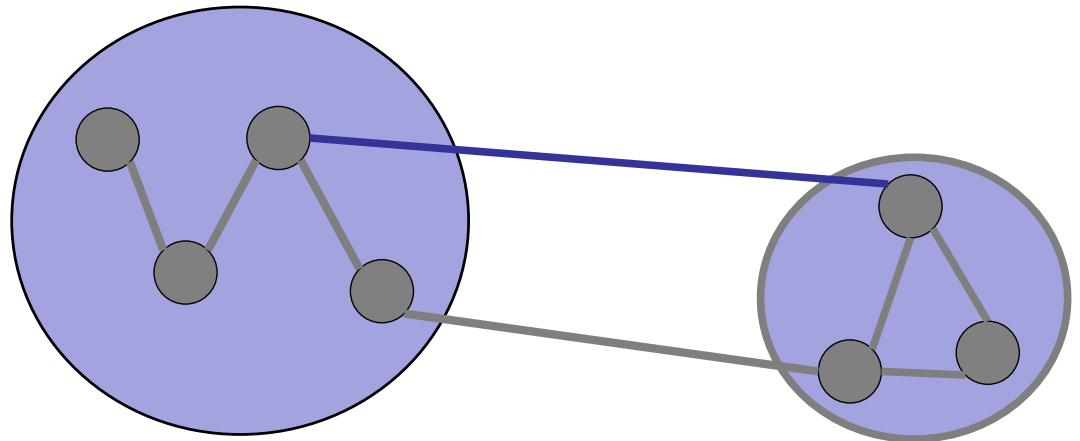
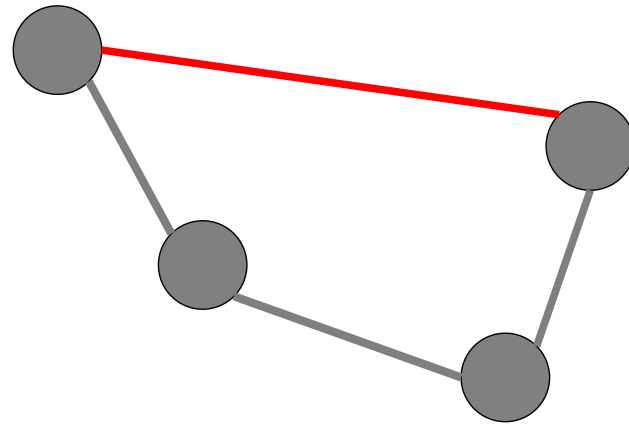
Generic MST Algorithm

Greedy Algorithm:

Repeat:

**Apply red rule or
blue rule to an
arbitrary edge.**

until no more edges
can be colored.



What is the running time of Kruskal's Algorithm on a connected graph?

1. $O(V)$
2. $O(E)$
3. $O(E \alpha)$
4. $O(V \alpha)$
- ✓ 5. $O(E \log V)$
6. $O(V \log E)$

Kruskal's Algorithm

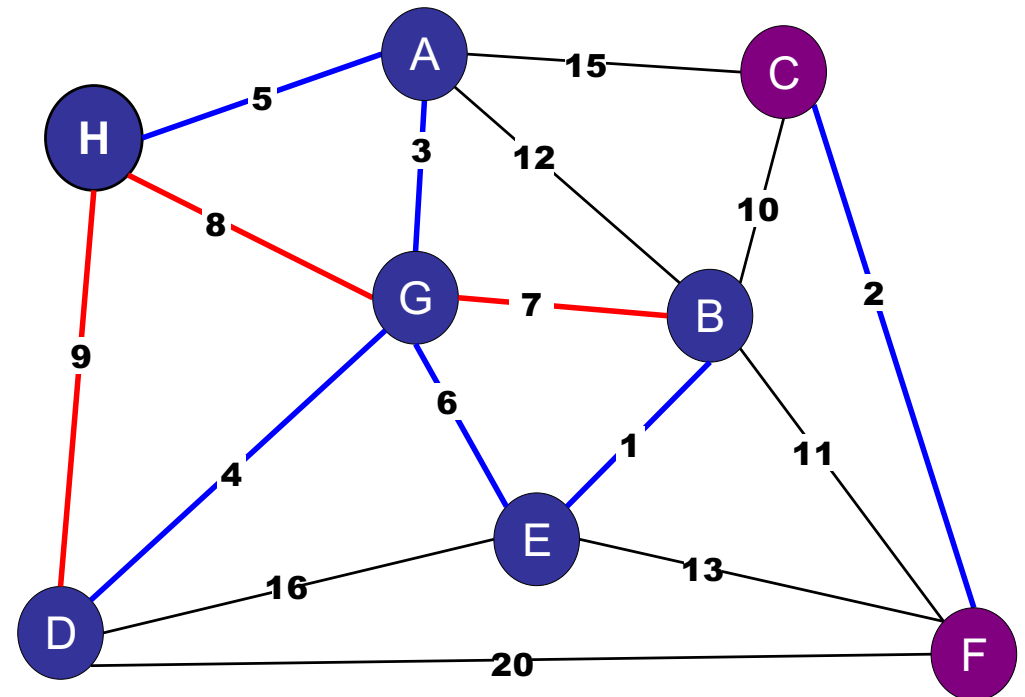
Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
 - If both endpoints are in the **same** blue tree, then color the edge red.
 - Otherwise, color the edge blue.

Performance:

- Sorting: $O(E \log E) = O(E \log V)$
- For E edges:
 - Find: $O(\alpha(n))$ or $O(\log V)$
 - Union: $O(\alpha(n))$ or $O(\log V)$



Roadmap

Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- **Boruvka's Algorithm**
- Variations

MST Algorithms

Classic:

- Prim's Algorithm
- Kruskal's Algorithm

Modern requirements:

- Parallelizable
- Faster in “good” graphs (e.g., planar graphs)
- Flexible

Boruvka's Algorithm

Origin: 1926

- Otakar Boruvka
- Improve the electrical network of Moravia

Based on generic algorithm:

- Repeat: add all “obvious” blue edges.
- Very simple, very flexible.

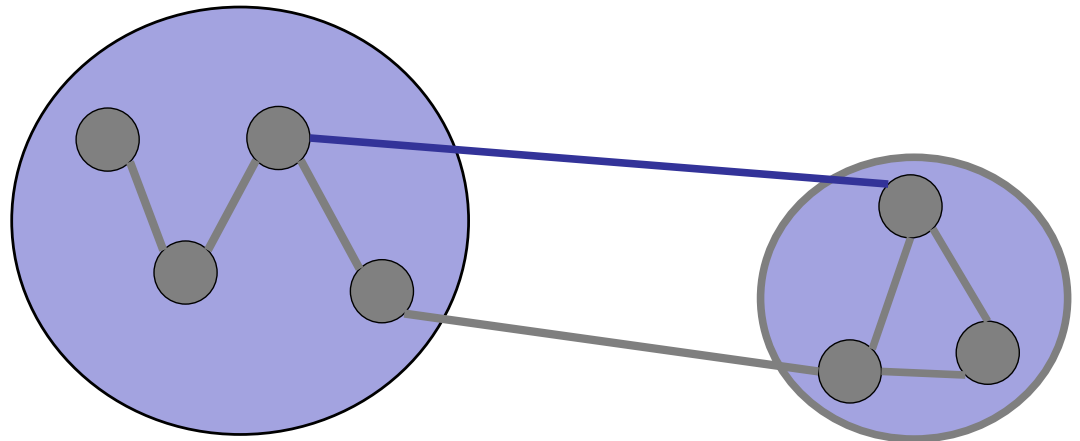
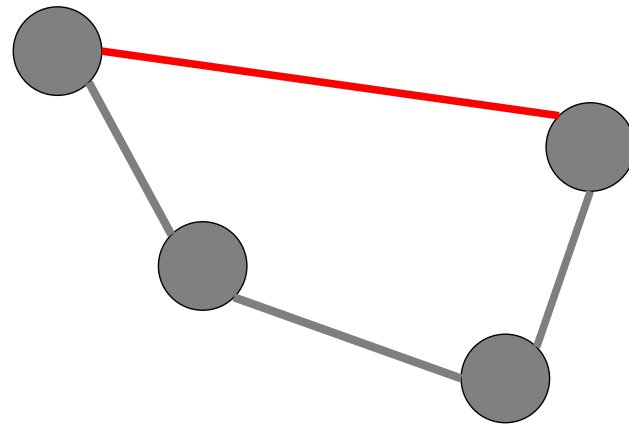
Generic MST Algorithm

Greedy Algorithm:

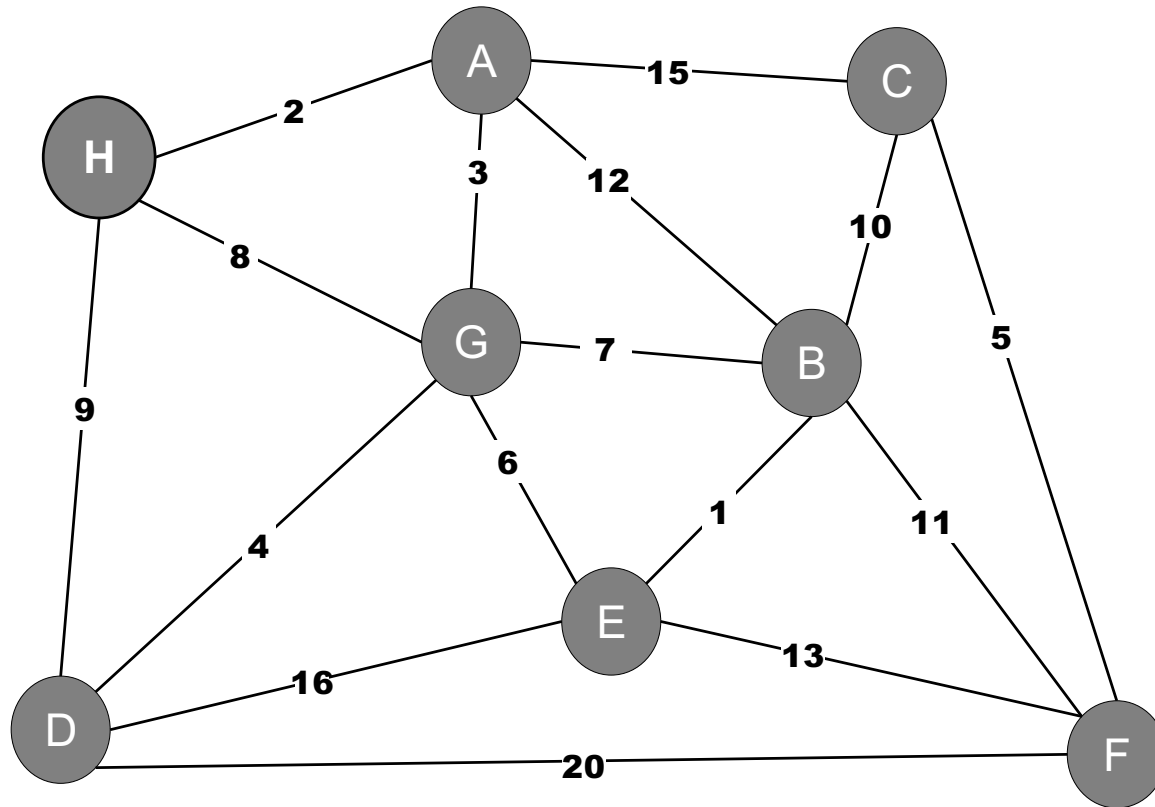
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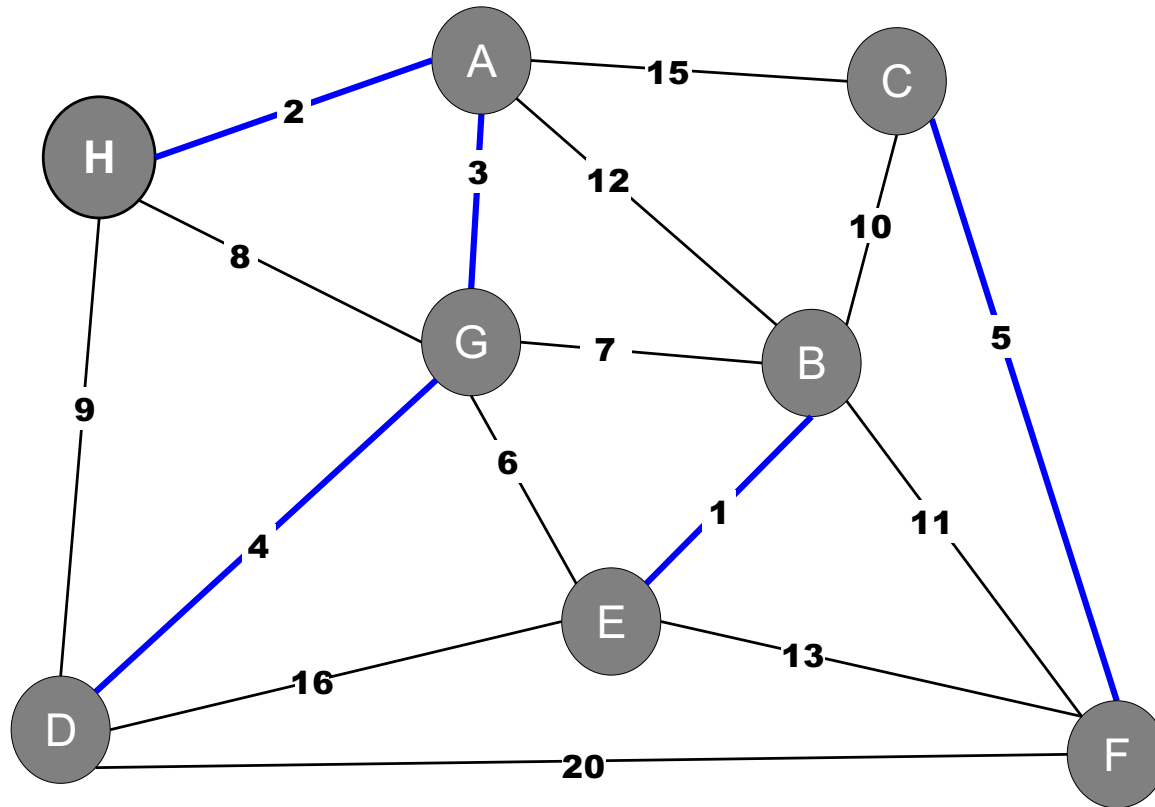
Boruvka's Example



Which edges are “obviously” in the MST?

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

Boruvka's Example

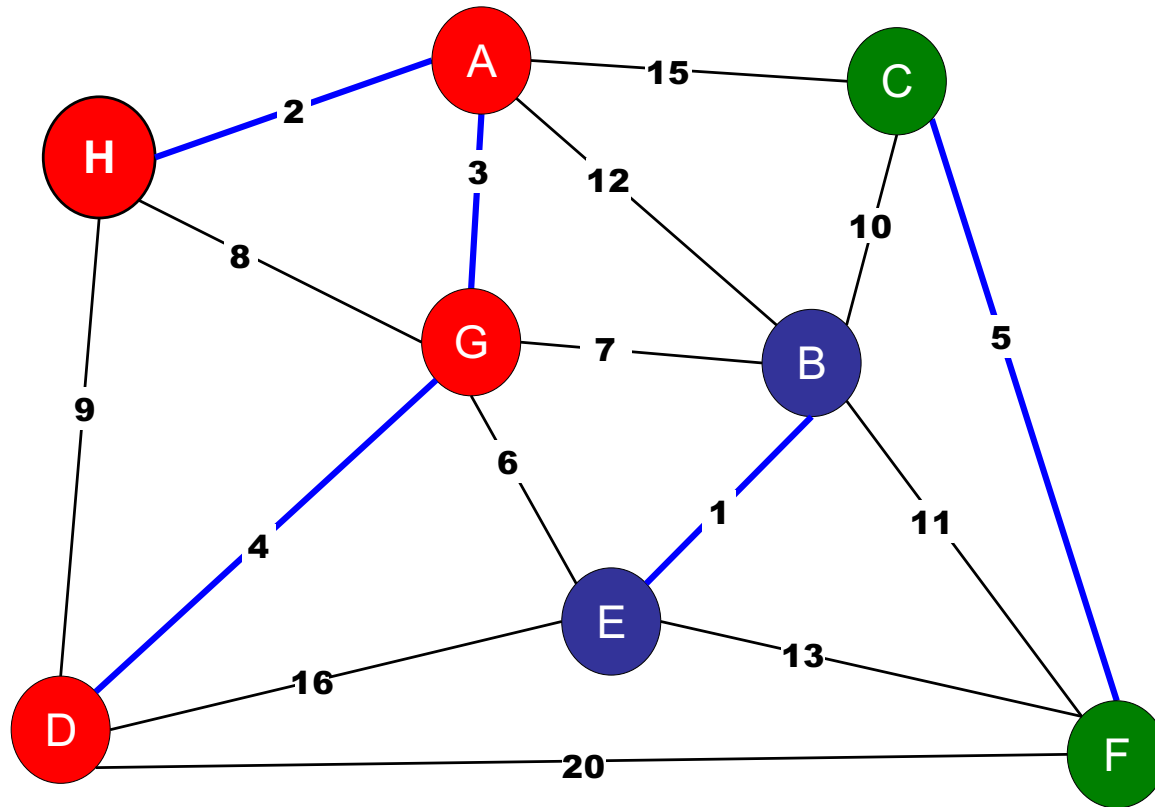


For every node: add minimum adjacent edge.

Add at least $n/2$ edges.

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
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Boruvka's Example

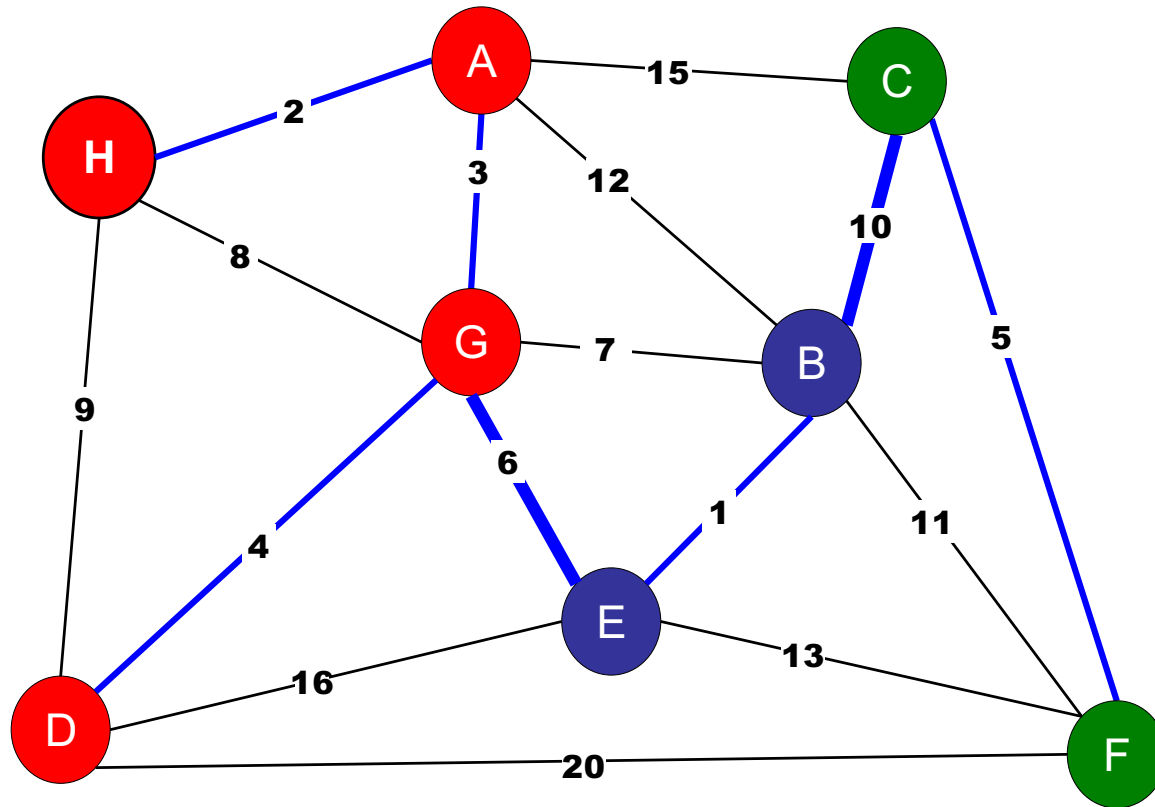


Look at connected components...

At most $n/2$ connected components.

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

Boruvka's Example



Repeat: for every connected components, add minimum outgoing edge.

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
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Boruvka's Algorithm

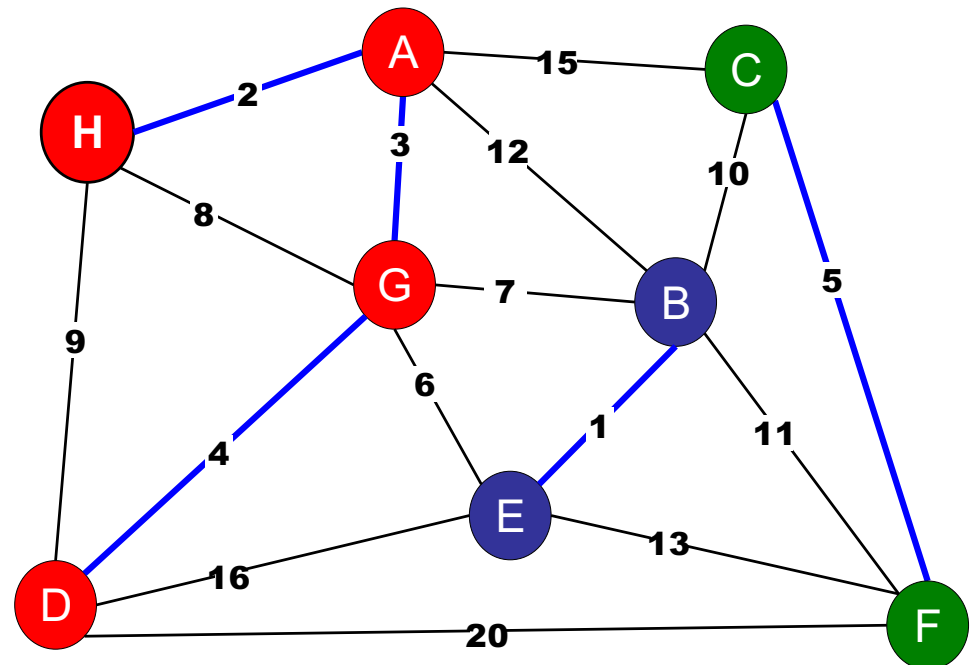
Boruvka's Algorithm

Initially:

- Create n connected components, one for each node in the graph.

One “Boruvka” Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.



Boruvka's Algorithm

Boruvka's Algorithm

Initially:

- Create **n** connected components, one for each node in the graph.

For each node: store a component identifier.



One “Boruvka” Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

Boruvka's Algorithm

Boruvka's Algorithm

Initially:

- Create **n** connected components, one for each node in the graph.

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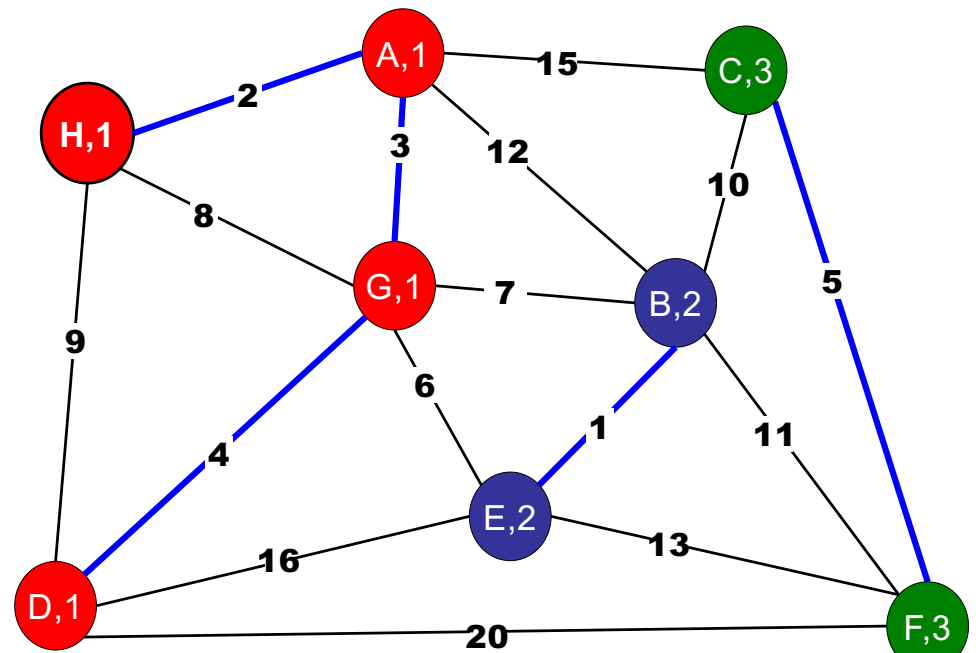
Component	1	2	3
Min cost edge	(G,E), 6	(G,E), 6	(B,C), 10
To be merged	1 and 2	1 and 2	2 and 3

For each node: store a component identifier.

DFS or BFS:

Check if edge connects two components.

Remember minimum cost edge connected to each component.



Boruvka's Algorithm

Boruvka's Algorithm

Initially:

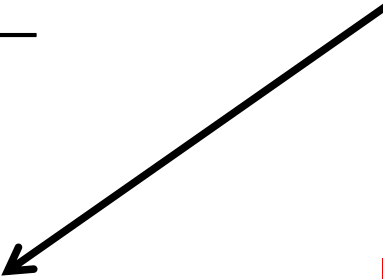
- Create **n** connected components, one for each node in the graph.

One “Boruvka” Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

Component	1	2	3
Min cost edge	(G,E), 6	(G,E), 6	(B,C), 10
To be merged	1 and 2	1 and 2	2 and 3
New ID:	1	1	1

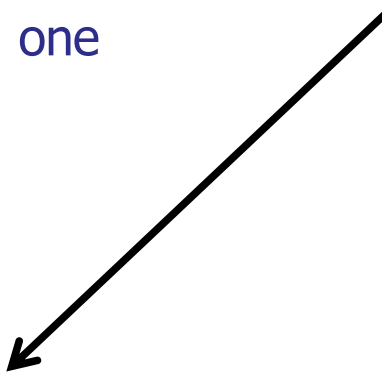
For each node: store a component identifier.



DFS or BFS:

Check if edge connects two components.

Remember minimum cost edge connected to each component.



Scan every node:

Compute new component ids.

Update component ids.

Mark added edges.



Boruvka's Algorithm

Boruvka's Algorithm

Initially:

- Create n connected components, one for each node in the graph.

One “Boruvka” Step: $O(V+E)$

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

For each node: $O(V)$
store a component identifier.

DFS or BFS: $O(V + E)$
Check if edge connects two components.

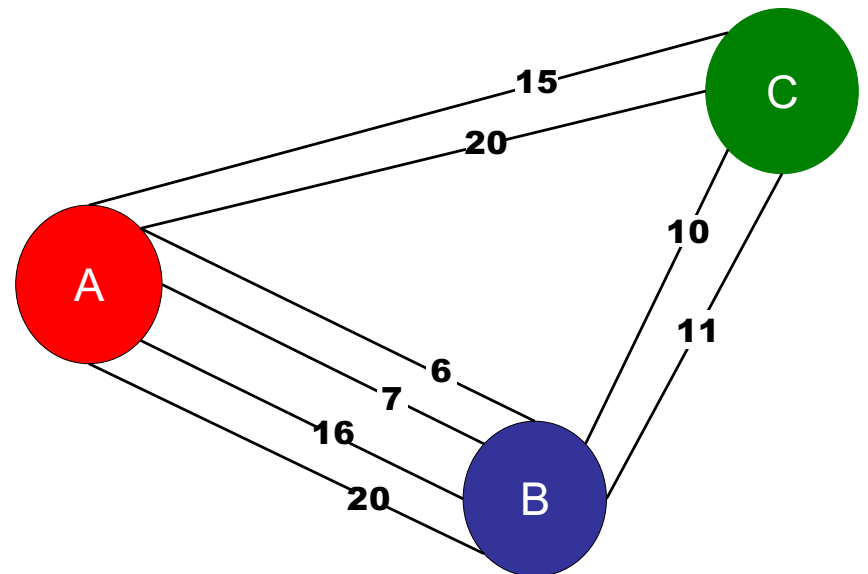
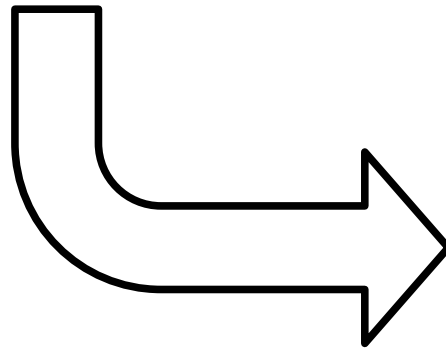
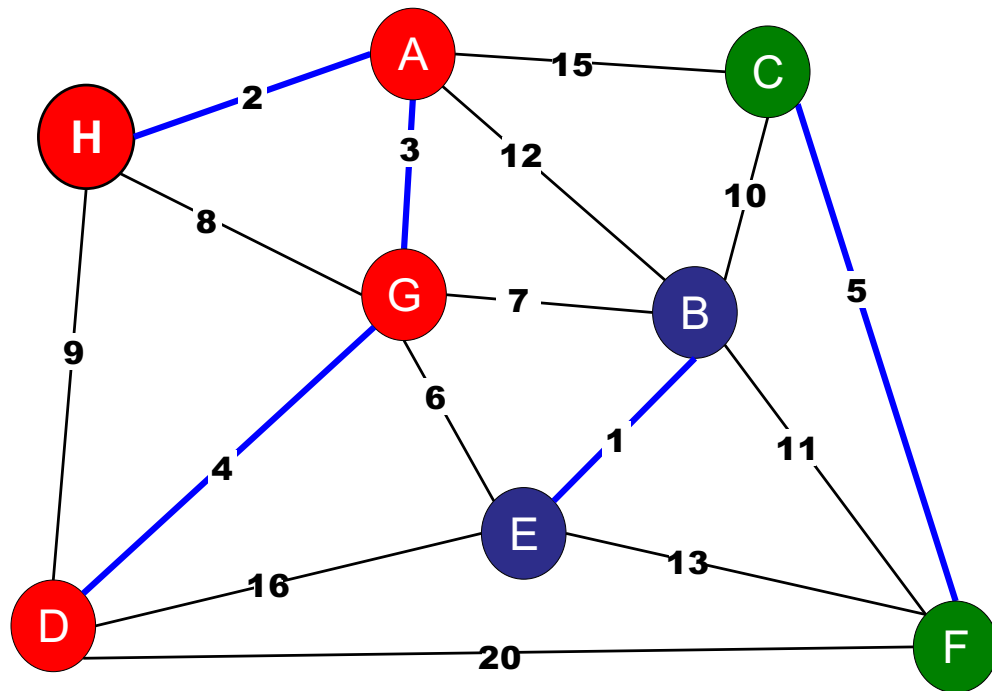
Remember minimum cost edge connected to each component.

Scan every node: $O(V)$
Compute new component ids.

Update component ids.

Mark added edges.

Boruvka's Example: Contraction



Boruvka's Algorithm

Boruvka's Algorithm

Initially:

- Create n connected components, one for each node in the graph.

In each “Boruvka” Step: $O(V+E)$

- Assume k components, initially.
- At least $k/2$ edges added.

Count edges:

Each component adds one edge.

Some choose same edge.

Each edge is chosen by at most two different components.

Boruvka's Algorithm

Boruvka's Algorithm

Initially:

- Create n connected components, one for each node in the graph.

In each “Boruvka” Step: $O(V+E)$

- Assume k components, initially.
- At least $k/2$ edges added.
- At least $k/2$ components merge.

Merging:

Each edge merges two components



Boruvka's Algorithm

Boruvka's Algorithm

Initially:

- Create n connected components, one for each node in the graph.

In each “Boruvka” Step: $O(V+E)$

- Assume k components, initially.
- At least $k/2$ edges added.
- At least $k/2$ components merge.
- At end, at most $k/2$ components remain.

Boruvka's Algorithm

Boruvka's Algorithm

Initially:

n components

At each step:

k components $\rightarrow k/2$ components.

Termination:

1 component

Conclusion:

At most $O(\log V)$ Boruvka steps.

Boruvka's Algorithm

Boruvka's Algorithm

Initially:

n components

At each step:

k components \rightarrow $k/2$ components.

Termination:

1 component

Conclusion:

At most $O(\log V)$ Boruvka steps.

Total time:

$O((E+V)\log V) = O(E \log V)$

Boruvka's Algorithm

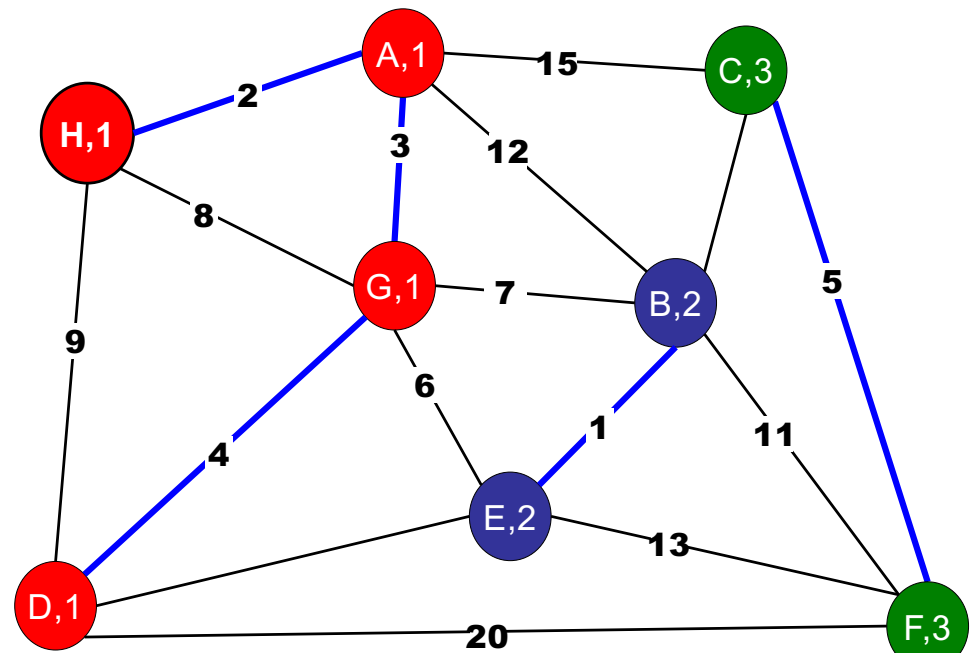
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Initially:

- Create n connected components, one for each node in the graph.

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- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.



Roadmap

So far:

Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm

Minimum Spanning Tree Summary

Classic greedy algorithms: $O(E \log V)$

- Prim's (Priority Queue)
- Kruskal's (Union-Find)
- Boruvka's

Best known: $O(m \alpha(m, n))$

- Chazelle (2000)

Holy grail and major open problem: $O(m)$

Minimum Spanning Tree Summary

Classic greedy algorithms: $O(E \log V)$

- Prim's (Priority Queue)
- Kruskal's (Union-Find)
- Boruvka's

Best known: $O(m \alpha(m, n))$

- Chazelle (2000)

Holy grail and major open problem: $O(m)$

- Randomized: Karger-Klein-Tarjan (1995)
- Verification: Dixon-Rauch-Tarjan (1992)

Roadmap

Today: Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm

Variations:

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree
- Steiner Tree