Process Management

## **Process Alternative - Threads**

Lecture 5

## Overview

### Threads

- Motivation
- Basic Idea

### Threads models

- Kernel vs User Thread
- Hybrid model

### Thread in Unix

- POSIX thread:
  - Create, Exit, Synchronization
  - Exploration

### Motivation for Thread

- Process is expensive:
  - Process creation under the fork() model:
    - Duplicate memory space
    - Duplicate most of the process context etc.
  - Context switch:
    - Requires saving/restoration of process Information
- It is hard for independent processes to communicate with each other:
  - Independent memory space → No easy way to pass information
  - Requires Inter-Process Communication (IPC)

# Motivation for Thread (cont)

- Thread was invented to overcome the problems with process model
  - Started out as a "quick hack" and eventually matured to be very popular mechanism

### Basic Idea:

- A traditional process has a single thread of control:
  - Only one instruction of the whole program is executing at any time
- We "simply" add more threads of control to the same process:
  - Multiple parts of the programs is executing at the same time conceptually

### Threads of control: Illustration

- Suppose we are preparing lunch, which consists of the following tasks:
  - Steam rice
  - Fry fish
  - Cook soup
- A pseudo-C program:

```
int main()
{
    steamRice( twoBowls );
    fryFish( bigFish );
    cookSoup( cornSoup );

    printf( "Lunch READY!!\n" );
    return 0;
}
```

## Threads of control: Illustration (cont)

 Process with a single thread will go through the functions sequentially

```
int main()
{
    steamRice( twoBowls );
    fryFish( bigFish );
    cookSoup( cornSoup );

    printf( "Lunch Ready\n" );
    return 0;
}
Time
```

- Suppose the tasks are independent:
  - Let's try to have multiple threads of control

## Multiple "threads of control" with fork ()

```
int result;
result = fork();
if (result != 0) {
    result = fork();
    if (result != 0) {
        steamRice( twoBowls );
    } else {
        fryFish( bigFish );
    }
} else {
    cookSoup( cornSoup );
    int
}
```

We effectively have two "threads" of control after fork()

```
int result;
result = fork();
if (result != 0) {
    result = fork();
    if (result != 0) {
        steamRice( twoBowls );
    } else {
        fryFish( bigFish );
    }
} else {
    cookSoup( cornSoup );
}
```

# New approach: Multi-Threading

```
int main()
                                                PC 1
    Thread 1 do { steamRice( twoBowls );
                                                PC 2
    Thread 2 do { fryFish( bigFish ); }
    Thread 3 do { cookSoup( cornSoup );
                                                PC 3
    Wait for all threads to finish;
   printf( "Lunch Ready\n");
    return 0;
```

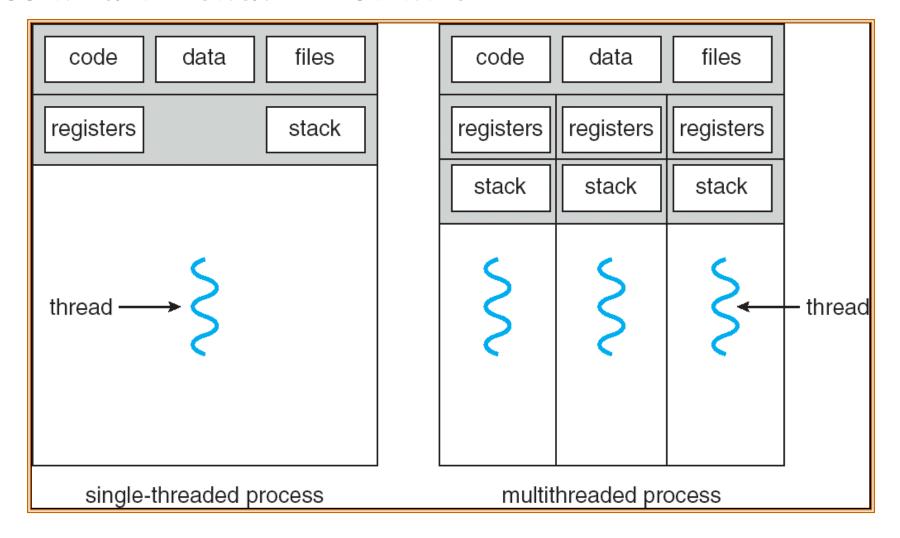
### Note:

- Pseudocode ②
- The three threads are concurrent

## Process and Thread

- A single process can have multiple threads:
  - known as multithreaded process
- Threads in the same process shares:
  - Memory Context: Text, Data, Heap
  - OS Context: Process id, other resources like files, etc.
- Unique information needed for each thread:
  - Identification (usually thread id)
  - Registers (General purpose and special)
  - "Stack" (more about this later)

## Process and thread: Illustration



Taken from Operating System Concepts (7<sup>th</sup> Edition) by Silberschatz, Galvin & Gagne, published by Wiley

## Process Context Switch VS Thread Switch

- Process context switch involves:
  - OS Context
  - Hardware Context
  - Memory Context
- Thread switch within the same process involves:
  - Hardware context:
    - Registers
    - "Stack" (actually just changing FP and SP registers)
- Thread is much "lighter" than process:
  - a.k.a. lightweight process

## Threads: Benefits

#### **Economy:**

 Multiple threads in the same process requires much less resources to manage compared to multiple processes

#### Resource sharing:

- Threads share most of the resources of a process
- No need for additional mechanism for passing information around

#### **Responsiveness:**

Multithreaded programs can appear much more responsive

#### Scalability:

Multithreaded program can take advantage of multiple CPUs

## Thread: **Problems**

### System Call Concurrency

- □ Parallel execution of multiple threads → parallel system call possible
  - Have to guarantee correctness and determine the correct behavior

#### Process Behavior:

- Impact on process operations
- Example:
  - fork() duplicate process, how about threads?
  - If a single thread executes exit(), how about the whole process?
  - If a single thread calls exec(), how about other threads?

# Thread Models

What are the ways to support threads?

# Two Major Thread Implementations

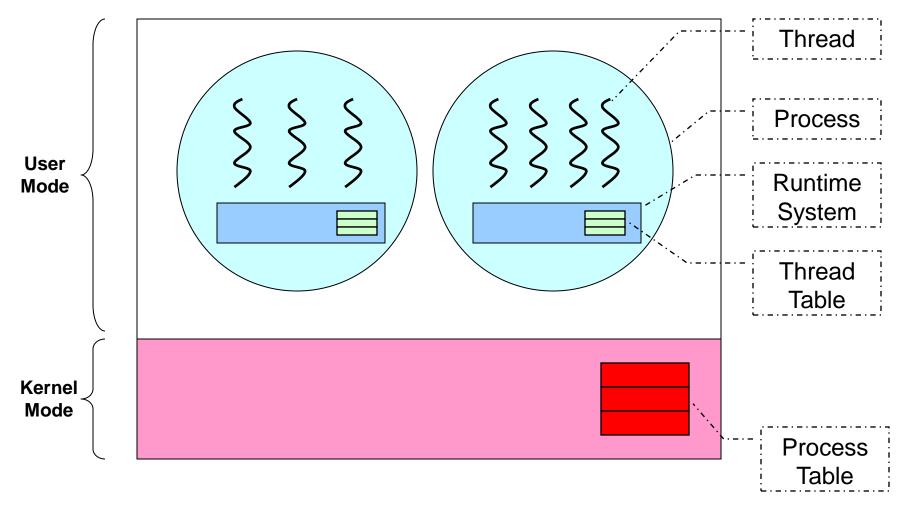
### User Thread:

- Thread is implemented as a user library
  - A runtime system (in the process) will handle thread related operation
- Kernel is not aware of the threads in the process

### Kernel Thread:

- Thread is implemented in the OS
  - Thread operation is handled as system calls
- Thread-level scheduling is possible:
  - Kernel schedule by threads, instead of by process
- Kernel may make use of threads for its own execution

## User Thread: Illustration



Adapted from Modern Operating System Concepts (3rd Edition) by Andrew Tanenbaum, published by Pearson

## User Thread: Pros and Cons

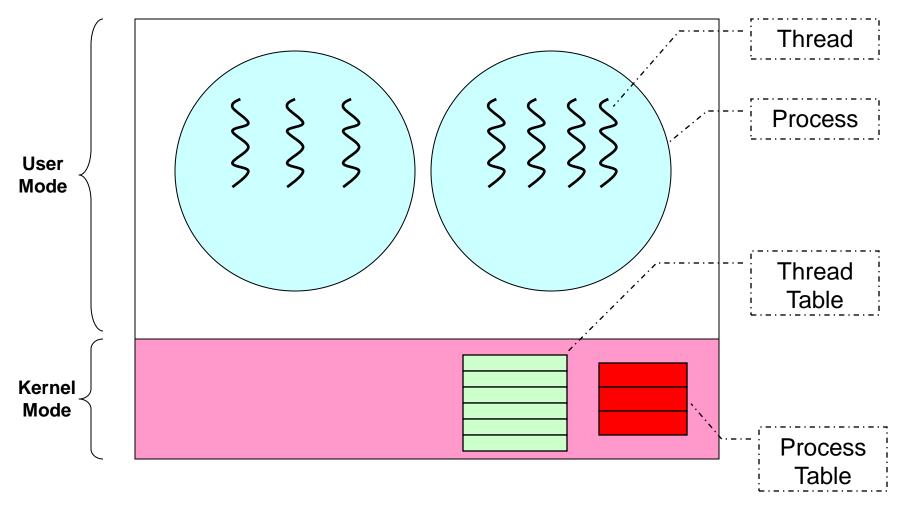
### Advantages:

- Can have multithreaded program on ANY OS
- Thread operations are just library calls
- Generally more configurable and flexible
  - e.g., customized thread scheduling policy

## Disadvantages:

- OS is not aware of threads, scheduling is performed at process level
  - One thread blocked → Process blocked → All threads blocked
  - Cannot exploit multiple CPUs!

## Kernel Thread: Illustration



Adapted from Modern Operating System Concepts (3rd Edition) by Andrew Tanenbaum, published by Pearson

### Kernel Threads: Pros and Cons

### Advantages:

- Kernel can schedule on thread levels:
  - More than 1 thread in the same process can run simultaneously on multiple CPUs

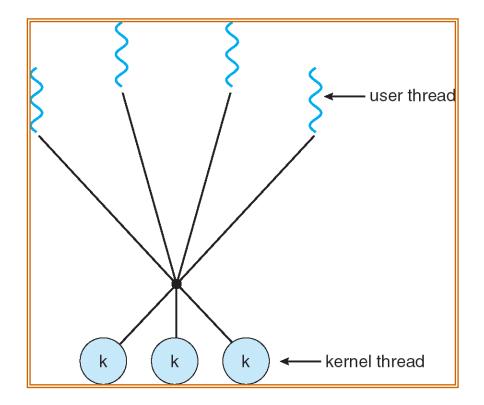
### Disadvantages:

- Thread operations is now a system call!
  - Slower and more resource intensive
- Generally less flexible:
  - Used by all multithreaded programs
  - If implemented with many features:
    - Expensive, overkill for simple program
  - If implemented with few features:
    - Not flexible enough for some programs

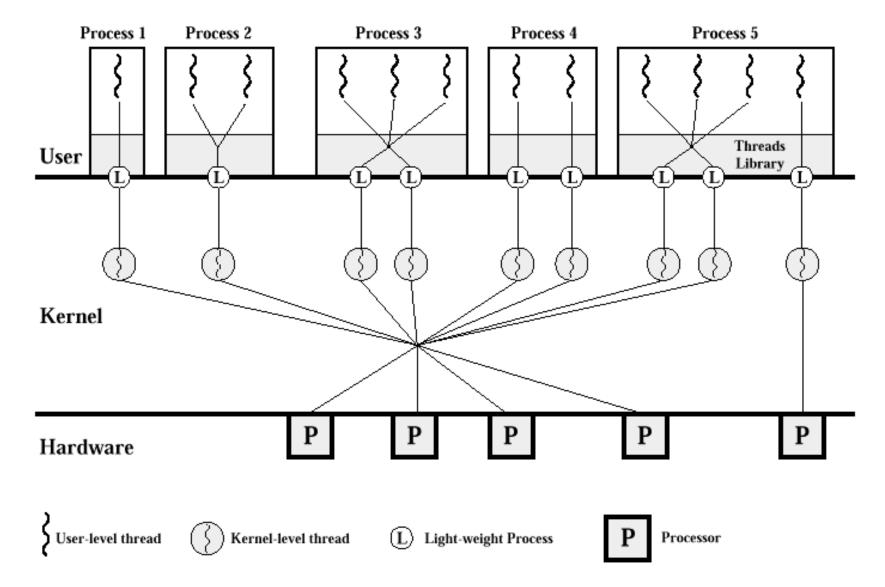
# Hybrid Thread Model

- Have both Kernel and User threads
  - OS schedule on kernel threads only
  - User thread can bind to a kernel thread

- Offer great flexibility
  - Can limit the concurrency of any process / user



# Hybrid Model Example: Solaris



## Threads on Modern Processor

- Threads started off as a software mechanism
  - User space library → OS aware mechanism
- There are hardware support on modern processors:
  - Essentially supply multiple sets of registers (GPRs, and special registers) to allow threads to run natively and in parallel on the same core
  - known as simultaneous multi-threading (SMT)
    - Example: Hyperthreading on Intel processor

# **POSIX** Threads

A popular thread API

# POSIX Threads: pthread

- Standard defined by the IEEE
  - Supported by most Unix variants
- Defines the API as well as the behavior
  - However, implementation is not specified
  - So, pthread can be implemented as user / kernel thread

 Will show a few example to highlight the differences between process and thread only

## Basics of pthread

- Header File:
  - #include <pthread.h>
- Compilation (flag is system dependent):
  - □ gcc XXXX.c -lpthread
- Useful datatypes:
  - pthread t: Data type to represent a thread id (TID)
  - pthread\_attr: Data type to represents attributes of a thread

# pthread Creation Syntax

Returns (0 = success; !0 = errors)

#### Parameters:

tidCreated: Thread Id for the created thread

threadAttributes: Control the behavior of the new thread

startRoutine: Function pointer to the function to be executed by thread

argForStartRoutine: Arguments for the startRoutine function

# pthread Termination Syntax

```
int pthread_exit( void* exitValue );
```

- Parameters:
  - exitValue: Value to be returned to whoever synchronize with this thread (more later)
- If pthread\_exit() is not used, a pthread will terminate automatically at the end of the startRoutine
  - If a "return XYZ;" statement is used, then "XYZ" is captured as the exitValue
  - Otherwise, the exitValue is not well defined

## pthread Creation & Termination: Example

```
//header files not shown
                                 Function to be executed
void* sayHello( void* arg )
                                     by a pthread
     printf("Just to say hello!\n");
     pthread exit( NULL );
                                  Pthread Termination
int main()
    pthread t tid;
                                   Pthread Creation
    pthread create( &tid, NULL, sayHello, NULL );
    printf("Thread created with tid %i\n", tid);
    return 0;
```

— [CS2106 L5 - AY2122 S1] — **28** 

# pthread: Sharing of memory space

```
//header files not shown
int globalVar;
                     Variable shared between pthreads
void* doSum( void* arg)
    int i;
     for (i = 0; i < 1000; i++)
          globalVar++;
                                    Using a shared variables
int main()
   pthread t tid[5]; //5 threads id
    int i;
    for (i = 0; i < 5; i++)
        pthread create( &tid[i], NULL, doSum, NULL );
    printf("Global variable is %i\n", globalVar);
    return 0;
```

What is the sum that we get (or should get)?

# pthread Simple Synchronization - Join

- To wait for the termination of another *pthread*:
- Returns(0 = success; !0 = errors)
- Parameters:
  - threadID: TID of the pthread to wait for
  - status: Exit value returned by the target pthread

# Pthread: Sharing of memory space V2.0

```
//header files not shown
int globalVar;
void* doSum( void* arg)
{ //same as before }
int main()
   pthread t tid[5]; //5 threads id
    int i;
    for (i = 0; i < 5; i++)
        pthread create( &tid[i], NULL, doSum, NULL );
    //Wait for all threads to finish
    for (i = 0; i < 5; i++)
                                                 Pthread
                                             Synchronization
        pthread_join( tid[i], NULL );
    printf("Global variable is %i\n", globalVar);
    return 0;
```

— [CS2106 L5 - AY2122 S1] — **31** 

## Pthread: A lot more!

- There are more interesting stuff about *pthread*:
  - Yielding (giving up CPU voluntarily)
  - Advanced synchronization
  - Scheduling policies
  - Binding to kernel threads
  - Etc.

As we cover new topics, you can explore the *pthread* library to see the application!

# Summary

- Thread:
  - Motivation
  - Difference between thread and process

- Thread Models:
  - User vs Kernel thread

Simple introduction to *pthread* library

## Reference

- Modern Operating System (3<sup>rd</sup> Edition)
  - Chapter 2.2

- Operating System Concepts (7<sup>th</sup> Edition)
  - Chapter 4
- Linux Pthread Man Pages
  - "man pthread....." for more