

# James Young

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## EDUCATION

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**The Hong Kong University of Science and Technology**  
*BEng in Electronic Engineering - Minor in Information Technology*

Hong Kong  
*Sept. 2020 – June 2024*

**Boston University**  
*Master of Science in Computer Science (Part Time)*

United States  
*Sept. 2024 – Present*

## SKILLS

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**Programming Languages:** Python, C++, Javascript  
**Tools/Platforms:** Linux, Git, Docker, Ansible, Kubernetes  
**Cloud:** AWS (DynamoDB, Lambda, EC2, S3)

## WORK EXPERIENCE

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**Software Developer Intern**  
*Intelligent Design Technology Limited*

December 2023 – February 2024  
*Hong Kong*

- Developed a prototype for real-time human fall detection for a Raspberry PI based robot.
- Fall detection uses Tensorflow and Movenet for pose estimation and heuristics for determining fall.

**Electronic Engineering Intern**  
*Kolour Think Tank*

August 2023  
*Hong Kong*

- Developed a digital utility meter reader that takes images of a utility meter with an ESP32-CAM, stores images to AWS S3, reads the meter reading with Rekognition, and stores the data in DynamoDB.

**IoT Intern**  
*Graphite Venture Limited*

December 2022 – May 2023  
*Hong Kong*

- Developed Arduino libraries for reading water sensor data with ESP32 and sending sensor data to AWS IoT Core through MQTT.

## PROJECTS

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### Serverless Face Blurring

- A serverless application that blurs faces on an image using OpenFaaS and Python. Stores the transformed image in a MinIO storage bucket.
- Application deployable on Kubernetes using MiniKube and Helm charts.

### Air Quality Monitoring Dashboard

- A fullstack project that stores and displays my home's air quality sensor data using AWS services.
- Data is stored and retrieved on DynamoDB using REST API with API Gateway and Lambda. Front-end uses HTML, CSS, and Javascript.

### Mini Robot Cleaner

- Created a robot car cleaner with a STM32 board written in C that can be wirelessly controlled through UDP or can roam autonomously
- Used Python for socket programming and PyQt5 to create GUI to control robot wirelessly