

Inverse of a Matrix

Theorem: if A is an invertible matrix, its inverse is unique.

Proof: By way of contradiction, suppose A has two inverses: A' and A'' . This means that $A'A = I = AA'$ and $A''A = I = AA''$. Well now show that $A' = A''$.

$$A' = A'I = A'(AA'') = (A'A)A'' = IA'' = A''$$

Thus we have shown that there can only be 1 inverse. I still feel iffy about this proof that there can only exist one inverse of a function, but sure.

How can we compute the inverse?

For a 2×2 matrix, if $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and A is invertible, then

$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

General case intuition: If A is invertible, and B is the inverse of A , then $AB = I$

We can think of this as a set of linear systems. We can use the matrix-column representation of systems to decouple this system.

$$A \begin{bmatrix} \vec{b}_1, \vec{b}_2, \dots, \vec{b}_n \end{bmatrix} = I = \begin{bmatrix} \vec{e}_1, \vec{e}_2, \dots, \vec{e}_n \end{bmatrix}$$

$\vec{e}_1 \dots \vec{e}_n$ represents the identity matrix.

$A\vec{b}_1$ can be solved with $[A|\vec{e}_1]$

$A\vec{b}_2$ can be solved with $[A|\vec{e}_2]$

$A\vec{b}_n$ can be solved with $[A|\vec{e}_n]$

note: Solving the system $[A|\vec{b}]$ uses the same sequence of ERO's for any \vec{b} ! The form of A determines what sequence of EROs are necessary!

for each $A\vec{b}_n$ we turn the matrix into $[RREF(A)|\vec{b}_n]$

Since there is only one inverse matrix, this will be $[I|\vec{b}_1]$

We can stack together all of these vectors back, which is performing $[A|I] \rightarrow [I|B]$. To summarize: in order to compute the inverse, we use the eros defined by a and act them on b and end up with a matrix B that will make the identity.

Rigorously, what is going on here?

Each ERO is multiplying the matrix A and multiplying it by a particular matrix. **#ERO is really multiplication by elementary matrices**

#elementary_matrices: Any matrix that can be obtained by performing an ERO on an identity matrix.

$$\begin{aligned} &\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \text{ swaps rows} \\ &\begin{bmatrix} 1 & 0 \\ 0 & -3 \end{bmatrix} \text{ scales by -3} \\ &\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \text{ does } r_1 \rightarrow r_1 + r_2 \end{aligned}$$

We can see this is due to swapping the identity, ie

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

What does this look like for a 3x3 matrix

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

We can undo ERO's by using their inverse matrixes.

For row swapping EROs, the inverse is itself

$$E = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, E^{-1} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$
$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -7 & 0 \\ 0 & 0 & 1 \end{bmatrix}, E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{7} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

see previous: [Matrix Algebra and Inverse](#)