

Scaling the Hierarchical Topic Modeling Mountain

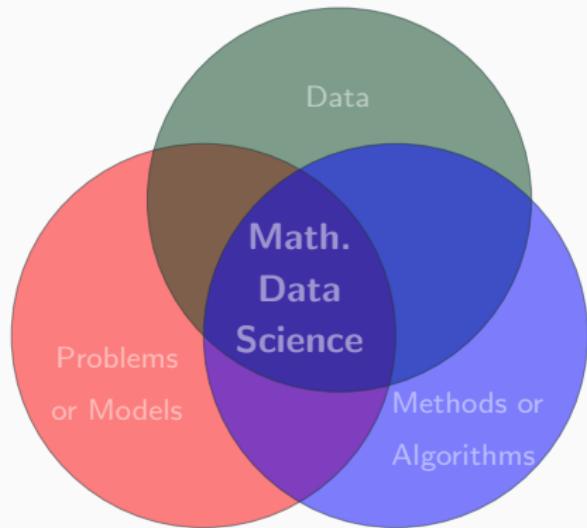
Neural NMF and Iterative Projection Methods

Jamie Haddock

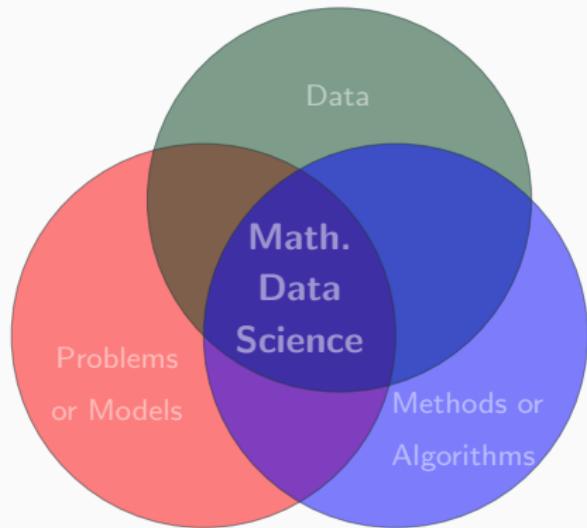
Harvey Mudd College,
January 28, 2020

Computational and Applied Mathematics
UCLA

Research Overview



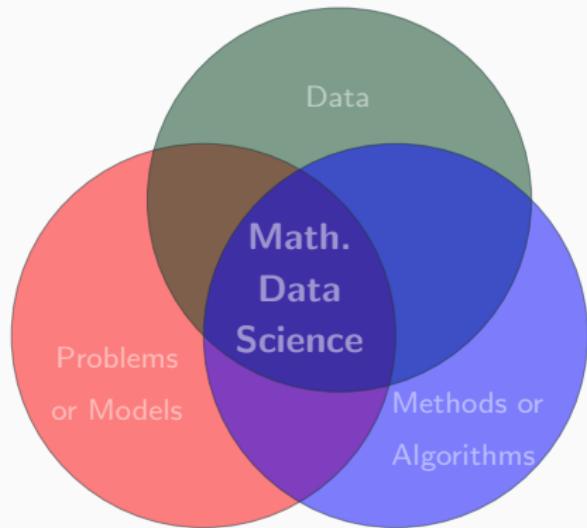
Research Overview



Mathematical Tools:

- ▷ numerical analysis
- ▷ probability theory
- ▷ convex geometry/analysis
- ▷ combinatorics
- ▷ polyhedral theory
- ▷ ...

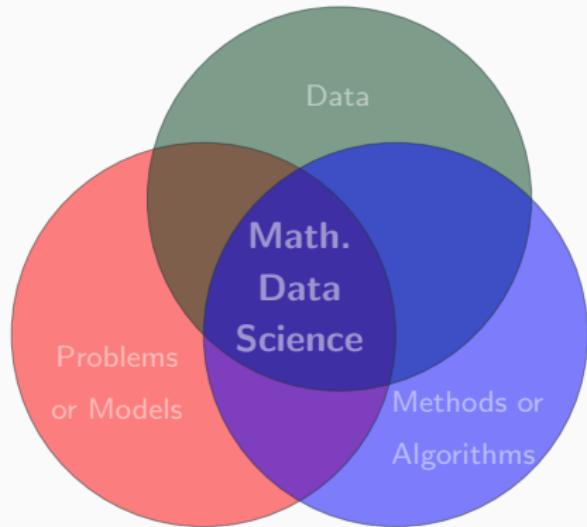
Research Overview



Data:

- ▷ **MyLymeData surveys**
- ▷ 20newsgroup
- ▷ Netlib linear programs
- ▷ UCI repository
- ▷ computerized tomography
- ▷ NBA data
- ▷ ...

Research Overview



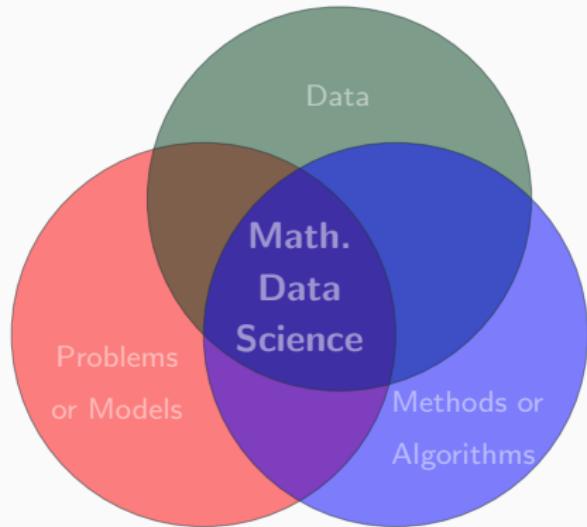
Problems or Models:

- ▷ **linear least-squares**
- ▷ linear programs
- ▷ **nonnegative matrix factorization**
- ▷ neural networks
- ▷ compressed sensing
- ▷ ...

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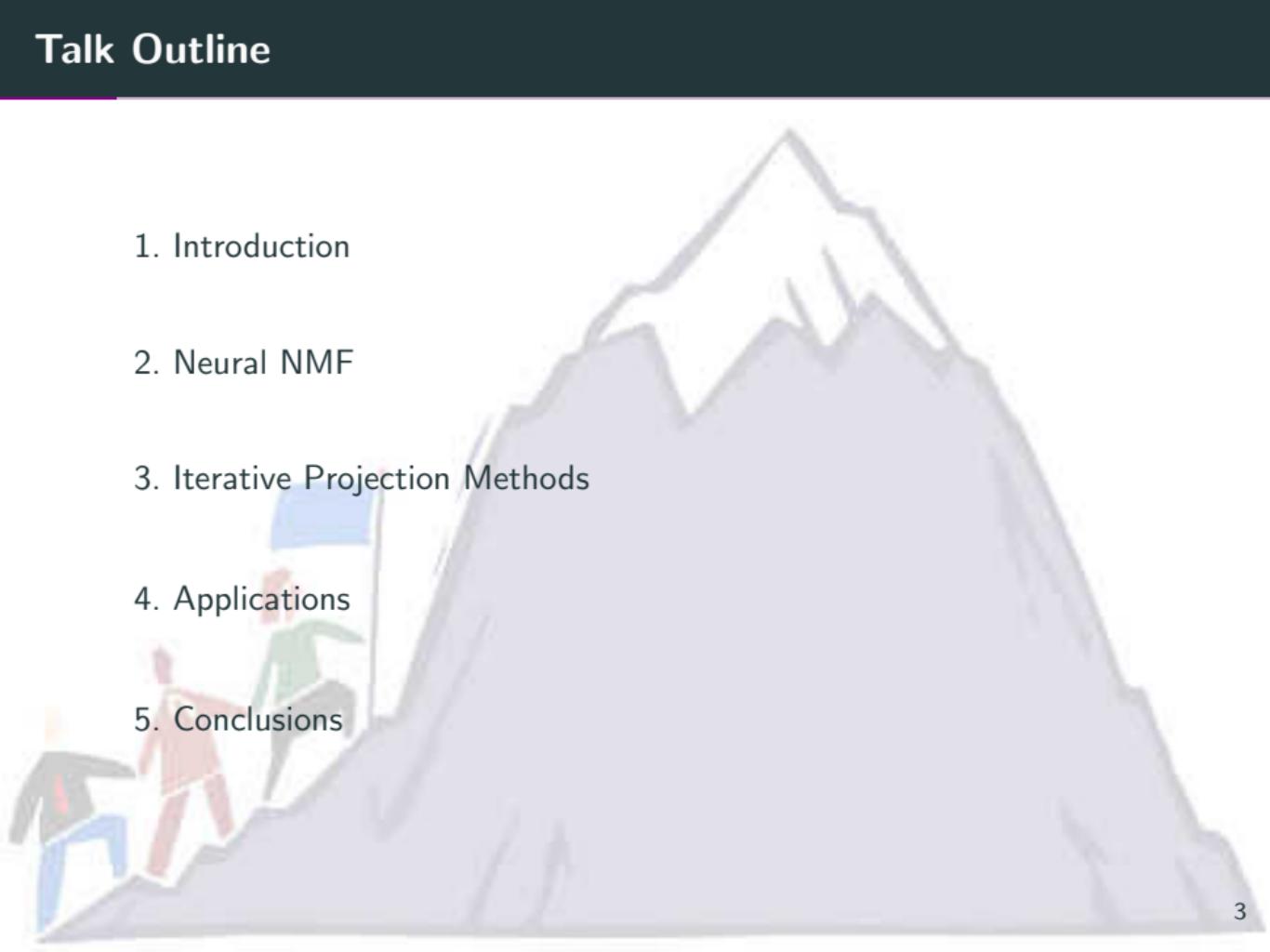
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Methods or Algorithms:

- ▷ perceptron
- ▷ **iterative projections**
- ▷ Wolfe's method
- ▷ iterative hard thresholding
- ▷ backpropagation
- ▷ ...

Talk Outline

- 
1. Introduction
 2. Neural NMF
 3. Iterative Projection Methods
 4. Applications
 5. Conclusions

Introduction

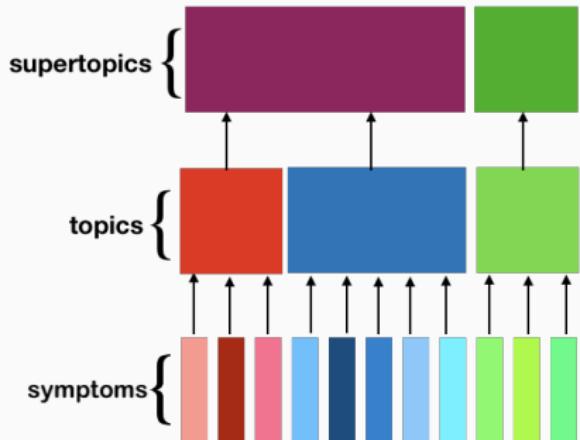
Motivation

- ▷ MyLymeData: large collection of Lyme disease patient survey data collected by LymeDisease.org (~12,000 patients, 100s of questions)



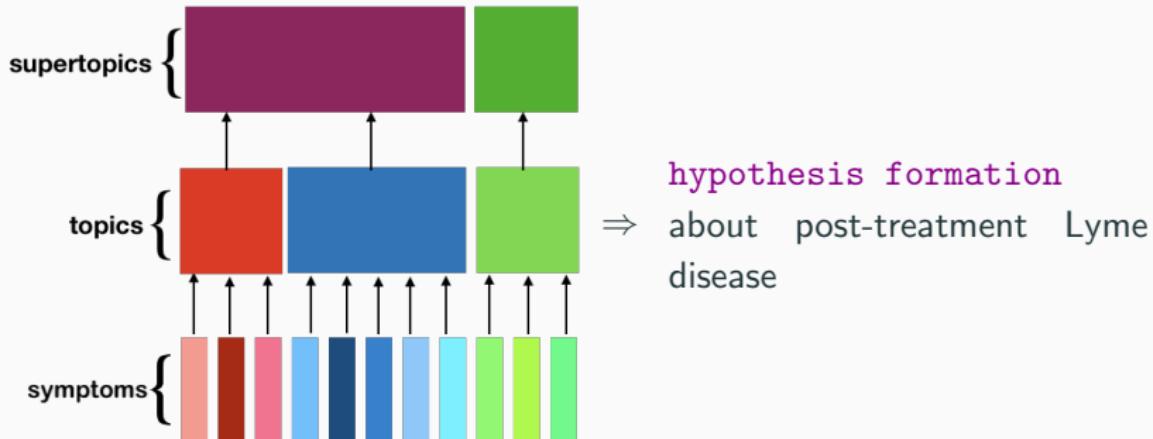
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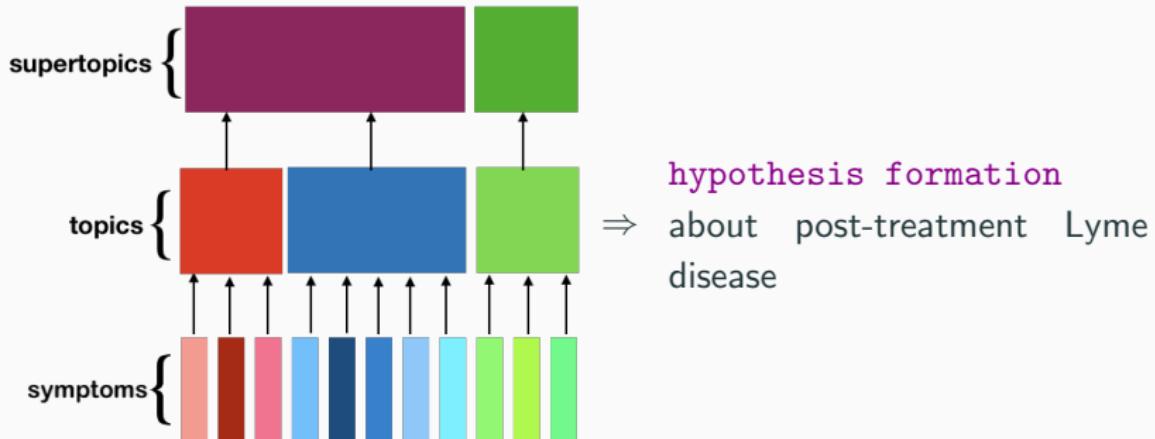
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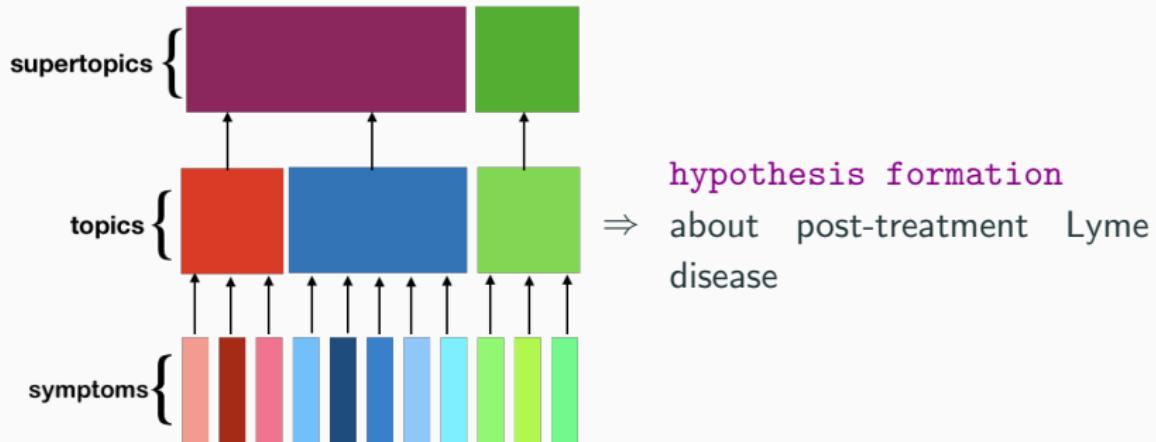
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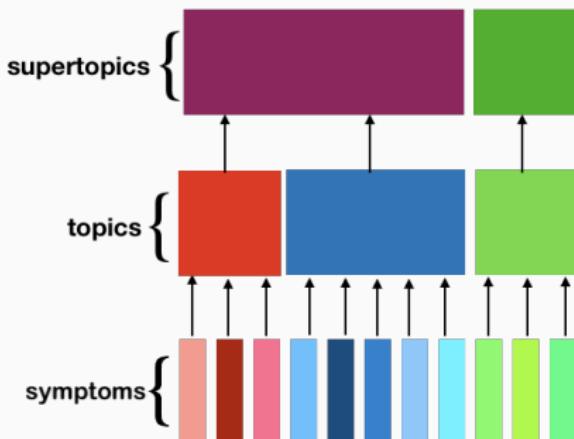
Main question: How can we identify the topic hierarchy of MyLymeData symptom questions?



Motivation



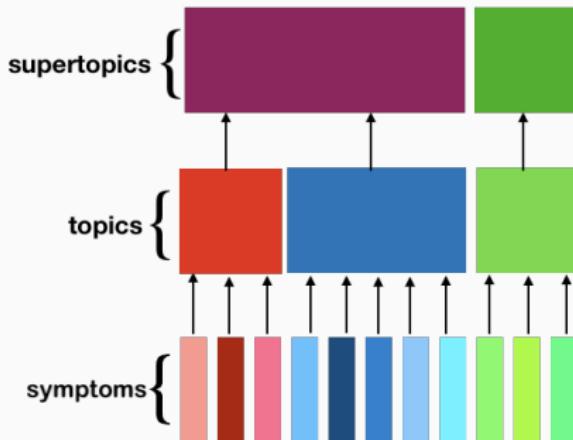
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Answer: Neural Nonnegative Matrix Factorization

[Gao, H., Molitor, Needell, Sadovnik, Will, Zhang '19]

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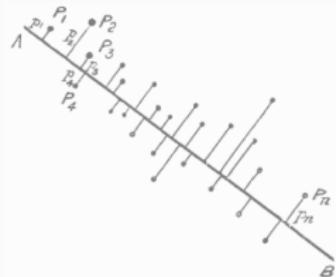
Sampling Kaczmarz-Motzkin Methods

[H., Ma '19], [De Loera, H., Needell '17]



Topic Modeling

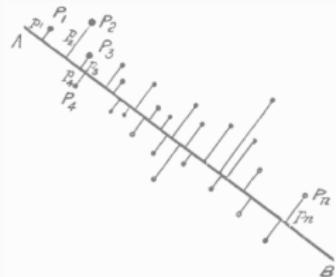
- ▷ principal component analysis (PCA)
 - [Pearson 1901]
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Pearson, K. (1901) *On lines and planes of closest fit to systems of points in space.*

Topic Modeling

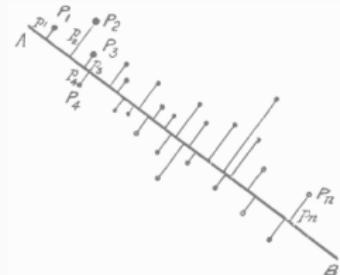
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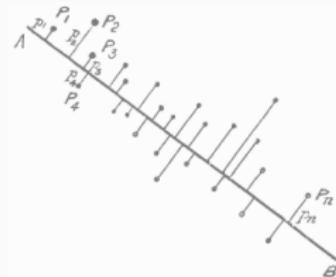
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- ▷ clustering (k -means, Gaussian mixtures)
 - [Lloyd 1957]
 - [Pearson 1894]



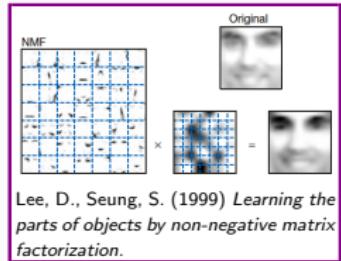
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- ▷ nonnegative matrix factorization (NMF)
 - [Paatero, Tapper 1994]
 - [Lee, Seung 1999]



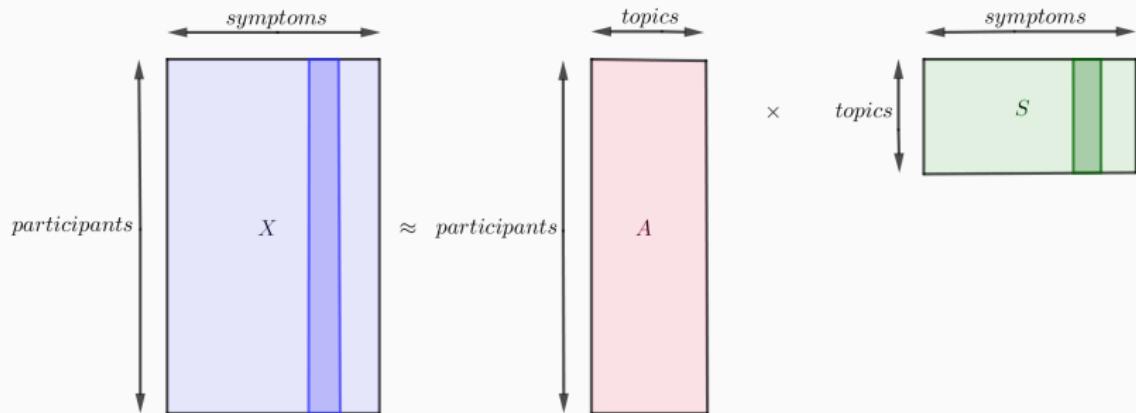
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Nonnegative Matrix Factorization (NMF)

Model: Given nonnegative data X , compute nonnegative A and S of lower rank so that

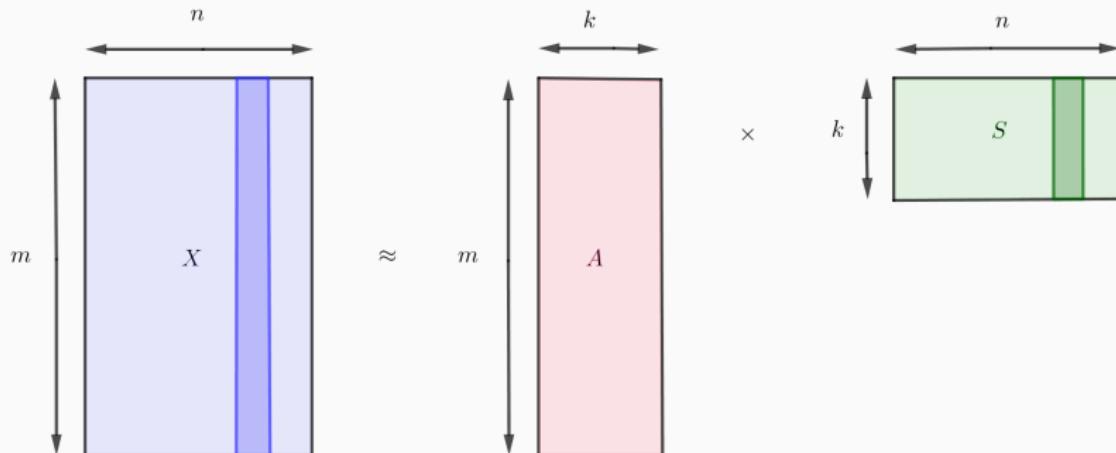
$$X \approx AS.$$



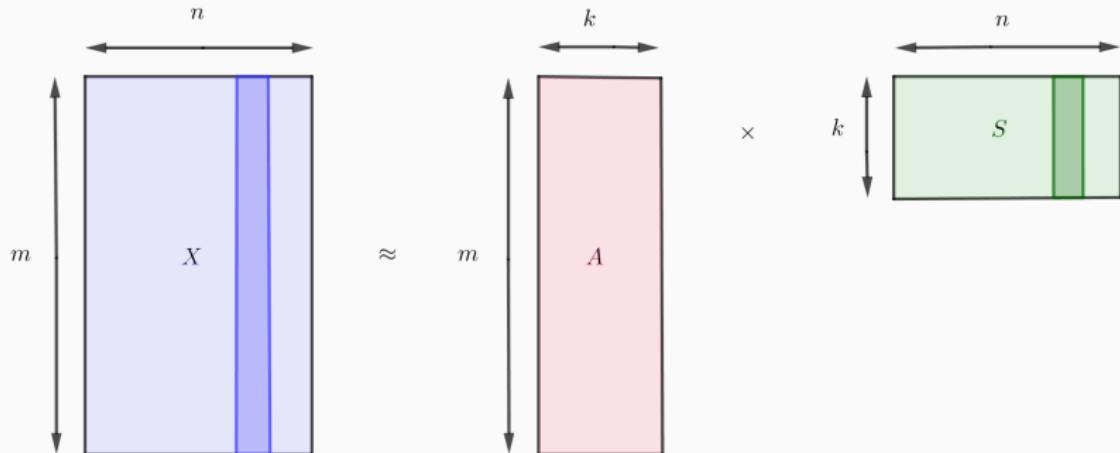
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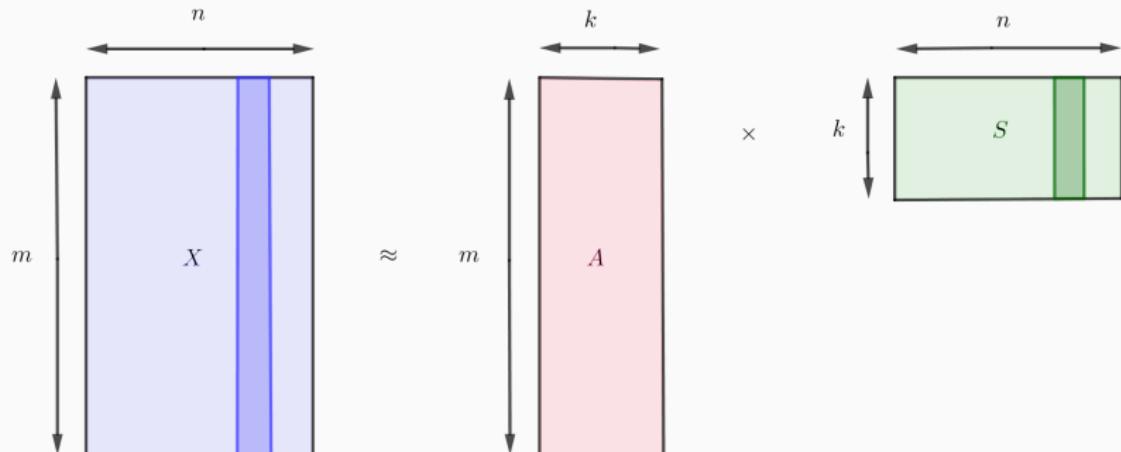
Nonnegative Matrix Factorization (NMF)



- ▷ Often formulated as optimization problem

$$\min_{A \in \mathbb{R}_{\geq 0}^{m \times k}, S \in \mathbb{R}_{\geq 0}^{k \times n}} \|X - AS\|_F.$$

Nonnegative Matrix Factorization (NMF)



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$$\min_{A \in \mathbb{R}_{\geq 0}^{m \times k}, S \in \mathbb{R}_{\geq 0}^{k \times n}} \|X - AS\|_F.$$

- ▷ Non-convex optimization problem, NP-hard to compute global optimum for fixed k [Vavasis 2008]

Hierarchical NMF

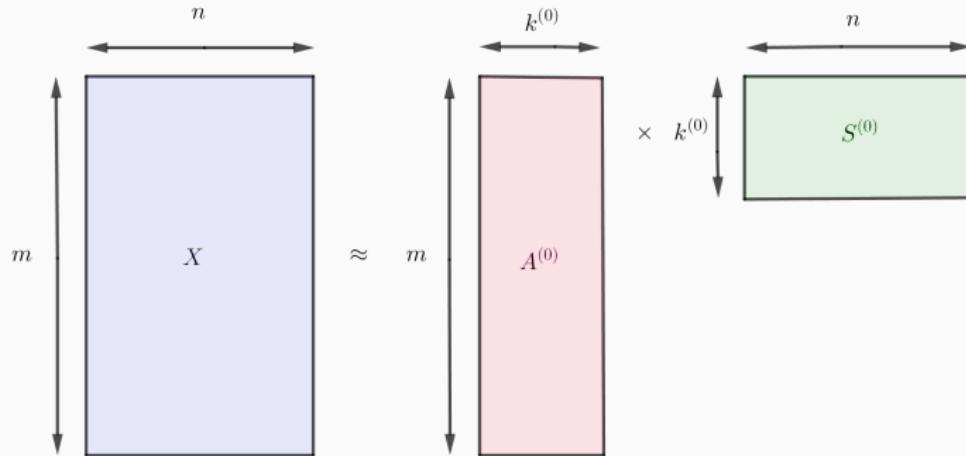
Model: Sequentially factorize

$$X \approx A^{(0)}S^{(0)}, S^{(0)} \approx A^{(1)}S^{(1)}, S^{(1)} \approx A^{(2)}S^{(2)}, \dots, S^{(\mathcal{L}-1)} \approx A^{(\mathcal{L})}S^{(\mathcal{L})}.$$

Hierarchical NMF

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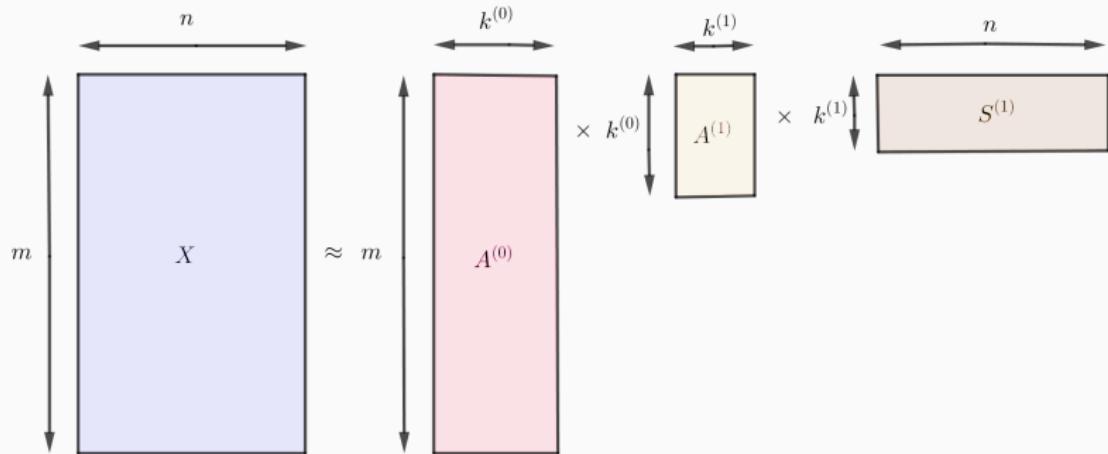
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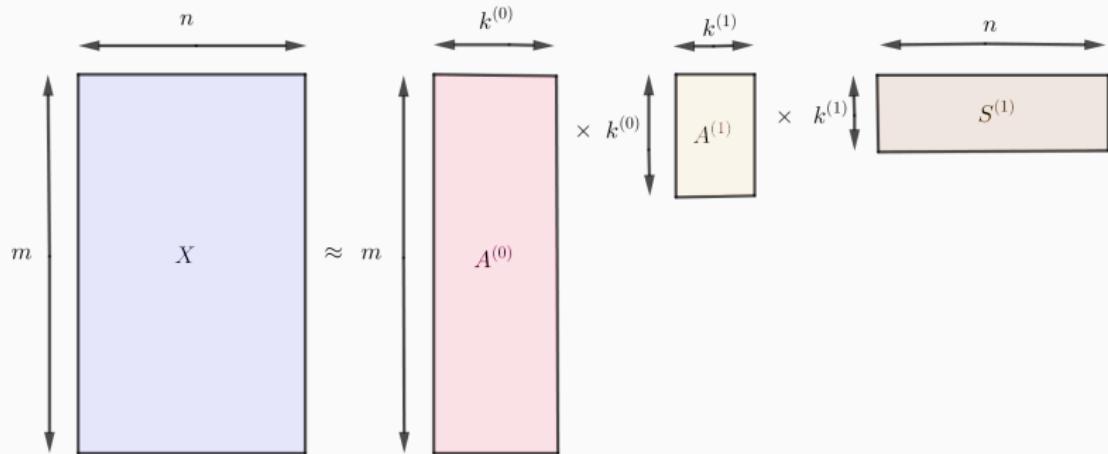
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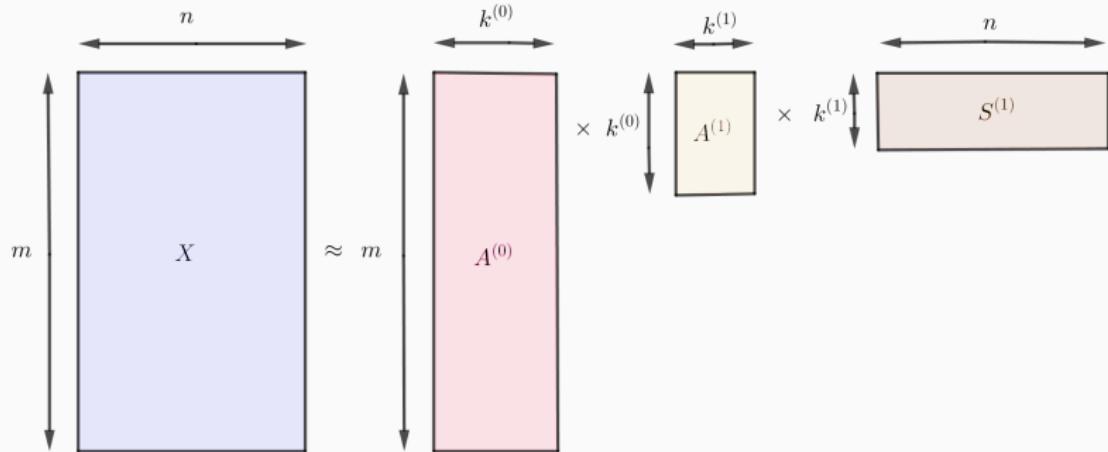


▷ $k^{(\ell)}$: supertopics collecting $k^{(\ell-1)}$ subtopics

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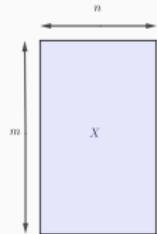


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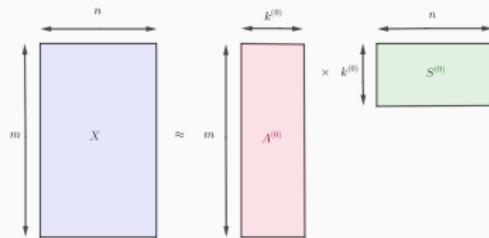
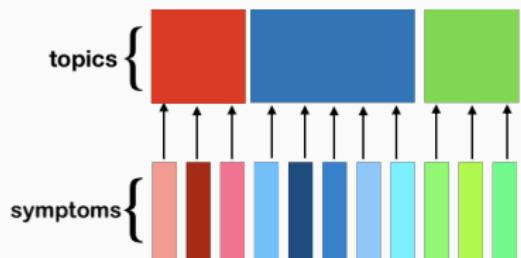
▷ error propagates through layers

Neural NMF

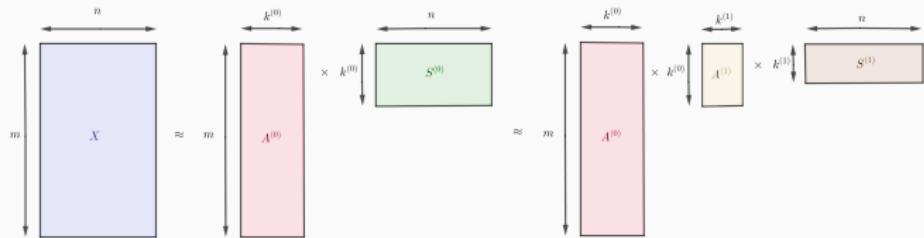
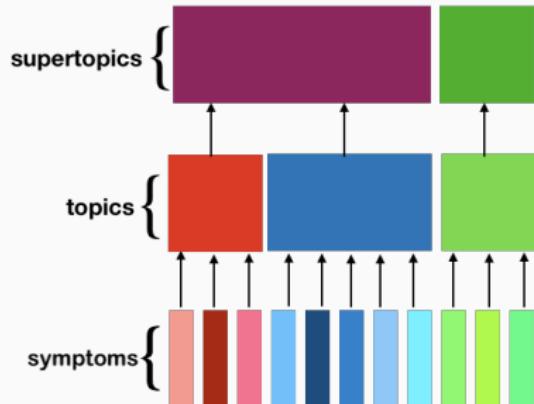
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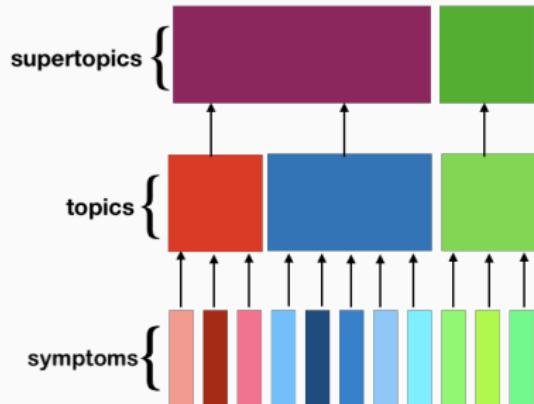
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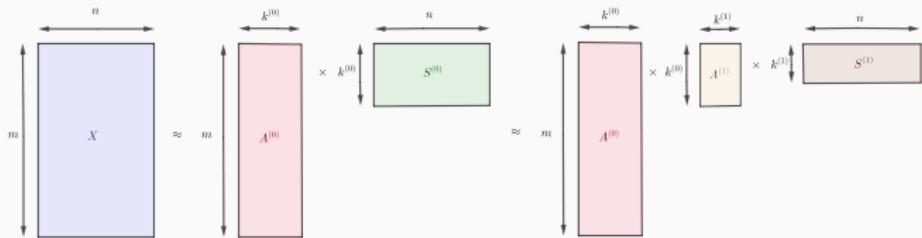
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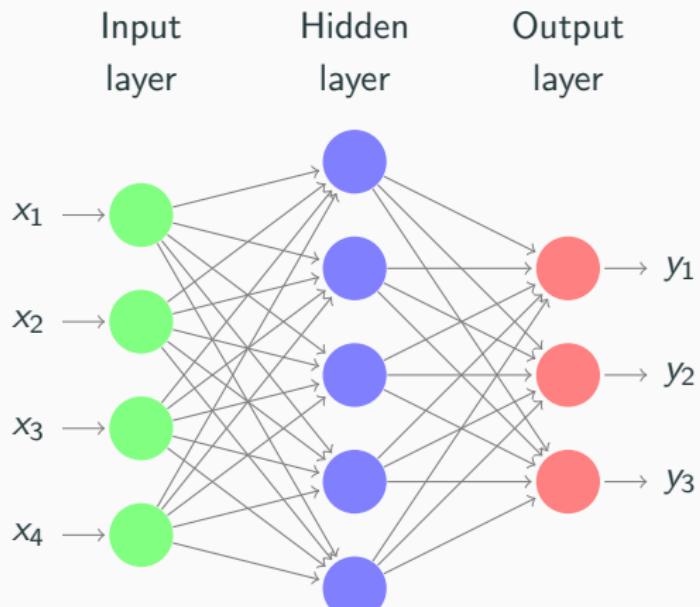
▷ hNMF can be implemented in a **feed-forward neural network** structure



Feed-forward Neural Networks

Goal: Identify weights W_1, W_2, \dots, W_L to minimize model error

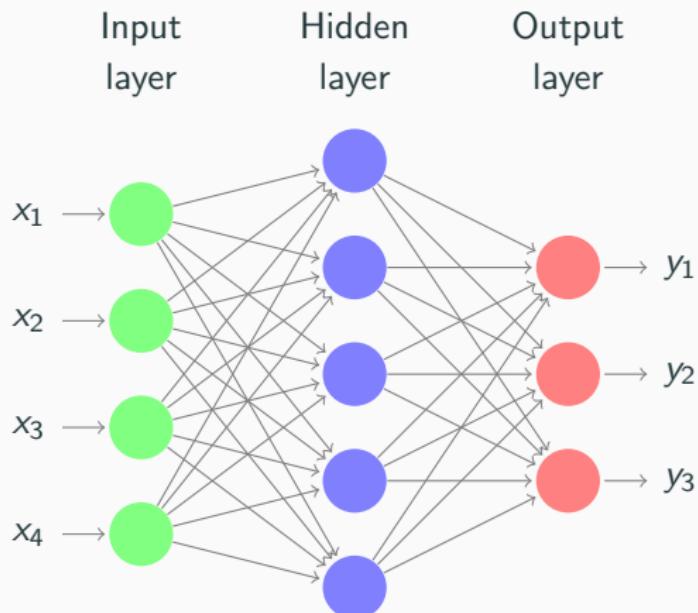
$$\sum_{n=1}^N E(\{W_i\}) = f(\mathbf{y}(\mathbf{x}_n, \{W_i\}), \mathbf{x}_n, \mathbf{t}_n).$$



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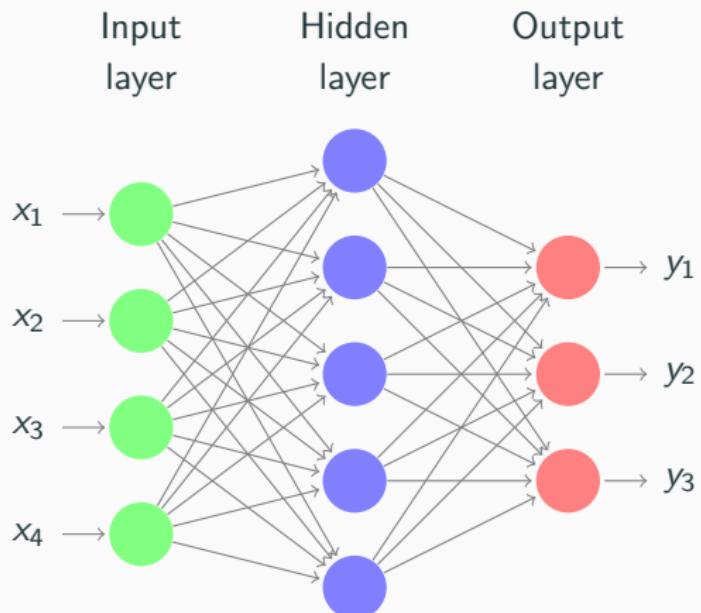
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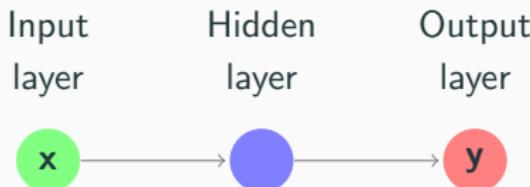
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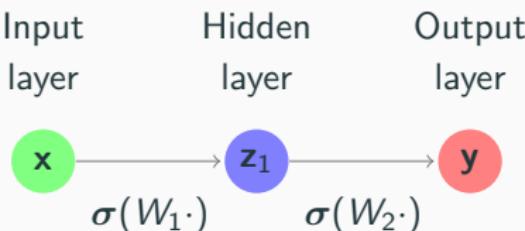
▷ forward

propagation:

$$\mathbf{z}_1 = \sigma(W_1 \mathbf{x}),$$

$$\mathbf{z}_2 = \sigma(W_2 \mathbf{z}_1), \dots,$$

$$\mathbf{y} = \sigma(W_L \mathbf{z}_{L-1})$$

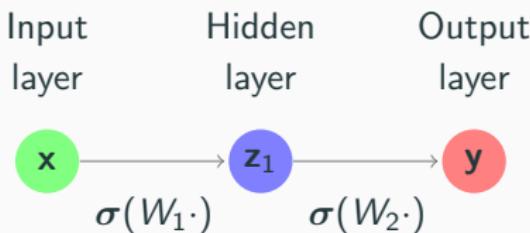


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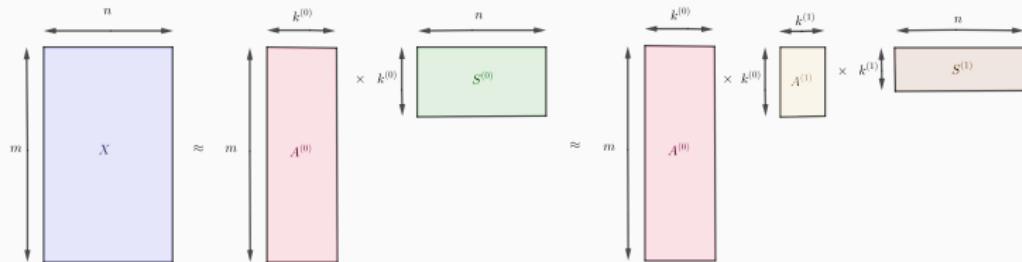
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- ▷ forward propagation:
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- ▷ back propagation:
update $\{W_i\}$ with
 $\nabla E(\{W_i\})$

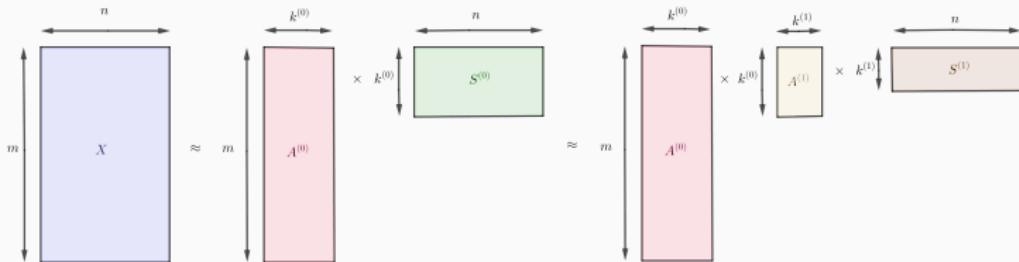
Our method: Neural NMF

Goal: Develop true forward and back propagation algorithms for hNMF.



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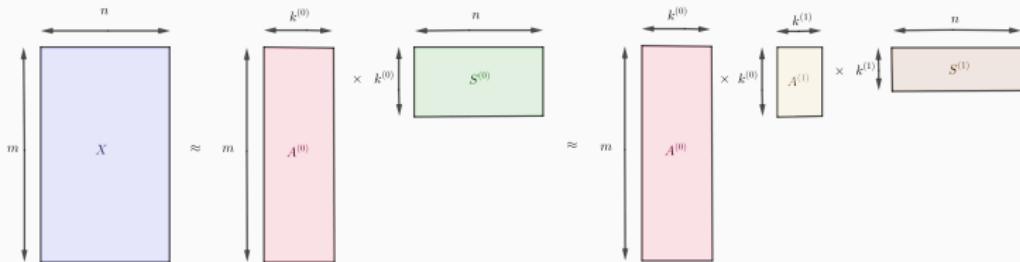
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- ▷ Regard the A matrices as independent variables, determine the S matrices from the A matrices.

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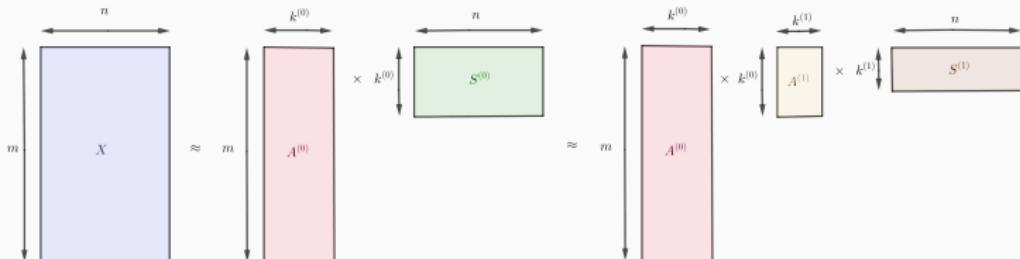
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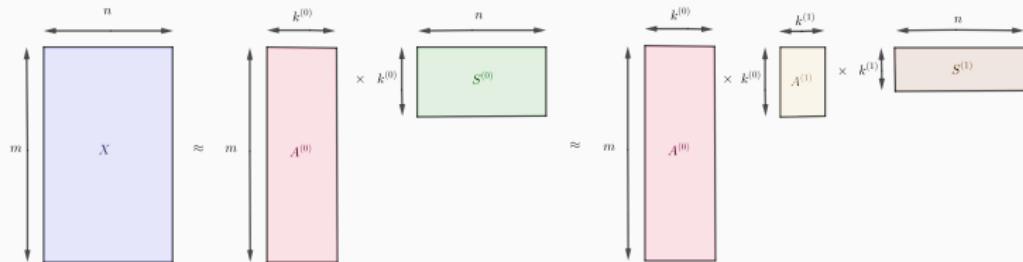
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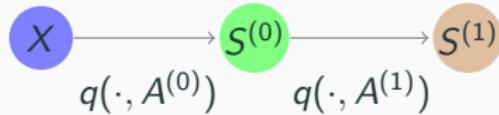
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- ▷ Pin the values of S to those of A by recursively setting $S^{(\ell)} := q(S^{(\ell-1)}, A^{(\ell)})$.

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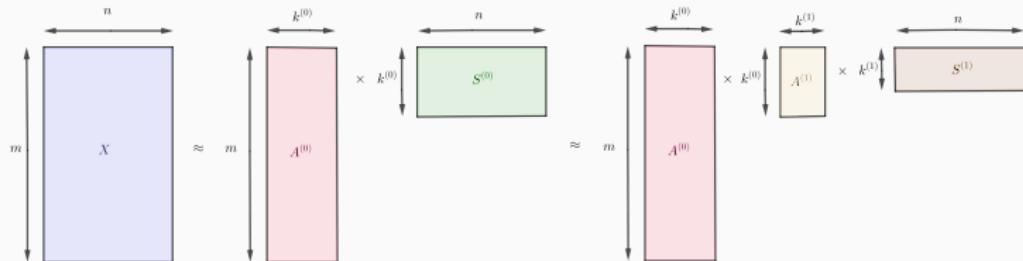


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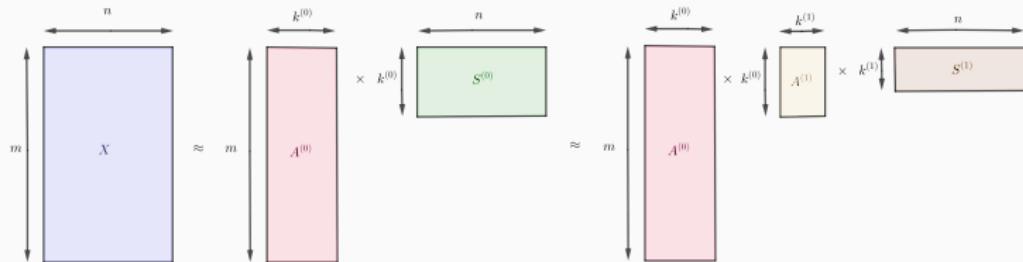
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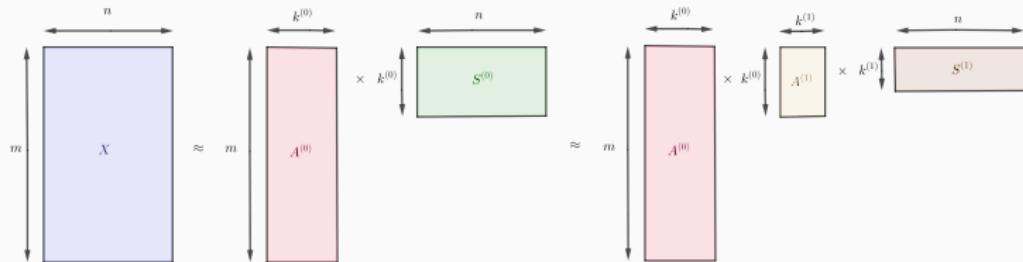


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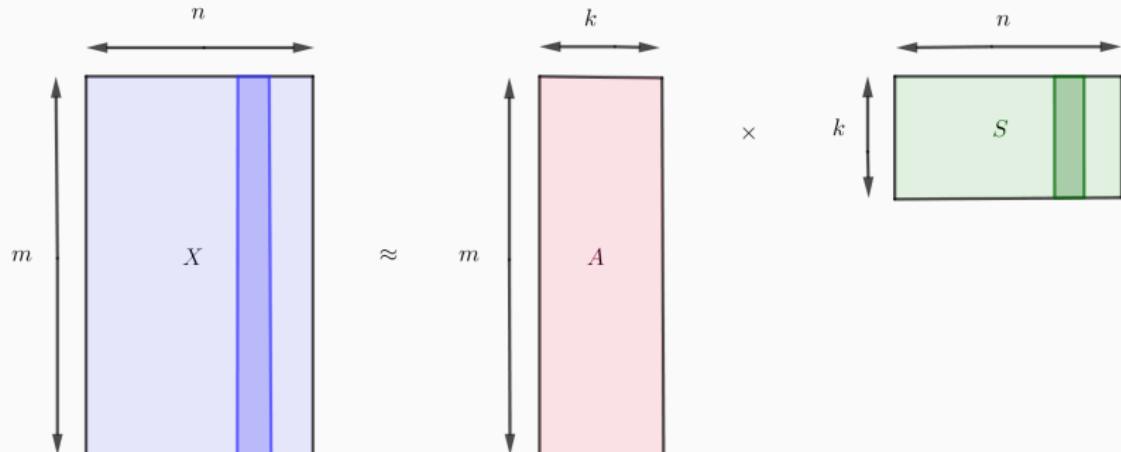


Training:

- ▷ forward propagation:
 $S^{(0)} = q(X, A^{(0)})$,
 $S^{(1)} = q(S^{(0)}, A^{(1)})$, ...,
 $S^{(L)} = q(S^{(L-1)}, A^{(L)})$
- ▷ back propagation: update $\{A^{(i)}\}$ with $\nabla E(\{A^{(i)}\})$

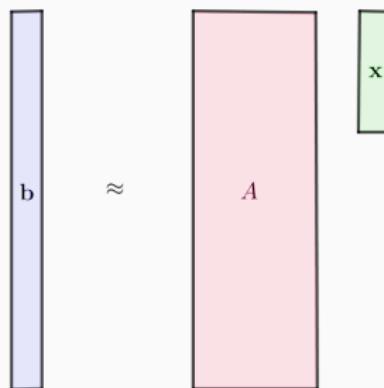
Least-squares Subroutine

- ▷ least-squares is a fundamental subroutine in forward-propagation



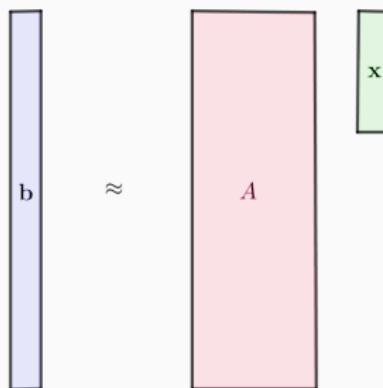
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Least-squares Subroutine

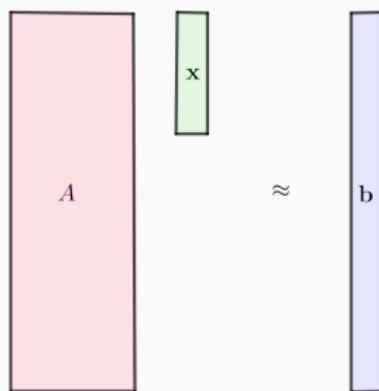
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- ▷ **iterative projection methods** can solve these problems

Iterative Projection Methods

General Setup



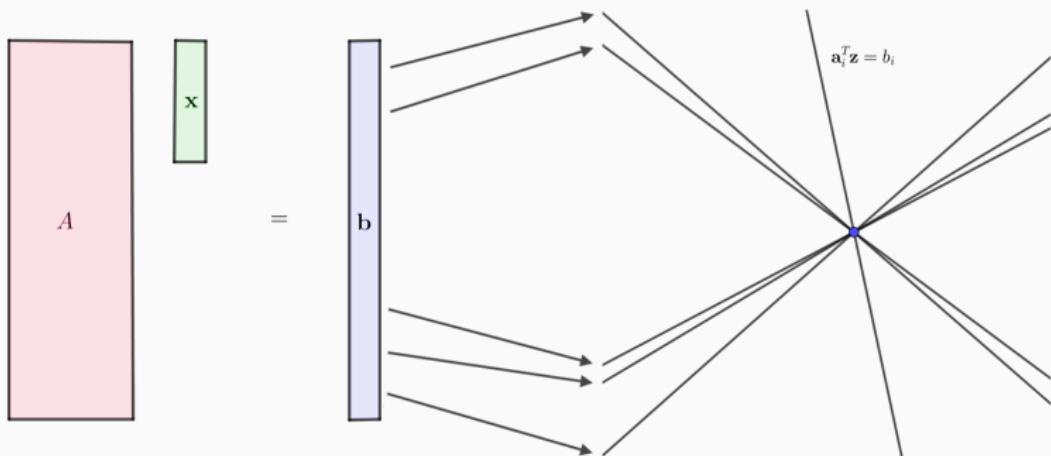
General Setup

We are interested in solving **highly overdetermined systems of equations**, $Ax = b$, where $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$ and $m \gg n$. Rows are denoted \mathbf{a}_i^T .

$$\begin{matrix} A & & \\ & \mathbf{x} & \\ & = & \\ & b & \end{matrix}$$

General Setup

We are interested in solving **highly overdetermined systems of equations**, $Ax = b$, where $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$ and $m \gg n$. Rows are denoted a_i^T .



Iterative Projection Methods

If $\{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} = \mathbf{b}\}$ is nonempty, these methods construct an **approximation** to a solution:

1. Randomized Kaczmarz Method



Applications:

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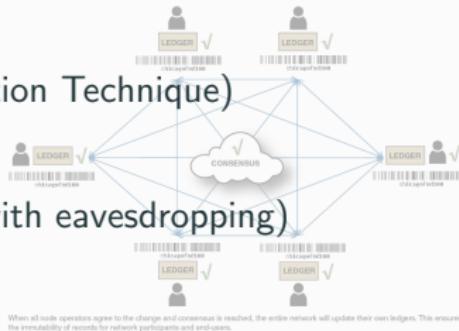
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2. Motzkin's Method
3. Sampling Kaczmarz-Motzkin Methods (SKM)



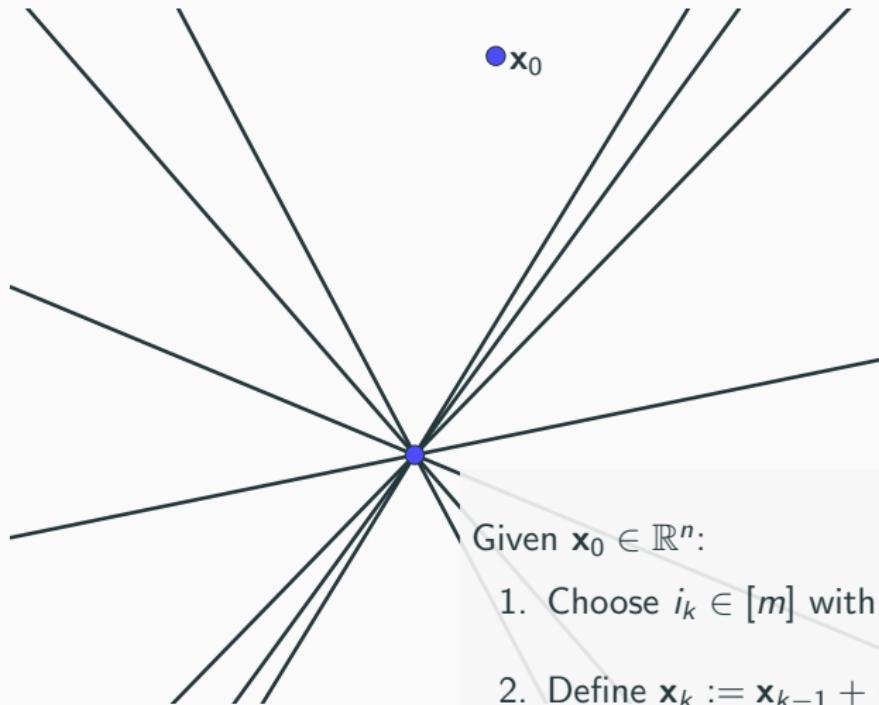
Applications:

1. Tomography (Algebraic Reconstruction Technique)
2. Linear programming
3. Average consensus (greedy gossip with eavesdropping)



When all node operators agree to the change and consensus is reached, the entire network will update their own ledgers. This ensures the immutability of records for network participants and end-users.

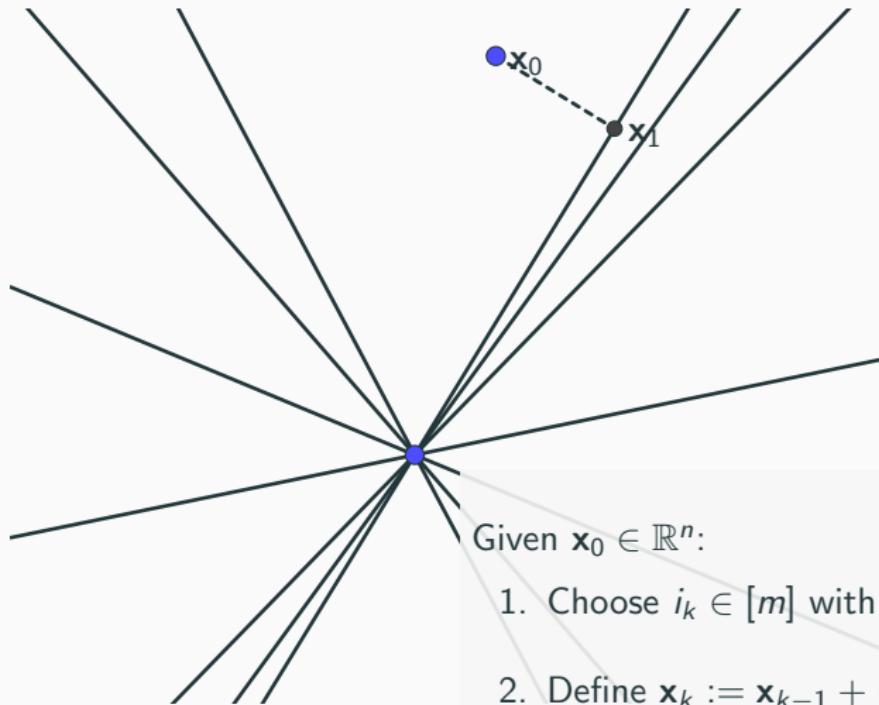
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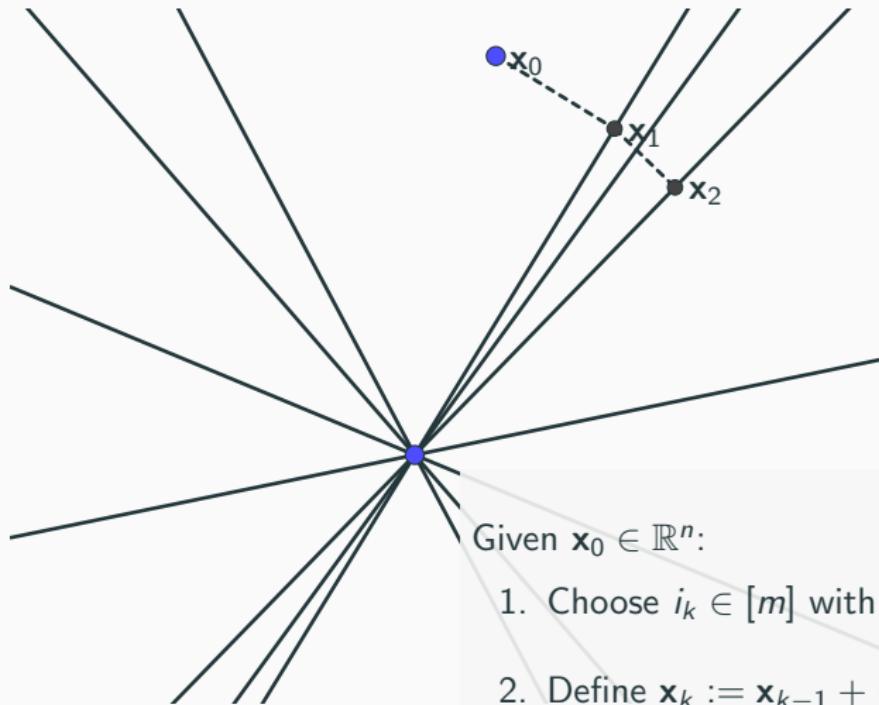
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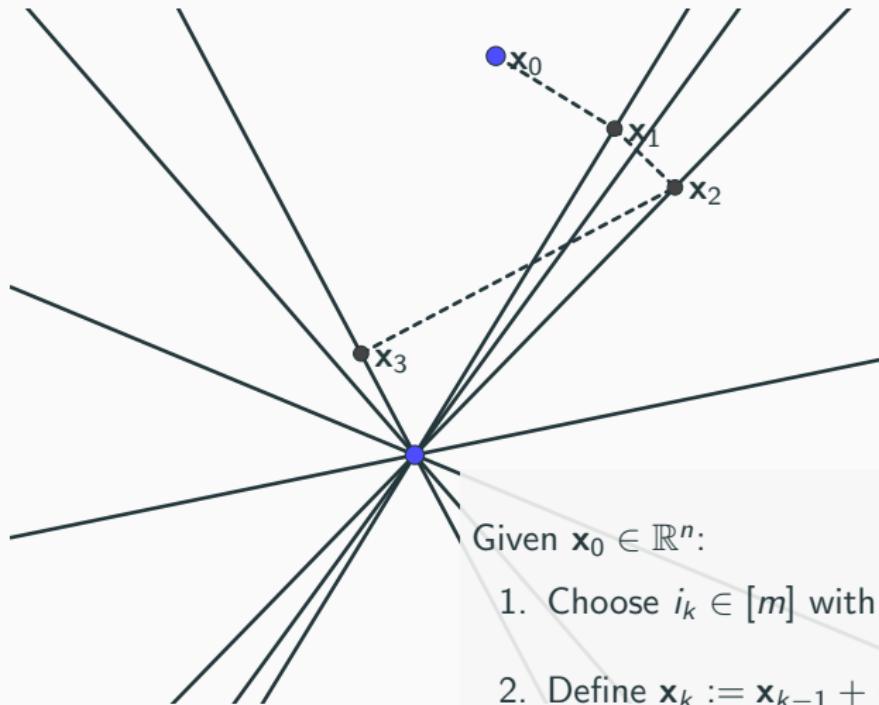
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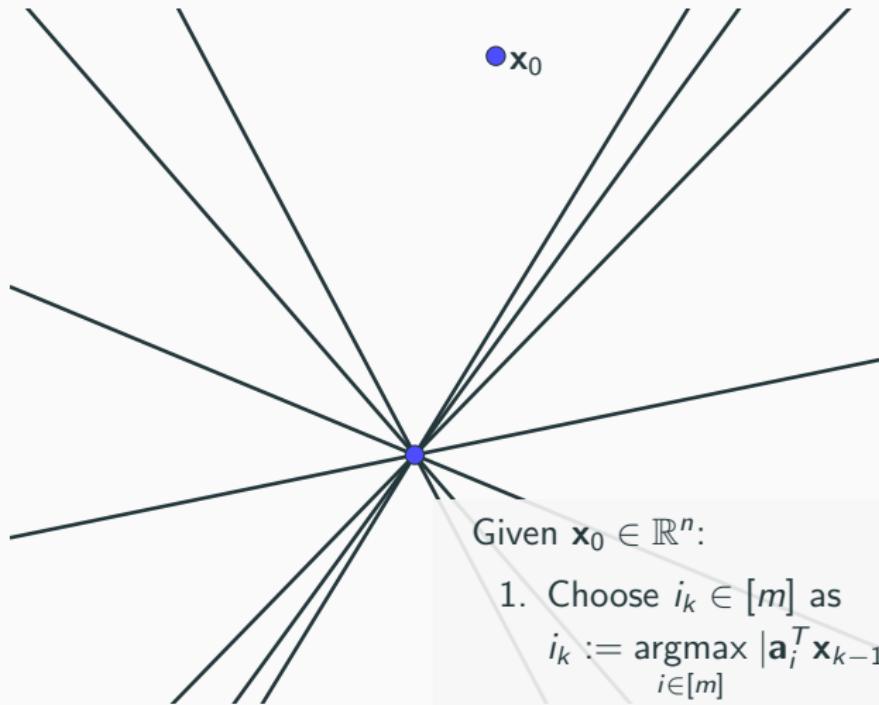
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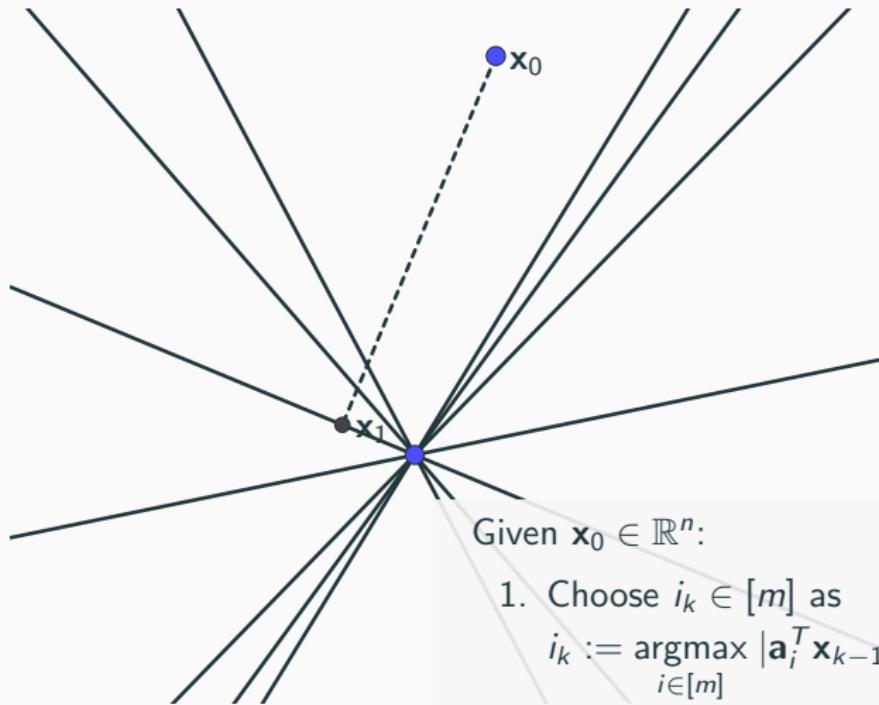
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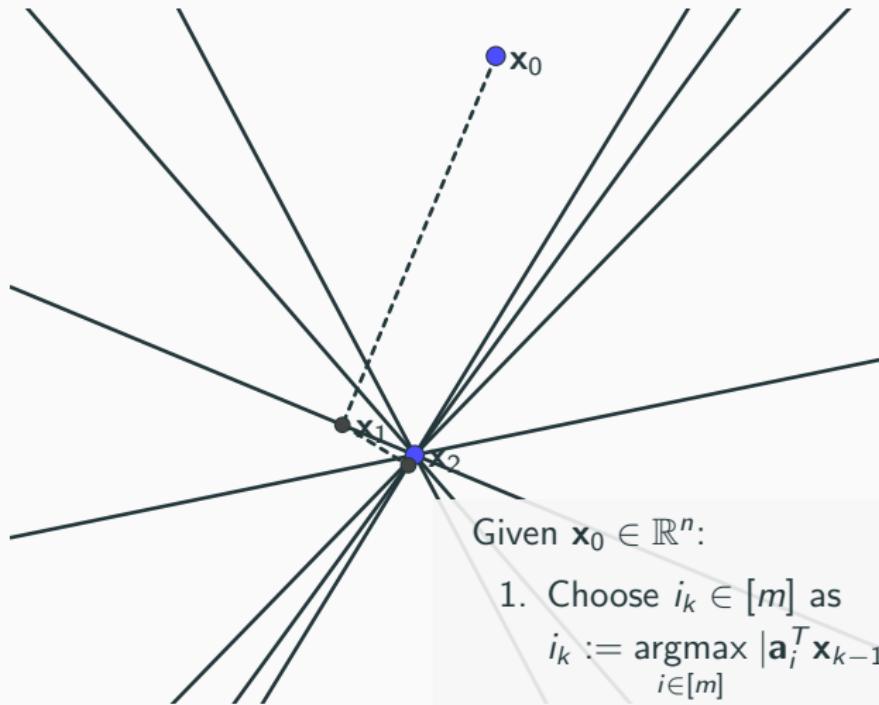
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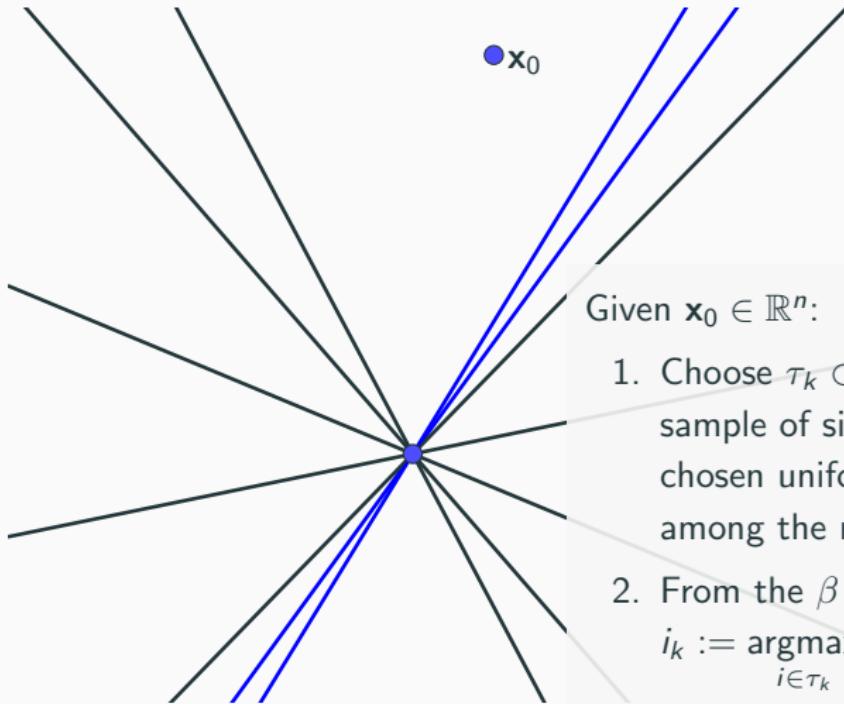
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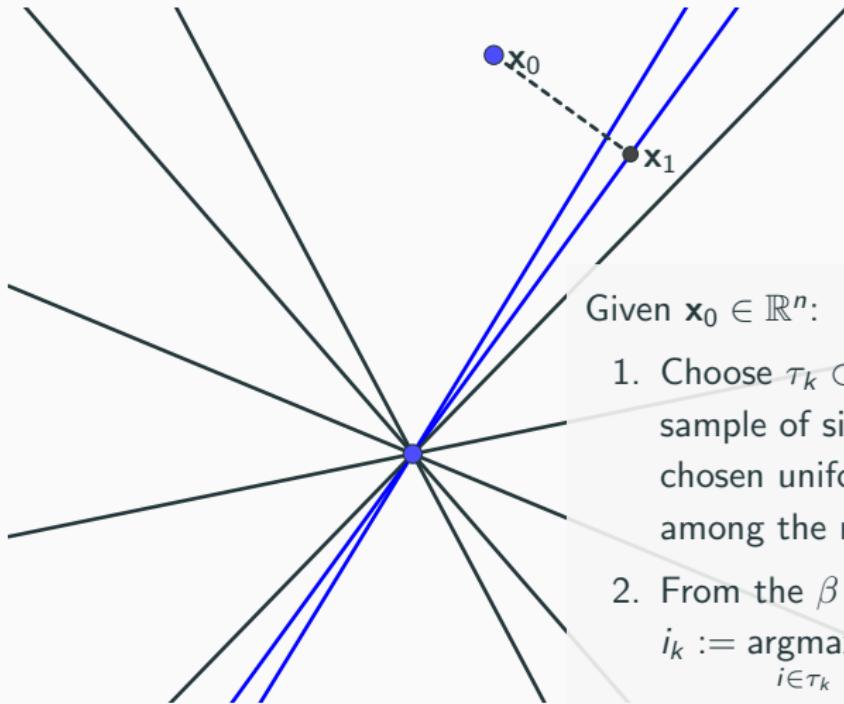
Our Hybrid Method (SKM)



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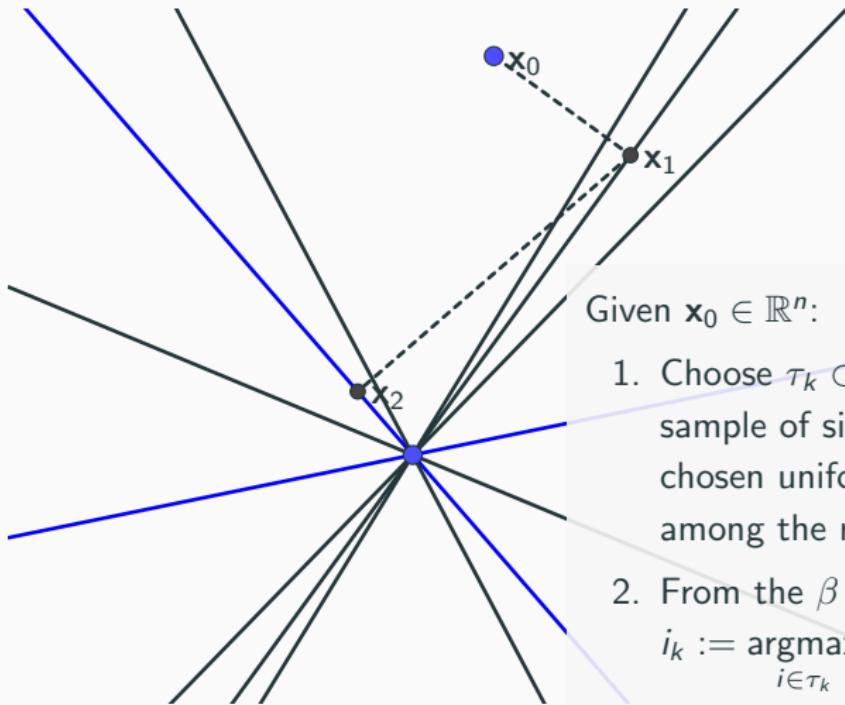
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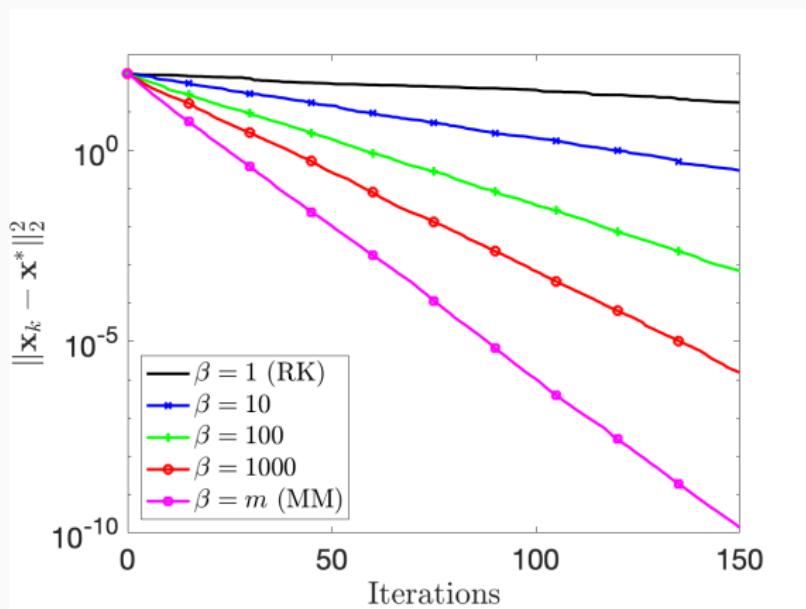
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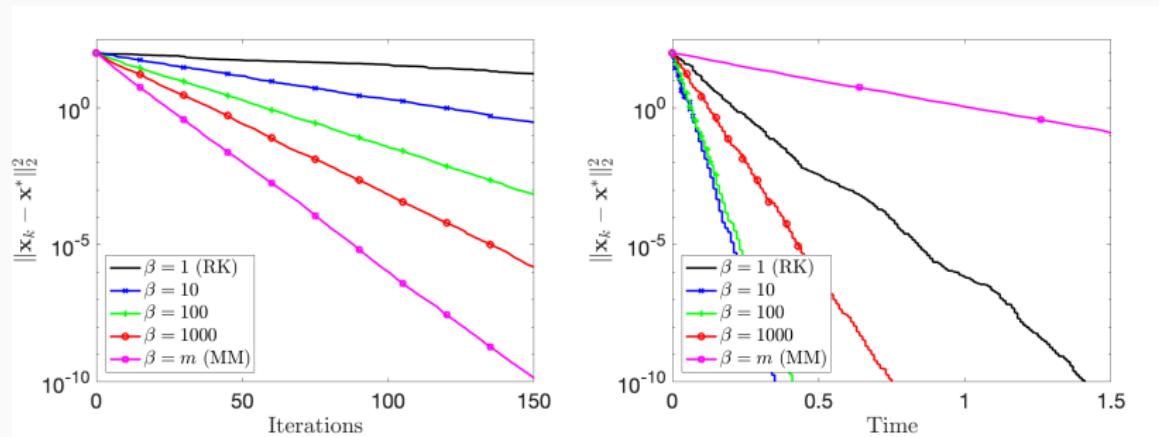
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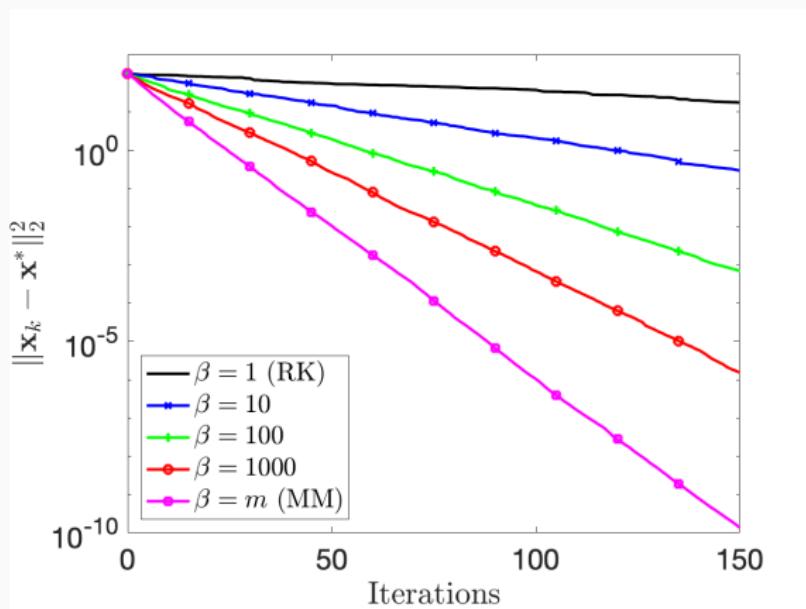
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Convergence Rates

Below are the convergence rates for the methods on a system, $\mathbf{A}\mathbf{x} = \mathbf{b}$, which is consistent with unique solution \mathbf{x} , whose rows have been normalized to have unit norm.

- ▷ RK (Strohmer, Vershynin '09):

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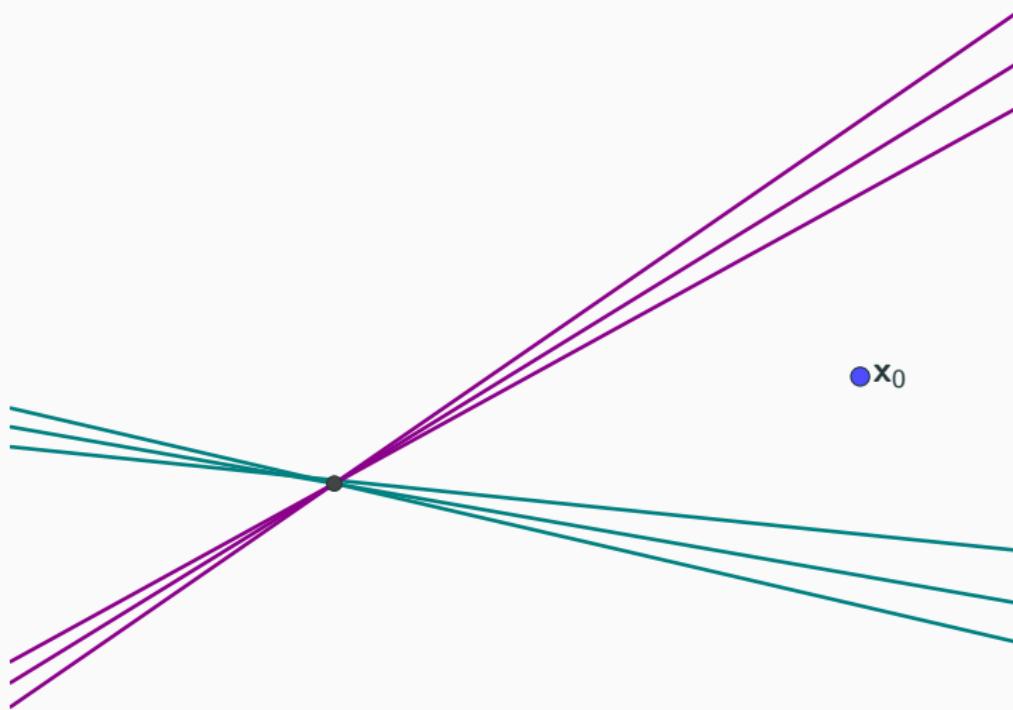
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Why are these all the same?

A Pathological Example



Structure of the Residual

Several works have used sparsity of the residual to improve the convergence rate of greedy methods.

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However, not much sparsity can be expected in most cases. Instead, we'd like to use dynamic range of the residual to guarantee faster convergence.

$$\gamma_k := \frac{\sum_{\tau \in \binom{[m]}{\beta}} \|A_\tau \mathbf{x}_k - \mathbf{b}_\tau\|_2^2}{\sum_{\tau \in \binom{[m]}{\beta}} \|A_\tau \mathbf{x}_k - \mathbf{b}_\tau\|_\infty^2}$$

Accelerated Convergence Rate

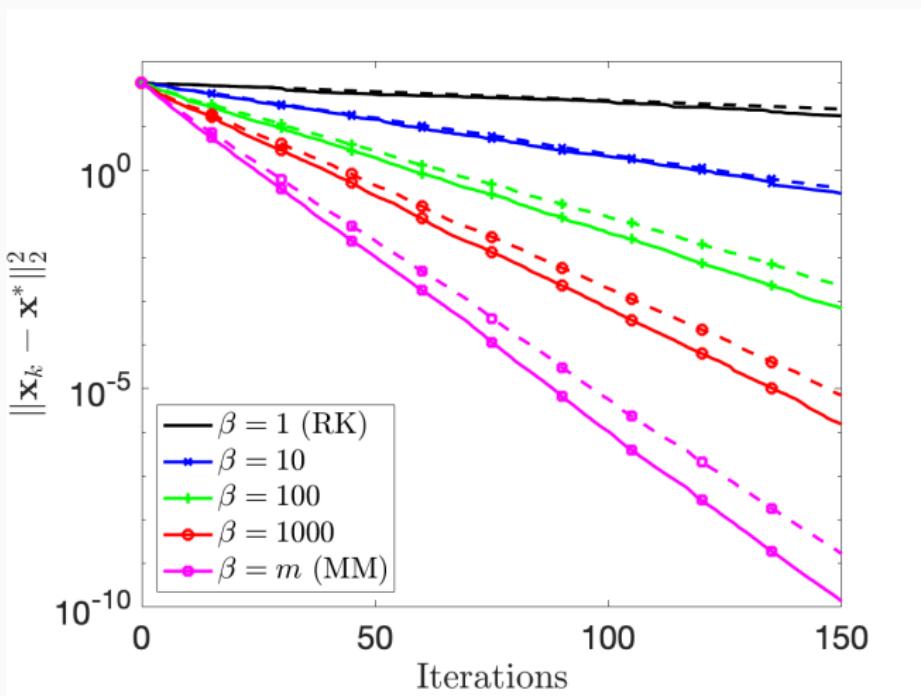
Theorem (H. - Ma 2019)

Let A be normalized so $\|\mathbf{a}_i\|_2 = 1$ for all rows $i = 1, \dots, m$. If the system $A\mathbf{x} = \mathbf{b}$ is consistent with the unique solution \mathbf{x}^* then the SKM method converges at least linearly in expectation and the rate depends on the dynamic range of the random sample of rows of A , τ_j . Precisely, in the $j + 1$ st iteration of SKM, we have

$$\mathbb{E}_{\tau_j} \|\mathbf{x}_{j+1} - \mathbf{x}^*\|_2^2 \leq \left(1 - \frac{\beta \sigma_{\min}^2(A)}{\gamma_j m}\right) \|\mathbf{x}_j - \mathbf{x}^*\|_2^2,$$

where $\gamma_j := \frac{\sum_{\tau \in \binom{[m]}{\beta}} \|A_\tau \mathbf{x}_j - \mathbf{b}_\tau\|_2^2}{\sum_{\tau \in \binom{[m]}{\beta}} \|A_\tau \mathbf{x}_j - \mathbf{b}_\tau\|_\infty^2}$.

Accelerated Convergence Rate



- ▷ A is 50000×100 Gaussian matrix, consistent system
- ▷ bound uses dynamic range of sample of β rows

What can we say about γ_j ?

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SKM	$\alpha = 1 - \frac{\sigma_{\min}^2(A)}{m}$
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- ▷ nontrivial bounds on γ_k for Gaussian and average consensus systems

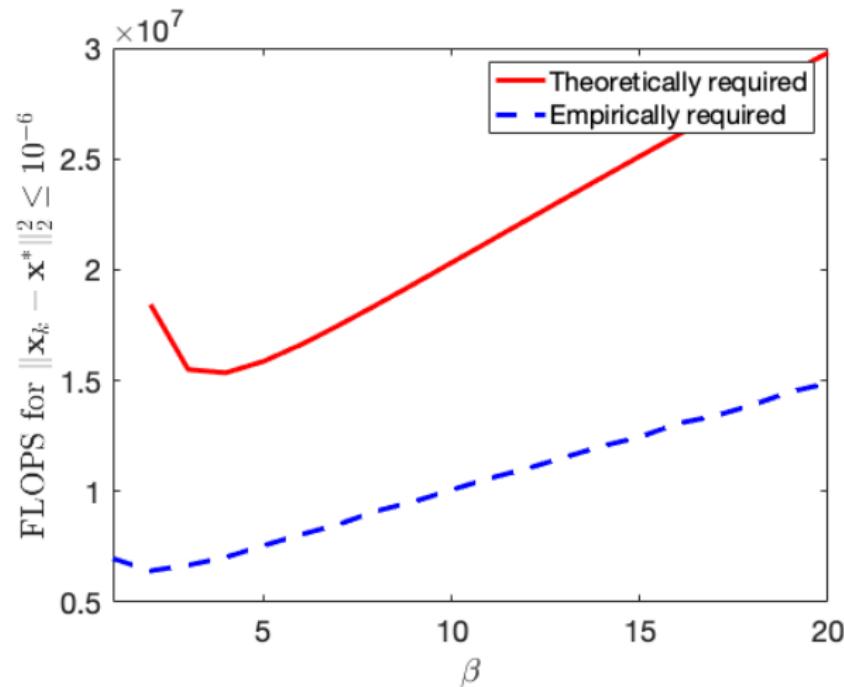
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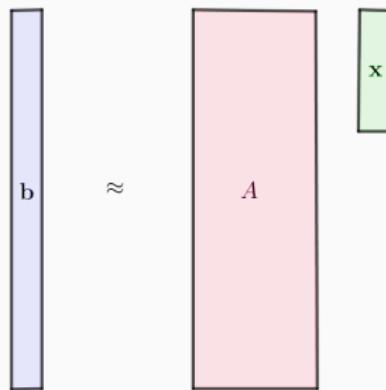
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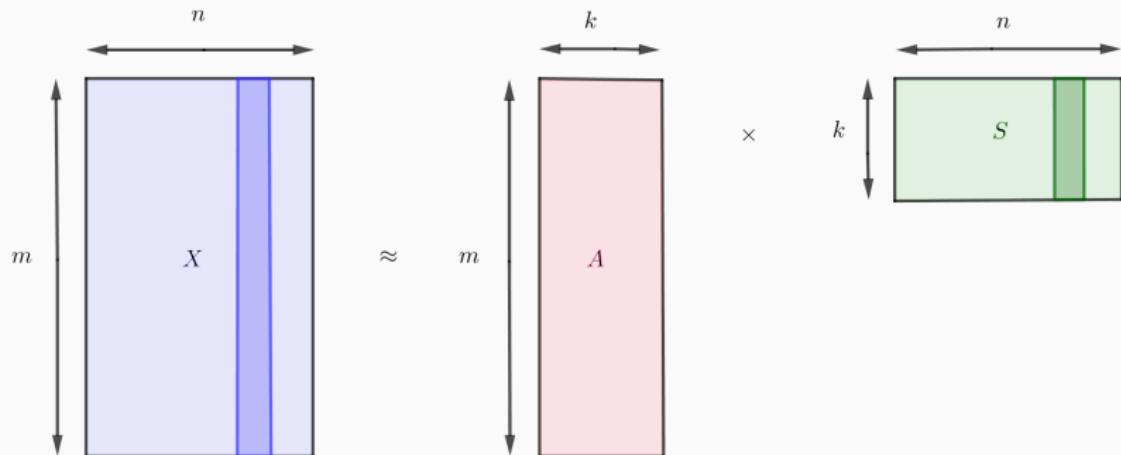
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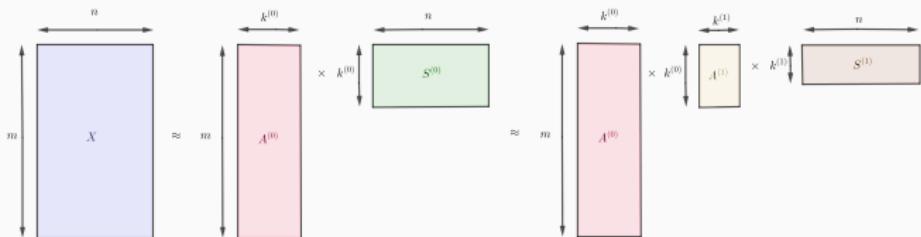
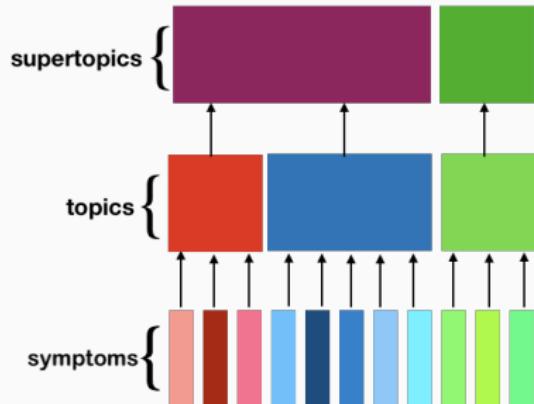
Back to Hierarchical NMF



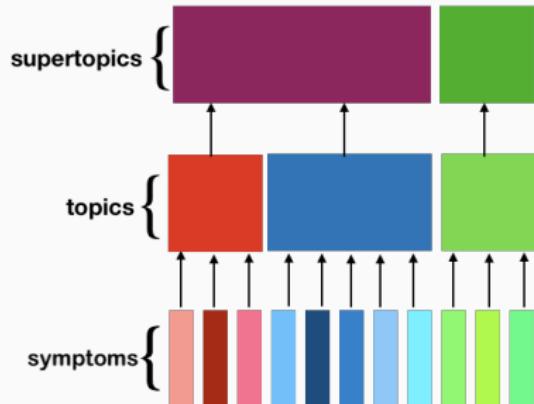
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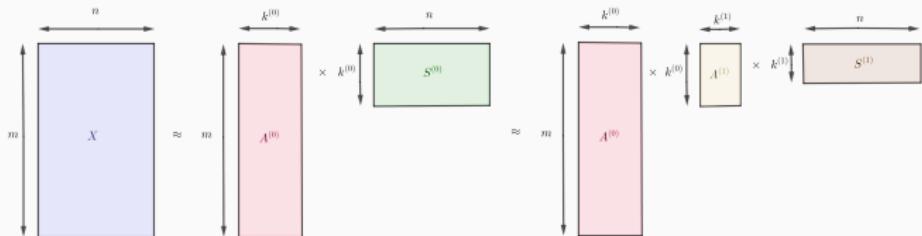


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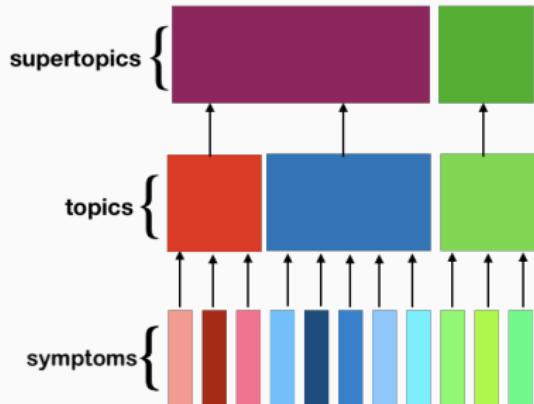


Compare:

▷ hNMF (sequential NMF)

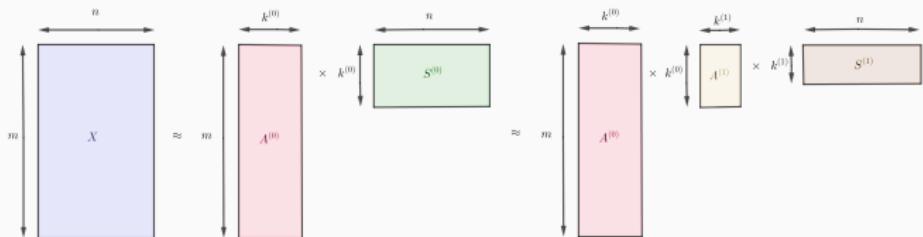


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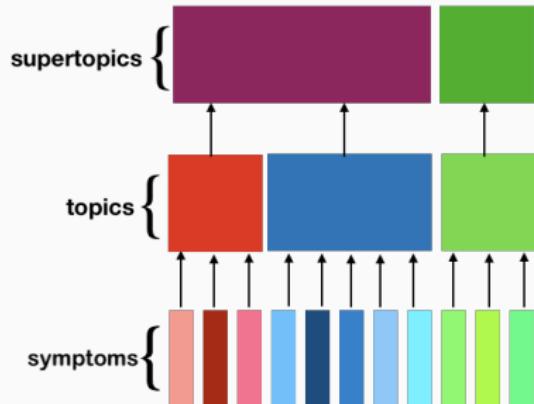


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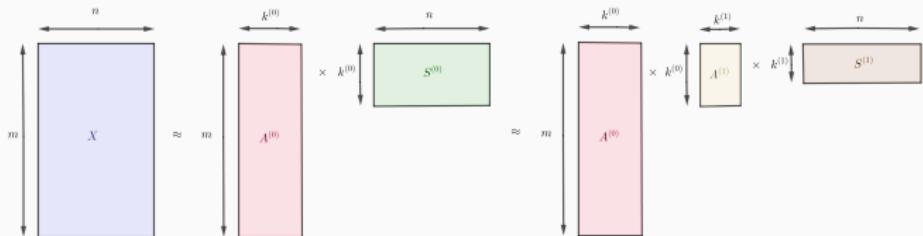


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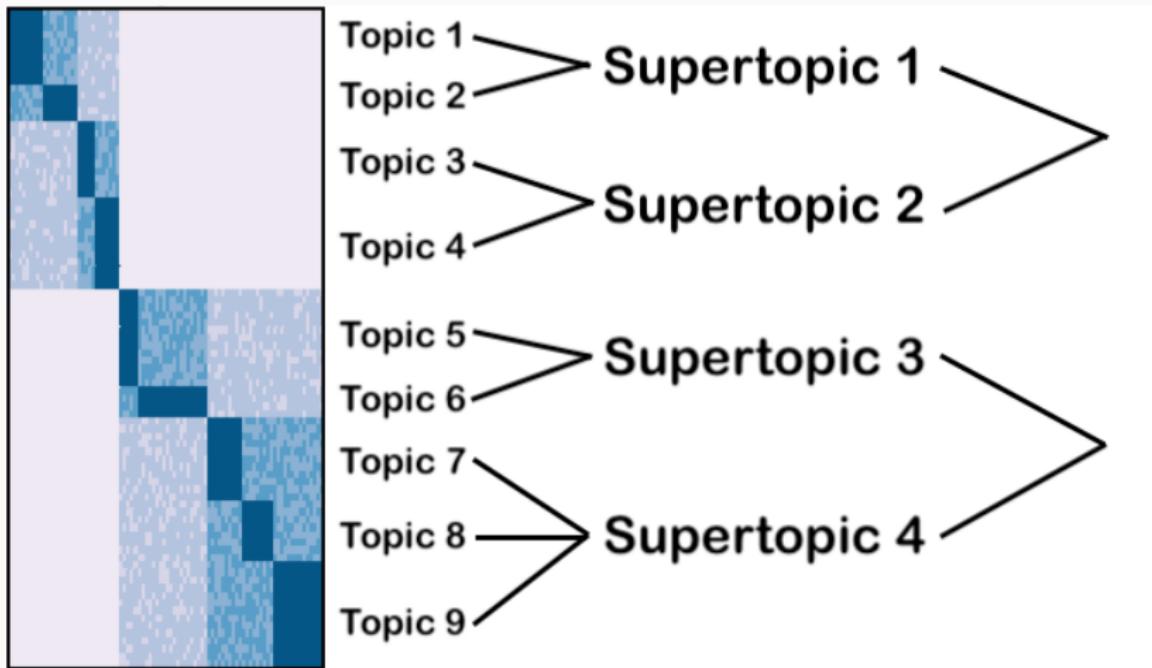
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- ▷ Neural NMF

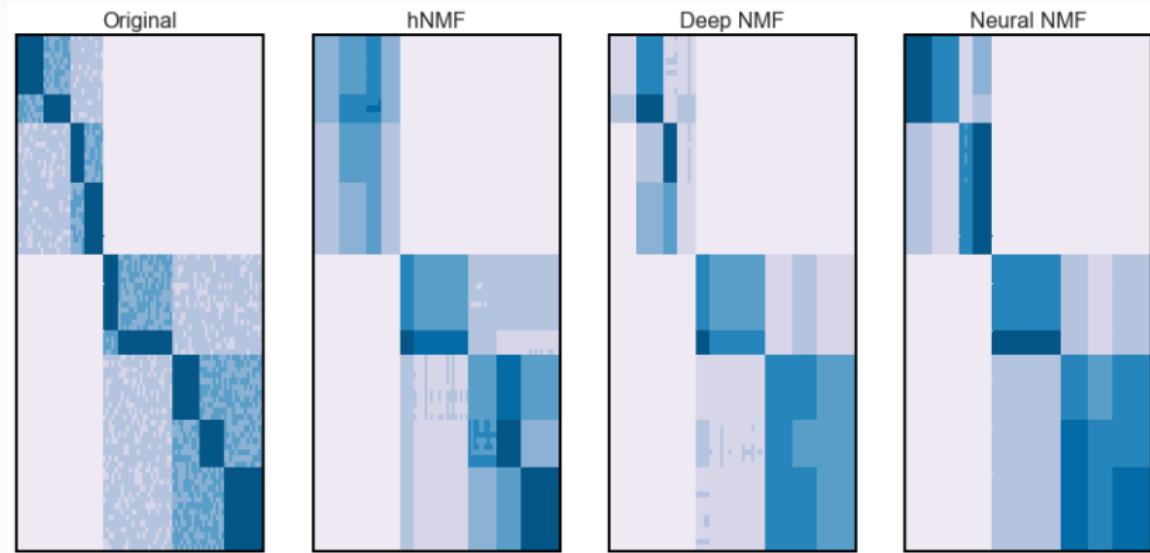


Applications

Experimental results: synthetic data

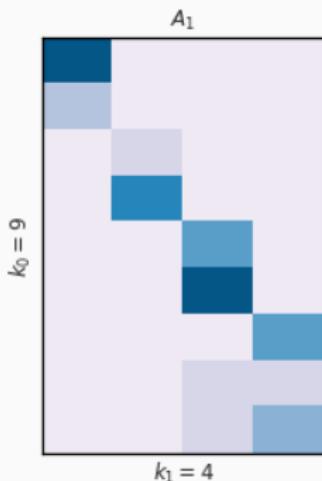
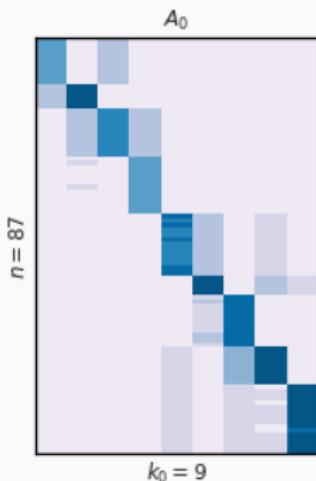
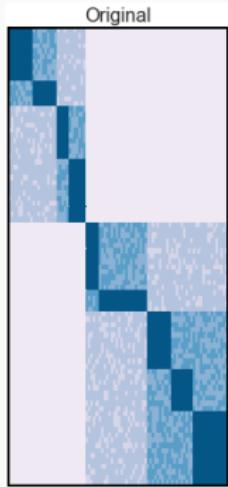


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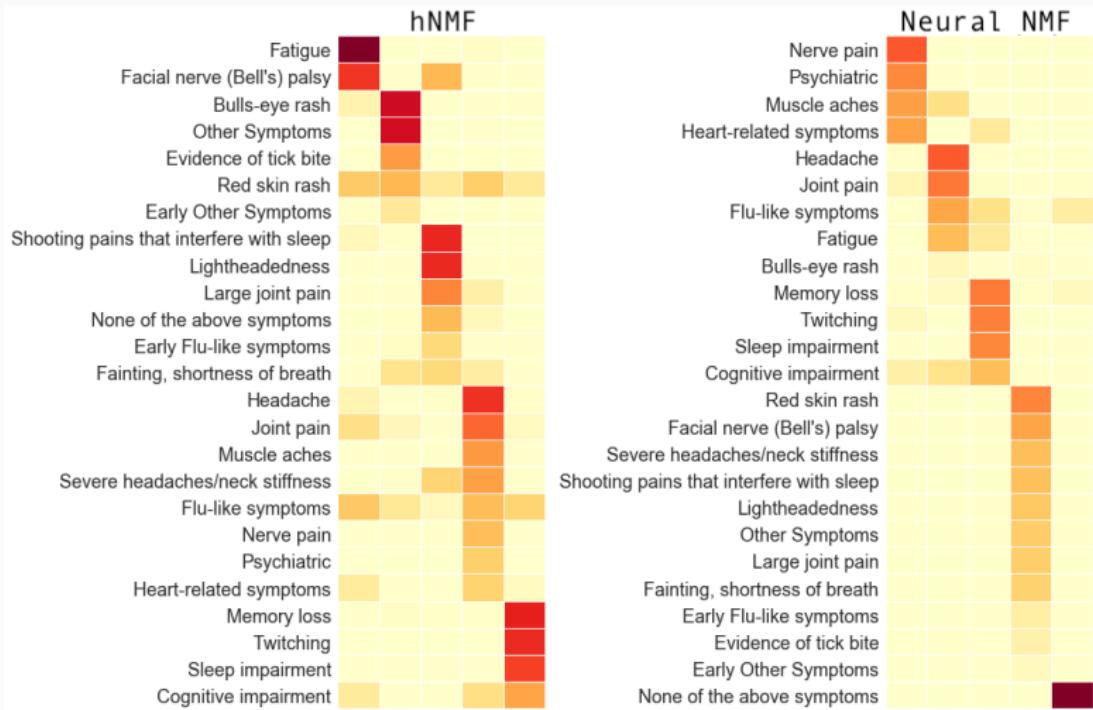
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 $(k^{(0)} = 9, k^{(1)} = 4)$

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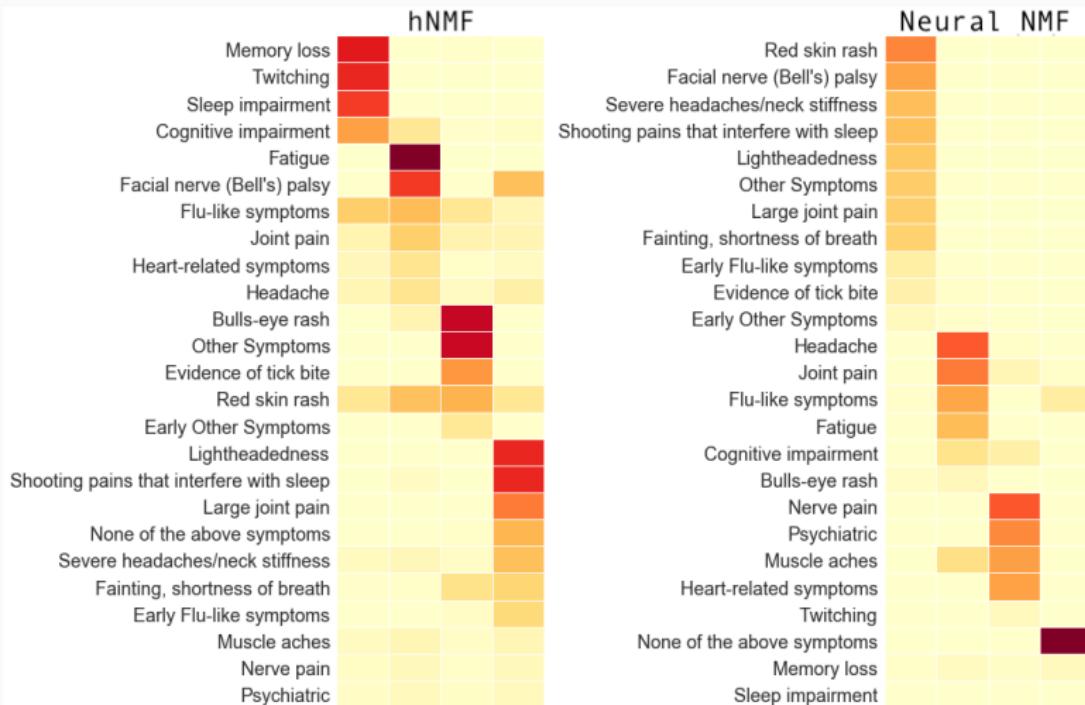


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Experimental results: MyLymeData



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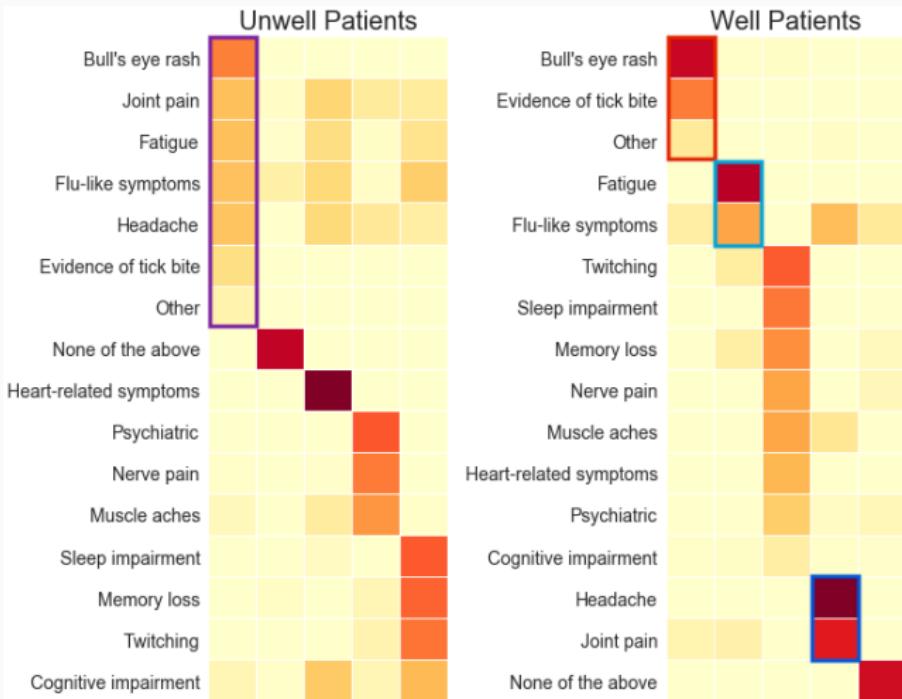


$$k^{(0)} = 6$$

$$k^{(1)} = 5$$

$$k^{(2)} = 4$$

Experimental results: MyLymeData



MyLymeData Takeaways



- ▷ bulls-eye rash (diagnosing symptoms) topic does not seem to persist for smaller number of topics



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- ▷ unwell and well patients have very different presentation of bulls-eye rash symptom in topics



- ▷ bulls-eye rash (diagnosing symptoms) topic does not seem to persist for smaller number of topics

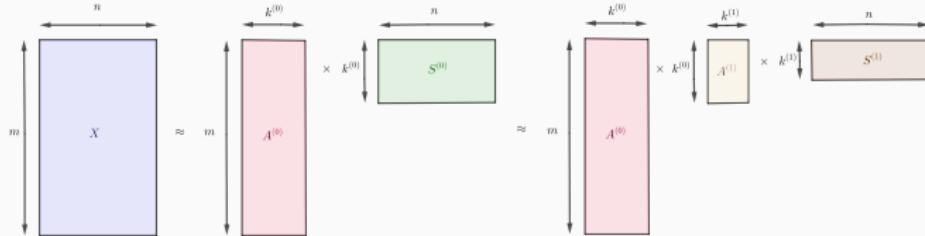
- ▷ unwell and well patients have very different presentation of bulls-eye rash symptom in topics

- ▷ patients unwell because lacking bulls-eye rash for diagnosis or indicative of different disease pathway?

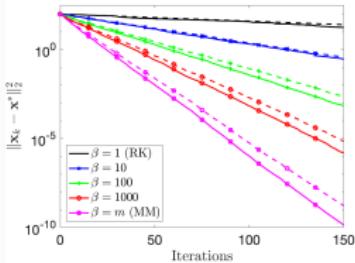
Conclusions

Conclusions

- ▷ hNMF model can be implemented as a feed-forward neural network



- ▷ presented our method **Neural NMF**
- ▷ described family of algorithms which can solve fundamental least-squares subroutine
- ▷ presented accelerated convergence analysis for **SKM**



- ▷ applied Neural NMF to synthetic data and MyLymeData

Related Current/Future Work

Nonnegative Tensor Decomposition (NTD):

- ▷ for dynamic topic modeling (stemming from WiSDM 2019)
- ▷ hierarchical NTD (joint with Needell, Vendrow*)
- ▷ robustness of nonnegative CANDECOMP/PARAFAC decomposition (joint with Kassab•)
- ▷ Applications: NBA data (joint with Liu*), temporal political data



Iterative Projection Methods:

- ▷ dynamic SKM methods (joint with Ma)
- ▷ corruption robust methods (joint with Needell, Rebrova, Swartworth•)
- ▷ AutoML hyperparameter selection (joint with Heiner*)
- ▷ Applications: linear network dynamics problems



* denotes undergraduate collaborator, • denotes graduate collaborator

Other Unrelated Work

Combinatorial Methods:

- ▷ Wolfe's method (joint with De Loera, Rademacher)
- ▷ Hansen-Lawson method
- ▷ Applications: metagenomic binning

Asynchronous Compressed Sensing:

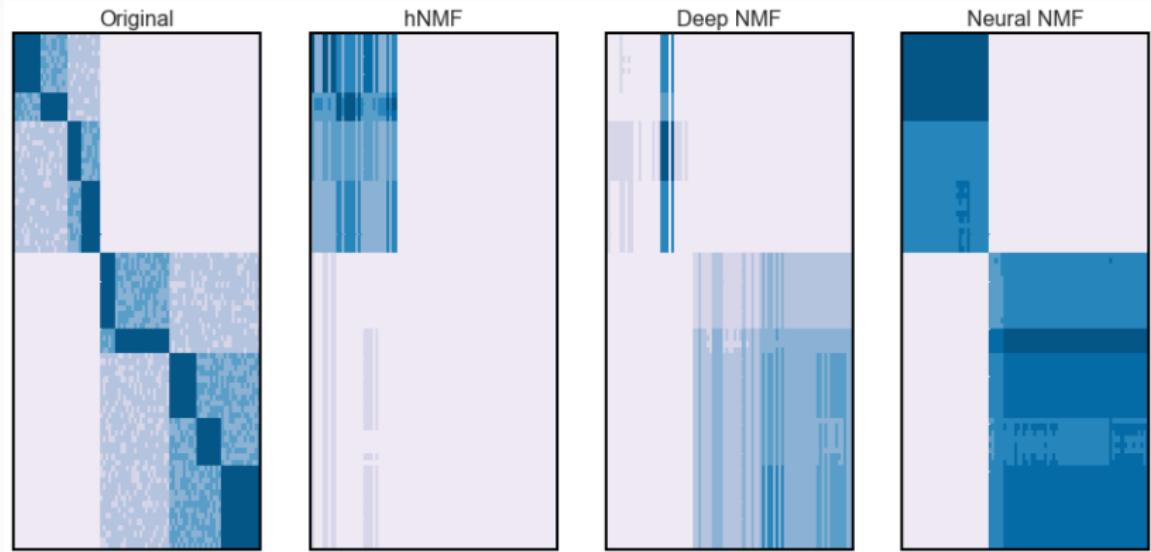
- ▷ Bayesian asynchronous methods (joint with Needell, Rahnavard, Zaeemzadeh)
- ▷ convergence analysis of IHT variants
- ▷ Sparse RK

Thanks for listening!

Questions?

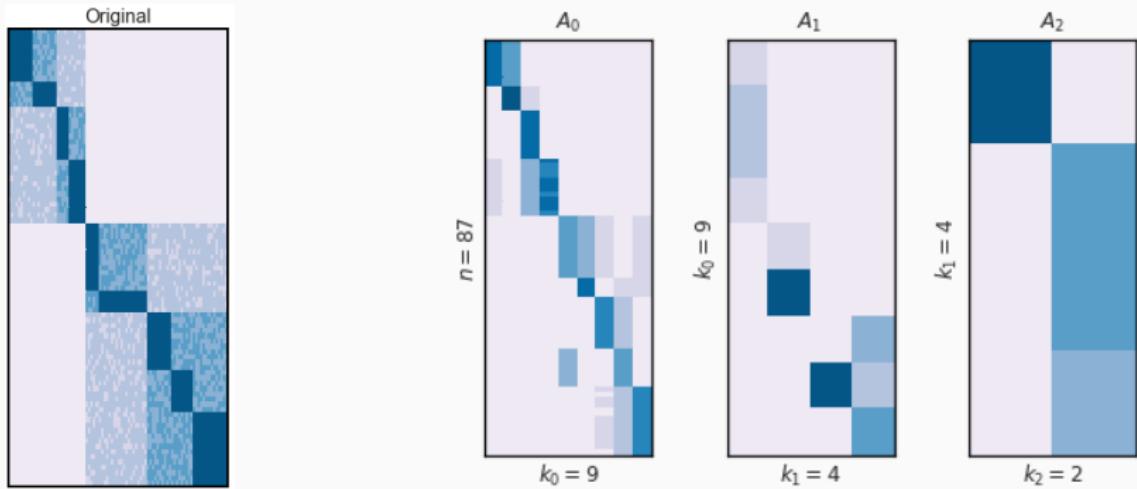
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Experimental results: synthetic data



- ▷ semisupervised reconstruction (40% labels) with three-layer structure ($k^{(0)} = 9, k^{(1)} = 4, k^{(2)} = 2$)

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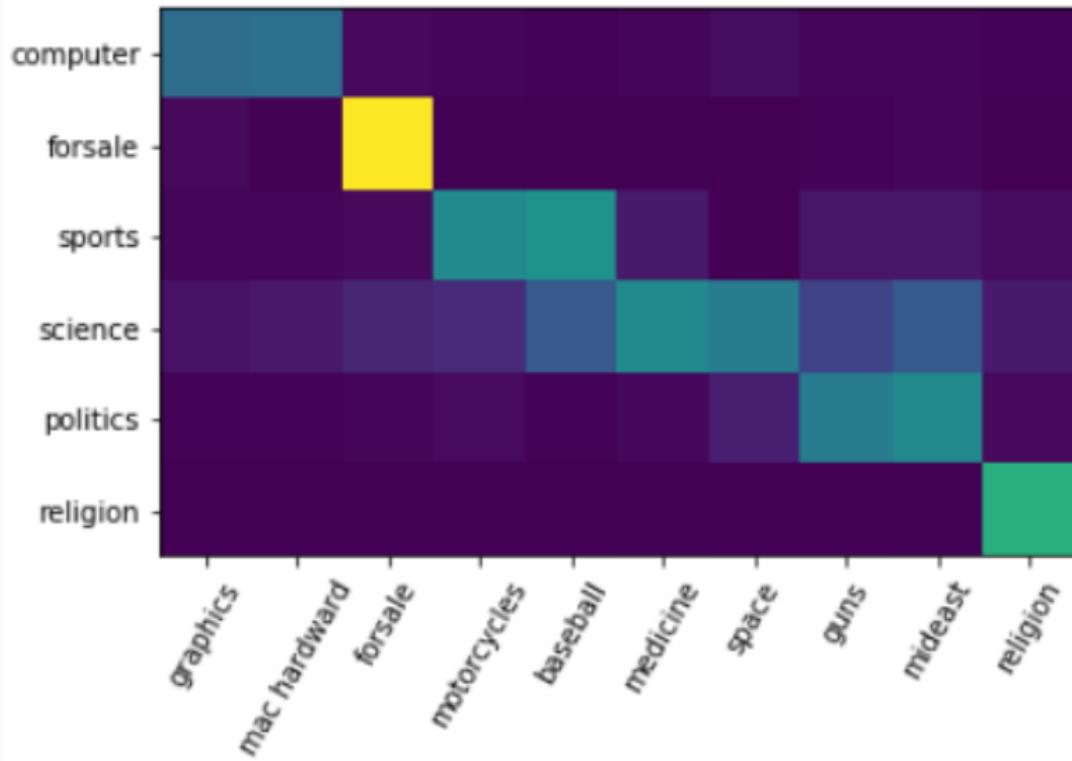
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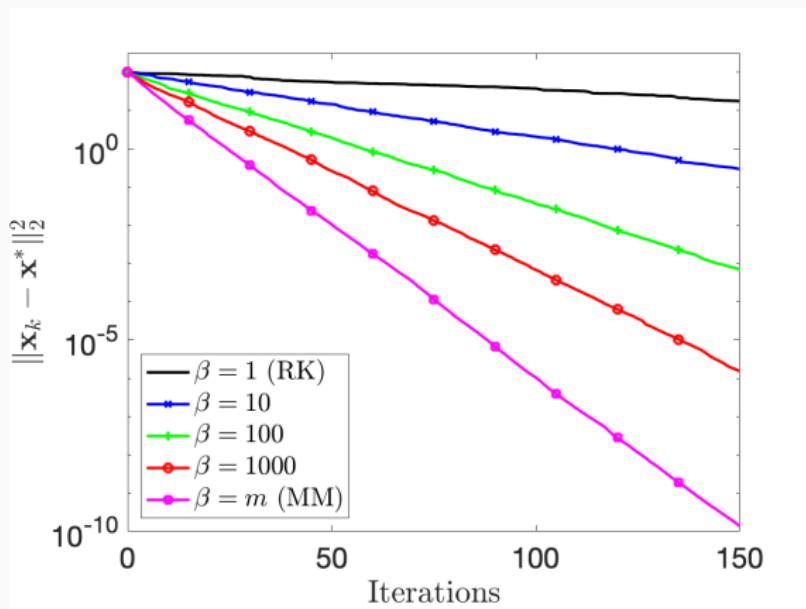
Table 1: Reconstruction error / classification accuracy

	Layers	Hier. NMF	Deep NMF	Neural NMF
Unsuper.	1	0.053	0.031	0.029
	2	0.399	0.414	0.310
	3	0.860	0.838	0.492
Semisuper.	1	0.049 / 0.933	0.031 / 0.947	0.042 / 1
	2	0.374 / 0.926	0.394 / 0.911	0.305 / 1
	3	0.676 / 0.930	0.733 / 0.930	0.496 / 0.990
Supervised	1	0.052 / 0.960	0.042 / 0.962	0.042 / 1
	2	0.311 / 0.984	0.310 / 0.984	0.307 / 1
	3	0.495 / 1	0.494 / 1	0.498 / 1

Experimental results: 20 Newsgroups data

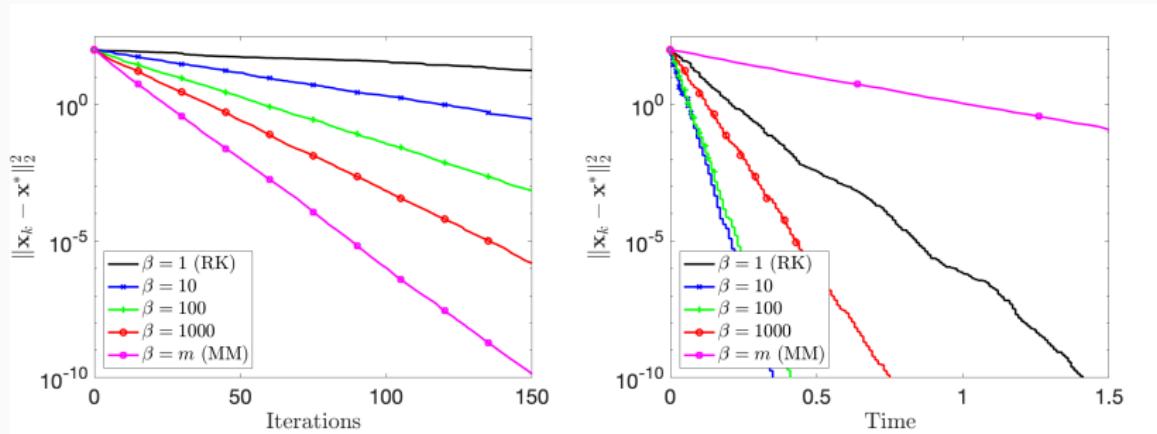


Experimental Convergence



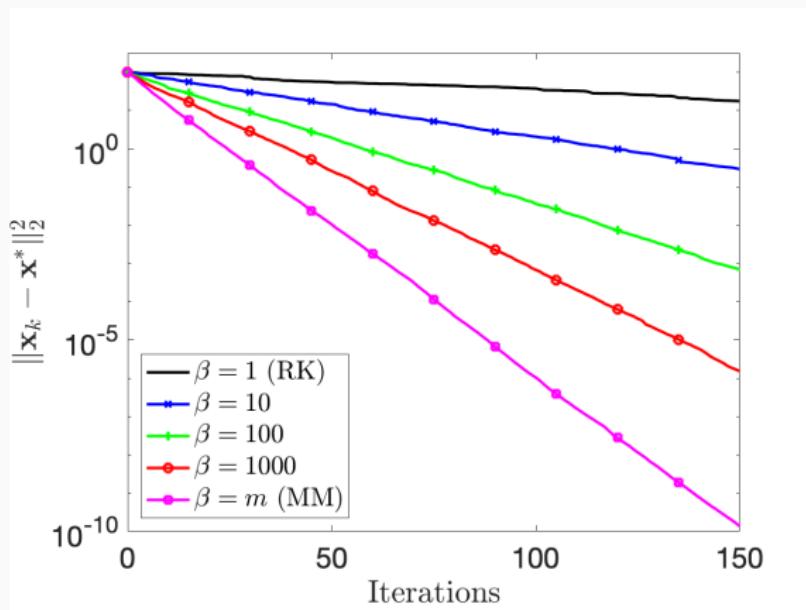
- ▷ β : sample size
- ▷ A is 50000×100 Gaussian matrix, consistent system
- ▷ ‘faster’ convergence for larger sample size

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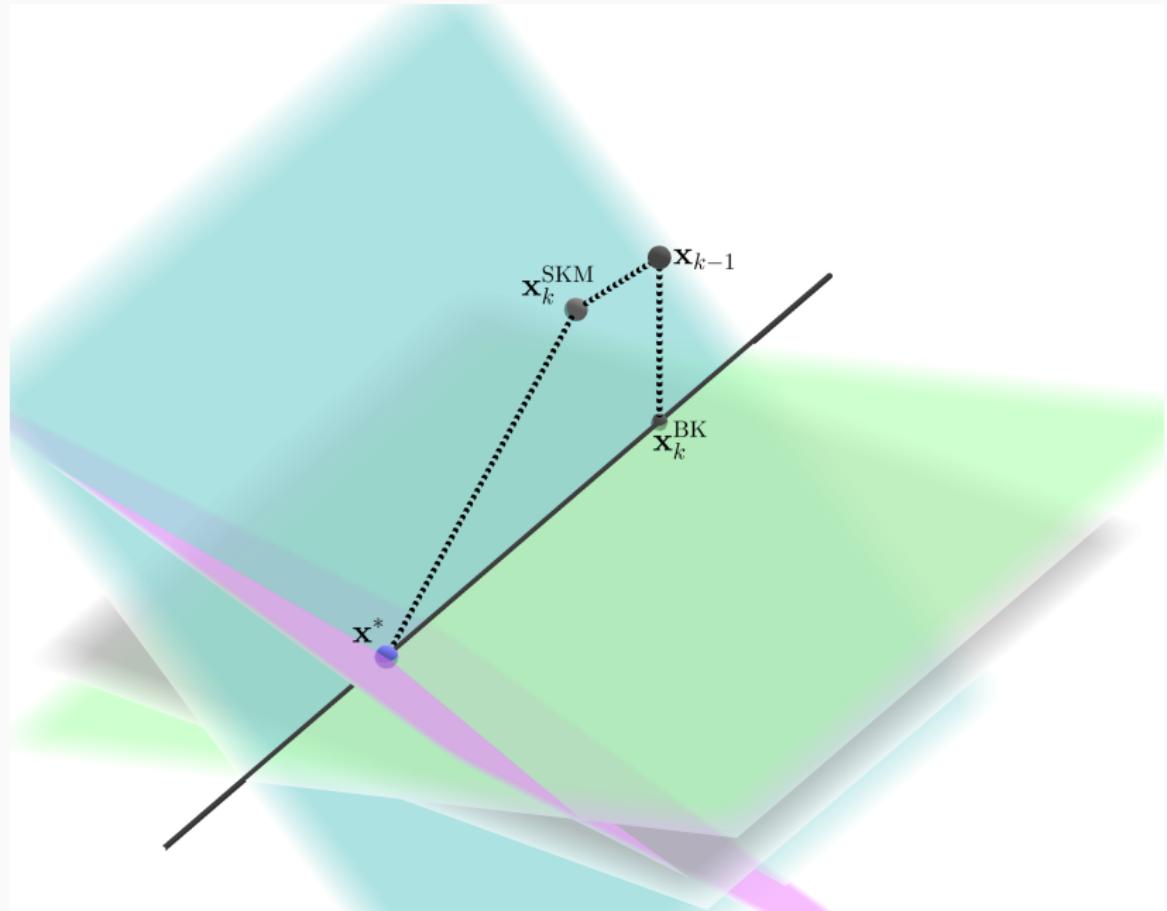
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- ▷ [Sun, Nasrabadi, Tran '17]
 - similar method lacking nonnegativity constraints

Block Kaczmarz



Bound on γ_j

$$\gamma_k \geq \frac{\beta}{m} \sigma_{\min}^2(A) \text{ when } A \text{ is row-normalized}$$