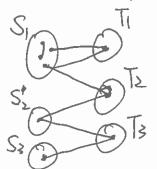
Problem 2: Obviously A&D are square matrices. (By checking multiplication)

(D. Show E= (AVBD*C)*. For convenience, call V= S&T when S corresponds to the news and columns in A; T corresponds to columns and rows in D. Thus E is the reachability matrix from S to S. Two vertices u, v & S. are connected of: i) exist a u-v path in S, or at least ii) exist a path from u to T to v.

A is the adjacency matrix for S. BD*C represents the connected, reachbility" that via a component in T, ues and ves can reach that in one step. Then it's enough to build E. Within Steps u could reach v, either in S or using traversing some vertices in T cnot necessarily in one connected component).



The my drawing on the left.

For vertices in each connected to reachability component in S, reachability is 1; else if it commoneut in S, to another component in S, to another compone

addition is or ", multiplication is "and",

here for multiplication with a nembrability wattrix, resulting materix only contains 0 or 1. same for D. D.

D F=EBD* & G=D* CE.

These two are similar, in fact $F = G^T$ since $F = G^T$ since

F represents the reachability from S to T. (G: Tto S). EBD* represents all possible ways a vertex $u \in S$ to reach a vertex $v \in T$. $EBD^*(u,v) = \sum_{x} E(u,x) (BD^*)(x,v) = \sum_{x} E(u,x) \cdot \sum_{y} B(x,y) \cdot D^*(y,v)$. That is, for any "bridge"/ connection between S and T, i.e. x.y here, as long as u could reach x (could be same) and y could reach v, with x.y, u-v path exists E and D^* represents reachability from S to S and T to T cw T only)

3 H= D*VGBD*

This comes from the ideal that a vertex ut is connected to vot if i) us in same connected component, which covered by D*, or ii) u connects to xinS (by 6); *V connects to y (by D*), and xny (by B). Note reachability is an epuivalence relation, thus xandy can be chosen properly to satisfy the description, of u-v path does exist through S.

For Voperation it is obvious, similar to existence of poth covered by either component, once we find shortest path, it comes from the min of the existings. And for matrix "multiplication" this can be seen as well: Consider MN(x,y) M(x,y) = min (M(x,s)+N(s,y)) where s is the appropriate vertex in designated set (corresponding to column index for X, and now index for Y). Thus multiplication counts for min length of path through a designated vertex set.

To see ABAP(1) = 2ASAP(1) + 6MSP(1) + O(n), consider a bipartition of V with equal sizes (approximately) V= V, \(\forall V_2\). Running D* consumes APSP (\forall_2). Then running BD* consumes MSP (=); E(BD) MSP(=); (BD*) C MSP(型); G(BD*) MSP(型); D*C MSP(型); (D*C)E MSP(=). Taking "V" operation is element-wise comparison, of G(n+Cz) time, D(n). Thus D* VGBD* and A VBD*C each takes $O(\frac{n^2}{4})$, in total $O(\frac{n^2}{2})$, or $O(n^2)$ Last ASAP (7) comes from (AVBD*C)* operation. Such divide-and-conquer takes APSP (3)+6MSP(1)+Our) as worst scenario upper bound for APSPCN). APSPCN) = 2APSP(生)+6MSP(生)+cn2 = 4APSP(年)+6(MSPC生)+地MSPL年)) ·- \le 2 P. A PSP (2/2) + (2 - 2/2) · Cn 2 + 6 (MSP (\frac{1}{2}) + 2/MSP (\frac{1}{2}) + ... + 2/MP (\frac{1}{2}) Since MSP superquardratic, MSP (2) MSP (2) 20mg Therefore APSPCN) & O(n2+ MSPCN). APSPCN)= D(MSPCN)+n2)