

```

\documentclass[11pt,a4paper]{article}

% -----
% PACKAGES
% -----
\usepackage[margin=2.5cm]{geometry}
\usepackage{amsmath,amssymb,amsfonts}
\usepackage{bm}
\usepackage{graphicx}
\usepackage{hyperref}
\usepackage{authblk}
\usepackage{cite}
\usepackage{pgfplots}

\pgfplotsset{compat=1.18}
\hypersetup{
    colorlinks=true,
    linkcolor=blue,
    citecolor=blue,
    urlcolor=blue
}

% -----
% SHORTCUTS
% -----
\newcommand{\dd}{\mathrm{d}}
\newcommand{\mpl}{\mathrm{M}_{\mathrm{Pl}}}
\newcommand{\Lag}{\mathcal{L}}
\newcommand{\Hubble}{\mathcal{H}}
\newcommand{\sig}{\sigma}
\newcommand{\Vsig}{V(\sigma)}
\newcommand{\rhotot}{\rho_{\mathrm{tot}}}
\newcommand{\rhom}{\rho_m}
\newcommand{\rhor}{\rho_r}
\newcommand{\rhos}{\rho_\sigma}
\newcommand{\ps}{p_\sigma}
\newcommand{\wde}{w_\sigma}
\newcommand{\Fmn}{F_{\mu\nu}}
\newcommand{\FmnFmn}{F_{\mu\nu} F^{\mu\nu} }

% -----
% TITLE + AUTHORS

```

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% -----
\title{\textbf{Flux--Scalar Cosmology: A Toy Lagrangian Model Linking\\ Cosmic Expansion, CMB Scales and Local Orbital Tests} }

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\affil[1]{Independent Researcher, Ireland}

\date{\today}

% -----
\begin{document}
\maketitle

\begin{abstract}
I hereby present a simple flux--scalar cosmological model in which a single coherence/flux field  $\sigma$  carries a residual ``flux tension'' that drives late--time acceleration. The model is defined at the level of a covariant Lagrangian, reduces to a minimally coupled scalar in a Friedmann--Lema tre--Robertson--Walker (FLRW) background, and admits a concrete potential motivated by a flux--exhaustion picture. We derive the background equations, map them to a set of numerically tractable variables, and show how the same framework can be confronted with cosmic expansion data, the CMB acoustic angular scale and a simple local test based on the Earth--Moon orbit with a slowly varying effective Newton's constant. This paper is intended as a first formalisation of the model for peer review.
\end{abstract}

\tableofcontents

% -----
\section{Introduction}
\label{sec:intro}

```

Late--time cosmic acceleration is usually modelled either by a pure cosmological constant or by a dynamical dark energy component.

In this work we explore a different organising principle: a flux / coherence scalar σ whose potential energy encodes a residual ``flux tension'' that is exhausted as the Universe expands. At the level of background dynamics the model behaves as a minimally coupled scalar field, but the interpretation is tied to an underlying flux picture.

The numerical experiments that motivated this work included:

```
\begin{itemize}
\item a flux--scalar cosmology code integrating the background and CMB-relevant distances;
\item a unified black-hole + accretion-disk + jet toy model with flux-driven horizons and outflows;
\item a local Earth--Moon orbital model with a slowly varying effective  $G$  plus a tidal torque calibrated to the observed lunar recession.
\end{itemize}
```

\end{itemize}

Here we take the first step towards a publishable formulation by writing down the covariant action, deriving the field equations and connecting them explicitly to the numerics.

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\section{Covariant action and flux--scalar Lagrangian}
\label{sec:lagrangian}

We work in four-dimensional spacetime with metric $g_{\mu\nu}$ and signature $(-, +, +, +)$. The fundamental action is

```
\begin{equation}
S = \int d^4x \sqrt{-g} \left[ \frac{\text{mpl}^2}{2} R - \frac{1}{2} g^{\mu\nu} (\nabla_\mu \sigma) \cdot (\nabla_\nu \sigma) - V(\sigma) + \text{Lag}_{\text{m}} + \text{Lag}_r \right],
\end{equation}
```

\label{eq:action_covariant}

\end{equation} where R is the Ricci scalar, $\text{mpl}^{-2} = 8\pi G$, Lag_m contains all non-relativistic matter fields, and Lag_r describes the radiation component.

The flux--scalar potential encodes the residual flux tension.
Motivated by the plateau-like behaviour used in the numerical CMB integrator, we choose

$$\begin{aligned} V(\sigma) &= \\ &V_0 \left(1 - e^{-\sigma/\mu}\right)^2, \end{aligned}$$

\label{eq:V_sigma}

\end{equation}

with $V_0 > 0$ setting the overall scale of the residual flux energy and μ controlling the rate at which the flux exhausts as σ evolves. For $\sigma \gg \mu$ the potential approaches a quasi-constant plateau $V(\sigma) \rightarrow V_0$, while near $\sigma \approx 0$ it is approximately quadratic,

$$\begin{aligned} V(\sigma) &\approx \frac{V_0}{\mu^2} \sigma^2 \\ &\quad (\sigma \ll \mu). \end{aligned}$$

\end{equation}

\subsection{Field equations}

Variation of the action \eqref{eq:action_covariant} with respect to the metric leads to the Einstein equations,

$$\begin{aligned} \text{mpl}^2 G_{\mu\nu} &= T_{\mu\nu}(\sigma) + \\ &T_{\mu\nu}(\text{m}) + \\ &T_{\mu\nu}(\text{r}), \end{aligned}$$

\end{equation}

where

$$\begin{aligned} T_{\mu\nu}(\sigma) &= \\ &\nabla_\mu \sigma \nabla_\nu \sigma - g_{\mu\nu} \left(\frac{1}{2} g^{\alpha\beta} \nabla_\alpha \sigma \nabla_\beta \sigma \right. \\ &- \left. g_{\mu\nu} V(\sigma) \right) \end{aligned}$$

\end{equation}

is the stress--energy tensor of the flux field.

Variation with respect to σ gives the Klein--Gordon equation for the flux scalar:

$$\Box \sigma - \frac{\partial V}{\partial \sigma} = 0,$$

`\label{eq:KG_general}`

`\end{equation}`

with $\Box \equiv g^{\mu\nu} \nabla_\mu \nabla_\nu$.

For the specific potential `\eqref{eq:V_sigma}` one has

$$\frac{\partial V}{\partial \sigma}$$

`=`

$$\frac{2 V_0}{\mu}$$

$$\left(1 - e^{-\sigma/\mu}\right) e^{-\sigma/\mu}.$$

`\label{eq:dV_dsigma}`

`\end{equation}`

% ======
=====

`\section{FLRW reduction and minisuperspace Lagrangian}`

`\label{sec:flrw}`

We adopt a spatially flat FLRW background,

`\begin{equation}`

$$\partial s^2 = -\partial t^2 + a(t)^2 \partial \mathbf{x}^2,$$

`\end{equation}`

with scale factor $a(t)$ and Hubble parameter $H = \dot{a}/a$.

Assuming homogeneity for the flux scalar,

$\sigma = \sigma(t)$, the action reduces to

`\begin{equation}`

$$S = \int dt \left[-3 \dot{a}^2 \frac{\dot{a}^2}{a^2} + \frac{1}{2} \dot{\sigma}^2 - V(\sigma) + L_m + L_r \right].$$

`\end{equation}`

Up to a total derivative, one may define the minisuperspace

Lagrangian

`\begin{equation}`

$$L_{\text{mini}} =$$

```

a^3 \left(
-3 \text{mpl}^2 \frac{\dot{a}^2}{a^2}
+ \frac{1}{2} \dot{\sigma}^2
- V(\sigma)
\right)
+ \text{Lag}_{\text{m}}^{\text{(eff)}}
+ \text{Lag}_{\text{r}}^{\text{(eff)}},
\label{eq:L_mini}
\end{equation}

```

where the matter and radiation pieces reduce to effective perfect fluids with $\rho_m \propto a^{-3}$ and $\rho_r \propto a^{-4}$.

Varying `\eqref{eq:L_mini}` with respect to a and σ yields the usual Friedmann and scalar-field equations:

```

\begin{aligned}
H^2
&= \frac{1}{3\text{mpl}^2} \\
&\left( \rho_r + \rho_m + \rho_\sigma \right), \\
\dot{H}
&= -\frac{1}{2\text{mpl}^2} \\
&\left( \rho_r + \rho_m + \dot{\sigma}^2 \right) \\
&\ddot{\sigma} + \frac{\partial V}{\partial \sigma} = 0.
\end{aligned}
\label{eq:sigma_eom}

```

`\end{align}`

Here

```

\begin{aligned}
\rho_\sigma &= \frac{1}{2} \dot{\sigma}^2 + V(\sigma), \\
\psi &= \frac{1}{2} \dot{\sigma}^2 - V(\sigma),
\end{aligned}

```

`\end{align}`

and the effective equation-of-state parameter of the flux field is

```

\begin{aligned}
w_{de}(a) &= \frac{\psi}{\rho_\sigma} \\
&= \frac{\frac{1}{2} \dot{\sigma}^2 - V(\sigma)}{\frac{1}{2} \dot{\sigma}^2 + V(\sigma)} \\
&= \frac{\dot{\sigma}^2 - V(\sigma)}{\dot{\sigma}^2 + V(\sigma)}.
\end{aligned}

```

`\end{equation}`

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\subsection{Numerical variables and comparison with code}
\label{subsec:numerics}
```

For numerical work it is convenient to trade cosmic time t for the e-fold variable $N = \ln a$. Denoting derivatives with respect to t by dots and with respect to N by primes, one has $\dot{N} / \dot{t} = H$ and thus

```
\begin{equation}
\dot{\sigma}' = \frac{\dot{\sigma}}{H}, \quad
v \equiv \dot{\sigma}.
\end{equation}
```

\end{equation}

In these variables the system

\eqref{eq:Friedmann}--\eqref{eq:sigma_eom} can be written as

```
\begin{aligned}
\dot{\sigma}' \\
&= \frac{v}{H}, \\
v' \\
&= -3v - \frac{1}{H} \frac{\dot{V}}{\dot{\sigma}},
\end{aligned}
```

\end{aligned}

with

```
\begin{equation}
H^2 \\
= \rho_r + \rho_m + \frac{1}{2}v^2 + V(\sigma),
\end{equation}
```

\end{equation}

in units where $\frac{8\pi G}{3} = 1$ and the present-day densities are encoded in Ω_{r0} and Ω_{m0} .

This is the form implemented in the flux--scalar CMB integrator used to generate the background and CMB distance plots in this work.

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\section{Flux--scalar black--hole + jet toy model}
\label{sec:bh_jet}
```

The cosmological flux--scalar model of Sec.\ref{sec:lagrangian} can be extended to a schematic black--hole + jet toy model by coupling the same flux field σ to an electromagnetic sector and a magnetised plasma that carries the jet.

The goal of this section is not to provide a full global solution,

but to exhibit a consistent covariant Lagrangian whose symmetry reductions match the structure used in the numerical BH + jet experiments motivating this work.

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% -----
\subsection{Covariant action with flux, EM field and plasma}
\label{subsec:bh_action}
```

We consider a stationary, axisymmetric spacetime with metric $g_{\mu\nu}$, and include three ingredients:

- (i) the flux scalar σ already introduced in Sec.~\ref{sec:lagrangian};
- (ii) an electromagnetic field A_μ with field strength $F_{\mu\nu} = \nabla_\mu A_\nu - \nabla_\nu A_\mu$, encoding both the accretion-disk magnetic field and the jet collimation;
- and (iii) an effective magnetised plasma described as a perfect fluid with 4-velocity u^μ , number density n and equation of state $p = p(n, \sigma)$.

The total action is

```
\begin{equation}
S_{\mathrm{BH+jet}} \\
= \\
\int \mathrm{d}^4x \sqrt{-g} \\
\left[ \right. \\
\frac{\mathrm{mpl}^2}{2} R \\
- \frac{1}{2} g^{\mu\nu} \\
\nabla_\mu \sigma \nabla_\nu \sigma \\
- V_{\mathrm{BH}}(\sigma) \\
- \frac{1}{4} K(\sigma) F_{\mu\nu} F^{\mu\nu} \\
+ \mathrm{Lag}_{\mathrm{plasma}}(n, u^\mu, \sigma) \\
\left. \right], \\
\label{eq:action_bhjet}
\end{equation}
```

\end{equation}

where:

```
\begin{itemize}
```

- \item $V_{\mathrm{BH}}(\sigma)$ is a local version of the flux potential, which we take for simplicity to coincide with the cosmological form,

```
\begin{equation}
```

$$V_{\mathrm{BH}}(\sigma) =$$

```

V_0 \left(1 - e^{-\sigma/\mu}\right)^2,
\label{eq:V_BH}
\end{equation}

```

allowing σ to interpolate between a high-flux core near the horizon and a relaxed state far away; item $K(\sigma)$ is a flux-dependent gauge kinetic function, encoding how the local flux state alters the effective magnetic stiffness. A minimal choice is

```

\begin{equation}
K(\sigma)
= 1 + \alpha \frac{\sigma}{\mu},
\label{eq:K_sigma}
\end{equation}

```

with a dimensionless parameter α governing the strength of the flux--magnetic coupling;

item $\text{Lag}_{\text{plasma}}$ is the effective plasma Lagrangian; for a perfect fluid we can write

```

\begin{equation}
\text{Lag}_{\text{plasma}}(n, u^\mu, \sigma, \lambda) \\
= -\rho(n, \sigma) \\
+ \lambda (u^\mu u_\mu + 1),
\label{eq:L_plasma}
\end{equation}

```

where $\rho(n, \sigma)$ is the energy density in the plasma (allowing a weak dependence on σ to represent flux loading of the jet) and λ is a Lagrange multiplier enforcing the normalisation $u^\mu u_\mu = -1$.

```
\end{itemize}
```

The term $K(\sigma) F_{mn} F_{mn}$ ensures that changes in the flux field modify the effective magnetic field strength and therefore the jet collimation and power. In the limit $K(\sigma) \rightarrow 1$ and $\partial \rho / \partial \sigma \rightarrow 0$, one recovers a standard magnetohydrodynamic BH + jet system minimally coupled to gravity.

Variation of `eqref{eq:action_bhjet}` with respect to $g_{\mu\nu}$, σ , A_μ and λ yields, respectively, the Einstein equations, the flux-scalar equation, the Maxwell equations with flux-dependent coupling, and the plasma normalisation condition,

```

\begin{aligned}
&\mpl^2 G_{\mu\nu}
\end{aligned}

```

```

&= T_{\mu\nu}^{\{\sigma\}} + T_{\mu\nu}^{\{F\}} +
T_{\mu\nu}^{\{\mathrm{plasma}\}}, \\
\label{eq:Einstein_bh} \\[3pt]
\Box \sigma - \frac{\partial}{\partial t} V_{\mathrm{BH}} \} \} \partial_t \sigma \\
&- \frac{1}{4} \frac{\partial}{\partial t} K \} \partial_t \sigma \}, \mathcal{F}_{\mu\nu} \mathcal{F}^{\mu\nu} \\
- \frac{\partial}{\partial t} \rho \} \partial_t \sigma = 0, \\
\label{eq:sigma_bh} \\[3pt]
\nabla_\mu \left( K(\sigma) F^{\mu\nu} \right) \\
&= J^\nu, \\
\label{eq:Maxwell_bh} \\[3pt]
u^\mu u_\mu &= -1,

```

\end{align}

where J^ν is the plasma 4-current and the stress--energy tensors have their usual forms for a scalar field, electromagnetic field and perfect fluid, modified by the $K(\sigma)$ factor in the electromagnetic sector.

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\subsection{Stationary, axisymmetric reduction}
\label{subsec:bh_reduction}

```

For concreteness we adopt a stationary, axisymmetric metric ansatz in Boyer--Lindquist-like coordinates (t, r, θ, ϕ) ,

\begin{equation}

$$\begin{aligned}
&\partial_t s^2 \\
&= \\
&-N(r, \theta)^2 \partial_t^2 \\
&+ A(r, \theta)^2 \partial_r^2 \\
&+ B(r, \theta)^2 \partial_\theta^2 \\
&+ C(r, \theta)^2 \\
&\quad [\partial_\theta \phi - \omega(r, \theta) \partial_t]^2,
\end{aligned}$$

\label{eq:metric_bh}

\end{equation}

with lapse N , frame-dragging frequency ω and radial/latitudinal warp factors A, B, C to be determined.

In the numerical toy model, we further restrict to a near-axis region $\theta \approx 0$ and treat the jet as a magnetised tube along the rotation axis. In this limit the fields depend effectively on r only, and the action \eqref{eq:action_bhjet} reduces to a one-dimensional ``minisuperspace'' Lagrangian of the form

\begin{equation}

```

\mathcal{L}_{\mathrm{BH, eff}} \\
= \\
\int \partial_\theta \partial_\phi, \\
N A B C, \\
\left[ \\
\frac{\partial^2}{\partial r^2} R_{\mathrm{eff}} \\
- \frac{1}{2} (\partial_r \sigma)^2 \\
- V_{\mathrm{BH}}(\sigma) \\
- \frac{1}{4} K(\sigma) F_{rt} F^{rt} \\
+ \mathcal{L}_{\mathrm{plasma, eff}}(r) \\
\right], \\
\label{eq:L_BH_eff}

```

where R_{eff} is the Ricci scalar of the reduced metric and $\mathcal{L}_{\mathrm{plasma, eff}}$ contains the effective radial dependence of the plasma variables along the jet.

In practice, the BH + jet numerical experiments use a simplified set of ODEs derived from \eqref{eq:L_BH_eff} under the assumptions of: (i) a fixed background metric close to Kerr or Schwarzschild near the horizon; (ii) a prescribed inflow profile for the accretion rate; and (iii) a flux-dependent mapping between the magnetic field strength and the jet power via $K(\sigma)$. The Lagrangian \eqref{eq:action_bhjet}--\eqref{eq:L_BH_eff} therefore serves as a formal parent theory for those toy models, clarifying how the flux field can, in principle, control both the horizon structure and the jet energetics in a unified way.

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% -----
\subsection{Interpretation within the flux picture}
\label{subsec:bh_interpretation}

```

Within the global flux picture, the parameter σ measures the local flux state of spacetime. Near a black hole, strong curvature and accretion can drive σ away from its cosmological value, altering both $V_{\mathrm{BH}}(\sigma)$ and the effective gauge coupling $K(\sigma)$. The former modifies the local energy density associated with the flux field, while the latter changes how efficiently magnetic fields tap rotational or accretion energy to power a jet.

Although the present work does not attempt a full numerical solution of the coupled system \eqref{eq:Einstein_bh}--\eqref{eq:Maxwell_bh}

in the BH + jet geometry, the existence of a consistent covariant Lagrangian with a single flux field σ is an important conceptual step. It makes explicit how the same degree of freedom that drives late-time cosmological acceleration could, at least in principle, participate in local high-energy phenomena such as jet launching and horizon physics.

\section{CMB acoustic scale and distance measures}
\label{sec:CMB}

\subsection{Derivation of the comoving distance and sound horizon}
\label{subsec:rs_derivation}

We briefly recall the standard derivation of the comoving distance and the sound horizon integrals used in Sec.\ref{sec:CMB}.

\subsubsection{Comoving distance}

For a spatially flat FLRW metric,

\begin{equation}\mathrm{d}s^2 = -\mathrm{d}t^2 + a^2(t) \mathrm{d}\bm{x}^2,\end{equation}

radial null geodesics satisfy $\mathrm{d}s^2 = 0$, so

\begin{equation}0 = -\mathrm{d}t^2 + a^2(t) \mathrm{d}r^2
 \quad \Rightarrow
 \mathrm{d}r = \frac{\mathrm{d}t}{a(t)}.\end{equation}

The comoving radial distance χ to a source observed at t_0 and emitted at t_{em} is then

\begin{equation}\chi = \int_{t_{\mathrm{em}}}^{t_0} \frac{\mathrm{d}t}{a(t)}.\end{equation}

Using $\mathrm{d}t = \mathrm{d}a/(a H)$, this becomes

\begin{equation}\chi(a_{\mathrm{em}}) = \int_{a_{\mathrm{em}}}^{a_0} \frac{\mathrm{d}a}{a^2 H(a)}.\end{equation}

\label{eq:chi_integral_derived}

The comoving distance to last scattering, used in the definition of θ_\star , is obtained by setting $a_{\mathrm{em}} = a_\star$ in Eq.\ref{eq:chi_integral_derived}, yielding Eq.(XX) in

Sec.~\ref{sec:CMB}.\footnote{Replace (XX) with the label you used for \$\chi_\star\$ in the main text.}

\subsubsection*{Sound horizon}

Before recombination, photons and baryons form a tightly coupled fluid. Linear perturbations in this fluid obey a wave equation whose solutions propagate at the sound speed $c_s(a)$, so that acoustic waves travel a comoving distance

\begin{equation}

$$r_s(a_\star) = \int_0^{\eta_\star} c_s(\eta) \, d\eta,$$

\end{equation}

where η is conformal time and η_\star is the conformal time at photon decoupling. By definition,

\begin{equation}

$$\frac{d\eta}{dt} = \frac{da}{dt} = \frac{da}{H(a)},$$

\end{equation}

so we can write

\begin{equation}

$$r_s(a_\star) = \int_0^{a_\star} \frac{c_s(a)}{a^2 H(a)} \, da,$$

\label{eq:rs_integral_derived}

\end{equation}

which is the expression used in Sec.~\ref{sec:CMB}.

The photon--baryon sound speed follows from the coupled fluid equations. For adiabatic perturbations in a relativistic photon gas with pressure $p_\gamma = \rho_\gamma / 3$ and pressureless baryons, one finds

\begin{equation}

$$c_s^2(a) = \frac{\partial p_\gamma}{\partial \rho_\gamma} = \frac{1}{3(1 + R(a))},$$

\quad

$$R(a) \equiv \frac{3 \rho_b}{4 \rho_\gamma},$$

\end{equation}

so that the only model dependence of $r_s(a_\star)$ and χ_\star within the flux--scalar framework enters through the modified expansion rate $H(a)$.

The comoving sound horizon at photon decoupling a_{\star} is

$$\begin{aligned} r_s(a_{\star}) \\ = \int_0^{a_{\star}} a^2 H(a) da, \end{aligned}$$

\end{equation}

where the baryon--photon sound speed is

$$\begin{aligned} c_s^2(a) \\ = \frac{1}{3(1 + R(a))}, \quad R(a) = \frac{3\rho_b}{4\rho_{\gamma}}. \end{aligned}$$

\end{equation}

The comoving distance to last scattering is

$$\begin{aligned} \chi_{\star} \\ = \int_{a_{\star}}^{\infty} \frac{da}{a^2 H(a)}, \end{aligned}$$

\end{equation}

and the corresponding acoustic angular scale is

$$\theta_{\star} = \frac{r_s(a_{\star})}{\chi_{\star}}.$$

\end{equation}

In the flux--scalar model both r_s and χ_{\star} are modified only via the altered expansion history $H(a)$; the radiation and baryon sectors are standard.

A minimal consistency check of the model is therefore that θ_{\star} can be brought into agreement with the measured CMB acoustic scale while keeping the late-time expansion rate compatible with local H_0 determinations.

\subsection{Parameter selection and numerical calibration}

\label{subsec:param_choice}

In the flux--scalar model the background expansion is controlled by three parameters that are not fixed by early--Universe physics:

- (i) the overall height of the flux potential V_0 ,
- (ii) the flux relaxation scale μ , and
- (iii) the present--day matter density parameter $\Omega_m 0$.

In the numerical implementation these parameters are chosen so that two independent requirements are simultaneously satisfied:

- (1) the CMB acoustic angular scale θ_{\star} is reproduced to

Planck accuracy, and (2) the late--time expansion rate $H(a)$ matches low--redshift distance indicators.

\paragraph{Step 1: Fixing Ω_{m0} by late--time distances.} For any trial pair (V_0, μ) , the background equations Eqs.\eqref{eq:Friedmann}--\eqref{eq:sigma_eom} are integrated from $N = \ln a = -10$ to $N = 0$ (the present). The matter density fraction Ω_{m0} is then adjusted so that the model reproduces the observed distance to $z \simeq 0.57$ (the BOSS CMASS redshift), i.e.

```
\begin{equation}
D_V(z=0.57) \\
= \\
\left[ (1+z)^2 D_A^2(z) \frac{c}{H(z)} \right]^{1/3},
\end{equation}
```

matches the corresponding BAO constraint. In practice we use a one-dimensional root-finding step on Ω_{m0} , keeping (V_0, μ) fixed, since the dependence of the low-\$z\$ distance ladder on V_0 and μ is extremely weak compared to its dependence on Ω_{m0} .

\paragraph{Step 2: Fixing V_0 by requiring the correct H_0 .} Once Ω_{m0} is determined, the value of V_0 is adjusted so that the model reproduces the observed Hubble rate today,

```
\begin{equation}
H(a=1; V_0, \mu, \Omega_{m0}) = H_0^{\mathrm{obs}}.
\end{equation}
```

Since V_0 appears additively in ρ_σ and dominates the late--time expansion when the flux field is near its plateau, H_0 is a monotonic function of V_0 , so a second one-dimensional root-solve converges rapidly.

\paragraph{Step 3: Fixing μ through the CMB acoustic scale.} With V_0 and Ω_{m0} fixed as above, the remaining freedom is the flux relaxation scale μ , which controls the redshift evolution of $w_\sigma(a)$. This in turn controls both the comoving distance to last scattering χ_\star and the sound horizon $r_s(a_\star)$ through their dependence on $H(a)$, cf.\eqref{eq:chi_integral_derived} and \eqref{eq:rs_integral_derived}. The model prediction for the CMB acoustic angular scale,

```
\begin{equation}
\theta_{\star}(V_0,\mu,\Omega_{m0})
= \frac{r_s(a_{\star})}{\chi_{\star}},
\end{equation}
```

is compared with the Planck value,

$$\theta_{\star}^{\mathrm{obs}} = 1.04109(30) \times 10^{-2}.$$

A final one-dimensional root-finding step in μ ensures that

```
\begin{equation}
\theta_{\star}(V_0,\mu,\Omega_{m0})
= \theta_{\star}^{\mathrm{obs}}.
\end{equation}
```

\paragraph{Summary of the calibration pipeline.}

The full calibration therefore proceeds in the nested order:

```
\[
\mu
; \longrightarrow;
V_0
; \longrightarrow;
\Omega_{m0}
\quad \text{(for convergence)}.
\]
```

Practically, in the numerical implementation we treat μ as the outermost scan variable, and for each trial value:

```
\begin{enumerate}
\item Solve for  $\Omega_{m0}$  such that late-time BAO distances match.
\item Solve for  $V_0$  such that  $H_0$  is correct.
\item Evaluate  $\theta_{\star}$  and update  $\mu$  until  $\theta_{\star}$  matches the Planck value.
\end{enumerate}
```

\end{enumerate}

Because both $H(a)$ and θ_{\star} respond smoothly to variations in (V_0, μ) , the procedure converges rapidly and uniquely for a wide range of initial guesses. This ensures that the flux--scalar model respects the two strongest geometric constraints on the expansion history: the CMB acoustic scale and low- z BAO distances.

```
% =====
=====
\subsection{Illustrative profiles and jet power scaling}
\label{subsec:bh_plots}
```

To make the role of the flux--dependent gauge kinetic function $K(\sigma)$ more concrete, it is useful to display simple illustrative profiles. In this subsection we adopt the minimal choice

$$\begin{aligned} \text{\begin\{equation\}} \\ K(\sigma) = 1 + \alpha \frac{\sigma}{\mu}, \\ \text{\label\{eq:K_sigma_linear\}} \end{aligned}$$

$\text{\end\{equation\}}$

with $\alpha > 0$ and μ the same flux scale that appears in $V_{\mathrm{BH}}(\sigma)$, cf.~Eq.~\eqref{eq:V_BH}. For small departures from the cosmological flux state, this linear form captures the idea that a higher local flux amplitude stiffens the magnetic sector.

Figure~\ref{fig:Ksigma_profile} shows a representative $K(\sigma)$ profile as a function of the dimensionless ratio σ/μ . In the numerical experiments, α is effectively calibrated so that the near-horizon flux state produces the observed range of jet powers for a given accretion rate.

```
\begin{figure}[t]
\centering
\begin{tikzpicture}
\begin{axis}[
    width=0.7\textwidth,
    xlabel={$\sigma / \mu$},
    ylabel={$K(\sigma)$},
    xmin=0, xmax=3,
    ymin=1, ymax=2.5,
    domain=0:3,
    samples=200,
    grid=both,
    legend style={at={(0.97,0.03)},anchor=south east}
]
\addplot[thick]
{1 + 0.5 * x}; % alpha = 0.5
\addlegendentry{$K(\sigma) = 1 + \alpha \sigma / \mu$}
\end{axis}
\end{tikzpicture}
\caption{Illustrative flux--dependent gauge kinetic function  $K(\sigma)$  as a function of  $\sigma / \mu$ , using the linear
```

form in Eq.~\eqref{eq:K_sigma_linear} with $\alpha = 0.5$.
In the full model, α and the functional form of K
can be constrained by jet observations.}
\label{fig:Ksigma_profile}
\end{figure}

A simple proxy for the jet power in Blandford--Znajek--type mechanisms is

\begin{equation}

$$P_{\text{jet}} \propto K(\sigma)^2 B^2 \Omega_{\text{H}}^2,$$

\end{equation}

where B is the magnetic field threading the horizon and Ω_{H} is the angular frequency of the black hole horizon. Holding B and Ω_{H} fixed, the dependence

on the flux field enters purely via $K(\sigma)$.
\footnote{In a more complete treatment, B will itself depend on the accretion flow and possibly on σ , but the present toy scaling suffices to show how a single flux degree of freedom can modulate jet power.}

Using the linear form \eqref{eq:K_sigma_linear}, the jet power scales as

\begin{equation}

$$P_{\text{jet}}(\sigma)$$

=

$$P_0 [1 + \alpha \frac{\sigma}{\mu}]^2,$$

\label{eq:Pjet_sigma}

\end{equation}

with P_0 a normalisation that absorbs $B^2 \Omega_{\text{H}}^2$ and geometric factors. Figure~\ref{fig:Pjet_profile} displays this scaling for a fiducial choice of parameters.

\begin{figure}[t]

\centering

\begin{tikzpicture}

\begin{axis}[

width=0.7\textwidth,

xlabel={\$\sigma / \mu\$},

ylabel={\$P_{\text{jet}}(\sigma) / P_0\$},

xmin=0, xmax=3,

ymin=1, ymax=4,

domain=0:3,

```

        samples=200,
        grid=both,
        legend style={at={(0.97,0.03)},anchor=south east}
    ]
    \addplot[thick]
        {(1 + 0.5 * x)^2}; % alpha = 0.5
    \addlegendentry{$P_{\mathrm{jet}}/P_0 = [1 + \alpha \sigma/\mu]^2$}
\end{tikzpicture}
\caption{Illustrative jet power scaling as a function of the flux field, using Eq.\eqref{eq:Pjet_sigma} with $\alpha = 0.5$. Even modest variations in the local flux state can, in this toy model, generate order-unity changes in jet power at fixed accretion rate and black-hole spin.}
\label{fig:Pjet_profile}
\end{figure}

```

These plots are not intended as fits to specific objects, but as a visual proof-of-principle: within the flux--scalar framework the same degree of freedom σ that drives cosmological acceleration can, via $K(\sigma)$, modulate the efficiency with which black holes launch relativistic jets.

```

\section{Local tests: effective gravity and the lunar orbit}
\label{sec:lunar}

```

Beyond background cosmology, the flux picture can feed into an effective Newton's constant $G_{\mathrm{eff}}(t)$ relevant for local dynamics. In the simplest toy implementation used here, the cosmological flux fraction Φ / S_{max} is computed from a separate entropy-like variable and then mapped to G_{eff} via

```

\begin{equation}
G_{\mathrm{eff}}(t) \\
= G_0 [1 + g_1 f_{\mathrm{flux}}(t)],
\end{equation}

```

where g_1 is a dimensionless coupling and f_{flux} is a bounded function constructed from the flux deficit or fraction in the cosmological sector.

As a concrete local test we consider the Earth--Moon system as a

two-body problem with a slowly varying $G_{\mathrm{eff}}(t)$ plus a phenomenological tidal torque. In a circular-orbit approximation, the orbital radius $R(t)$ responds to both the tidal gain in angular momentum and the secular drift in G_{eff} . The toy model used in this work calibrates the tidal torque to reproduce the observed 3.8 cm/yr lunar recession while allowing for an additional, subdominant contribution from $G_{\mathrm{eff}}(t)$.

\subsection{Lunar orbit model: variable gravity and tidal torque}
\label{subsec:lunar_equations}

The Earth--Moon toy model used in this work is deliberately simple: we work with a dimensionless system in which

```
\[
G_0 = 1, \quad R_0 = 1, \quad M_{\oplus} = 1, \quad
M_{\rm M} = 0.0123,
```

where R_0 is the current mean Earth--Moon distance and $M_{\oplus}, M_{\rm M}$ are the Earth and Moon masses respectively. Time is measured in years and the integration runs for $T_{\max} = 50 \text{ yr}$ with time step $\Delta t = \text{dt}$.

The model couples a slowly varying effective Newton's constant $G_{\mathrm{eff}}(t)$, obtained from the cosmological flux sector, to a Keplerian two-body problem plus a phenomenological tidal torque that drives the observed recession.

\subsubsection{Keplerian orbit with $G_{\mathrm{eff}}(t)$ }

Let $\mathbf{r}(t) = (x(t), y(t))$ be the Moon's position in the orbital plane and $R(t) = |\mathbf{r}(t)|$ the orbital radius. At each time step, the effective Newton's constant is computed from the flux fraction $\phi_{\mathrm{flux}}(t)$,

$$G_{\mathrm{eff}}(t) = G_0 [1 + g_1 \phi_{\mathrm{flux}}(t)],$$

\label{eq:Geff_lunar}

\end{equation}

where g_1 is a small dimensionless coupling fixed elsewhere in the cosmological model. The gravitational acceleration is then purely Newtonian with G_0 to $G_{\mathrm{eff}}(t)$:

\begin{align}

```

\ddot{\bm{r}}(t)
&= - \frac{G_{\rm eff}(t), M_{\oplus} }{M_{\oplus}^3} \bm{R}(t)^3, \bm{r}(t),
\label{eq:newton_vector}\qquad
\ddot{x}
&= - \frac{G_{\rm eff}(t), M_{\oplus} }{M_{\oplus}^3} R^3, x,
\qquad
\ddot{y}
&= - \frac{G_{\rm eff}(t), M_{\oplus} }{M_{\oplus}^3} R^3, y.
\end{aligned}

```

These equations are integrated with a simple explicit scheme in the code (velocity and position updates per time step).

\subsubsection{Tidal torque and angular momentum gain}

On top of the variable gravity, we include a phenomenological tidal torque that transfers angular momentum from the Earth's spin to the Moon's orbit. The code models this as a secular gain in the Moon's orbital angular momentum \$L\$,

```

\begin{equation}
\dot{L} = \tau_{\rm tide}(t)
= \tau_0 \frac{M_{\oplus} M_{\rm M}}{R^2} G_{\rm eff}(t),
\label{eq:Ldot_tidal}
\end{equation}

```

where \$\tau_0\$ is a dimensionless ``tidal_torque_factor'' later calibrated to reproduce the observed recession rate.

For convenience the numerical implementation works with the specific angular momentum

```

\begin{equation}
h(t) \equiv \frac{L(t)}{M_{\rm M}}
= R^2 \dot{\phi},
\end{equation}

```

\end{equation}

so that Eq.\ref{eq:Ldot_tidal} becomes

```

\begin{equation}
\dot{h}(t)
= \frac{\dot{L}}{M_{\rm M}}
= \tau_0 \frac{M_{\oplus}}{R^2} G_{\rm eff}(t).
\label{eq:hdot_tidal}
\end{equation}

```

\end{equation}

In the code this is implemented via a discrete update

```

\begin{equation}

```

```

h(t + \Delta t)
= h(t) + \dot{h}(t) \Delta t.
\end{equation}

```

\subsubsection*{Mapping to the semi-major axis and \$R(t)\$}

Assuming a nearly circular orbit, the semi-major axis a_{orb} is related to the specific angular momentum by the usual Keplerian relation with $G_{\text{eff}}(t)$,

```

\begin{equation}
h^2(t)
= G_{\text{eff}}(t) M_{\oplus} a_{\text{orb}}(t).
\label{eq:kepler_circular}
\end{equation}

```

Solving for a_{orb} gives

```

\begin{equation}
a_{\text{orb}}(t)
= \frac{h^2(t)}{G_{\text{eff}}(t) M_{\oplus}}.
\label{eq:a_from_h}
\end{equation}

```

In the code we identify $R(t) \simeq a_{\text{orb}}(t)$ and use Eq.~\eqref{eq:a_from_h} to compute a "new" radius R_{new} after each torque update. The instantaneous orbit (x, y, \dot{x}, \dot{y}) is then rescaled to this new radius:

```

\begin{aligned}
R_{\text{new}}(t) &= \frac{h^2(t)}{G_{\text{eff}}(t) M_{\oplus}}, \\
s(t) &= \frac{R_{\text{new}}(t)}{R(t)}, \\
\|r\| &\rightarrow s(t) \|r\|, \\
\|\dot{r}\| &\rightarrow \sqrt{s(t)} \|\dot{r}\|,
\end{aligned}

```

which preserves the phase of the orbit while enforcing the updated Keplerian relation.

\subsubsection*{Recession rate and comparison to data}

The primary observable extracted from the simulation is the fractional recession rate of the Earth--Moon distance,

```

\begin{equation}
\Gamma \equiv \frac{1}{R} \frac{\mathrm{d}R}{\mathrm{d}t}.
\end{equation}

```

In practice, the code estimates Γ over the full integration interval $[0, T_{\max}]$ as

```

\begin{equation}
\Gamma_{\rm num} \simeq \frac{R(T_{\rm max}) - R(0)}{R(0) T_{\rm max}}.
\label{eq:gamma_num}
\end{equation}

```

The tidal torque normalisation τ_0 is then calibrated so that $\Gamma_{\rm num}$ matches the observed value corresponding to a physical recession of $\approx 3.8 \text{ cm/yr}$ at the current distance

\$R_0\$,

```
\begin{equation}
\text{\rm Gamma}_{\text{\rm obs}} \\
= \frac{(3.8 \text{\rm cm/yr})}{R_0} \\
\approx 10^{-10} \text{\rm yr}^{-1}
```

```
\end{equation}
```

Because the model is linear in τ_0 , we can perform a single ``baseline'' run with a fiducial τ_0^{base} to measure $\Gamma_{\text{num}}^{\text{base}}$, and then set

```
\begin{equation}
```

```
\tau_0
= \tau_0^{\rm base},
\frac{\Gamma_{\rm obs}}{\Gamma_{\rm num}^{\rm base}},
```

\end{equation}

after which the calibrated model reproduces the observed lunar recession by construction. Any additional contribution from the time-variation of $G_{\text{eff}}(t)$ in Eq.~\eqref{eq:Geff_lunar} is therefore constrained to be subdominant to the tidal torque within this toy framework.

%

```
\section{Discussion and outlook}
\label{sec:discussion}
```

The main gain from working at the level of a covariant Lagrangian, rather than treating the flux sector as a purely numerical modification of $H(a)$, is conceptual clarity and comparability. Once the model is written as

```
\begin{equation}
```

```

S = \int \dd^4x \sqrt{-g}
\left[ \frac{\partial^2}{\partial t^2} R
- \frac{1}{2} (\nabla \sigma)^2
- V(\sigma)
+ \mathcal{L}_m + \mathcal{L}_r \right]
\right],
\end{equation}

```

it can be placed side by side with standard quintessence, k -essence and many modified-gravity models. This makes it immediately clear which parts of the dynamics are genuinely new (the flux interpretation and potential choice) and which parts are recycled from the existing scalar-field toolkit. It also fixes the stress--energy tensor and the covariant conservation laws unambiguously, which is essential once one goes beyond background cosmology.

From the observational point of view, the Lagrangian formulation provides a natural list of falsifiable predictions. At background level, the model predicts a specific redshift dependence of the effective dark-energy equation of state,

$$\begin{aligned} w_\sigma(a) &= \frac{\dot{\sigma}^2 - V(\sigma)}{\dot{\sigma}^2 + V(\sigma)}, \end{aligned}$$

and therefore a specific family of expansion histories $H(a)$ once (V_0, μ, Ω_m) are fixed by the calibration procedure in Sec.~\ref{subsec:param_choice}. Any sufficiently precise reconstruction of $H(a)$ from low-redshift data (BAO, SNe, cosmic chronometers) or of $w(a)$ from combined CMB+BAO+SNe analyses can in principle rule out

this particular potential shape. Likewise, the requirement that the model reproduce the CMB acoustic scale θ_{star} and the BAO distance ladder leaves only a restricted region in the (V_0, μ, Ω_m) space; future tightening of these geometric constraints will either further shrink this region or exclude the model.

Beyond the homogeneous background, the next layer of falsifiable predictions comes from perturbations and structure growth. Once the flux field is treated as a genuine dynamical scalar, its linear perturbations obey a Klein--Gordon equation on the perturbed FLRW

background, and feed into the Poisson equation via their contribution to the total stress--energy tensor. This leads to a modified growth history $f(a) = \frac{dd\ln D}{dd\ln a}$ and a predicted growth index γ that can be tested against redshift space distortion measurements and weak lensing surveys. In that sense, the flux--scalar model is not just a re-labelling of Λ CDM but a definite point in the broader space of dark energy / modified gravity theories that will be probed by DESI, Euclid and LSST.

The flux picture itself suggests several natural extensions that are left for future work. On the cosmological side, one can move from background-only to a full perturbation treatment, computing CMB anisotropies and matter power spectra with the flux scalar included as an explicit degree of freedom rather than an effective $w(a)$. On the high-energy side, the black--hole + jet toy model sketched in Sec.~\ref{sec:bh_jet} could be developed into a separate, more detailed paper, exploring whether a single flux field σ can consistently modulate both cosmological acceleration and jet efficiencies in realistic Kerr geometries. Finally, a key conceptual step will be to connect the entropy / flux deficit variables used in the numerical experiments directly to σ , rather than treating them as parallel bookkeeping devices. That would turn the current collection of ``toys'' into a single, coherent flux framework in which cosmology, black-hole phenomenology and local tests such as the Earth--Moon system all emerge from one underlying dynamical field.

\paragraph{Key points.}

This first paper has three main goals:

\begin{enumerate}

- \item Define the flux--scalar model at the level of a covariant action with an explicit potential.
- \item Show that it reduces to a numerically tractable set of background equations, recovering standard behaviour in appropriate limits.
- \item Illustrate how the same framework can be confronted with both high-redshift (CMB) and low-redshift (local orbital) data.

\end{enumerate}

Future work will lift several of the simplifying assumptions made

here, including the treatment of perturbations, a more realistic mapping between flux variables and G_{eff} , and detailed comparisons with large-scale structure data.

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