

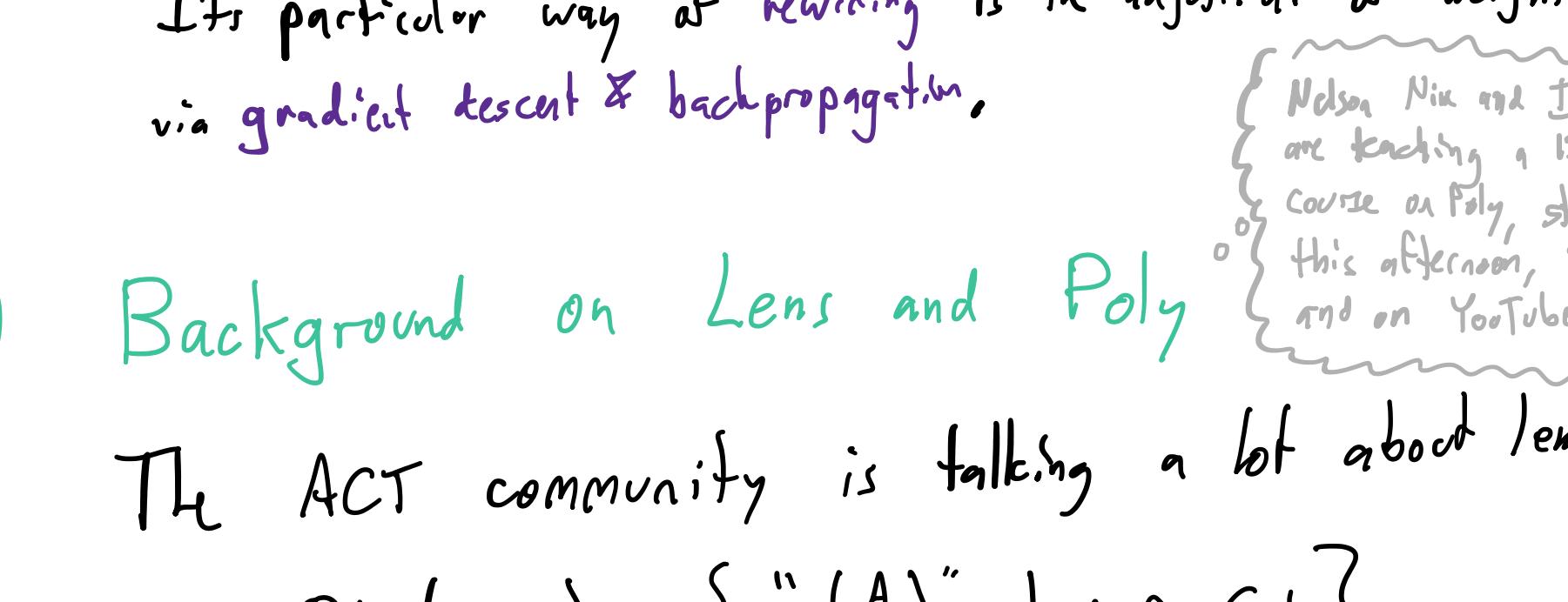
Learners' Languages

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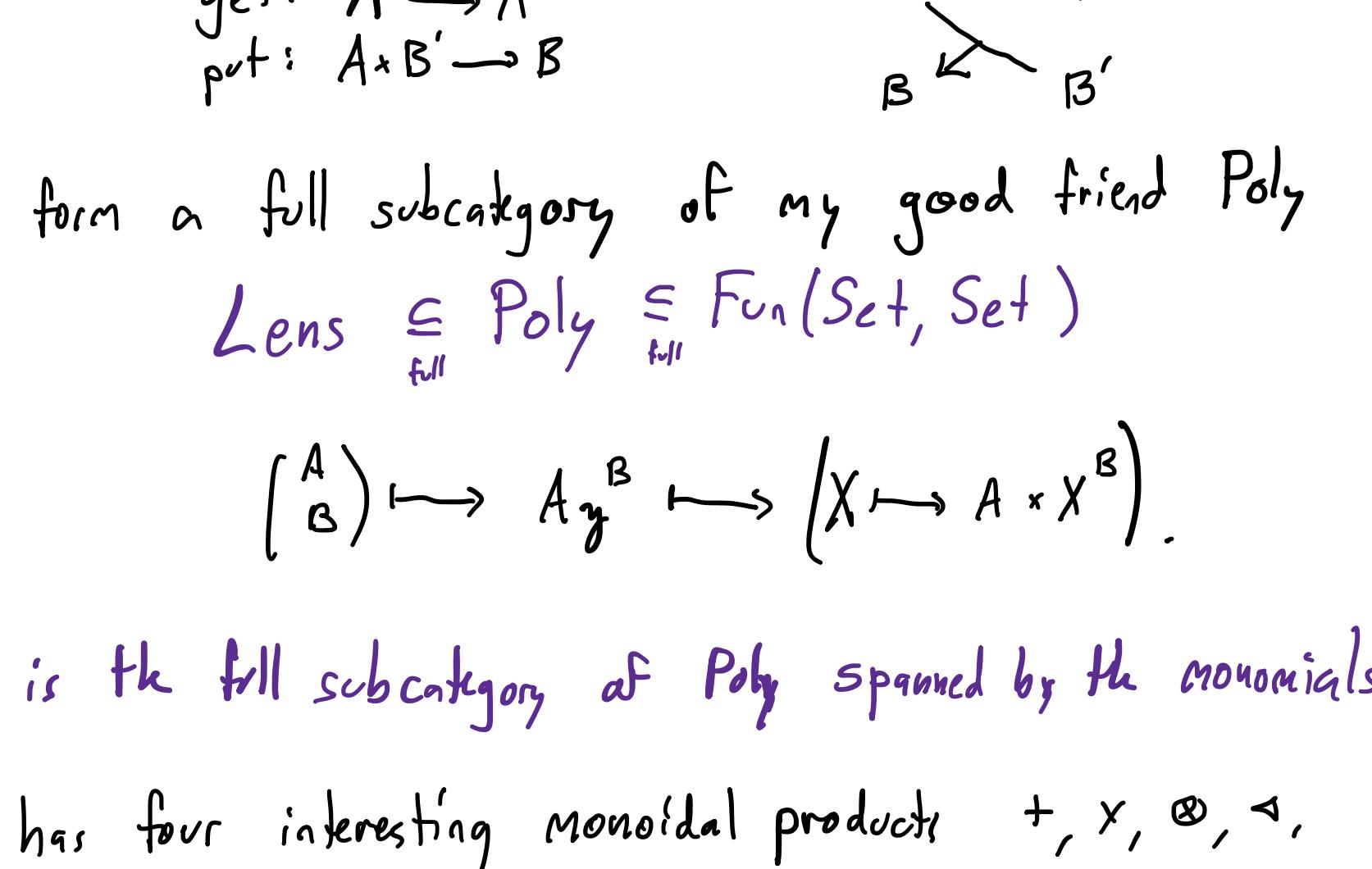
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① Introduction

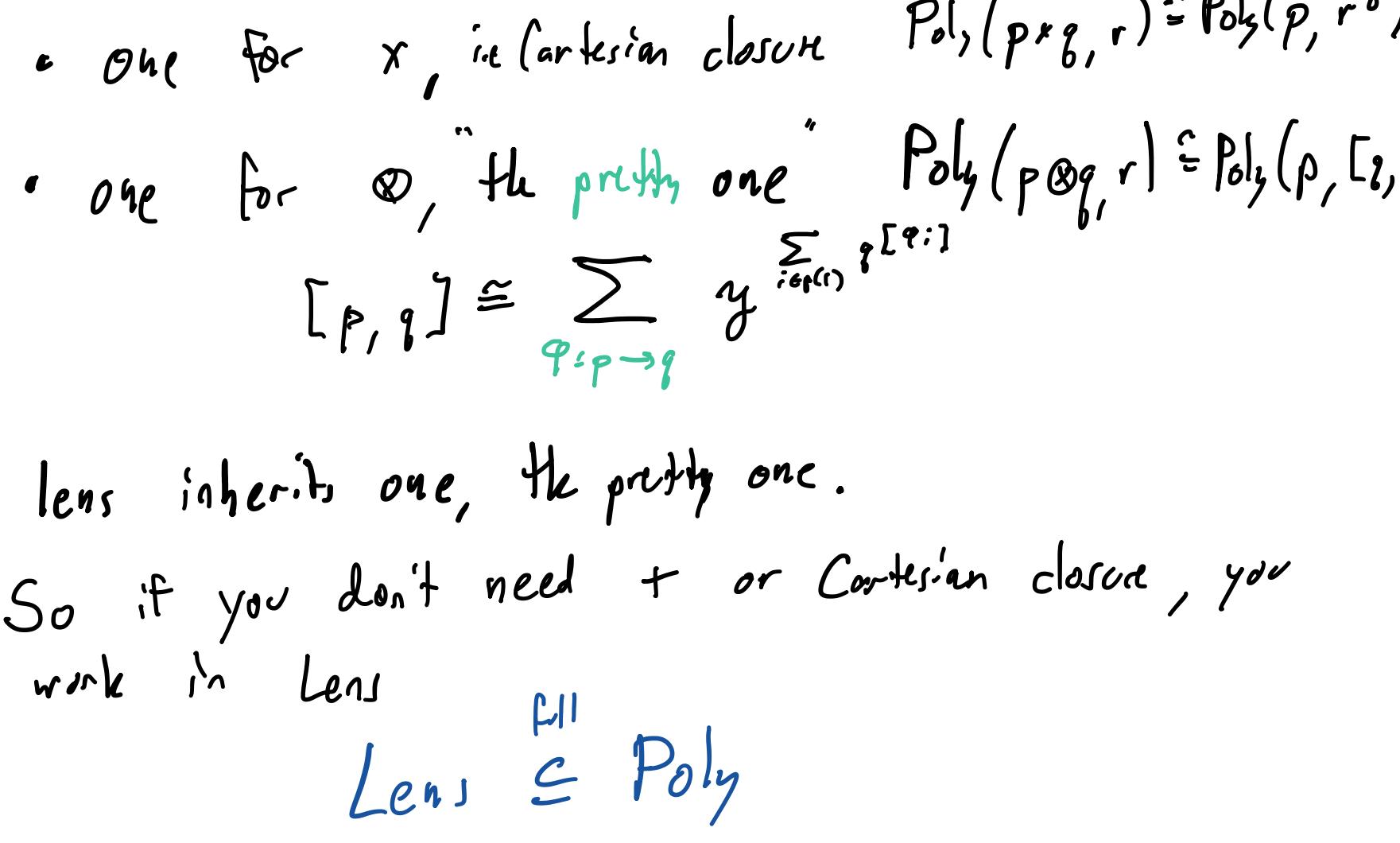
Suppose you have a bunch of interfaces



with outputs and inputs, and you can interconnect them



But in fact, you can do more than interconnect them once and for all time — you can watch what flows along all the input & output wires, and dynamically rewire them:



It turns out that the "you" character above — your particular way of deciding when and how to rewire your machines — can be modeled as an object in a topos. This means that mathematicians have pre-defined a great type theory and logic for describing "your" character traits.

It also turns out that each "neuron" and each "population of neurons" in a deep learning architecture is such a character. Its particular way of rewiring is the adjustment of "weights & biases" via gradient descent & backpropagation.

② Background on Lens and Poly

The ACT community is talking a lot about lenses.

$$\text{Ob}(\text{Lens}) := \left\{ \begin{pmatrix} A \\ B \end{pmatrix} \mid A, B \in \text{Set} \right\}$$

$$\text{Lens} \left(\begin{pmatrix} A \\ B \end{pmatrix}, \begin{pmatrix} A' \\ B' \end{pmatrix} \right) := \text{Set}(A, A') \times \text{Set}(A \times B', B)$$

$$\begin{array}{l} \text{get: } A \rightarrow A' \\ \text{put: } A \times B' \rightarrow B \end{array} \qquad \begin{array}{l} A \rightarrow A' \\ B \leftarrow B' \end{array}$$

They form a full subcategory of my good friend Poly

$$\text{Lens} \subseteq \text{Poly} \subseteq \text{Fun}(\text{Set}, \text{Set})$$

$$\begin{pmatrix} A \\ B \end{pmatrix} \hookrightarrow A \otimes B \hookrightarrow (X \mapsto A \times B^X).$$

Lens is the full subcategory of Poly spanned by the monomials.

Poly has four interesting monoidal products $+$, \times , \otimes , \dashv , of which Lens inherits three:

$$\text{Lens} \xrightarrow{\text{full}} \text{Poly}$$

$$\begin{array}{c} x \longmapsto x \\ \otimes \longmapsto \otimes \\ \dashv \longmapsto \dashv \end{array} \} \text{ strong monoidal}$$

So Lens is like "Poly without coproducts".

From the context of dynamical systems, it only excludes "interfaces that can change in time", where "allowable input can vary, based on position".

Poly also has two monoidal closures:

$$\bullet \text{ one for } x, \text{ in Cartesian closure } \text{Poly}(p \times q, r) \cong \text{Poly}(p, r^B)$$

$$\bullet \text{ one for } \otimes, \text{ the pretty one } \text{Poly}(p \otimes q, r) \cong \text{Poly}(p, [r])$$

$$[p, q] \cong \sum_{\substack{y \in \text{Set} \\ p \otimes q \rightarrow y}} y^{\sum_{x \in p} [q : x]}$$

And lens inherits one, the pretty one.

So if you don't need $+$ or Cartesian closure, you can work in Lens

$$\text{Lens} \subseteq \text{Poly}$$

$$\begin{pmatrix} A \\ B \end{pmatrix} \hookrightarrow A \otimes B$$

$$x \longmapsto x$$

$$\otimes \longmapsto \otimes$$

$$\dashv \longmapsto \dashv$$

$$[,] \longmapsto [,]$$

But there's another subtle difference. Polynomials $p \in \text{Poly}$ are naturally thought of as fractions

$$p: \text{Set} \rightarrow \text{Set}$$

so it's natural to talk about coalgebras

$$S \xrightarrow{p} p(S), \quad S \in \text{Set}$$

which have a nice interpretation as dynamical systems with state set S . For example, if $p = B \otimes_A$,

a function $S \rightarrow B \times S^A$ can be rewritten as a pair of functions

$$S \xrightarrow{\text{output } B \text{'s}} \quad \text{"output } B \text{'s"}$$

$$A \times S \rightarrow S \quad \text{"update using input } A \text{'s"}$$

Objects $\begin{pmatrix} A \\ B \end{pmatrix}$ in Lens aren't typically thought of as functors,

so a coalgebra on $\begin{pmatrix} A \\ B \end{pmatrix}$ sounds weird. However, it turns out that there's a bijection

$$\text{Lens} \left(\begin{pmatrix} S \\ B \end{pmatrix}, \begin{pmatrix} A \\ B \end{pmatrix} \right) \cong \text{Set}(S, B \otimes^A) = B \otimes^A - \text{Coalg}$$

so we can get around the weirdness and see dynamical systems totally within lens. (Yay!)

But there's a little snag left to deal with.

From the Poly / functor point of view, the natural sort of map to consider between interface-p dynamical systems is a map of coalgebras:

$$S \xrightarrow{q} p(S)$$

$$f \downarrow \quad \downarrow p(f)$$

$$S' \xrightarrow{q'} p'(S').$$

$$T \quad \quad \quad \quad \quad T \in \text{Set}(S, S')$$

But from the lens point of view, the natural sort of map to consider between interface-p dynamical systems is a map in the slice category $\text{Lens}/\begin{pmatrix} A \\ B \end{pmatrix} \left(\begin{pmatrix} S \\ S' \end{pmatrix}, \begin{pmatrix} A \\ B \end{pmatrix} \right)$

$$\begin{pmatrix} S \\ S' \end{pmatrix} \xrightarrow{q} \begin{pmatrix} A \\ B \end{pmatrix}$$

$$\downarrow \quad \quad \quad \downarrow$$

$$\begin{pmatrix} S' \\ S \end{pmatrix} \xrightarrow{q'} \begin{pmatrix} A \\ B \end{pmatrix}$$

These turn out to be very different!

$$\text{Lens}/\begin{pmatrix} A \\ B \end{pmatrix} \left(q, q' \right) \neq B \otimes^A - \text{Coalg}(q, q')$$

SAME OBJECTS
TOTALLY DIFFERENT MORPHISMS!

And that's the difference between Bruno Gavranovic et al.'s "Para(Lens)" approach

and today's "Coalgebraic" approach.

I'll let their group explain the merits of their approach.

The main merit of the approach in Learners' languages is that for any $p \in \text{Poly}$, the category

$$p - \text{Coalg}$$

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Thus, while you can talk about "learners", in the sense of

Backprop as functor, in either setting (we'll see how soon), we get a ready-made language of dependent type theory and its associated higher-order logic if we use the coalgebra maps as morphisms.

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