Geometry of Interaction for ZX-Diagrams

Kostia Chardonnet, Benoît Valiron, Renaud Vilmart

Univ. of Bologna Univ. Paris Saclay, LMF

SYCO 11

• Classical bits as vectors:
$$|0\rangle := \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 and $|1\rangle := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

• Classical bits as vectors: $|0\rangle := \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $|1\rangle := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

• Arbitrary quantum bits (qubits): $\alpha |0\rangle + \beta |1\rangle$

- Classical bits as vectors: $|0\rangle := \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $|1\rangle := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
- Arbitrary quantum bits (qubits): $\alpha |0\rangle + \beta |1\rangle$

• Larger systems:
$$q_0 \otimes q_1$$
, $|01\rangle = |0\rangle \otimes |1\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ $A \otimes B = \begin{pmatrix} a_{00}B & a_{01}B & \cdots \\ a_{10}B & \ddots \\ \vdots & & \vdots \end{pmatrix}$

- Classical bits as vectors: $|0\rangle := \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $|1\rangle := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
- Arbitrary quantum bits (qubits): $\alpha |0\rangle + \beta |1\rangle$

• Larger systems:
$$q_0 \otimes q_1$$
, $|01\rangle = |0\rangle \otimes |1\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ $A \otimes B = \begin{pmatrix} a_{00}B & a_{01}B & \cdots \\ a_{10}B & \ddots \\ \vdots & & \end{pmatrix}$

• Operation are linear maps

•
$$H := \frac{1}{\sqrt{2}} \stackrel{|0\rangle}{\underset{|1\rangle}{|0\rangle}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{cases} |0\rangle \mapsto \frac{|0\rangle + |1\rangle}{\sqrt{2}} \\ |1\rangle \mapsto \frac{|0\rangle - |1\rangle}{\sqrt{2}} \end{cases}$$
 is unitary

•
$$H := \frac{1}{\sqrt{2}} \stackrel{|0\rangle}{|1\rangle} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{cases} |0\rangle \mapsto \frac{|0\rangle + |1\rangle}{\sqrt{2}} \\ |1\rangle \mapsto \frac{|0\rangle - |1\rangle}{\sqrt{2}} \text{ is unitary} \end{cases}$$

•
$$|+\rangle := H |0\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$$

 $|-\rangle := H |1\rangle = \frac{|0\rangle - |1\rangle}{\sqrt{2}}$

•
$$H := \frac{1}{\sqrt{2}} \stackrel{|0\rangle}{|1\rangle} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{cases} |0\rangle \mapsto \frac{|0\rangle + |1\rangle}{\sqrt{2}} \\ |1\rangle \mapsto \frac{|0\rangle - |1\rangle}{\sqrt{2}} \end{cases}$$
 is unitary

$$|+\rangle := H |0\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$$
$$|-\rangle := H |1\rangle = \frac{|0\rangle - |1\rangle}{\sqrt{2}}$$

• CNOT :=
$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} = \begin{cases} |0x\rangle \mapsto |0x\rangle \\ |1x\rangle \mapsto |1-x\rangle \end{cases}$$

• Was introduced by Coecke and Duncan in 2008

- Was introduced by Coecke and Duncan in 2008
- Is part of the Categorical Quantum Mechanics program (Abramsky&Coecke'04)

- Was introduced by Coecke and Duncan in 2008
- Is part of the Categorical Quantum Mechanics program (Abramsky&Coecke'04)

• Manipulates string diagrams e.g.



- Was introduced by Coecke and Duncan in 2008
- Is part of the Categorical Quantum Mechanics program (Abramsky&Coecke'04)
- Manipulates string diagrams e.g. $\frac{\pi}{2}$



Relaxes unitarity

- Was introduced by Coecke and Duncan in 2008
- Is part of the Categorical Quantum Mechanics program (Abramsky&Coecke'04)
- Manipulates string diagrams e.g. $\frac{\pi}{2}$



- Relaxes unitarity
- Is Universal (can encode any linear map)

- Was introduced by Coecke and Duncan in 2008
- Is part of the Categorical Quantum Mechanics program (Abramsky&Coecke'04)
- Manipulates string diagrams e.g.



- Relaxes unitarity
- Is Universal (can encode any linear map)
- Lack a direct operational interpretation (this work!)

ZX-Calculus in Short

Generators















(Id)

,

(Swap)

(Cap)

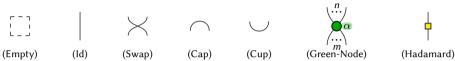
(Cup)

(Green-Node)

(Hadamard)

ZX-Calculus in Short

Generators



Compositions

$$\begin{array}{c|c} & \cdots & & \cdots & \\ \hline D_2 & \circ & D_1 \\ \hline \cdots & & \end{array}$$

$$\begin{array}{c|c} & \cdots & \\ \hline D_1 \\ \hline \end{array} \otimes \begin{array}{c} & \cdots \\ \hline D_2 \\ \hline \end{array} \ = \ \begin{array}{c|c} & \cdots & \\ \hline D_1 \\ \hline \end{array} \begin{array}{c} & \cdots \\ \hline D_2 \\ \hline \end{array}$$

ZX-Calculus in Short

Generators



Compositions

$$\begin{array}{c|c} & \cdots & & \\ \hline D_2 & & D_1 \\ \hline & \cdots & & D_2 \\ \hline \end{array}) \circ \begin{array}{c|c} & \cdots & & \\ \hline D_1 & & \\ \hline D_2 & & \\ \hline \end{array}$$

$$\begin{bmatrix} \dots \\ D_1 \\ \dots \end{bmatrix} \otimes \begin{bmatrix} \dots \\ D_2 \\ \dots \end{bmatrix} \ = \ \begin{bmatrix} \dots \\ D_1 \\ \dots \end{bmatrix} \begin{bmatrix} \dots \\ D_2 \\ \dots \end{bmatrix}$$

Standard Interpretation

Linear Maps :
$$\mathbf{ZX} \to \mathcal{M}(\mathbb{C})$$

$$= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

• A spider:
$$\begin{pmatrix} n \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ 0 \\ \dots \\ 0 \end{pmatrix} = \begin{cases} |0 \dots 0\rangle \mapsto |0 \dots 0\rangle \\ |1 \dots 1\rangle \mapsto e^{i\alpha} |1 \dots 1\rangle \\ |0 \dots 0\rangle \mapsto |0 \dots 0\rangle \\ |0 \dots 1\rangle \mapsto e^{i\alpha} |1 \dots 1\rangle \end{cases}$$

• A change of basis:
$$\frac{1}{\sqrt{2}} :: \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{cases} |0\rangle \mapsto \frac{|0\rangle + |1\rangle}{\sqrt{2}} \\ |1\rangle \mapsto \frac{|0\rangle - |1\rangle}{\sqrt{2}} \end{cases}$$

• A spider:
$$\begin{pmatrix} n \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix} = \begin{cases} \begin{vmatrix} 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & \vdots \\ \vdots & \ddots & \vdots \\ \vdots & 0 & 0 & 0 \\ 0 & \cdots & 0 & e^{i\alpha} \\ \end{pmatrix} = \begin{cases} \begin{vmatrix} 0 & \dots & 0 \\ 1 & \dots & 1 \\ 0 & \dots & 1 \\ \end{pmatrix} \mapsto \underbrace{e^{i\alpha}}_{0} \begin{vmatrix} 1 & \dots & 1 \\ 0 & \dots & 1 \\ \end{pmatrix}$$

• A change of basis:
$$\frac{1}{\sqrt{2}} :: \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{cases} |0\rangle \mapsto \frac{|0\rangle + |1\rangle}{\sqrt{2}} \\ |1\rangle \mapsto \frac{|0\rangle - |1\rangle}{\sqrt{2}} \end{cases}$$

• Wires:
$$\left| \begin{array}{c} :: \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{array} \right| = \left| x \right\rangle \mapsto \left| x \right\rangle, \quad \right\rangle :: \left(\begin{array}{ccc} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right) = \left| xy \right\rangle \mapsto \left| yx \right\rangle$$

• A spider:
$$\begin{pmatrix} n \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix} = \begin{cases} \begin{vmatrix} 0 & \cdots & 0 \\ 0 & 0 & \vdots \\ \vdots & \ddots & \vdots \\ \vdots & 0 & 0 \\ 0 & \cdots & 0 & e^{i\alpha} \end{pmatrix} = \begin{cases} \begin{vmatrix} 0 & \cdots & 0 \\ 1 & \cdots & 1 \\ 0 & \cdots & 1 \end{vmatrix} \mapsto \frac{e^{i\alpha}}{0} \begin{vmatrix} 1 & \cdots & 1 \\ 0 & \cdots & 1 \end{vmatrix}$$

• A change of basis:
$$\frac{1}{\sqrt{2}} :: \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{cases} |0\rangle \mapsto \frac{|0\rangle + |1\rangle}{\sqrt{2}} \\ |1\rangle \mapsto \frac{|0\rangle - |1\rangle}{\sqrt{2}} \end{cases}$$

• Wires:
$$\left| \begin{array}{cc} \vdots & \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = |x\rangle \mapsto |x\rangle, \quad \middle\times :: \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = |xy\rangle \mapsto |yx\rangle$$

•
$$\bigcup$$
 :: $(1\ 0\ 0\ 1) = |xy\rangle \mapsto \delta_{x=y} : \mathbb{C}^2 \to \mathbb{C}$

Token & Token State



Token

3-tuple $(e, d, b) \in \mathcal{E}(D) \times \{\uparrow, \downarrow\} \times \{0, 1\}$ where:

- *e* is an edge of the ZX-Diagram *D*.
- *d* is a direction.
- *b* is the state of the token.

Token & Token State

$$D = \begin{bmatrix} a_0 & a_1 \\ b_1 & b_1 \end{bmatrix}$$

Token

3-tuple $(e, d, b) \in \mathcal{E}(D) \times \{\uparrow, \downarrow\} \times \{0, 1\}$ where:

- e is an edge of the ZX-Diagram D.
- *d* is a direction.
- *b* is the state of the token.

Token State

A token state is a **sum** of **products** of tokens with complex coefficients.

Token & Token State

$$D = \begin{bmatrix} a_0 & a_1 \\ e_1 & e_2 \\ b_1 & b_1 \end{bmatrix}$$

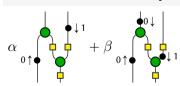
Token

3-tuple $(e, d, b) \in \mathcal{E}(D) \times \{\uparrow, \downarrow\} \times \{0, 1\}$ where:

- e is an edge of the ZX-Diagram D.
- *d* is a direction.
- *b* is the state of the token.

Token State

A *token state* is a **sum** of **products** of tokens with complex coefficients.



$$\langle t | t' \rangle = \begin{cases} 1 & \text{if } t = t' \\ 0 & \text{if } t \neq t' \end{cases}$$

• Collisions : $\downarrow x \\ \uparrow x \\ \sim$

• Collisions : $\begin{picture}(20,0) \put(0,0){\line(0,0){120}} \put(0,0)$

$$\oint_{\Phi}
\downarrow_{\neg_X}$$
 $\longrightarrow 0$

• Collisions : $\downarrow \uparrow x \\ \uparrow x \\ \leadsto \qquad \qquad \downarrow \uparrow x \\ \downarrow \uparrow \neg x \\ \leadsto \qquad 0$



• Collisions:
$$\oint \uparrow x \leftrightarrow \downarrow x \leftrightarrow 0$$

• Diffusions:
$$x \downarrow \phi \cdots \phi \Rightarrow e^{ix\alpha} \xrightarrow{x \uparrow \phi \cdots \phi \uparrow x} x$$

$$\stackrel{\blacklozenge}{\stackrel{\downarrow}{\stackrel{\downarrow}{\stackrel{}}}} \stackrel{\times}{\longrightarrow} \frac{1}{\sqrt{2}} \left(\stackrel{\downarrow}{\stackrel{\blacklozenge}{\stackrel{}}} \downarrow 0 + (-1)^x \stackrel{\downarrow}{\stackrel{\blacktriangleright}{\stackrel{}}} \downarrow 1 \right)$$

• Collisions :
$$\downarrow \uparrow x \\ \uparrow x \\ \rightsquigarrow \qquad \qquad \downarrow \uparrow x \\ \uparrow \neg x \\ \rightsquigarrow 0$$

$$\oint \oint x \longrightarrow 0$$

• Diffusions: $x \downarrow \downarrow \cdots \downarrow x$ $\Rightarrow e^{ix\alpha} \xrightarrow{x \uparrow \downarrow \cdots \downarrow x} x$

$$x\downarrow$$
 \searrow \searrow \downarrow x

$$\stackrel{\blacklozenge}{\stackrel{\downarrow}{\vdash}} {}^{x} \rightsquigarrow \frac{1}{\sqrt{2}} \left(\stackrel{\downarrow}{\stackrel{\blacktriangleright}{\blacktriangleright}} {}_{\downarrow 0} + (-1)^{x} \stackrel{\downarrow}{\stackrel{\blacktriangleright}{\blacktriangleright}} {}_{\downarrow 1} \right)$$

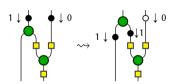
$$x \downarrow b \longrightarrow b \uparrow x$$

$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

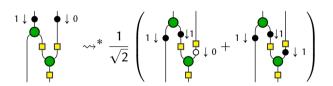
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



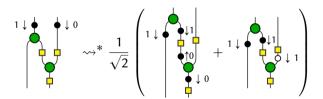
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \boxed{\begin{array}{c} 1 \\ \sqrt{2} \\ \end{array}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} |11\rangle$$



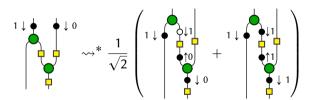
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



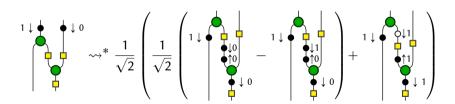
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



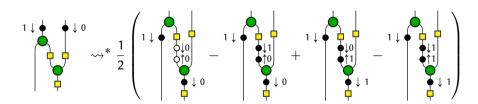
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \boxed{\begin{array}{c} 1 \\ \sqrt{2} \\ \end{array}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} |11\rangle$$



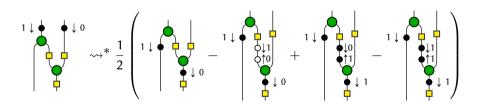
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



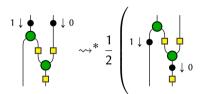
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$

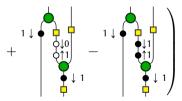


$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$

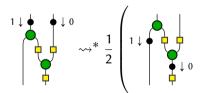


$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \boxed{ \begin{array}{c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ \end{array} } \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



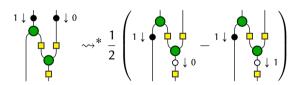


$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$

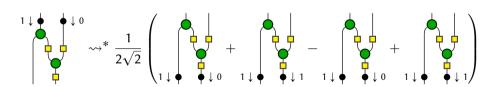




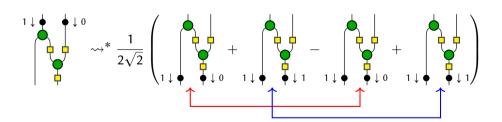
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



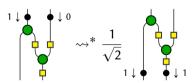
$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} \, |11\rangle$$



$$\frac{1}{\sqrt{2}} \, \mathsf{CNOT} = \boxed{\begin{array}{c} 1 \\ \sqrt{2} \\ \end{array}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \implies |10\rangle \mapsto \frac{1}{\sqrt{2}} |11\rangle$$



Avoiding Errors

Rewriting System

We define \rightsquigarrow as exactly one diffusion rule followed by all possible collision rules until none applies.

Want to avoid:

• Having multiple tokens on the same edge that don't collide: $\bigvee_{i=1}^{n} x_i$



Non-termination.

Avoiding Errors

Rewriting System

We define \rightsquigarrow as *exactly* one **diffusion rule** followed by all possible **collision** rules until none applies.

Want to avoid:

- Having multiple tokens on the same edge that don't collide: $\bigvee_{v}^{x} x$
- Non-termination.

Two invariants:

- **Well-Formedness**: Avoid two tokens going in the same direction on a path.
- Cycle-Balancedness: Avoid tokens alone in cycles.

Polarity

Polarity in a Path

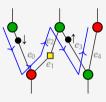
 $p = (e_0, e_1, e_2, e_3, e_4)$ is an oriented path.

- If a token follows the path +1
- If it goes against it -1
- If it is not on the path 0



• Here, polarity

$$P(p, (e_0 \downarrow x)(e_3 \uparrow y)) = P(p, (e_0 \downarrow x)) + P(p, (e_3 \uparrow y)) = 0$$



Well-Formed Token State

Given a ZX-Diagram and a Token State, it is **Well-Formed** if for every path p its Polarity $\in \{-1, 0, 1\}$.

Well-Formed Token State

Given a ZX-Diagram and a Token State, it is **Well-Formed** if for every path p its Polarity $\in \{-1, 0, 1\}$.

- Well-Formedness preserved under <->.
- Well-formed states cannot reach "bad configurations".

Well-Formed Token State

Given a ZX-Diagram and a Token State, it is **Well-Formed** if for every path p its Polarity $\in \{-1, 0, 1\}$.

- Well-Formedness preserved under *→*.
- Well-formed states cannot reach "bad configurations".

Cycle-Balanced Token State

Given a ZX-Diagram and a Token State, it is **Cycle-Balanced** if for every cycle c its Polarity = 0.

Well-Formed Token State

Given a ZX-Diagram and a Token State, it is **Well-Formed** if for every path p its Polarity $\in \{-1, 0, 1\}$.

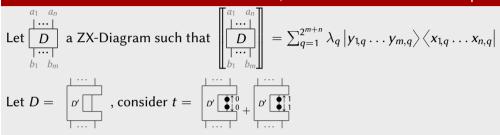
- Well-Formedness preserved under <->.
- Well-formed states cannot reach "bad configurations".

Cycle-Balanced Token State

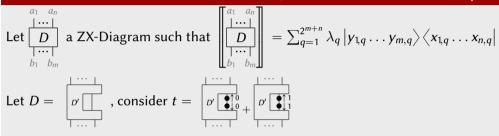
Given a ZX-Diagram and a Token State, it is **Cycle-Balanced** if for every cycle c its Polarity = 0.

- Termination of well-formed, cycle-balanced token state.
- Local confluence of well-formed, cycle-balanced token state.

(Simulation of Standard Interpretation)



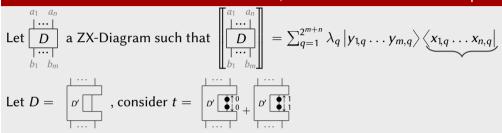
(Simulation of Standard Interpretation)



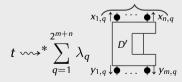
Then

$$t \leadsto^* \sum_{q=1}^{2^{m+n}} \lambda_q \int_{y_{1,q}}^{x_{1,q}} \int_{\phi \dots \phi}^{\phi \dots \phi} x_{n,q}$$

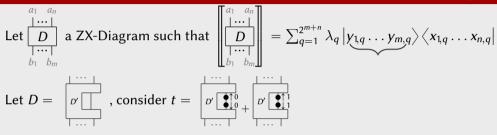
(Simulation of Standard Interpretation)



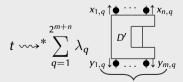
Then



(Simulation of Standard Interpretation)



Then



Conclusion

Conclusion

- The Token Machine gives us a very general framework to study ZX-Calculus.
- More operational approach to ZX-Calculus.
- Can be easily adapted to extensions of ZX-Calculus (SOP, Mixed-Processes).
- General enough for any tensor networks.