

# Introduction to statistical inference

Maarten Speekenbrink

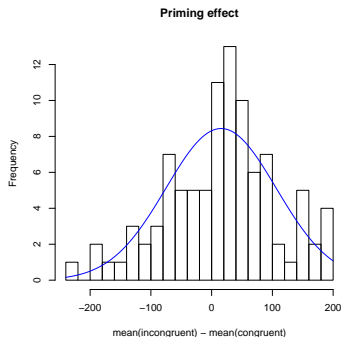
Experimental Psychology  
University College London

Statistics lecture 2

# Outline

- 1 Statistical inference
  - Introduction
  - Statistical decision making
  - Hypothesis testing
- 2 The  $F$  test
- 3 Decision errors and power
  - Estimating power
  - Improving power
- 4 Confidence intervals

# A statistical model of retroactive priming



- We have data  $Y_i$  and model

$$Y_i \sim N(\mu, \sigma)$$

We do not know  $\mu$  and  $\sigma$

## Some notation

Throughout the course, we will mainly use **linear models**. These have the general form

$$Y_i = \beta_0 + \beta_1 \times X_{1i} + \beta_2 \times X_{2i} + \dots + \beta_{p-1} \times X_{p-1,i} + \epsilon_i$$

where the  $\beta_j$ 's (beta's) are **parameters** and the  $X_j$ 's are **predictor** variables. The final term  $\epsilon_i$  (epsilon) is an **error** term, the part of the data which is not predictable from the model. For the error, we usually assume

$$\epsilon_i \sim N(0, \sigma)$$

# Some notation

Throughout the course, we will mainly use **linear models**. These have the general form

$$Y_i = \beta_0 + \beta_1 \times X_{1i} + \beta_2 \times X_{2i} + \dots + \beta_{p-1} \times X_{p-1,i} + \epsilon_i$$

where the  $\beta_j$ 's (beta's) are **parameters** and the  $X_j$ 's are **predictor** variables. The final term  $\epsilon_i$  (epsilon) is an **error** term, the part of the data which is not predictable from the model. For the error, we usually assume

$$\epsilon_i \sim N(0, \sigma)$$

Note that the  $\beta_j$ 's are generally unknown parameters of the population. To distinguish these from **estimated** parameters, we will use

$$Y_i = b_0 + b_1 \times X_{1i} + b_2 \times X_{2i} + \dots + b_{p-1} \times X_{p-1,i} + e_i$$

for an **estimated model**.

# A simple model

For consistency, we rewrite our population model

$$Y_i \sim N(\mu, \sigma)$$

in linear model form as

$$Y_i = \mu + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

and then

$$Y_i = \beta_0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

(so  $\beta_0 = \mu$ )

Note that there are no predictor variables here. All we know is that the observations come from the same population.

# Statistical inference

- Data is a sample from the “population”, a hypothetical construct defined as the collection of all possible observations (from all people at all times).
- We'd like to say something about the population (e.g., it's mean), not about the sample.
- Because we've sampled from the population, we can use the data to infer properties of the population. This is *statistical inference*. Two (related) methods:
  - Estimation: given a sample (data), estimate population parameter and a range of (more or less) likely values
  - Testing: given the sample data, decide whether population parameter is equal to a hypothetical value
- Always need a model of the population

# Is the retroactive priming effect real?

In Bem's (2011) study, the average retroactive priming effect was positive. Our model of retroactive priming can be stated in the following three equivalent ways:

$$\text{priming}_i \sim N(\mu, \sigma)$$

$$\text{priming}_i = \mu + \epsilon_i$$

$$Y_i = \beta_0 + \epsilon_i$$

$$\epsilon_i \sim N(0, \sigma)$$

$$\epsilon_i \sim N(0, \sigma)$$

where the last version uses the standard GLM notation, so  $Y_i = \text{priming}_i$  and  $\beta_0 = \mu$ .



# Is the retroactive priming effect real?

In Bem's (2011) study, the average retroactive priming effect was positive. Our model of retroactive priming can be stated in the following three equivalent ways:

$$\text{priming}_i \sim N(\mu, \sigma)$$

$$\text{priming}_i = \mu + \epsilon_i$$

$$Y_i = \beta_0 + \epsilon_i$$

$$\epsilon_i \sim N(0, \sigma)$$

$$\epsilon_i \sim N(0, \sigma)$$

where the last version uses the standard GLM notation, so  $Y_i = \text{priming}_i$  and  $\beta_0 = \mu$ .

How likely is it that  $\beta_0 \neq 0$ ?

# Is the retroactive priming effect real?

In Bem's (2011) study, the average retroactive priming effect was positive. Our model of retroactive priming can be stated in the following three equivalent ways:

$$\text{priming}_i \sim N(\mu, \sigma)$$

$$\text{priming}_i = \mu + \epsilon_i$$

$$Y_i = \beta_0 + \epsilon_i$$

$$\epsilon_i \sim N(0, \sigma)$$

$$\epsilon_i \sim N(0, \sigma)$$

where the last version uses the standard GLM notation, so  $Y_i = \text{priming}_i$  and  $\beta_0 = \mu$ .

How likely is it that  $\beta_0 \neq 0$ ?

Two decisions: decide  $\beta_0 = 0$  or decide  $\beta_0 \neq 0$ .

# Decisions, decisions... (slight detour)

- Two possible states: “ill” and “well”
- Two decisions: “treat” and “send home”
- Each combination of state and decision has a consequence (utility)

		Patient	
		Ill	Well
Doctor	Treat	$a$	$b$
	Send home	$c$	$d$

- Based on symptoms, doctor can assign probabilities  $p(\text{ill})$  and  $p(\text{well}) = 1 - p(\text{ill})$
- Principle of maximum expected utility: choose the action with the highest expected utility.
  - decide to treat if

$$p(\text{ill}) \times a + p(\text{well}) \times b > p(\text{ill}) \times c + p(\text{well}) \times d$$

- decide to send home otherwise

# Decisions, decisions... (slight detour)

- Two possible states: “ill” and “well”
- Two decisions: “treat” and “send home”
- Each combination of state and decision has a consequence (utility)

		Patient	
		Ill	Well
Doctor	Treat	$a$	$b$
	Send home	$c$	$d$

- Based on symptoms, doctor can assign probabilities  $p(\text{ill})$  and  $p(\text{well}) = 1 - p(\text{ill})$
- Principle of maximum expected utility: choose the action with the highest expected utility.
  - decide to treat if

$$p(\text{ill}) \times a + p(\text{well}) \times b > p(\text{ill}) \times c + p(\text{well}) \times d$$

- decide to send home otherwise

# Decisions, decisions... (slight detour)

- Two possible states: “ill” and “well”
- Two decisions: “treat” and “send home”
- Each combination of state and decision has a consequence (utility)

		Patient	
		Ill	Well
Doctor	Treat	$a$	$b$
	Send home	$c$	$d$

- Based on symptoms, doctor can assign probabilities  $p(\text{ill})$  and  $p(\text{well}) = 1 - p(\text{ill})$
- Principle of **maximum expected utility**: choose the action with the highest expected utility.
  - decide to treat if

$$p(\text{ill}) \times a + p(\text{well}) \times b > p(\text{ill}) \times c + p(\text{well}) \times d$$

- decide to send home otherwise

# Too many decisions...

- Rather uncommon that there are only two possible states; number of possible states (e.g., parameter values) often infinite
- Often one properly specified hypothesis, but alternative unspecified. E.g.
  - $H_0$  (null-hypothesis):  $\beta_0 = B_0$  (e.g., mean priming effect in population is  $B_0 = 0$ ).
  - $H_a$  (alternative):  $\beta_0 \neq B_0$  (mean priming effect in population is different from  $B_0$ ).
- Again two decisions: accept  $H_0$  or accept  $H_a$ . What is the best decision?

# Too many decisions...

- Rather uncommon that there are only two possible states; number of possible states (e.g., parameter values) often infinite
- Often one properly specified hypothesis, but alternative unspecified. E.g.
  - $H_0$  (null-hypothesis):  $\beta_0 = B_0$  (e.g., mean priming effect in population is  $B_0 = 0$ ).
  - $H_a$  (alternative):  $\beta_0 \neq B_0$  (mean priming effect in population is different from  $B_0$ ).
- Again two decisions: accept  $H_0$  or accept  $H_a$ . What is the best decision?

# Too many decisions...

- Rather uncommon that there are only two possible states; number of possible states (e.g., parameter values) often infinite
- Often one properly specified hypothesis, but alternative unspecified. E.g.
  - $H_0$  (null-hypothesis):  $\beta_0 = B_0$  (e.g., mean priming effect in population is  $B_0 = 0$ ).
  - $H_a$  (alternative):  $\beta_0 \neq B_0$  (mean priming effect in population is different from  $B_0$ ).
- Again two decisions: accept  $H_0$  or accept  $H_a$ . What is the best decision?



# Too many decisions...

- Rather uncommon that there are only two possible states; number of possible states (e.g., parameter values) often infinite
- Often one properly specified hypothesis, but alternative unspecified. E.g.
  - $H_0$  (null-hypothesis):  $\beta_0 = B_0$  (e.g., mean priming effect in population is  $B_0 = 0$ ).
  - $H_a$  (alternative):  $\beta_0 \neq B_0$  (mean priming effect in population is different from  $B_0$ ).
- Again two decisions: accept  $H_0$  or accept  $H_a$ . What is the best decision?

# Too many decisions...

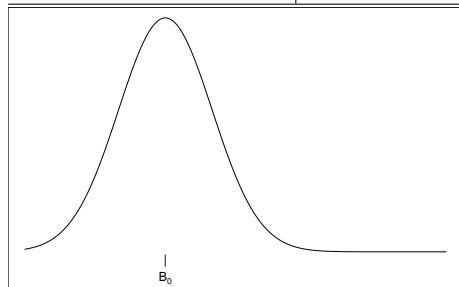
- Rather uncommon that there are only two possible states; number of possible states (e.g., parameter values) often infinite
  - Often one properly specified hypothesis, but alternative unspecified. E.g.
    - $H_0$  (null-hypothesis):  $\beta_0 = B_0$  (e.g., mean priming effect in population is  $B_0 = 0$ ).
    - $H_a$  (alternative):  $\beta_0 \neq B_0$  (mean priming effect in population is different from  $B_0$ ).
- (a capital  $B_j$  is used to denote an *a priori* value of  $\beta_j$ ; usually  $B_0 = 0$ , but this does not have to be the case)
- Again two decisions: accept  $H_0$  or accept  $H_a$ . What is the best decision?

# Too many decisions...

- Rather uncommon that there are only two possible states; number of possible states (e.g., parameter values) often infinite
  - Often one properly specified hypothesis, but alternative unspecified. E.g.
    - $H_0$  (null-hypothesis):  $\beta_0 = B_0$  (e.g., mean priming effect in population is  $B_0 = 0$ ).
    - $H_a$  (alternative):  $\beta_0 \neq B_0$  (mean priming effect in population is different from  $B_0$ ).
- (a capital  $B_j$  is used to denote an **a priori** value of  $\beta_j$ ; usually  $B_0 = 0$ , but this does not have to be the case)
- Again two decisions: accept  $H_0$  or accept  $H_a$ . What is the best decision?

# Deciding between hypotheses

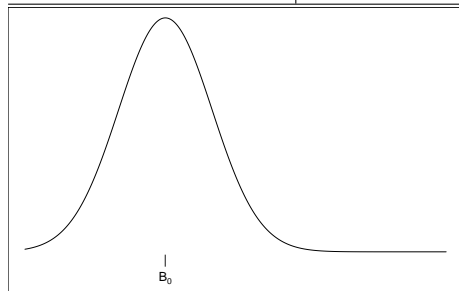
		population	
		$H_0: \beta_0 = B_0$	$H_a: \beta_0 \neq B_0$
decision	accept $H_0$	correct	type II error
	reject $H_0$	type I error	correct



- In this simple model, the sample mean  $\bar{Y}$  is the best estimator of  $\beta_0$ . Under  $H_0$ , we can work out the sampling distribution of  $\bar{Y}$

# Deciding between hypotheses

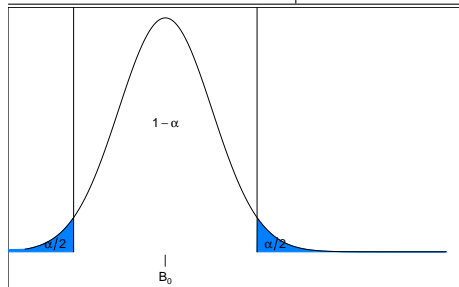
		population	
		$H_0: \beta_0 = B_0$	$H_a: \beta_0 \neq B_0$
decision	accept $H_0$	correct	type II error
	reject $H_0$	type I error	correct



- If  $\bar{Y}$  is unlikely when  $H_0$  is true, we reject  $H_0$
- We fix  $p(\text{Type I error} | H_0) = \alpha$  by finding critical value(s). This significance level  $\alpha$  is conventionally set to  $\alpha = .05$

# Deciding between hypotheses

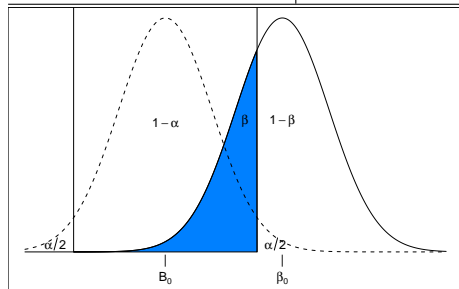
		population	
		$H_0: \beta_0 = B_0$	$H_a: \beta_0 \neq B_0$
decision	accept $H_0$	correct	type II error
	reject $H_0$	type I error	correct



- If  $\bar{Y}$  is unlikely when  $H_0$  is true, we reject  $H_0$
- We fix  $p(\text{Type I error} | H_0) = \alpha$  by finding critical value(s). This significance level  $\alpha$  is conventionally set to  $\alpha = .05$

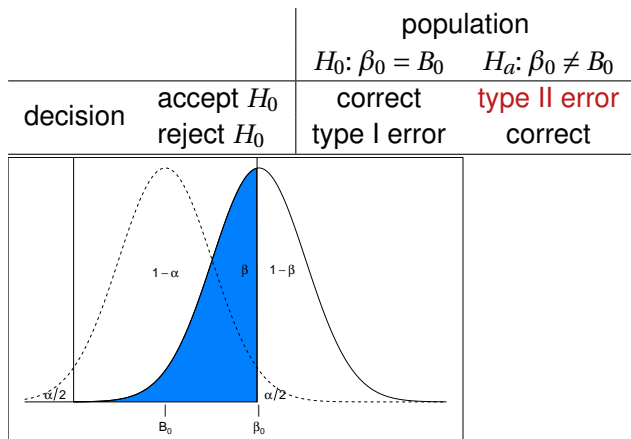
# Deciding between hypotheses

		population	
		$H_0: \beta_0 = B_0$	$H_a: \beta_0 \neq B_0$
decision	accept $H_0$	correct	type II error
	reject $H_0$	type I error	correct



- Without knowing  $\beta_0$ , cannot determine  $p(\text{Type II error} | H_a) = \beta$

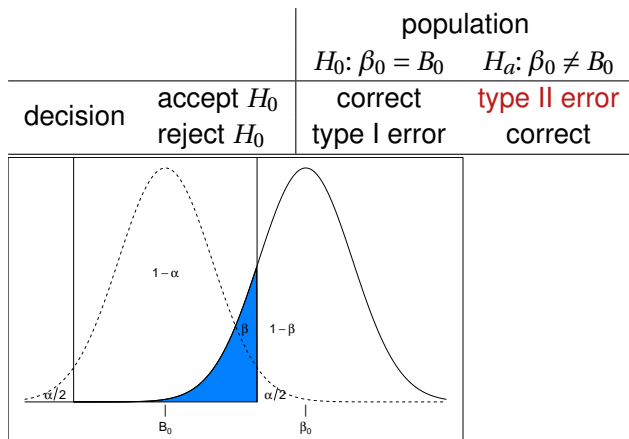
# Deciding between hypotheses



- Without knowing  $\beta_0$ , cannot determine  $p(\text{Type II error} | H_a) = \beta$



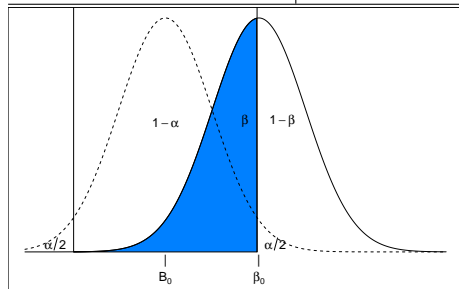
# Deciding between hypotheses



- Without knowing  $\beta_0$ , cannot determine  $p(\text{Type II error} | H_a) = \beta$

# Deciding between hypotheses

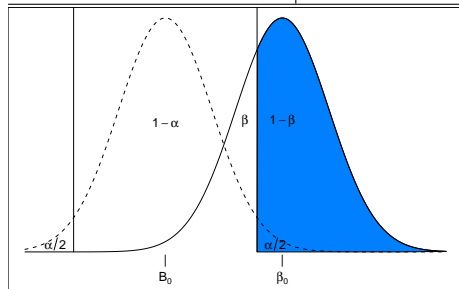
		population	
		$H_0: \beta_0 = B_0$	$H_a: \beta_0 \neq B_0$
decision	accept $H_0$	correct	type II error
	reject $H_0$	type I error	correct



- Without knowing  $\beta_0$ , cannot determine  $p(\text{Type II error} | H_a) = \beta$

# Deciding between hypotheses

		population	
		$H_0: \beta_0 = B_0$	$H_a: \beta_0 \neq B_0$
decision	accept $H_0$	correct	type II error
	reject $H_0$	type I error	<b>correct</b>



- Without knowing  $\beta_0$ , cannot determine  $p(\text{Type II error} | H_a) = \beta$
- The *power* of a test,  $p(\text{reject } H_0 | H_a) = 1 - \beta$ , is thus also unknown

# Null hypothesis significance testing

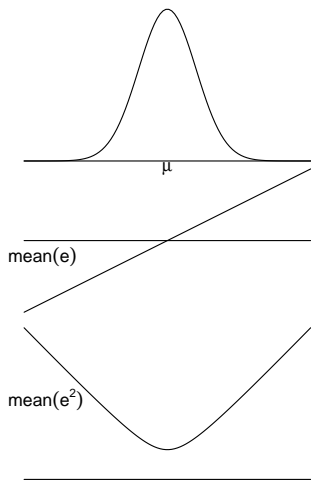
- Essentially: focus on a single hypothesis ( $H_0$ )
- Work out sampling distribution of a statistic, assuming  $H_0$  is true
- If the value of the statistic in the data is unlikely given that  $H_0$  is true, reject  $H_0$
- Fix the probability of falsely rejecting  $H_0$  to  $\alpha$ , usually  $\alpha = .05$
- The procedure is entirely based on keeping a specific error rate (Type I errors) within a certain bound. Without additional knowledge, we know nothing about the other error rate (Type II errors).

# To estimate or not to estimate...

- If  $\beta_0 = 0$ , we should predict (future) priming effects as 0
- If  $\beta_0 \neq 0$ , we'd probably be better off using an estimated  $\beta_0$  for future predictions
- Using  $\hat{\beta}_0 = b_0 = \bar{Y}$  minimizes Sum of Squared Error in the sample
- Using  $\beta_0 = \mu$  minimizes the Sum of Squared Error in the population
- $\bar{Y}$  is unlikely to be (exactly) equal to  $\mu$ , so predictions  $\hat{Y} = \bar{Y}$  are unlikely to be best for new samples
- If we have a prior idea about the value of  $\beta_0$ , would that lead to better predictions for future data?

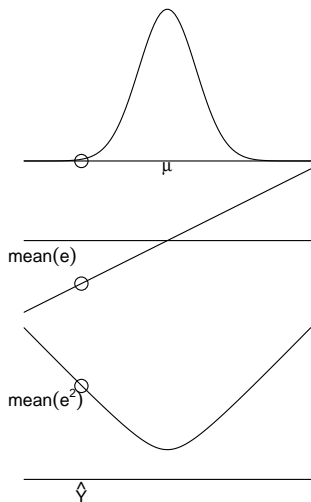
# To estimate or not to estimate...

- If  $\beta_0 = 0$ , we should predict (future) priming effects as 0
- If  $\beta_0 \neq 0$ , we'd probably be better off using an estimated  $\beta_0$  for future predictions
- Using  $\hat{\beta}_0 = b_0 = \bar{Y}$  minimizes Sum of Squared Error in the sample
- Using  $\beta_0 = \mu$  minimizes the Sum of Squared Error in the population
- $\bar{Y}$  is unlikely to be (exactly) equal to  $\mu$ , so predictions  $\hat{Y} = \bar{Y}$  are unlikely to be best for new samples
- If we have a prior idea about the value of  $\beta_0$ , would that lead to better predictions for future data?



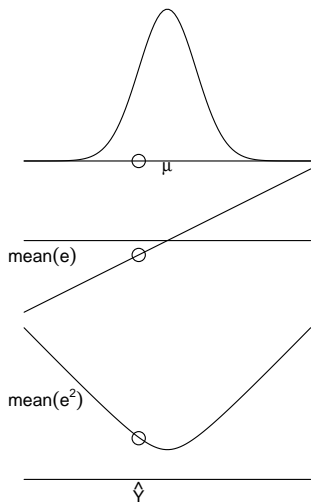
# To estimate or not to estimate...

- If  $\beta_0 = 0$ , we should predict (future) priming effects as 0
- If  $\beta_0 \neq 0$ , we'd probably be better off using an estimated  $\beta_0$  for future predictions
- Using  $\hat{\beta}_0 = b_0 = \bar{Y}$  minimizes Sum of Squared Error in the sample
- Using  $\beta_0 = \mu$  minimizes the Sum of Squared Error in the population
- $\bar{Y}$  is unlikely to be (exactly) equal to  $\mu$ , so predictions  $\hat{Y} = \bar{Y}$  are unlikely to be best for new samples
- If we have a prior idea about the value of  $\beta_0$ , would that lead to better predictions for future data?



# To estimate or not to estimate...

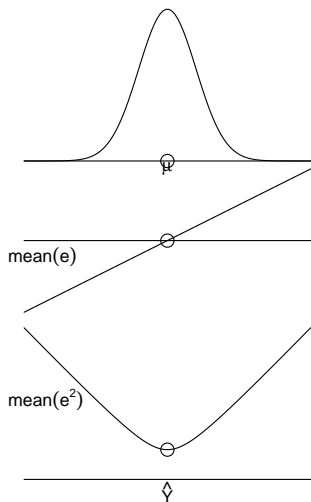
- If  $\beta_0 = 0$ , we should predict (future) priming effects as 0
- If  $\beta_0 \neq 0$ , we'd probably be better off using an estimated  $\beta_0$  for future predictions
- Using  $\hat{\beta}_0 = b_0 = \bar{Y}$  minimizes Sum of Squared Error in the sample
- Using  $\beta_0 = \mu$  minimizes the Sum of Squared Error in the population
- $\bar{Y}$  is unlikely to be (exactly) equal to  $\mu$ , so predictions  $\hat{Y} = \bar{Y}$  are unlikely to be best for new samples
- If we have a prior idea about the value of  $\beta_0$ , would that lead to better predictions for future data?





# To estimate or not to estimate...

- If  $\beta_0 = 0$ , we should predict (future) priming effects as 0
- If  $\beta_0 \neq 0$ , we'd probably be better off using an estimated  $\beta_0$  for future predictions
- Using  $\hat{\beta}_0 = b_0 = \bar{Y}$  minimizes Sum of Squared Error in the sample
- Using  $\beta_0 = \mu$  minimizes the Sum of Squared Error in the population
- $\bar{Y}$  is unlikely to be (exactly) equal to  $\mu$ , so predictions  $\hat{Y} = \bar{Y}$  are unlikely to be best for new samples
- If we have a prior idea about the value of  $\beta_0$ , would that lead to better predictions for future data?



# Back to the future

- Population model

$$Y_i = \beta_0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

- Two hypotheses:

$$H_0 : \beta_0 = 0$$

$$H_a : \beta_0 \neq 0$$

- Two models:

$$\text{MODEL C : } Y_i = 0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A : } Y_i = \beta_0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

# Back to the future

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

- MODEL C (compact) is contained in (nested under) MODEL A (augmented)
  - The value 0 in MODEL C is one of the many possible values of  $\beta_0$  in MODEL A
- Should we use MODEL C or MODEL A?
  - Compare the prediction error of MODEL C with the prediction error of MODEL A
  - When  $\beta_0$  is estimated to minimize sample error, the sample error of MODEL A can never be higher than the sample error of MODEL C
  - We shouldn't just pick the model with the lowest sample error; we want to minimize the error in the population!

# Back to the future

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

- MODEL C (compact) is contained in (nested under) MODEL A (augmented)
  - The value 0 in MODEL C is one of the many possible values of  $\beta_0$  in MODEL A
- Should we use MODEL C or MODEL A?
  - Compare the prediction error of MODEL C with the prediction error of MODEL A
  - When  $\beta_0$  is estimated to minimize sample error, the sample error of MODEL A can never be higher than the sample error of MODEL C
  - We shouldn't just pick the model with the lowest sample error; we want to minimize the error in the population!

# Back to the future

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

- MODEL C (compact) is contained in (nested under) MODEL A (augmented)
  - The value 0 in MODEL C is one of the many possible values of  $\beta_0$  in MODEL A
- Should we use MODEL C or MODEL A?
  - Compare the prediction error of MODEL C with the prediction error of MODEL A
  - When  $\beta_0$  is estimated to minimize sample error, the sample error of MODEL A can never be higher than the sample error of MODEL C
  - We shouldn't just pick the model with the lowest sample error; we want to minimize the error in the population!

# Back to the future

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

- MODEL C (compact) is contained in (nested under) MODEL A (augmented)
  - The value 0 in MODEL C is one of the many possible values of  $\beta_0$  in MODEL A
- Should we use MODEL C or MODEL A?
  - Compare the prediction error of MODEL C with the prediction error of MODEL A
  - When  $\beta_0$  is estimated to minimize sample error, the sample error of MODEL A can never be higher than the sample error of MODEL C
  - We shouldn't just pick the model with the lowest sample error; we want to minimize the error in the population!

# Back to the future

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

- MODEL C (compact) is contained in (nested under) MODEL A (augmented)
  - The value 0 in MODEL C is one of the many possible values of  $\beta_0$  in MODEL A
- Should we use MODEL C or MODEL A?
  - Compare the prediction error of MODEL C with the prediction error of MODEL A
  - When  $\beta_0$  is estimated to minimize sample error, the sample error of MODEL A can never be higher than the sample error of MODEL C
  - We shouldn't just pick the model with the lowest sample error; we want to minimize the error in the population!

# What is a substantial reduction in error?

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

- We know that

$$\text{SSE(C)} \geq \text{SSE(A)}$$

(the Sum of Squared Errors of MODEL C is at least as large as that for MODEL A). But is the difference substantial?

- If MODEL C is correct, then

$$F = \frac{\text{SSE(C)} - \text{SSE(A)}}{\text{SSE(A)} / (n - 1)} = \frac{\text{SSR}}{\text{MSE(A)}}$$

follows an  $F$  distribution with parameters  $\text{df}_1 = 1$  and  $\text{df}_2 = n - 1$



# What is a substantial reduction in error?

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

- We know that

$$\text{SSE(C)} \geq \text{SSE(A)}$$

(the Sum of Squared Errors of MODEL C is at least as large as that for MODEL A). But is the difference substantial?

- If MODEL C is correct, then

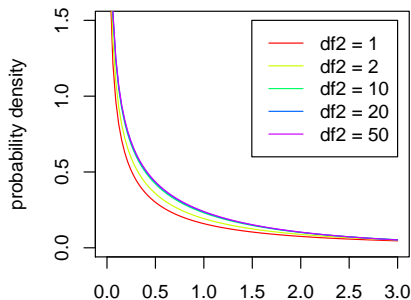
$$F = \frac{\text{SSE(C)} - \text{SSE(A)}}{\text{SSE(A)} / (n - 1)} = \frac{\text{SSR}}{\text{MSE(A)}}$$

follows an  $F$  distribution with parameters  $\text{df}_1 = 1$  and  $\text{df}_2 = n - 1$

# The $F$ distribution

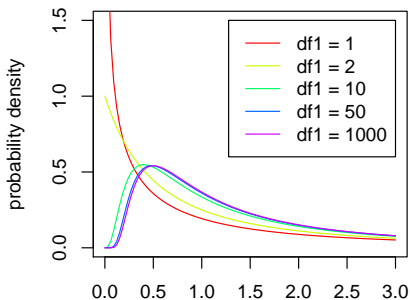
- $F \geq 0$  (an  $F$  value is never negative!)
- Two parameters,  $df_1$  and  $df_2$
- Mean:  $\frac{df_2}{df_2 - 2}$  (for  $df_2 > 2$ )

**df1 = 1**



F

**df2 = 2**



F

# Back to the future 2

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

## Back to the future 2

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

Estimated MODEL A:

$$\begin{aligned} Y_i &= b_0 + e_i \\ &= 15.58 + e_i \end{aligned}$$

## Back to the future 2

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

Estimated MODEL A:

$$\begin{aligned} Y_i &= b_0 + e_i \\ &= 15.58 + e_i \end{aligned}$$

$$\text{SSE(A)} = 782,596.6$$

$$\text{SSE(C)} = 805,900.1$$

## Back to the future 2

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \qquad \epsilon_i \sim N(0, \sigma)$$

Estimated MODEL A:

$$\begin{aligned} Y_i &= b_0 + e_i \\ &= 15.58 + e_i \end{aligned}$$

$$\text{SSE(A)} = 782,596.6$$

$$\text{SSE(C)} = 805,900.1$$

$$F = \frac{805,900.1 - 782,596.6}{782,596.6 / (96 - 1)} = 2.829$$

# Back to the future 2

$$\text{MODEL C: } Y_i = 0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

$$\text{MODEL A: } Y_i = \beta_0 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

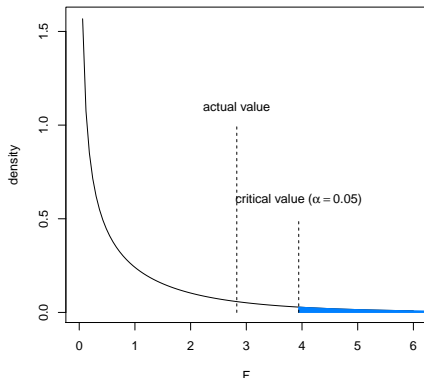
Estimated MODEL A:

$$\begin{aligned} Y_i &= b_0 + e_i \\ &= 15.58 + e_i \end{aligned}$$

$$\text{SSE(A)} = 782,596.6$$

$$\text{SSE(C)} = 805,900.1$$

$$F = \frac{805,900.1 - 782,596.6}{782,596.6 / (96 - 1)} = 2.829$$



# Proportional Reduction in Error

- While useful for hypothesis testing, the  $F$  statistic is not so easy to interpret
- A useful measure for **effect size** is the Proportional Reduction in Error (PRE)

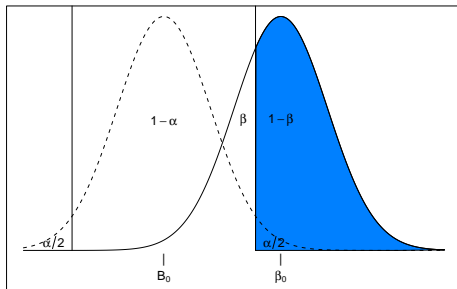
$$\text{PRE} = \frac{\text{SSE}(C) - \text{SSE}(A)}{\text{SSE}(C)}$$

- The PRE has a value between 0 (useless) and 1 (extremely good)
- As with most things in statistics, we have to distinguish between the sample and population value of the PRE. The population value of the PRE is usually denoted as  $\eta^2$  (eta-squared)
- For this data,  $\text{PRE} = (805,900.1 - 782,596.6)/805,900.1 = .0289$

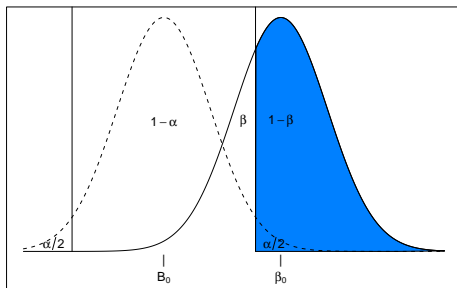


# Power

- Remember: we have only fixed the probability of falsely rejecting the null hypothesis (Type I error)
- Because we don't know  $\beta_0$ , we don't know the probability of falsely accepting the null hypothesis (Type II error)
- If the difference between  $\beta_0$  and  $B_0$  is small, the probability of correctly rejecting the null hypothesis (power) may be very small indeed



# Estimating power



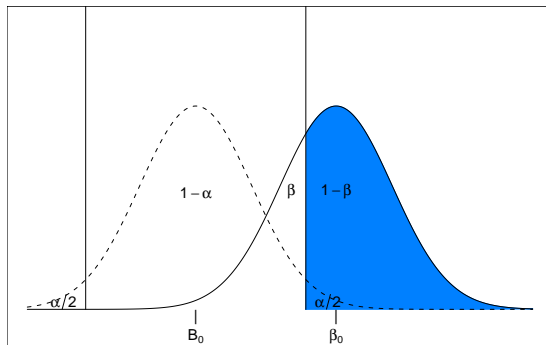
A priori power calculation:

- Computed using more or less sensible (a priori) values for PRE.

A posteriori power calculation:

- Some (including SPSS) estimate  $1 - \beta$  assuming estimated MODEL A is the true population model. They call this “observed power”. This is not a great idea. . .

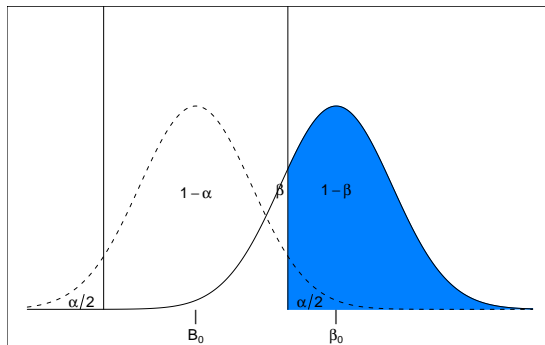
# Improving power



Before

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$

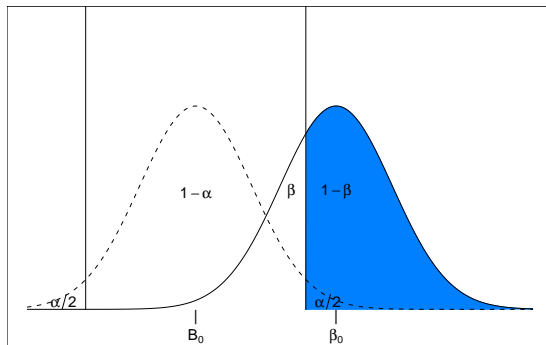
# Improving power



After

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$

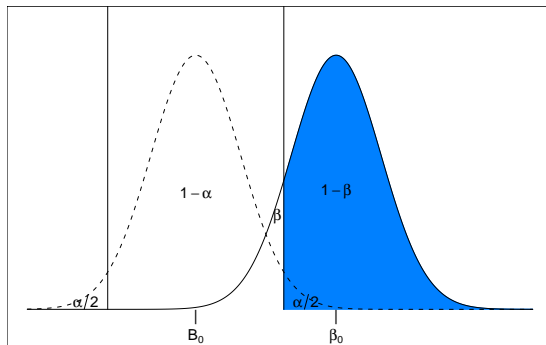
# Improving power



Before

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$

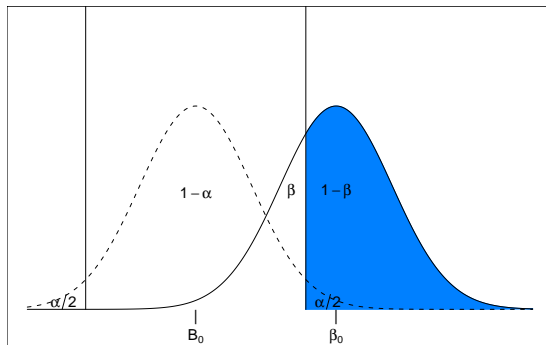
# Improving power



After

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$

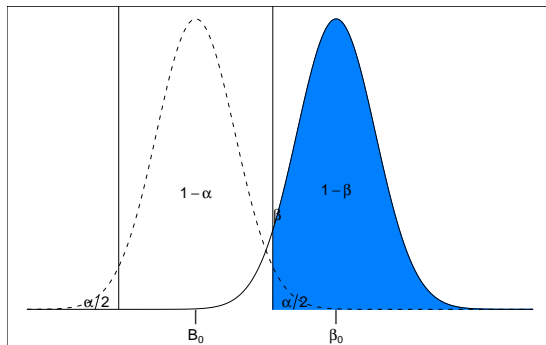
# Improving power



Before

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$

# Improving power

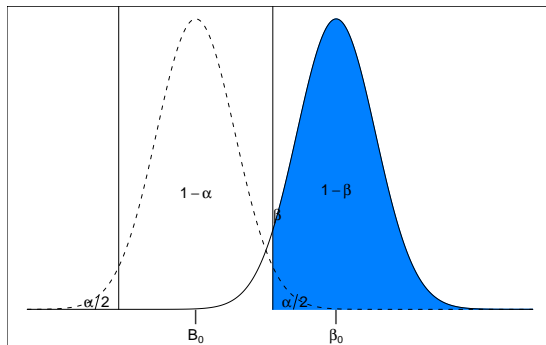


After

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$



# Improving power



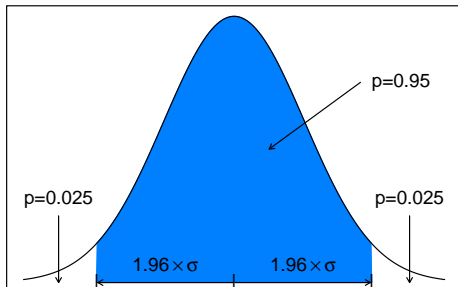
After

- Increasing  $\alpha$
- Decreasing error
- Increasing  $n$

Decreasing error and increasing  $n$  both decrease the variance of the sampling distribution

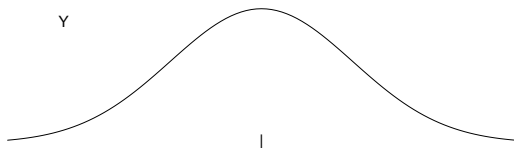
# Confidence intervals

- An interval such that the probability that a value lies outside the interval has a predefined probability
  - e.g.,  $p = 0.95$  (or 95%) confidence interval
- For a Normal distribution, the width of a 95% confidence interval is approx.  $3.92 \times \sigma$



- A confidence interval is computed from a sample, so has a *sampling distribution*

# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

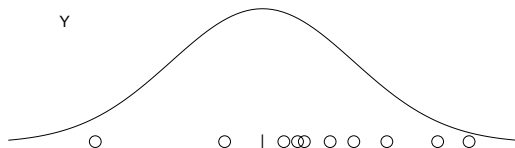
$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- 
- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

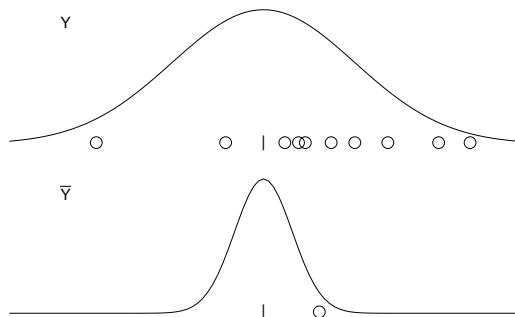
$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- 
- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

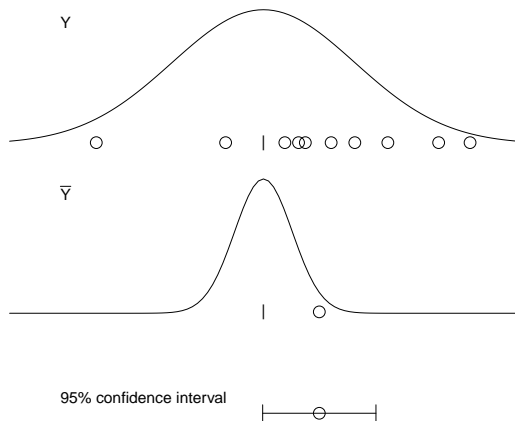
$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- 
- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

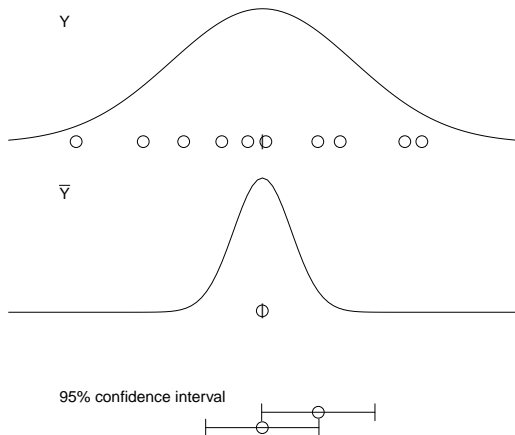
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$



- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

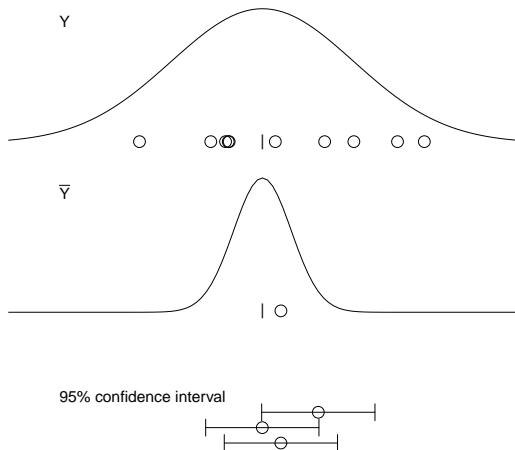
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

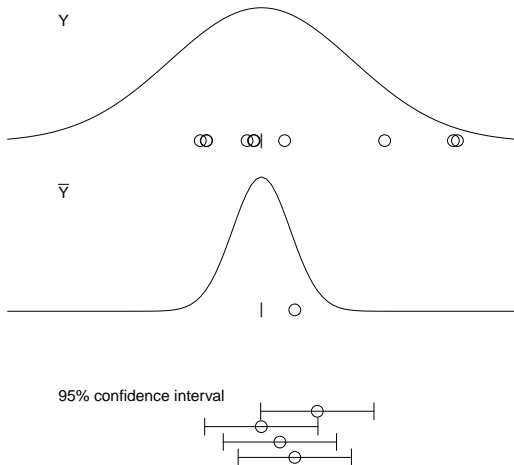
$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- And again...

- Oops... population mean outside interval



# Confidence intervals ( $\sigma$ known)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

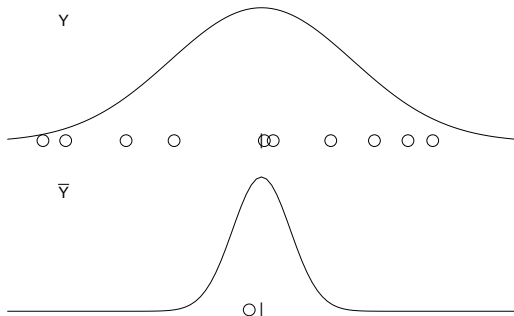
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

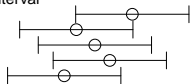
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

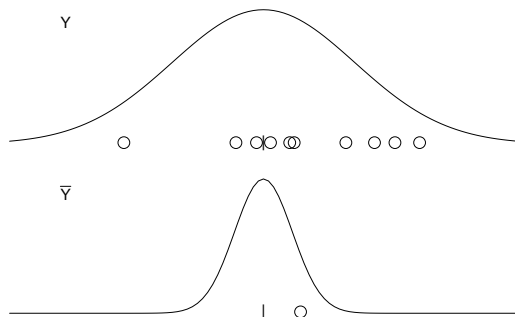
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

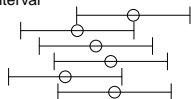
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

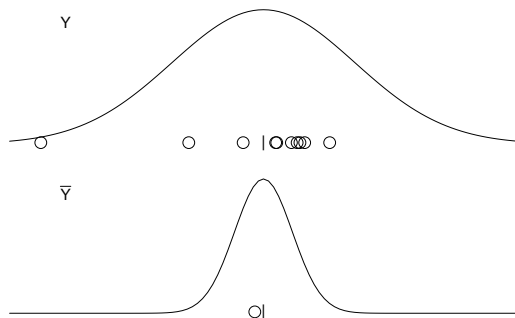
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

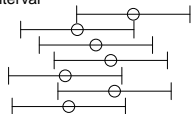
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

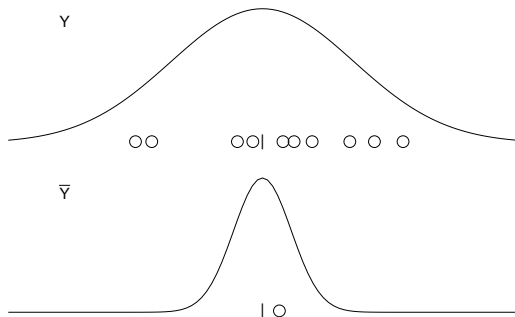
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

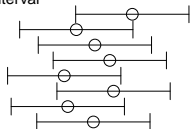
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

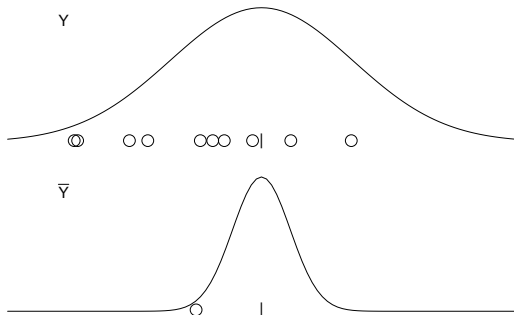
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

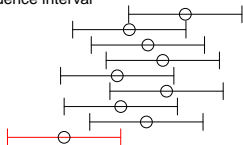
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

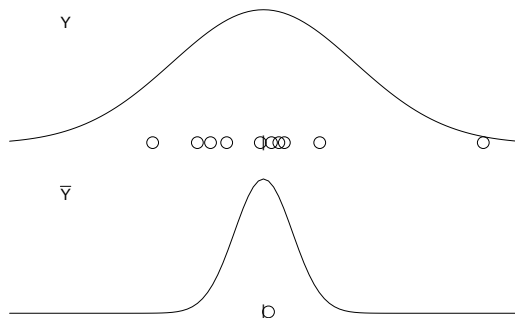
$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

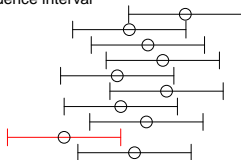
$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- And again...
- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

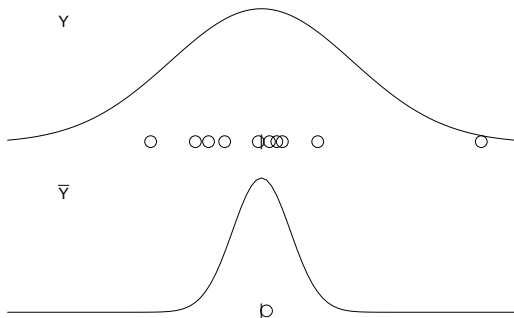
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

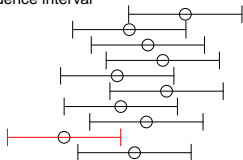
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ known)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

Sampling distribution

$$\bar{Y} \sim N\left(\mu, \frac{\sigma}{\sqrt{n}}\right)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm 1.96 \times \frac{\sigma}{\sqrt{n}}$$

- After infinite repetitions, 95% of the confidence intervals contain population mean



# Computation

- Based on the sampling distribution of a parameter. In previous example,  $\sigma$  (population S.D.) was assumed known. If we have to estimate  $\sigma$  from sample data, we should take the resulting error into account in the confidence intervals.
- To estimate  $\sigma$ , we use the unbiased estimator of the population variance (note that  $p = 1$  here)

$$\hat{\sigma}^2 = \text{MSE} = \frac{\text{SSE}}{n-p} = \frac{\sum_{i=1}^n (Y_i - \hat{Y}_i)^2}{n-p}$$

- Confidence interval for sample mean with estimated standard deviation  $\hat{\sigma} = \sqrt{\text{MSE}}$ :

$$\bar{Y} \pm t_{n-1; \alpha/2} \frac{\sqrt{\text{MSE}}}{\sqrt{n}}$$

$t_{n-1; \alpha/2}$  is critical value of  $t$  when  $\text{df} = n - 1$ , and significance is  $\alpha$  (e.g.,  $\alpha = .05$  for a 95% confidence interval).

# Computation

- Based on the sampling distribution of a parameter. In previous example,  $\sigma$  (population S.D.) was assumed known. If we have to estimate  $\sigma$  from sample data, we should take the resulting error into account in the confidence intervals.
- To estimate  $\sigma$ , we use the unbiased estimator of the population variance (note that  $p = 1$  here)

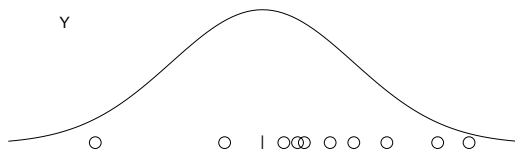
$$\hat{\sigma}^2 = \text{MSE} = \frac{\text{SSE}}{n-p} = \frac{\sum_{i=1}^n (Y_i - \hat{Y}_i)^2}{n-p}$$

- Confidence interval for sample mean with estimated standard deviation  $\hat{\sigma} = \sqrt{\text{MSE}}$ :

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \frac{\sqrt{\text{MSE}}}{\sqrt{n}}$$

$F_{1,n-1;\alpha}$  is critical value of  $F$  when  $\text{df}_1 = 1$ ,  $\text{df}_2 = n - 1$ , and significance is  $\alpha$  (e.g.,  $\alpha = .05$  for a 95% confidence interval).

# Confidence intervals ( $\sigma$ unknown)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Take a sample

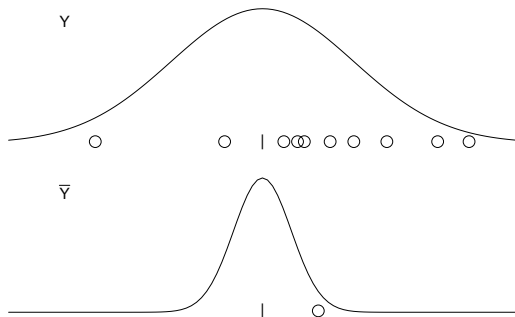
- Compute mean  $\bar{Y}$

- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- 
- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Take a sample

- Compute mean  $\bar{Y}$

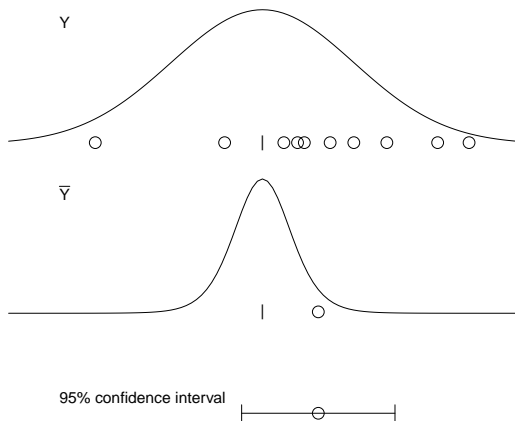
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



- Population distribution

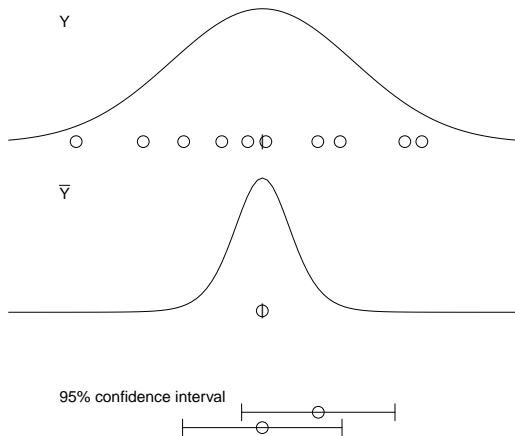
$$Y \sim N(\mu, \sigma)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- And again...
- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

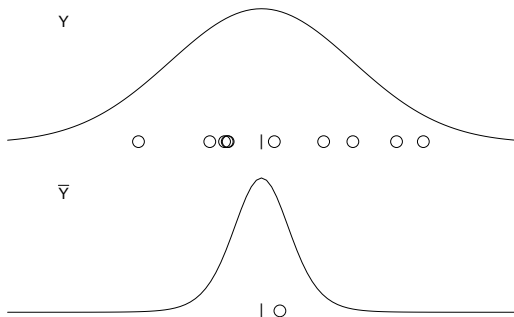
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

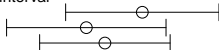
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

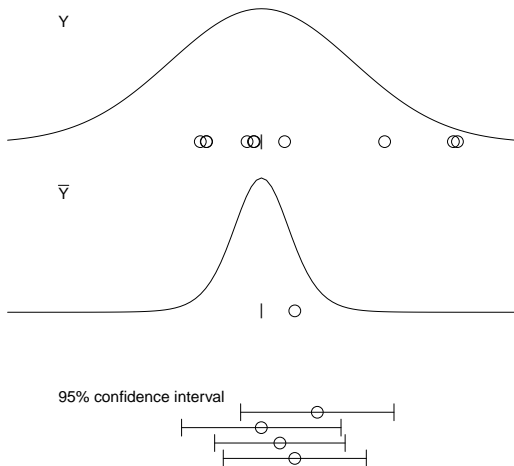
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

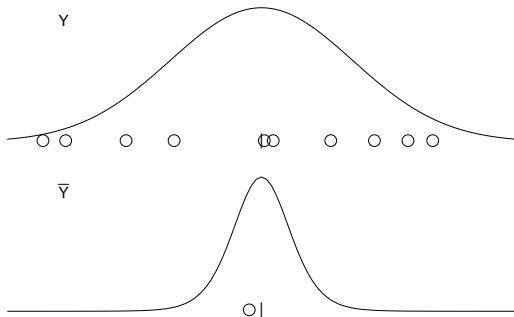
$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- And again...

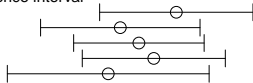
- Oops... population mean outside interval



# Confidence intervals ( $\sigma$ unknown)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

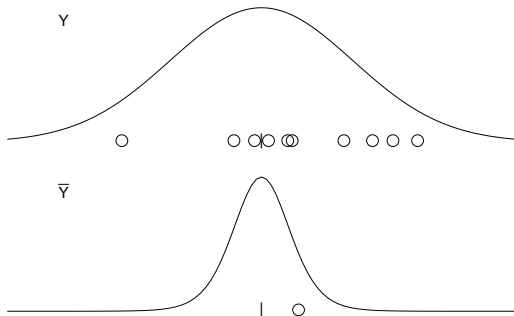
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

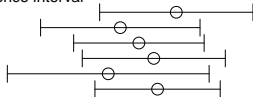
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

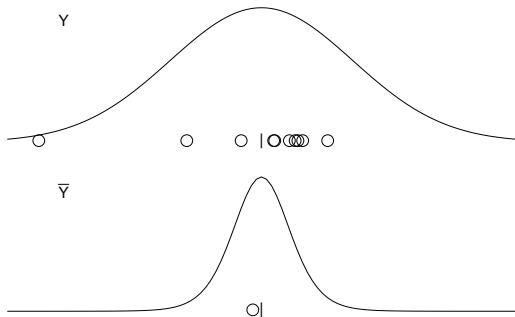
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

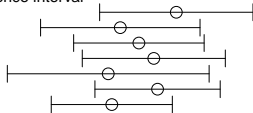
- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

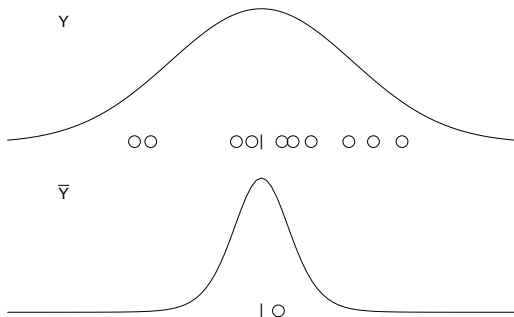
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- And again...

- Oops... population mean outside interval

# Confidence intervals ( $\sigma$ unknown)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

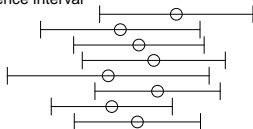
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

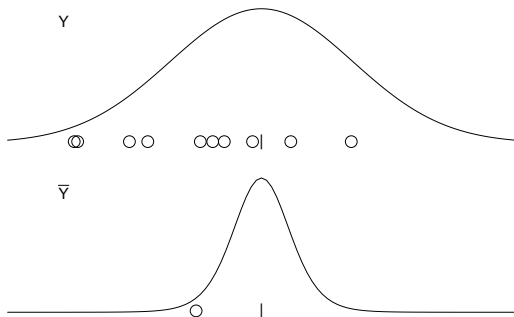
- And again...

- Oops... population mean outside interval

95% confidence interval



# Confidence intervals ( $\sigma$ unknown)



- Population distribution

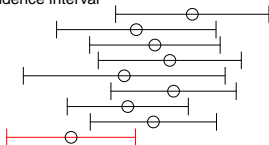
$$Y \sim N(\mu, \sigma)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

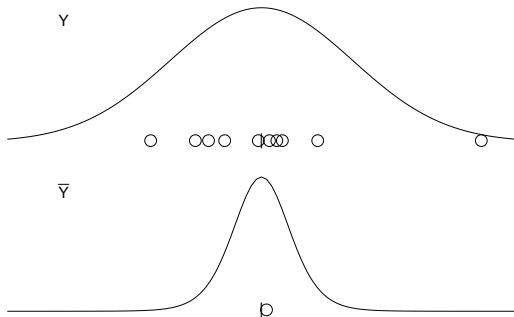
$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- And again...
- Oops... population mean outside interval

95% confidence interval



# Confidence intervals ( $\sigma$ unknown)



- Population distribution

$$Y \sim N(\mu, \sigma)$$

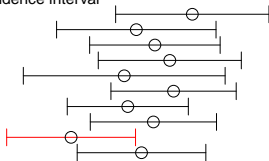
- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

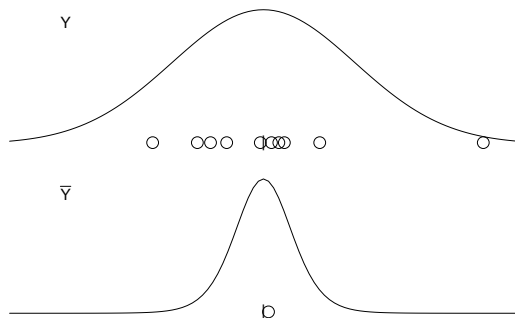
- And again...

- Oops... population mean outside interval

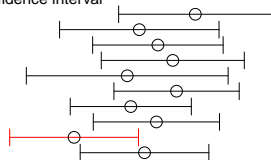
95% confidence interval



# Confidence intervals ( $\sigma$ unknown)



95% confidence interval



- Population distribution

$$Y \sim N(\mu, \sigma)$$

- Take a sample
- Compute mean  $\bar{Y}$
- Confidence interval

$$\bar{Y} \pm \sqrt{F_{1,n-1;\alpha}} \times \frac{\sqrt{MSE}}{\sqrt{n}}$$

- After infinite repetitions, 95% of the confidence intervals contain population mean
- Oops... population mean outside interval

# Interpretation and usage

- Correct interpretation
  - if we take infinite samples from the population and compute the  $x\%$  (or  $1 - \alpha$ ) confidence interval, then the true parameter lies within  $x\%$  of those confidence intervals (which differ from sample to sample)
- Equivalent information to hypothesis test, e.g.
  - if  $B_0$  does not lie in  $1 - \alpha$  confidence interval for  $\beta_0$ , this implies that MODEL C will be rejected in favour of MODEL A in a hypothesis test with a significance level of  $\alpha$ .



# Summary of key points

- Null hypothesis significance testing is about making decisions:
  - Should I accept or reject the null hypothesis  $H_0$ ?
  - Based on a sampling distribution of a statistic of interest (e.g., sample mean), assuming  $H_0$  is true.
  - Can't work out sampling distribution under the alternative hypothesis  $H_a$ , because it is usually too vague
- In the General Linear Model framework, hypothesis testing is a decision between estimating or fixing parameters. We base this decision on the comparison of two models:
  - A general (augmented) MODEL A in which parameters are estimated
  - A constrained (compact) MODEL C which fixes some of these parameters
  - If the error of the MODEL A is substantially smaller than the error of MODEL C, we decide to estimate and use MODEL A for our predictions
  - Error comparison based on the  $F$ -test
- Confidence intervals can provide same information as significance tests

## Look ahead

The model comparison framework used today is general. Take MODEL A

$$Y_i = \beta_0 + \beta_1 \times X_{1i} + \dots + \beta_{p-1} \times X_{p-1,i} + \epsilon_i \quad \epsilon_i \sim N(0, \sigma)$$

and create MODEL C by fixing certain parameters  $\beta_j$  to a priori values  $B_j$ .

Decide whether to accept or reject these a priori values with an  $F$ -test:

$$\begin{aligned} F &= \frac{(\text{SSE}(\text{C}) - \text{SSE}(\text{A})) / (\text{PA} - \text{PC})}{\text{SSE}(\text{A}) / (n - \text{PA})} \\ &= \frac{\text{MSR}}{\text{MSE}(\text{A})} \end{aligned}$$

where PA is the number of estimated parameters in MODEL A, and PC the number of estimated parameters in MODEL C

# Further reading

This lecture:

- Judd, McClelland & Ryan, chapter 4

Next lecture:

- Judd, McClelland & Ryan, chapters 5 & 6