Homework 2: Classification and Bias-Variance Trade-offs

Introduction

This homework is about classification and bias-variance trade-offs. In lecture we have primarily focused on binary classifiers trained to discriminate between two classes. In multiclass classification, we discriminate between three or more classes. Most of the material for Problem 1 and Problem 3, and all of the material for Problem 2 will be covered by the end of the Tuesday 2/8 lecture. The rest of the material will be covered by the end of the Thursday 2/10 lecture. We encourage you to read CS181 Textbook's Chapter 3 for more information on linear classification, gradient descent, classification in the discriminative setting (covers multiclass logistic regression and softmax), and classification in the generative setting. Read Chapter 2.8 for more information on the trade-offs between bias and variance.

As a general note, for classification problems we imagine that we have the input matrix $\mathbf{X} \in \mathbb{R}^{N \times D}$ (or perhaps they have been mapped to some basis $\mathbf{\Phi}$, without loss of generality) with outputs now "one-hot encoded." This means that if there are K output classes, rather than representing the output label y as an integer $1, 2, \ldots, K$, we represent \mathbf{y} as a "one-hot" vector of length K. A "one-hot" vector is defined as having every component equal to 0 except for a single component which has value equal to 1. For example, if there are K = 7 classes and a particular data point belongs to class 3, then the target vector for this data point would be $\mathbf{y} = [0, 0, 1, 0, 0, 0, 0, 0]$. We will define C_1 to be the one-hot vector for the 1st class, C_2 for the 2nd class, etc. Thus, in the previous example $\mathbf{y} = C_3$. If there are K total classes, then the set of possible labels is $\{C_1 \ldots C_K\} = \{C_k\}_{k=1}^K$. Throughout the assignment we will assume that each label $\mathbf{y} \in \{C_k\}_{k=1}^K$ unless otherwise specified. The most common exception is the case of binary classification (K = 2), in which case labels are the typical integers $y \in \{0,1\}$.

In problems 1 and 3, you may use numpy or scipy, but not scipy.optimize or sklearn. Example code given is in Python 3.

Please type your solutions after the corresponding problems using this LATEX template, and start each problem on a new page.

Please submit the writeup PDF to the Gradescope assignment 'HW2'. Remember to assign pages for each question. You must include your plots in your writeup PDF. The supplemental files will only be checked in special cases, e.g. honor code issues, etc.

Please submit your LATEX file and code files to the Gradescope assignment 'HW2 - Supplemental'.

Problem 1 (Exploring Bias and Variance, 10 pts)

In this problem, we will explore the bias and variance of a few different model classes when it comes to logistic regression.

Consider the true data generating process $y \sim \text{Bern}(f(x)), f(x) = 0.4 \times \sin(1.2x) + 0.5$, where $x \in [-3, 3]$, and $y \in \{0, 1\}$. Recall that for a given x, bias and variance are defined in terms of expectations over randomly drawn datasets D from this underlying data distribution:

$$\operatorname{Bias}[\hat{f}(x)] = \mathbb{E}_D[\hat{f}(x)] - f(x)$$
$$\operatorname{Variance}[\hat{f}(x)] = \mathbb{E}_D[(\hat{f}(x) - \mathbb{E}_D[\hat{f}(x)])^2]$$

Here, $\hat{f}(x)$ is our estimator (learned through logistic regression on a given dataset D). We will directly explore the bias-variance trade-off by drawing multiple such datasets and fitting different logistic regression models to each. Remember that we, the modelers, do not usually see the true data distribution. Knowledge of the true f(x) is only exposed in this problem to (1) make possible the simulation of drawing multiple datasets, and (2) to serve as a pedagogical tool in allowing verification of the true bias.

1. Consider the three bases $\phi_1(x) = [1, x]$, $\phi_2(x) = [1, x, x^2]$, $\phi_3(x) = [1, x, x^2, x^3, x^4, x^5]$. For each of these bases, generate 10 datasets of size N = 30 using the starter code provided, and fit a logistic regression model using sigmoid($w^T\phi(x)$) to each dataset by using gradient descent to minimize the negative log likelihood. This means you will be running gradient descent 10 times for each basis, once for each dataset. Note that the classes are represented with 0's and 1's.

Use random starting values of w, $\eta = 0.001$, take 10,000 update steps for each gradient descent run, and make sure to average the gradient over the data points (for each step). These parameters, while not perfect, will ensure your code runs in a reasonable amount of time. The emphasis of this problem is on capturing the bias-variance trade-off, so don't worry about attaining perfect precision in the gradient descent as long as this trade-off is captured in the final models.

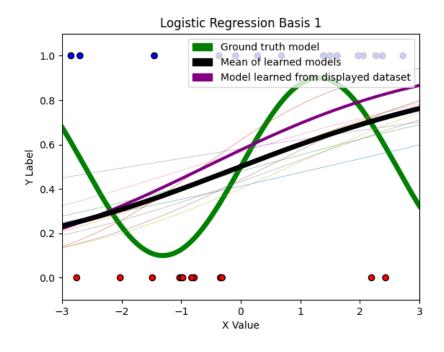
Note: Overflow RuntimeWarnings due to np.exp should be safe to ignore, if any. Also, to reduce stress from randomness in students' solutions (due to randomized weight initialization differences), in line 109 of the T2_P1.py starter code, we call np.random.seed(1738) to set a deterministic random seed. Please do not change this! In addition, please do not change the randomized weight initialization code in lines 42-46.

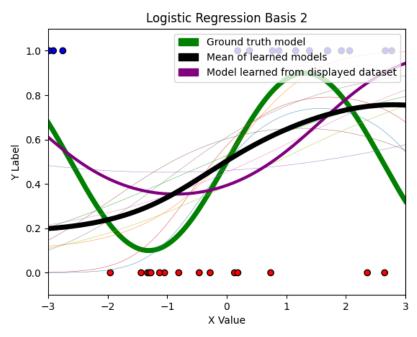
- 2. Create three plots, one for each basis. Starter code is available which you may modify. By default, each plot displays three types of functions: (1) the true data-generating distribution f(x) (the probability that y = 1 for different x). (2) all 10 of the prediction functions learned from each randomly drawn dataset, and (3) the mean of the 10 prediction functions. Moreover, each plot also displays 1 of the randomly generated datasets and highlights the corresponding prediction function learned by this dataset.
- 3. How are bias and variance reflected in the 3 types of curves on the graphs? How do the fits of the individual and mean prediction functions change? Keeping in mind that none of the model classes match the true generating process exactly, discuss the extent to which each of the bases approximates the true process.

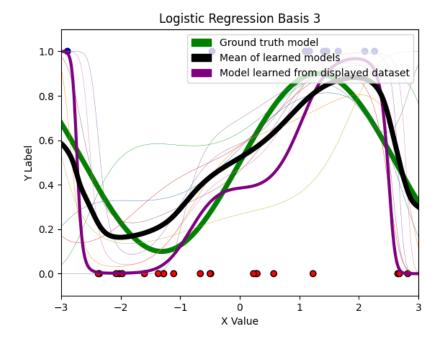
Note: In this problem, we are not interested in whether the model is more biased for certain inputs x compared to other inputs x'. We are interested in the overall bias and variance of $\hat{f}(x)$ across the different basis choices. In other words, we want to investigate how the bias between $\hat{f}(x)$ and the ground truth as well as the variance of $\hat{f}(x)$ will be different over different basis choices.

4. If we were to increase the size of each dataset drawn from N=30 to a larger number, how would the variance change? The bias? Why might this be the case?

Solution 1.2:







Solution 1.3:

Looking at the graph for each basis, it appears that going in increasing order of basis functions (basis 1, basis 2, basis 3), bias decreases while variance increases.

Looking at the graph corresponding basis 1, we see that the curve representing the mean of learned models is almost linear. With this basis, bias is very high as the models have little to no response towards variation in the data, leading the model to fit a generalized shape of the ground truth model. At the same time, variance in the models produced by this basis function are very low and all 10 models appear for the most part homogeneous. Overall, the models created by this basis function underfit the ground truth model.

Looking at the graph corresponding basis 2, we see that the curve representing the mean of learned models has a shape more similar to the ground truth model than basis 1. This can be attributed to reduced bias, as the learned models are more responsive to change in the data. At the same time, this leads to higher variance amongst learned models, as can be seen by the higher disparity between the mean of learned models and the model learned from the displayed dataset and between different learned models in general. Overall this basis function fits the ground truth model reasonably well and is a medium between basis 1 and basis 3 in terms of bias and variance.

Finally, looking at the graph for basis 3, we see that the curve representing the mean of learned models follows the ground truth model with fairly good accuracy. This is because of low bias, causing the learned models to be very responsive to the dataset. However, while this basis function generates models whose mean closely models the ground truth, there is the highest level of variance as the learned models respond very dramatically to the randomly drawn datasets from which they are trained. Overall, this leads this basis function to create models which overfit the model and may not generalize well to new data points.

Solution 1.4:

If we were to increase the size of each dataset drawn to a larger number, variance would definitely decrease. Variation between larger datasets would be on average lower as the overall trends of these datasets would more accurately represent the ground truth model. As such, the variance of generated models would decrease as datasets would be more similar. At the same time, bias would not change significantly but might decrease slightly in response to an increase in the size of each dataset. Bias appears to be affected more by the basis used than the size of the dataset drawn. For example, if we were to increase the size of the dataset used for Basis 1, we would not significantly decrease bias as the basis does not have a high enough dimensionality to model the ground truth in a highly specific manner. Potentially, in the case of Basis 3, with an increase of size in the dataset, the overall trend of the dataset would more closely resemble ground truth, allowing generated models to have lower bias.

Problem 2 (Maximum likelihood in classification, 15pts)

Consider now a generative K-class model. We adopt class prior $p(\mathbf{y} = C_k; \boldsymbol{\pi}) = \pi_k$ for all $k \in \{1, \dots, K\}$ (where π_k is a parameter of the prior). Let $p(\mathbf{x}|\mathbf{y} = C_k)$ denote the class-conditional density of features \mathbf{x} (in this case for class C_k). Consider the data set $D = \{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^n$ where as above $\mathbf{y}_i \in \{C_k\}_{k=1}^K$ is encoded as a one-hot target vector and the data are independent.

- 1. Write out the log-likelihood of the data set, $\ln p(D; \pi)$.
- 2. Since the prior forms a distribution, it has the constraint that $\sum_k \pi_k 1 = 0$. Using the hint on Lagrange multipliers below, give the expression for the maximum-likelihood estimator for the prior class-membership probabilities, i.e. $\hat{\pi}_k$. Make sure to write out the intermediary equation you need to solve to obtain this estimator. Briefly state why your final answer is intuitive.

For the remaining questions, let the class-conditional probabilities be Gaussian distributions with the same covariance matrix

$$p(\mathbf{x}|\mathbf{y} = C_k) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}), \text{ for } k \in \{1, \dots, K\}$$

and different means μ_k for each class.

- 3. Derive the gradient of the log-likelihood with respect to vector μ_k . Write the expression in matrix form as a function of the variables defined throughout this exercise. Simplify as much as possible for full credit.
- 4. Derive the maximum-likelihood estimator $\hat{\mu}_k$ for vector $\boldsymbol{\mu}_k$. Briefly state why your final answer is intuitive.
- 5. Derive the gradient for the log-likelihood with respect to the covariance matrix Σ (i.e., looking to find an MLE for the covariance). Since you are differentiating with respect to a *matrix*, the resulting expression should be a matrix!
- 6. Derive the maximum likelihood estimator $\hat{\Sigma}$ of the covariance matrix.

Hint: Lagrange Multipliers. Lagrange Multipliers are a method for optimizing a function f with respect to an equality constraint, i.e.

$$\min_{\mathbf{x}} f(\mathbf{x}) \text{ s.t. } g(\mathbf{x}) = 0.$$

This can be turned into an unconstrained problem by introducing a Lagrange multiplier λ and constructing the Lagrangian function,

$$L(\mathbf{x}, \lambda) = f(\mathbf{x}) + \lambda g(\mathbf{x}).$$

It can be shown that it is a necessary condition that the optimum is a critical point of this new function. We can find this point by solving two equations:

$$\frac{\partial L(\mathbf{x}, \lambda)}{\partial \mathbf{x}} = 0$$
 and $\frac{\partial L(\mathbf{x}, \lambda)}{\partial \lambda} = 0$

Cookbook formulas. Here are some formulas you might want to consider using to compute difficult gradients. You can use them in the homework without proof. If you are looking to hone your matrix calculus skills, try to find different ways to prove these formulas yourself (will not be part of the evaluation of this homework). In general, you can use any formula from the matrix cookbook, as long as you cite it. We opt for the following common notation: $\mathbf{X}^{-\top} := (\mathbf{X}^{\top})^{-1}$

$$\begin{split} \frac{\partial \mathbf{a}^{\top} \mathbf{X}^{-1} \mathbf{b}}{\partial \mathbf{X}} &= -\mathbf{X}^{-\top} \mathbf{a} \mathbf{b}^{\top} \mathbf{X}^{-\top} \\ \frac{\partial \ln |\det(\mathbf{X})|}{\partial \mathbf{X}} &= \mathbf{X}^{-\top} \end{split}$$

Solution 2.1:

To give the expression for the log-likelihood of the data set, $\ln p(D;\pi)$, we first have the following:

$$p(D;\pi) = p(\{(x_i, y_i)\}_{i=1}^n; \pi) = \prod_{i=1}^n p(x_i, y_i; \pi) = \prod_{i=1}^n \prod_{k=1}^K (p(y_i = C_k; \pi) \cdot p(x_i | y_i = C_k))^{I_{y_i = C_k}}$$

where $I_{y_i=C_k}$ is the indicator random variable that $y_i=C_k$. Taking the natural log, we have:

$$\ln p(D; \pi) = \ln \left(\prod_{i=1}^{n} \prod_{k=1}^{K} (p(y_i = C_k; \pi) \cdot p(x_i | y_i = C_k))^{I_{y_i = C_k}} \right)$$

$$= \sum_{i=1}^{n} \sum_{k=1}^{K} I_{y_i = C_k} \ln(\pi_k \cdot p(x_i | y_i = C_j))$$

$$= \sum_{i=1}^{n} \sum_{k=1}^{K} I_{y_i = C_k} (\ln(\pi_k) + \ln(p(x_i | y_i = C_k)))$$

Solution 2.2:

To give the expression for the maximum-likelihood estimator for the prior class-membership probabilities, i.e. $\hat{\pi}_k$, we wish minimize the negative log likelihood of the data set:

$$-\sum_{i=1}^{n} \sum_{k=1}^{K} I_{y_i=C_k} \left(\ln(\pi_k) + \ln(p(x_i|y_i=C_k)) \right)$$

With the following constraint:

$$\sum_{k} \pi_k - 1 = 0$$

To do this, we can we can introduce a Lagrange multiplier λ and construct a Lagrangian function to transform this into an unconstrained problem:

$$L(\pi, \lambda) = -\sum_{i=1}^{n} \sum_{k=1}^{K} I_{y_i = C_k} \left(\ln(\pi_k) + \ln(p(x_i | y_i = C_j)) \right) + \lambda(\sum_k \pi_k - 1)$$

The optimum is a critical point of this function. As such, differentiating with respect to π_k we have:

$$-\sum_{i=1}^{N} \frac{I_{y_i = C_k}}{\pi_k} + \lambda = -\frac{1}{\pi_k} \sum_{n=1}^{N} I_{y_i = C_k} + \lambda$$

Next, we set the derivative equal to 0 and solving for π_k :

$$-\frac{1}{\pi_k} \sum_{i=1}^{N} I_{y_i = C_k} + \lambda = 0$$
$$\pi_k = \frac{\sum_{i=1}^{N} I_{y_i = C_k}}{\lambda}$$

Differentiating our Lagrangian function with respect to λ , we have:

$$\sum_{k} \pi_k - 1$$

Substituting π_k into this expression, setting it equal to 0, and solving for λ , we have:

$$\sum_{k} \pi_{k} - 1 = \sum_{k} \frac{\sum_{i=1}^{N} I_{y_{i} = C_{k}}}{\lambda} - 1 = 0$$

$$\lambda = \sum_{i=1}^{N} \sum_{k=1}^{K} I_{y_{i} = C_{k}}$$

Substituting λ back into our expression for π_k , we have:

$$\hat{\pi}_k = \frac{\sum_{i=1}^N I_{y_i = C_k}}{\lambda} = \frac{\sum_{i=1}^N I_{y_i = C_k}}{\sum_{i=1}^N \sum_{k=1}^K I_{y_i = C_k}} = \frac{N_k}{N_1 + \dots + N_K} = \frac{N_k}{N}$$

where N_k is the number of data points in the class C_k and N is the total number of data points. This result is intuitive as it means that the maximum likelihood solution for π_k is the fraction of data points in the data set that are within class C_k .

Solution 2.3:

Taking the expression for the log likelihood, we substitute the class-conditional densities with Gaussian conditional densities.

$$\ln p(D; \pi) = \sum_{i=1}^{n} \sum_{k=1}^{K} I_{y_i = C_k} \left(\ln(\pi_k) + \ln(p(x_i | y_i = C_k)) \right) = \sum_{i=1}^{n} \sum_{k=1}^{K} I_{y_i = C_k} \left(\ln(\pi_k) + \ln(\mathcal{N}(x_i | \mu_k, \Sigma)) \right)$$

When taking the gradient with respect to μ_k we may disregard any terms not involving μ_k , giving us:

$$\sum_{i=1}^{n} I_{y_i = C_k} \ln(\mathcal{N}(x_i | \mu_k, \Sigma)) = -\frac{1}{2} \sum_{i=1}^{n} I_{y_i = C_k} (x_i - \mu_k)^T \Sigma^{-1} (x_i - \mu_k) + c$$

Next, taking the gradient, we then have:

$$-\frac{1}{2}\sum_{i=1}^{N} -2I_{y_i=C_k}\Sigma^{-1}(x_i - \mu_k) = \sum_{i=1}^{N} I_{y_i=C_k}\Sigma^{-1}(x_i - \mu_k)$$

Solution 2.4:

Taking our gradient of the log-likelihood with respect to μ_k , to derive the maximum-likelihood estimator $\hat{\mu}_k$ for vector μ_k , we set our gradient to 0 and solve for μ_k :

$$\sum_{i=1}^{N} I_{y_i = C_k} \Sigma^{-1}(x_i - \mu_k) = 0$$

$$\sum_{i=1}^{N} I_{y_i = C_k}(x_i - \mu_k) = 0$$

$$\sum_{i=1}^{N} I_{y_i = C_k}(x_i) - \sum_{i=1}^{N} I_{y_i = C_k}(\mu_k) = 0$$

$$\sum_{i=1}^{N} I_{y_i = C_k}(x_i) = \sum_{i=1}^{N} I_{y_i = C_k}(\mu_k)$$

$$\mu_k = \frac{\sum_{i=1}^{N} I_{y_i = C_k}(x_i)}{\sum_{i=1}^{N} I_{y_i = C_k}}$$

$$\hat{\mu}_k = \frac{1}{N_k} \sum_{i=1}^{N} I_{y_i = C_k}(x_i)$$

where N_k is the number of data points in the class C_k . This result is intuitive as it means that the maximum likelihood solution for μ_k is the average of all the data points assigned to class C_k .

Solution 2.5:

When taking the gradient with respect to Σ we may disregard any terms not involving Σ , giving us:

$$-\frac{1}{2}\sum_{i=1}^{n}\sum_{k=1}^{K}I_{y_{i}=C_{k}}\ln|\Sigma| - \frac{1}{2}\sum_{i=1}^{n}\sum_{k=1}^{K}I_{y_{i}=C_{k}}(x_{i} - \mu_{k})^{T}\Sigma^{-1}(x_{i} - \mu_{k})$$

Making use of the "matrix cookbook formulas" we take the derivative with respect to Σ , giving us:

$$\frac{1}{2}N\Sigma^{-T} - \frac{1}{2}\sum_{i=1}^{n}\sum_{k=1}^{K}I_{y_i=C_k}\Sigma^{-T}(x_i - \mu_k)(x_i - \mu_k)^T\Sigma^{-T}$$

Solution 2.6:

Taking our gradient of the log-likelihood with respect to Σ , to derive the maximum-likelihood estimator $\hat{\Sigma}$ for the matrix Σ , we set our gradient to 0 and solve for Σ :

$$\frac{1}{2}N\Sigma^{-T} - \frac{1}{2}\sum_{i=1}^{n}\sum_{k=1}^{K}I_{y_i=C_k}\Sigma^{-T}(x_i - \mu_k)(x_i - \mu_k)^T\Sigma^{-T} = 0$$

$$\frac{1}{2}N\Sigma = \frac{1}{2}\sum_{i=1}^{n}\sum_{k=1}^{K}I_{y_i=C_k}(x_i - \mu_k)(x_i - \mu_k)^T$$

$$\Sigma = \frac{1}{N}\sum_{i=1}^{n}\sum_{k=1}^{K}I_{y_i=C_k}(x_i - \mu_k)(x_i - \mu_k)^T$$

This expression is intuitive as it gives that the maximum likelihood solution for the shared co-variance matrix is the weighted average of the all individual covariance matrices.

Problem 3 (Classifying Stars, 15pts)

You're tasked with classifying three different kinds of stars using their magnitudes and temperatures. See star.png for a plot of the data, adapted from http://astrosci.scimuze.com/stellar_data.htm and available as data/hr.csv, which you will find in the Github repository.

The CSV file has three columns: type, magnitude, and temperature. The first few lines look like this:

```
Type, Magnitude, Temperature
Dwarf, -5.8, -0.35
Dwarf, -4.1, -0.31
...
```

In this problem, you will code up 4 different classifiers for this task:

- a) A three-class generalization of logistic regression, also known as softmax regression, in which you implement gradient descent on the negative log-likelihood. In Question 2 you will explore the effect of using different values for the learning rate η (self.eta) and regularization strength λ (self.lam). Make sure to include a bias term and to use L2 regularization. See CS181 Textbook's Chapter 3.6 for details on multi-class logistic regression and softmax. For your implementation, use the loss and gradient expressions provided there.
- b) A generative classifier with Gaussian class-conditional densities with a *shared covariance* matrix across all classes. Feel free to re-use your Problem 2 results.
- c) Another generative classifier with Gaussian class-conditional densities, but now with a *separate covariance* matrix learned for each class. (Note: The staff implementation can switch between the two Gaussian generative classifiers with just a few lines of code.)
- d) **A kNN classifier** in which you classify based on the k=1,3,5 nearest neighbors and the following distance function:

$$dist(star_1, star_2) = ((mag_1 - mag_2)/3)^2 + (temp_1 - temp_2)^2$$

where nearest neighbors are those with the smallest distances from a given point.

Note 1: When there are more than two labels, no label may have the majority of neighbors. Use the label that has the most votes among the neighbors as the choice of label.

Note 2: The grid of points for which you are making predictions should be interpreted as our test space. Thus, it is not necessary to make a test point that happens to be on top of a training point ignore itself when selecting neighbors.

After implementing the above classifiers, complete the following exercises:

- 1. Plot the decision boundaries generated by each classifier for the dataset. Include them in your PDF. Identify the similarities and differences among the classifiers. What explains the differences?
- 2. For logistic regression only, make a plot with "Number of Iterations" on the x-axis and "Negative Log-Likelihood Loss" on the y-axis for several configurations of the hyperparameters η and λ . Specifically, try the values 0.05, 0.01, and 0.001 for each hyperparameter. Limit the number of gradient descent iterations to 200,000. What are your final choices of learning rate (η) and regularization strength (λ), and why are they reasonable? How does altering these hyperparameters affect the ability to converge, the rate of convergence, and the final loss (a qualitative description is sufficient)? You only need to submit one plot for your final choices of hyperparameters.

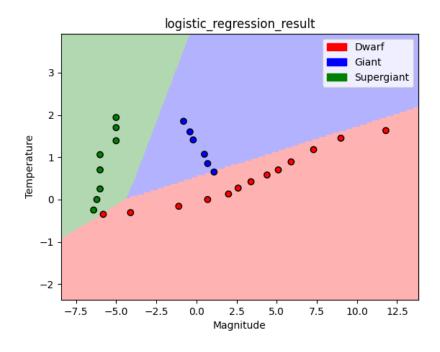
Note: The *likelihood* of the model is the probability of data given the model—it should not include the regularization term. The *objective* is the combination of the likelihood and the regularizer.

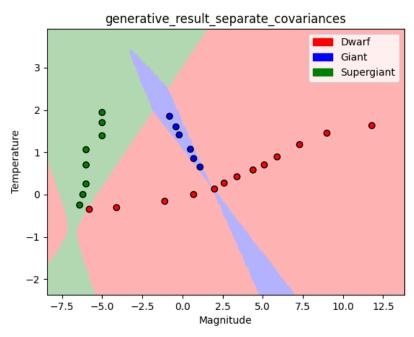
- 3. For both Gaussian generative models, report the negative log-likelihood loss. Which model has a lower loss, and why? For the separate covariance model, be sure to use the covariance matrix that matches the true class of each data point.
- 4. Consider a star with Magnitude 6 and Temperature 2. To what class does each classifier assign this star? Do the classifiers give any indication as to whether or not you should trust them?

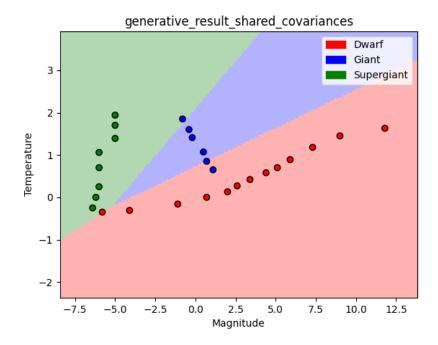
Problem 3 (cont.)

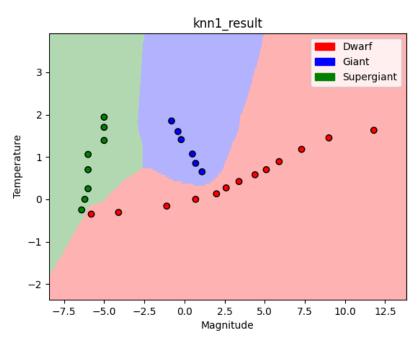
Implementation notes: Run the controller file, T2_P3.py, to test your code. Write the actual implementations in the GaussianGenerativeModel, LogisticRegression, and KNNModel classes, which are defined in the three T2_P3_ModelName.py files. These classes follow the same interface pattern as sklearn. Their code currently outputs nonsense predictions just to show the high-level interface, so you should replace their predict() implementations. You'll also need to modify the hyperparameter values in T2_P3.py for logistic regression.

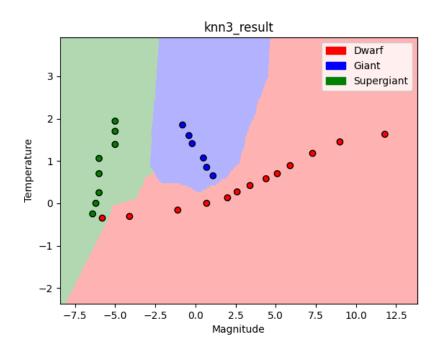
Solution 3.1:

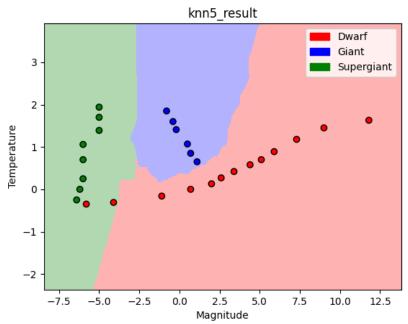












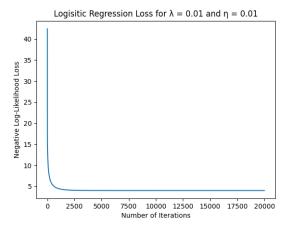
Of the classifiers, we observe that the logistic regression and Gaussian generative models with shared covariance classify similarly and have the most simple linear decision boundaries. The Gaussian generative model with separate covariances classifies in a distinct manner from all other classifiers and has more complicated and unique decision boundaries. The kNN classifiers have decision boundaries that loosely resemble those of the logistical regression and Gaussian generative models but have jagged-nonlinear decision boundaries.

The differences between these classifiers can be explained by the different implementations of each classifier.

The logistic regression and Gaussian generative models with shared covariance are the most simplified/generalized classifiers and thus have the most simple decision boundaries. The logistic regression classifier utilizes regularization to simplify regression lines while the Gaussian generative model uses a shared covariance for for the Gaussian class-conditional densities of all data points. By comparison, the Gaussian generative model with separate covariance has more complex decision boundaries as each class has its own covariance matrix for the Gaussian class-conditional densities.

The jagged decision boundaries of the kNN classifiers make sense as classification relies on proximal training data points, whose positions are distributed in a sporadic nonlinear manner. As the value of k increases, we see these classifiers start to misclassify at the boundary between Dwarf and Supergiant (k = 3, k = 5). This is due to the influence of more points in classification. Since there are more Supergiant training data points close to the boundary than there are Dwarf training data points, as k increases, classification at this boundary is skewed more and more towards the Supergiant class.

Solution 3.2:



My choices for learning rate and regularization strength were $\eta = 0.01$ and $\lambda = 0.01$. These choices were reasonable as they helped minimize the loss of our model in the least number of iterations across all other choices.

Increasing the learning rate caused too large a step size, leading the gradient descent algorithm to continually overshoot the ideal update of our parameters by taking too large a step in the opposite direction of the gradient, making it near impossible to converge and resulting in high loss. On the flip side, decreasing the learning rate caused too small of a step size that we were not making significant enough updates to our parameters through each to actually improve the model, meaning the rate of convergence was very slow and also resulting in more loss.

For the regularization strength, using too large of a strength leads our model to become unresponsive to data, incurring high bias and leading to higher loss. On the other hand, using too low of a strength leads to higher variation where the model overfits the data and does not generalize well, leading to higher loss on data outside the training set.

Solution 3.3:

For negative log-likelihood of the model with separate covariance I had 64.173 while for the model with shared covariance, I had 116.572. The model with separate covariance has lower loss. This is because the model uses a different covariance matrix for each class, allowing it to fit a matrix with lower covariances to classes with data that is less spread (Giand and Supergiant) while fitting a matrix of higher covariances to

classes with more spread out data points (Dwarf), leading it to incure less negative log-likelihood loss. On the other hand, the shared covariance model uses the same covariance on all classes and thus incurs more loss.

Solution 3.4:

This star was classified as a Dwarf by all classifiers except the logistic regression model and Gaussian generative model with shared covariance, which classified it as a Giant. This is likely because these two models have the most simplified linear decision boundaries. While there is not any data from the training set to compare the correctness of either classification, the classifiers with more complex decision boundaries seem to overfit the model and more skewed towards the training data, leading me to be more skeptical of their classifications. As such, I would be inclined to trust the more genarlized logistic regression model and Gaussian generative model with shared covariance classification.

Name

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Collaborators and Resources

Whom did you work with, and did you use any resources beyond cs181-textbook and your notes?

Calibration

Approximately how long did this homework take you to complete (in hours)?

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