

- ★ \hbar, G, k_B
- What is mechanics? • What is classical mechanics?
 - Why do we care about classical mechanics? • Is the universe quantum or classical?
 - Is classical mechanics "complete"? Has everything been discovered?
 - What are the main concepts of classical mechanics?
 - What are the formulations of classical mechanics?

There are "levels" of theory. For example, Newtonian gravitation and Coulomb's law are empirical laws. They describe how masses behave in the presence of other masses and charges in the presence of other charges, but their applicability is limited to masses and charges, respectively.

★ How would a "higher level" theory look like? Higher level of abstraction? More "fundamental"?

A higher level theory would tell you, e.g., the properties that empirical laws must have, rules that they must follow, the structure of the theory. The more fundamental a theory is, the more general the principles it is based on must be.

★ What is the most fundamental principle you can think of?

Conservation laws (and some definitions)

8/24/21 (2)

HG Eq. 1.3

Consider Newton's Second law $\vec{F} = m\vec{a} = \frac{d}{dt}\vec{p} \equiv \dot{\vec{p}}$
with $\vec{p} = m\vec{v}$, $\vec{a} = \frac{d}{dt}\vec{v}$, $\vec{v} = \frac{d}{dt}\vec{r}$ for a particle.

$$\text{If } \vec{F} = 0 \Rightarrow \frac{d\vec{p}}{dt} = 0$$

\vec{p} is the linear momentum

$$d\vec{p} = 0$$

$$\int d\vec{p} = 0$$

$$\vec{p} + C = 0$$

$$\vec{p} = \text{constant}$$

Also known as Newton's first law

Conservation theorem for the linear momentum of a particle:
if the total force is zero,
linear momentum is conserved

Let's now define the angular momentum as $\vec{L} = \vec{r} \times \vec{p}$
about point O

Eq. 1.9

And the torque as $\vec{N} = \vec{r} \times \vec{F} = \vec{r} \times \frac{d}{dt}(m\vec{v})$

$d(u \cdot v) = u \cdot dv + v \cdot du$ ← product rule

$$\frac{d}{dt}(\underbrace{\vec{r} \times m\vec{v}}_{\vec{r} \times \vec{p} = \vec{L}}) = \vec{r} \times \frac{d}{dt}(m\vec{v}) + m\vec{v} \times \frac{d}{dt}\vec{r} \quad \cancel{\vec{r} \times \frac{d}{dt}\vec{r}}$$

$$\frac{d}{dt}\vec{L} = \vec{r} \times \frac{d}{dt}(m\vec{v}) + m\vec{v} \times \vec{v} \quad \text{vanishes since angle is zero}$$

$$\frac{d}{dt}\vec{L} = \vec{L} = \vec{N}$$

Eq. 1.11

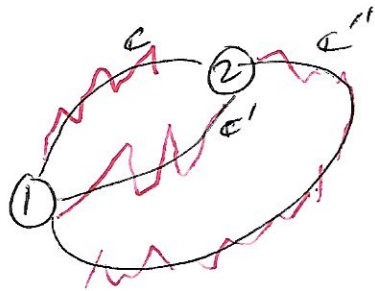
The value of a line integral

(4)

$$\int_C \vec{F}(\vec{r}) \cdot d\vec{r} = \int_C (F_x dx + F_y dy + F_z dz) \quad *$$

depends implicitly on the time since $\vec{r}(t)$

over a path C from point ① to point ② in general depends not only on ① and ②, but also on the path C along which we integrate.



★ What are the conditions for path independence?

Define a line integral as independent of path in a domain D in space if for every pair of points ① and ② in D , integral $*$ has the same value for all paths in D that start at ① and end at ②.

A "well-known" theorem of vector analysis says that a line integral is independent of the path in D if and only if

$$\vec{F} = \nabla f, \quad \text{so} \quad F_x = \frac{\partial f}{\partial x}; \quad F_y = \frac{\partial f}{\partial y}; \quad F_z = \frac{\partial f}{\partial z}$$

I will prove the if, but (not) the only if.

Let C be any path in D from point ① to point ②

given by $\vec{r}(t) = \vec{x}(t)\hat{i} + \vec{y}(t)\hat{j} + \vec{z}(t)\hat{k}; \quad a \leq t \leq b$

$$d\vec{r}(t) = d\vec{x}(t)\hat{i} + d\vec{y}(t)\hat{j} + d\vec{z}(t)\hat{k}$$

$$\int_C \vec{F}(\vec{r}) \cdot d\vec{r} = \int_C F_x dx + F_y dy + F_z dz$$

$$= \int_a^b \left(F_x \frac{dx}{dt} + F_y \frac{dy}{dt} + F_z \frac{dz}{dt} \right) dt$$

we make time-explicit

Let $\vec{F}(\vec{r}) = \nabla f$, then

$$\int_C \vec{F}(\vec{r}) \cdot d\vec{r} = \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt$$

$$= \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt$$

$$= \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt = \int_a^b \frac{df}{dt} dt = f(x(t), y(t), z(t)) \Big|_{t=a}^{t=b} = f(x(b), y(b), z(b)) - f(x(a), y(a), z(a))$$

$$\Rightarrow \int_a^b df = f[x(t), y(t), z(t)] \Big|_{t=a}^{t=b} = f(x(b), y(b), z(b)) - f(x(a), y(a), z(a))$$

Eq. 1.16

For convenience, let $f = -V(\vec{r})$, then $\vec{F} = -\nabla V(\vec{r})$.

~~V~~ V is called the potential energy. A force field in which the work done by an external force on a particle is independent of the path taken is called a conservative force field.

Notice that this would not happen in general and friction is a particularly important case. But when it holds, then $T_2 - T_1 = V_1 - V_2$

$$\Rightarrow T_1 + V_1 = T_2 + V_2$$

Eq. 1.18

Conservation theorem for the energy of a particle: if the forces acting on a particle are conservative, then the total energy of the particle, $T+V$, is conserved.