

Arduino UNO Timer and Interrupts

What is timer interrupts?

- timer interrupts allow a task to be performed at a very specific moment in time
- `loop()` cannot do that because it is difficult to tell how long a statement takes
- Arduino timer interrupts pause the normal sequence of events and execute the set of commands specified
- interrupts are useful for measuring an incoming signal at equally spaced intervals, sending out a signal periodically etc.

Clear Timer on Compare Match (CTC Mode)

- There are three timers in Uno called timer0, timer1, and timer2
- Each timer has a counter and is incremented on each clock tick
- interrupt is triggered when the counter reaches a specific value, stored in the compare match register
- the counter will be reset to 0 after reaching the value
- how often interrupts occur depend on the compare match value

Timer Interrupt Program Structure

- In `setup()`
 - setup up the right frequency of the timer by specifying the parameters appropriately
- define interrupt function
 - The interrupt function of Timer~~X~~ is `ISR(TIMERX_COMPA_vect)`
 - e.g. the interrupt function of Timer1 is `ISR(TIMER1_COMPA_vect)`
 - put the tasks you want to perform periodically inside the interrupt function
- In `loop()`
 - no statement is needed here if everything you want to do is in the interrupt function

Timer Parameters

- clock speed
 - Arduino clock runs at 16MHz
 - fastest speed the interrupts can occur (once every $1/16,000,000$ second)
- maximum counter value (when to trigger interrupt)
 - timer0 and timer2 are 8 bit timers (maximum counter value = 255)
 - timer1 is 16-bit (at most 65535)
 - e.g. suppose we set the counter value of timer1 = 65535. Interrupts will occur every $65536/16,000,000$ seconds ($\sim 4\text{ms}$) in timer1 if we increment the timer in every tick
- prescaler (slow down counter increment)
 - timer speed (how often the counter increments) = Arduino clock speed / prescaler

Setting the right value

desired interrupt frequency

$$= \text{Arduino clock speed} / (\text{prescaler} * (\text{compare match register} + 1))$$

compare match register

$$= \text{Arduino clock speed} / (\text{prescaler} * \text{desired interrupt frequency}) - 1$$

e.g. we want an interrupt every second (1Hz). Let the prescaler = 1024

$$\text{compare match register} = [16,000,000 / (1024 * 1)] - 1 = 15624$$

Timer1 should be used

Prescaler

- prescaler set by using appropriate values
- Each timer has its own combinations

Timer 0

CS02	CS01	CS00	Description
0	0	0	No clock source (Timer/Counter stopped)
0	0	1	$\text{clk}_{\text{I/O}}$ (No prescaling)
0	1	0	$\text{clk}_{\text{I/O}}/8$ (From prescaler)
0	1	1	$\text{clk}_{\text{I/O}}/64$ (From prescaler)
1	0	0	$\text{clk}_{\text{I/O}}/256$ (From prescaler)
1	0	1	$\text{clk}_{\text{I/O}}/1024$ (From prescaler)
1	1	0	External clock source on T0 pin. Clock on falling edge.
1	1	1	External clock source on T0 pin. Clock on rising edge.

Timer 2

CS22	CS21	CS20	Description
0	0	0	No clock source (Timer/Counter stopped).
0	0	1	clk_{r2s} (No prescaling)
0	1	0	$\text{clk}_{\text{r2s}}/8$ (From prescaler)
0	1	1	$\text{clk}_{\text{r2s}}/32$ (From prescaler)
1	0	0	$\text{clk}_{\text{r2s}}/64$ (From prescaler)

Timer 1

Table 16-5. Clock Select Bit Description

CS12	CS11	CS10	Description
0	0	0	No clock source (Timer/Counter stopped).
0	0	1	$\text{clk}_{\text{I/O}}/1$ (No prescaling)
0	1	0	$\text{clk}_{\text{I/O}}/8$ (From prescaler)
0	1	1	$\text{clk}_{\text{I/O}}/64$ (From prescaler)
1	0	0	$\text{clk}_{\text{I/O}}/256$ (From prescaler)
1	0	1	$\text{clk}_{\text{I/O}}/1024$ (From prescaler)
1	1	0	External clock source on T1 pin. Clock on falling edge.
1	1	1	External clock source on T1 pin. Clock on rising edge.

Timer setup code (1)

- Reset the timer (**X** refers to the timer number)
 - `TCCRXA = 0; // e.g. TCCR0A = 0; for timer0`
 - `TCCRXB = 0;`
 - `TCNTX = 0;`
- set the compare match register
 - `OCRXA = value; // e.g. OCR0A = 124;`
- turn on CTC mode
 - `TCCR0A |= (1 << WGM01); //for timer0`
 - `TCCR1B |= (1 << WGM12); //for timer1`
 - `TCCR2A |= (1 << WGM21); //for timer2`

Timer setup code (2)

- set prescaler

- `TCCR2B |= (1 << CS22);`
 // Timer 2; prescaler = 64
- `TCCR1B |= (1 << CS11);`
 // Timer 1; prescaler = 8
- `TCCR0B |= (1 << CS02) | (1 << CS00);`
 // Timer 0; prescaler = 1024

- enable timer compare interrupt

- `TIMSKx |= (1 << OCIExA);`
 // e.g. `TIMSK0 |= (1 << OCIE0A);`