```
sketch.ino:
#include <Wire.h>
#include <WiFi.h>
#include < DHT.h>
#include < PubSubClient.h>
#include < Arduino.h >
#include <Adafruit_MPU6050.h>
#include <Adafruit_Sensor.h>
#define DHT_PIN 12
#define PULSE_PIN 35
#define MQTT_SERVER "broker.emqx.io"
#define MQTT_PORT 1883
const char *ssid = "Wokwi-GUEST";
const char *password = "";
#define MQTT_TOPIC_HR "/heartRate"
#define MQTT_TOPIC_TEMP "/tempValue"
#define MQTT_TOPIC_HUM "/humValue"
#define MQTT_TOPIC_ACCEL "/accelData"
#define MQTT_TOPIC_GYRO "/gyroData"
WiFiClient espClient;
PubSubClient client(espClient);
DHT dht(DHT_PIN, DHT22);
Adafruit_MPU6050 mpu;
void setup() {
Wire.begin(23, 22); // SDA on GPIO 23, SCL on GPIO 22
Serial.begin(115200);
Serial.println("Hello, ESP32!");
connectToWiFi();
```

client.setServer(MQTT\_SERVER, MQTT\_PORT);

```
dht.begin();
// Initialize MPU6050
if (!mpu.begin()) {
  Serial.println("MPU6050 not connected!");
 while (1);
}
Serial.println("MPU6050 connected!");
}
void loop() {
if (!client.connected()) {
 reconnect();
}
float temperature = dht.readTemperature();
float humidity = dht.readHumidity();
// Read pulseValue from PULSE_PIN
int16_t pulseValue = analogRead(PULSE_PIN);
// Convert pulseValue to voltage
float voltage = pulseValue * (3.3 / 4095.0);
// Calculate heartRate from voltage (simplified example, adjust as needed)
int heartRate = (voltage / 3.3) * 675;
// Print HeartRate
Serial.print("Heart Rate: ");
 Serial.print(heartRate);
```

```
Serial.print(" Temp: ");
Serial.print(temperature);
Serial.print(" Humidity: ");
Serial.println(humidity);
// Read MPU6050 data
sensors_event_t accel, gyro, temp;
mpu.getEvent(&accel, &gyro, &temp);
Serial.print("Accel: ");
Serial.print(accel.acceleration.x); Serial.print(", ");
Serial.print(accel.acceleration.y); Serial.print(", ");
Serial.println(accel.acceleration.z);
Serial.print("Gyro: ");
Serial.print(gyro.gyro.x); Serial.print(", ");
Serial.print(gyro.gyro.y); Serial.print(", ");
Serial.println(gyro.gyro.z);
client.publish(MQTT_TOPIC_HR, String(heartRate).c_str());
client.publish(MQTT_TOPIC_TEMP, String(temperature).c_str());
client.publish(MQTT_TOPIC_HUM, String(humidity).c_str());
String accelData = String(accel.acceleration.x) + "," + String(accel.acceleration.y) + "," +
String(accel.acceleration.z);
String gyroData = String(gyro.gyro.x) + "," + String(gyro.gyro.y) + "," + String(gyro.gyro.z);
client.publish(MQTT_TOPIC_ACCEL, accelData.c_str());
client.publish(MQTT_TOPIC_GYRO, gyroData.c_str());
delay(1000); // Increased delay to 1 second for more stability
```

```
}
void connectToWiFi() {
 WiFi.begin(ssid, password);
 while (WiFi.status() != WL_CONNECTED) {
  delay(1000);
  Serial.println("Connecting to WiFi...");
 }
 Serial.println("Connected to WiFi");
}
void reconnect() {
 while (!client.connected()) {
  if (client.connect("esp32_neopixel_controller")) {
   Serial.println("Connected to MQTT");
   // subscribeToCommands();
  } else {
   Serial.print("Failed, rc=");
   Serial.print(client.state());
   Serial.println("Retrying in 5 seconds...");
   delay(5000);
 }
 }
}
diagram.json:
{
 "version": 1,
 "author": "ProCoding Whitehat JR",
 "editor": "wokwi",
 "parts": [
```

```
{ "type": "board-esp32-devkit-c-v4", "id": "esp", "top": 0, "left": 0, "attrs": {} },
 { "type": "chip-pulsesensor", "id": "chip1", "top": 154.62, "left": 148.8, "attrs": {} },
 {
   "type": "wokwi-dht22",
   "id": "dht1",
   "top": -18.9,
   "left": -149.4,
   "attrs": { "temperature": "68.7", "humidity": "36.5" }
 },
 { "type": "wokwi-mpu6050", "id": "imu1", "top": 51.82, "left": 155.92, "attrs": {} }
],
 "connections": [
 ["esp:TX", "$serialMonitor:RX", "", []],
 ["esp:RX", "$serialMonitor:TX", "", []],
 ["chip1:GND", "esp:GND.1", "black", ["h-28.8", "v67.2", "h-134.4", "v-38.4"]],
 ["dht1:VCC", "esp:5V", "red", ["v0"]],
 ["esp:5V", "chip1:VCC", "red", ["h-33.41", "v38.4", "h163.2", "v-67.2"]],
 ["esp:GND.1", "dht1:GND", "black", ["h0"]],
 ["dht1:SDA", "esp:12", "green", ["v0"]],
 ["chip1:OUT0", "esp:35", "green", ["h-38.4", "v-211.2", "h-134.4", "v115.2"]],
 ["imu1:GND", "esp:GND.1", "black", ["v0"]],
 ["imu1:VCC", "esp:3V3", "red", ["v0"]],
 ["imu1:SCL", "esp:22", "green", ["v0"]],
 ["imu1:SDA", "esp:23", "green", ["v0"]]
],
"dependencies": {}
Pulsesensor.chip.json:
 "name": "pulse-sensor",
 "author": "ProCoding Whitehat JR",
```

```
"pins": [
  "GND",
  "VCC",
  "",
  "OUT0",
  "",
  "",
  ""
 ],
 "controls": [
 {
   "id": "pulseValue",
   "label": "Heart Rate",
   "type": "slider",
   "min":0,
   "max":675
 }
 ]
}
```

#### Pulsesensor.chip.c:

```
//Pulse sensor reference: https://www.eecs.yorku.ca/~jr/res/m/MD/PulseSensor.pdf
//https://www.elprocus.com/pulse-sensor-working-principle-and-its-applications/
#include "wokwi-api.h"
#include <stdio.h>
#include <stdlib.h>

typedef struct {
    pin_t pin;
    int pulseValue;
} chip_data_t;
```

```
void chip_timer_callback(void *data) {
 chip_data_t *chip_data = (chip_data_t*)data;
// Read pulseValue in pulseValue variable
int pulseValue = attr_read(chip_data->pulseValue);
// Calculate volts
float volts = pulseValue *3.3/675;
// Send volts on the pin
printf("%f \n", volts);
 pin_dac_write(chip_data->pin, volts);
}
void chip_init() {
printf("Hello from custom chip!\n");
chip_data_t *chip_data = (chip_data_t*)malloc(sizeof(chip_data_t));
// Initialize pulseValue
chip_data->pulseValue = attr_init("pulseValue", 0);
// Initialize pin
chip_data->pin = pin_init("OUT0", ANALOG);
 const timer_config_t config = {
  .callback = chip_timer_callback,
 .user_data = chip_data,
};
timer_t timer_id = timer_init(&config);
timer_start(timer_id, 1000, true);
}
```

#### Libraries.c:

- # Wokwi Library List
- # See https://docs.wokwi.com/guides/libraries
- # Automatically added based on includes:

DHT sensor library

PubSubClient

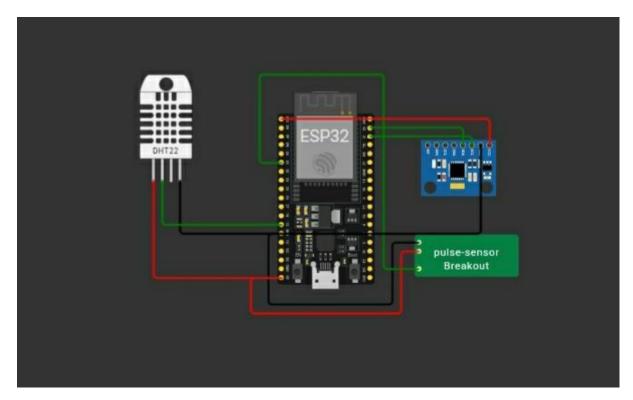
DHT sensor library for ESPx

Adafruit MPU6050

# **Library Manager:**

- DHT sensor library
- PubSubClient
- DHT sensor

### Simulation:



# OUTPUT:

Hello, ESP32!

Connecting to WiFi...

Connecting to WiFi...

Connected to WiFi

MPU6050 connected!

Connected to MQTT

Heart Rate: 0 Temp: 68.70 Humidity: 36.50

Accel: 0.00, 0.00, 9.81

Gyro: 0.00, 0.00, 0.00