

Stationarity and Unit Root Tests

Jordan Andersen
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Motivation

ARMA and ARIMA models assume constant variance, mean and autocovariance in order to make reliable predictions (weak stationarity).

When a series is nonstationary, the models parameters become unstable and its predictions unreliable.

This makes it essential to diagnose and address non-stationarity before attempting modeling and forecasting in order to produce reliable estimates.

Theoretical Background

Definition (Hyndman 2018)

Strict Stationarity: the joint distributions of a time series are time-invariant.

Weak stationarity: constant mean and variance, and autocovariance that is only dependent on lags, not on time.

Granger & Newbold (1974)

Landmark paper demonstrating spurious correlations between non-stationary time series that shared stochastic trends.

Called for methods such as first-differencing before modeling and forecasting.

Dickey & Fuller (1981)

One of the first tests to determine the presence of a unit root.

Sensitive to heteroskedasticity in the errors and structural breaks.

Null: unit root exists

Alternative: no unit root

Phillips-Perron (1988)

Allows for heteroskedasticity and serial correlation in the errors.

Depends on kernel choices to estimate long-run variance of the errors.

Null: unit root exists

Alternative: no unit root

KPSS (1991)

Complementary null hypothesis to ADF and PP tests.

Sensitive to structural breaks and small, finite samples.

Null: series is level or trend-stationary

Alternative: unit root exists

Simulation

Granger and Newbold (1974) demonstrated that shared stochastic trends lead to spurious correlations, advocating for transformations like first-differencing before modeling and forecasting.

A Monte Carlo simulation of regressing two independent random walks produced a type 1 error rate of 76.3%.

First differencing to achieve stationarity prior to modeling led to insignificant results and a low R squared value.

Monte Carlo Simulation

| Simulations | Error_Rate | Average_R_Squared |
|-------------|------------|-------------------|
| 1000 | 0.763 | 0.242012 |

Spurious Correlation between X and Y

| Dependent variable: | |
|---------------------|-----------------------------|
| Y | |
| X | -0.677*** (0.115) |
| Constant | -0.836 (0.510) |
| ----- | |
| Observations | 100 |
| R2 | 0.268 |
| Adjusted R2 | 0.261 |
| Residual Std. Error | 2.451 (df = 98) |
| F Statistic | 35.940*** (df = 1; 98) |
| ===== | |
| Note: | *p<0.1; **p<0.05; ***p<0.01 |

Differenced Regression of X and Y

| Dependent variable: | |
|---------------------|-----------------------------|
| diff(Y) | |
| diff(X) | 0.023 (0.095) |
| Constant | -0.106 (0.091) |
| ----- | |
| Observations | 99 |
| R2 | 0.001 |
| Adjusted R2 | -0.010 |
| Residual Std. Error | 0.907 (df = 97) |
| F Statistic | 0.058 (df = 1; 97) |
| ===== | |
| Note: | *p<0.1; **p<0.05; ***p<0.01 |

Case Study

Use GDP data* from the USA, Japan and Brazil to assess non-stationarity and appropriate techniques to achieve stationarity prior to modeling and forecasting.

Japan

- Rapid growth into 1990
- Relative stagnation afterwards

USA

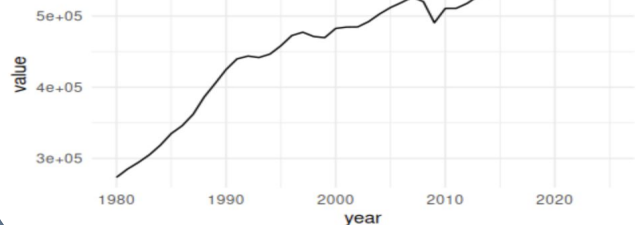
- Persistent upward trend
- Small structural breaks in 2008 (Financial Crisis) and 2020 (Covid-19)

Brazil

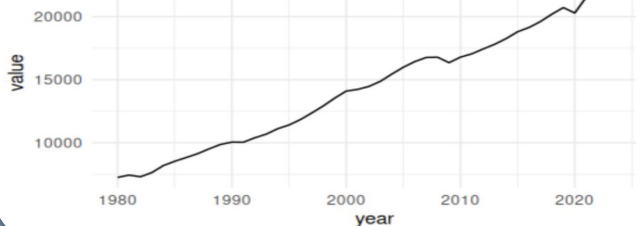
- Relative stagnation until mid-1990s
- Upward trending growth until 2010
- Stagnation between 2010-2020 before trending upward again

*Data comes from the IMF's World Economic Outlook database (2025)

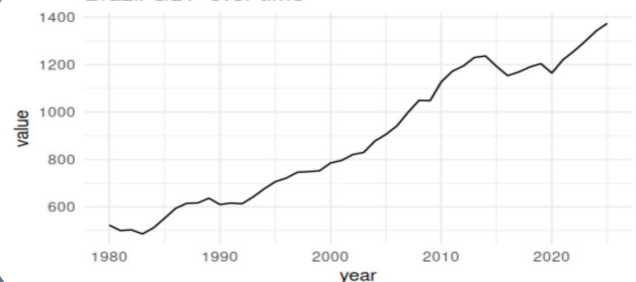
Japan GDP over time



USA GDP over time



Brazil GDP over time



Case Study

Table 4: USA Unit Root and Stationarity Tests

| | Test | Statistic | P_Value | H0 |
|------------------------|-----------------|------------|-----------|---------------------------|
| Dickey-Fuller | ADF | -1.4613697 | 0.7881234 | Unit root (nonstationary) |
| Dickey-Fuller Z(alpha) | Phillips-Perron | -8.3447886 | 0.6110551 | Unit root (nonstationary) |
| KPSS Level | KPSS (Level) | 1.2461842 | 0.0100000 | Stationary (Level) |
| KPSS Trend | KPSS (Trend) | 0.1127233 | 0.1000000 | Stationary (Trend) |

Table 5: Japan Unit Root and Stationarity Tests

| | Test | Statistic | P_Value | H0 |
|------------------------|-----------------|-----------|-----------|---------------------------|
| Dickey-Fuller | ADF | -2.586601 | 0.3407153 | Unit root (nonstationary) |
| Dickey-Fuller Z(alpha) | Phillips-Perron | -3.704918 | 0.8996941 | Unit root (nonstationary) |
| KPSS Level | KPSS (Level) | 1.115804 | 0.0100000 | Stationary (Level) |
| KPSS Trend | KPSS (Trend) | 0.272580 | 0.0100000 | Stationary (Trend) |

Table 6: Brazil Unit Root and Stationarity Tests

| | Test | Statistic | P_Value | H0 |
|------------------------|-----------------|-----------|-----------|---------------------------|
| Dickey-Fuller | ADF | -2.324430 | 0.4449583 | Unit root (nonstationary) |
| Dickey-Fuller Z(alpha) | Phillips-Perron | -9.800383 | 0.5205049 | Unit root (nonstationary) |
| KPSS Level | KPSS (Level) | 1.230161 | 0.0100000 | Stationary (Level) |
| KPSS Trend | KPSS (Trend) | 0.123278 | 0.0920777 | Stationary (Trend) |

USA

- ADF and PP tests, rejects the null hypothesis of weak stationarity.
- KPSS trend-stationary test fails to reject the null hypothesis of trend-stationarity, suggesting that the non-stationarity in the USA data is due to a deterministic trend.
- De-trending could be more efficient than first-differencing.

Japan

- ADF and PP tests fail to reject the null hypothesis of a unit root.
- KPSS level test also reject the null hypothesis of weak stationarity. KPSS trend test rejects the null hypothesis of trend-stationarity. Japan's GDP is not stationary around a deterministic trend, shocks to the series will be persistent throughout time.
- Japan's GDP is a near-unit-root series, rather than a clearly trend-stationary or difference-stationary series.

Brazil

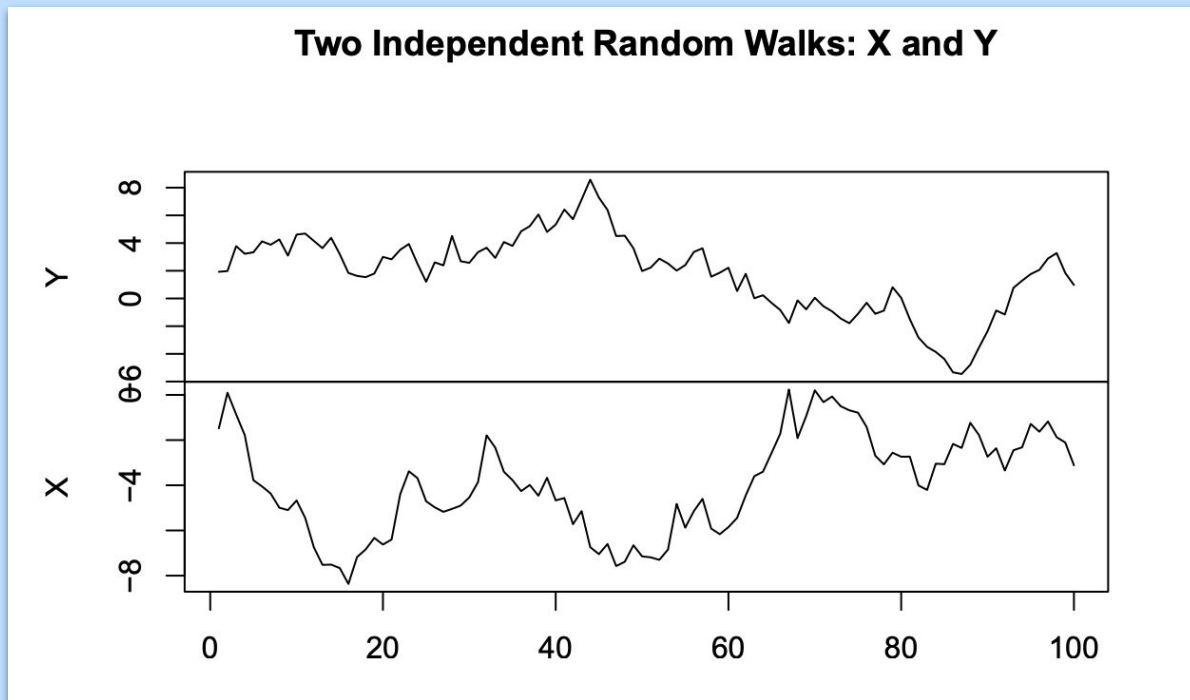
- ADF and PP tests fail to reject the null hypothesis of a unit root.
- KPSS level test rejects the null hypothesis of stationarity. KPSS trend test produces a p-value > 0.05 but less than 0.10.
- Tests struggle to deal with structural breaks in the data.

Conclusions

- 1 Detecting non-stationarity and unit roots are necessary steps for producing valid models and forecasting with accuracy.
- 2 Non-stationarity produces spurious regression relationships, inflates goodness-of-fit measures, and undermines statistical validity when left unaddressed.
- 3 Unit root tests come with strengths and weaknesses, and a complete analysis requires inference from multiple tests to determine the best methods for producing a stationary series.

Thank you!

Appendix



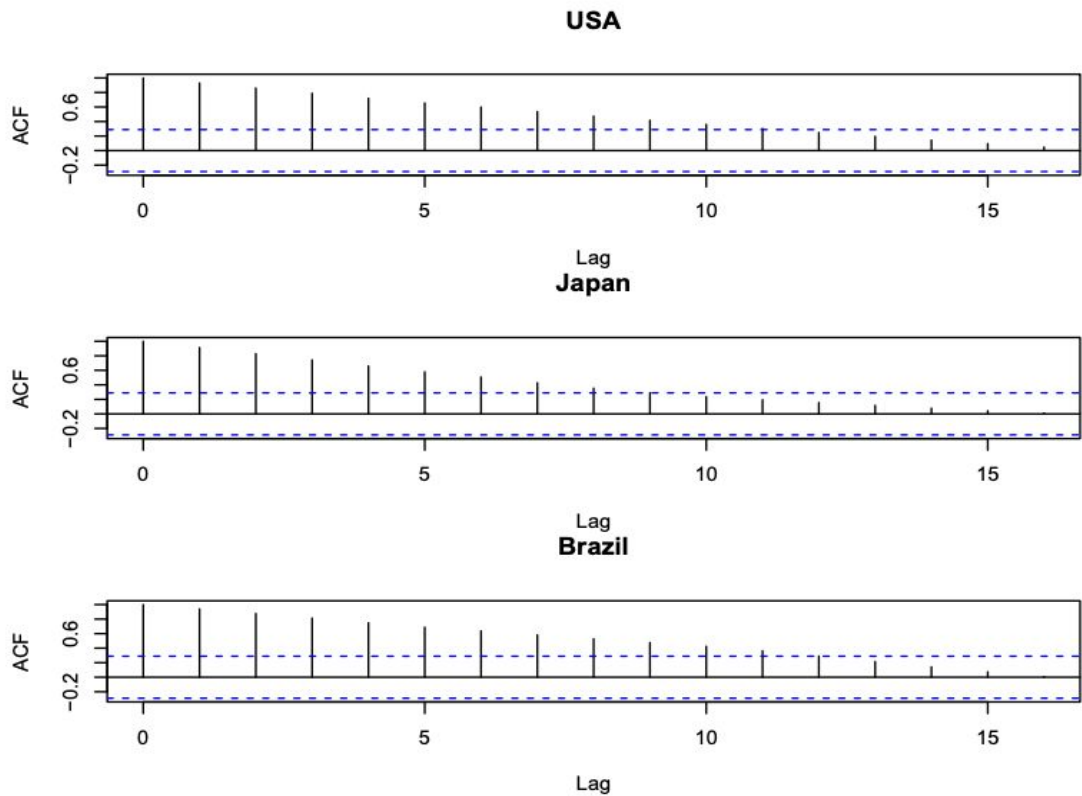
Two simulated independent random walks: X and Y

| Series | ADF_Statistic | ADF_P_Value | Method |
|--------|---------------|-------------|------------------------------|
| X | -1.6428 | 0.7246 | Augmented Dickey-Fuller Test |
| Y | -1.5093 | 0.7799 | Augmented Dickey-Fuller Test |

ADF Test results for X and Y simulated random walk series

| Series | KPSS_Statistic | KPSS_P_Value | Method |
|--------|----------------|--------------|----------------------------------|
| X | 0.4519 | 0.0548 | KPSS Test for Level Stationarity |
| Y | 0.4327 | 0.0631 | KPSS Test for Level Stationarity |
| X | 0.2931 | 0.0100 | KPSS Test for Trend Stationarity |
| Y | 0.3506 | 0.0100 | KPSS Test for Trend Stationarity |

KPSS Test results for X and Y simulated random walk series



ACF Plots for GDP time series