

	1	2	3	4	5	6
A			<div>TMC2209</div> <div></div> <div>File: tmc2209.kicad_sch</div>			
B			<div>TMC51X0</div> <div></div> <div>File: tmc51x0.kicad_sch</div>			
C						
D					<div>Janelia Research Campus</div> <div>Sheet: / File: trinamic-wiring.kicad_sch</div> <div>Title: Trinamic Wiring</div> <div>Size: A4Date: 2024-08-01</div> <div>KiCad E.D.A. kicad 7.0.11</div>	<div>Rev: 0.5</div> <div>Id: 1/25</div>
	1	2	3	4	5	6

	1	2	3	4	5	6
A						
B						
C						
D						
	1	2	3	4	5	6

description

File: tmc2209-description.kicad\_sch

microcontroller

File: tmc2209-microcontroller.kicad\_sch

stepper-controller

File: tmc2209-stepper-controller.kicad\_sch

teensy40

File: tmc2209-teensy40.kicad\_sch

mega2560

File: tmc2209-mega2560.kicad\_sch

uno

File: tmc2209-uno.kicad\_sch

unidirectional

File: tmc2209-unidirectional.kicad\_sch

unidirectional-multiple

File: tmc2209-unidirectional-multiple.kicad\_sch

unidirectional-multiple-address

File: tmc2209-unidirectional-multiple-address.kicad\_sch

unidirectional-multiple-uart

File: tmc2209-unidirectional-multiple-uart.kicad\_sch

bidirectional-coupled

File: tmc2209-bidirectional-coupled.kicad\_sch

bidirectional-coupled-multiple-address

File: tmc2209-bidirectional-coupled-multiple-address.kicad\_sch

bidirectional-coupled-multiple-uart

File: tmc2209-bidirectional-coupled-multiple-uart.kicad\_sch

Janelia Research Campus

Sheet: /TMC2209/

File: tmc2209.kicad\_sch

Title: Trinamic Wiring

Size: A4

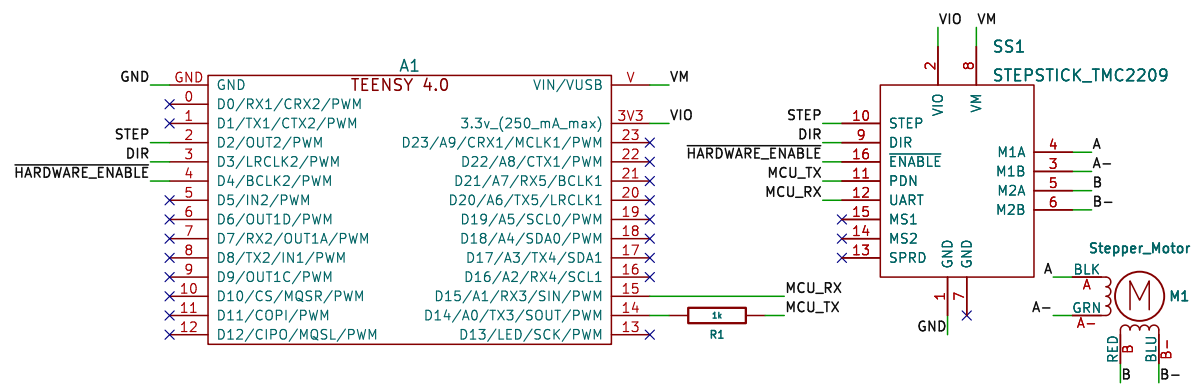
Date: 2024-08-01

Rev: 0.5

KiCad E.D.A. kicad 7.0.11

Id: 2/25

MCU\_RX and R1 are optional if only unidirectional communication is desired.



Must solder jumper pads on the SilentStepStick to connect both the UART and PDN pins to the PDN\_UART line on the chip!

STEP, DIR, and HARDWARE\_ENABLE are optional connections to the microcontroller. STEP and DIR signals may be left disconnected if only moveAtVelocity method is used. STEP and DIR signals usually come from a dedicated stepper controller, like the TMC429. HARDWARE\_ENABLE may be tied to ground if only software enable is desired. Most examples assume STEP, DIR, and HARDWARE\_ENABLE are not connected to the microcontroller and that HARDWARE\_ENABLE is tied to ground on the TMC2209.

Janelia Research Campus

Sheet: /TMC2209/teensy40/

File: tmc2209-teensy40.kicad\_sch

**Title: Trinamic Wiring**

Size: A4

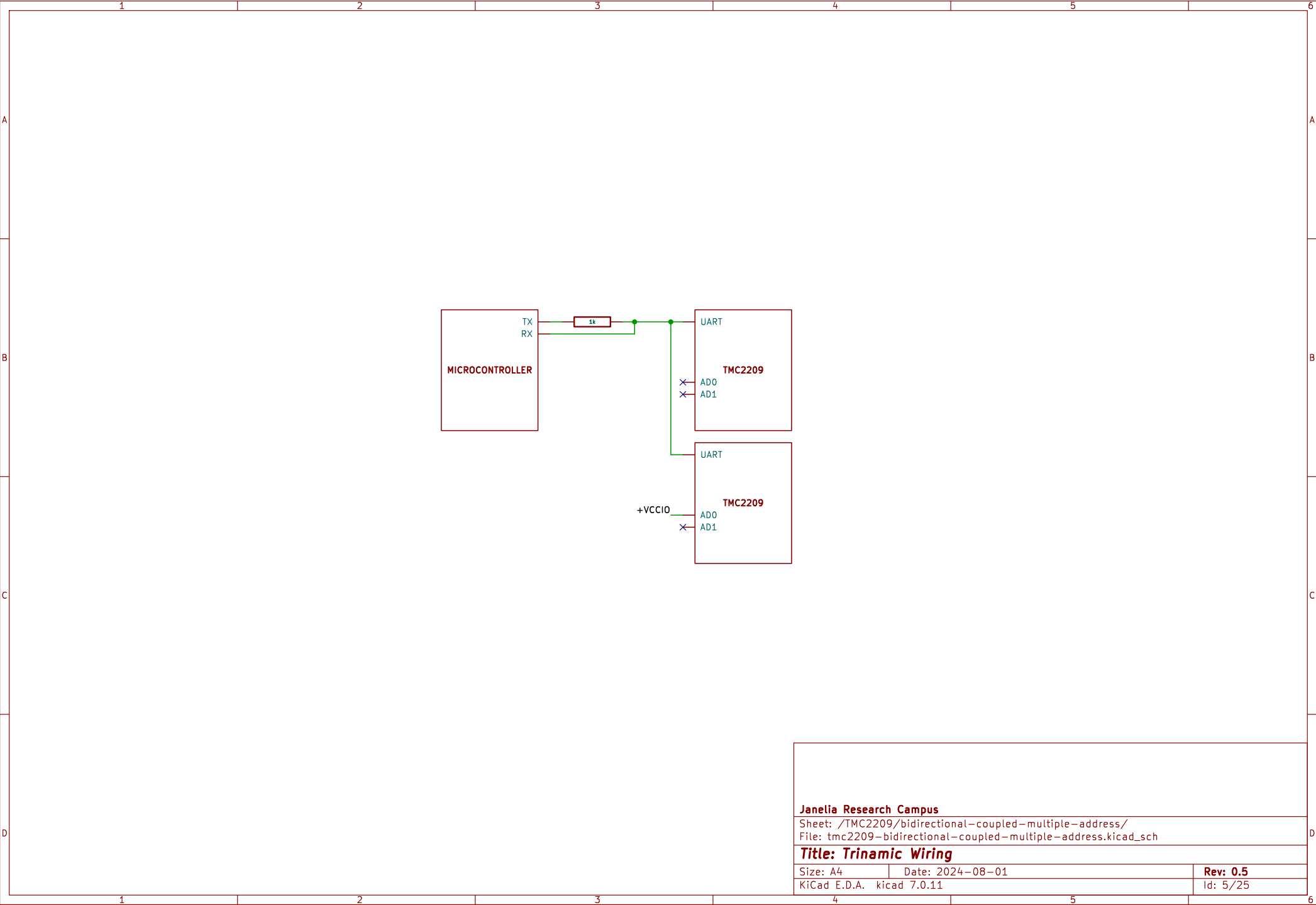
Date: 2024-08-01

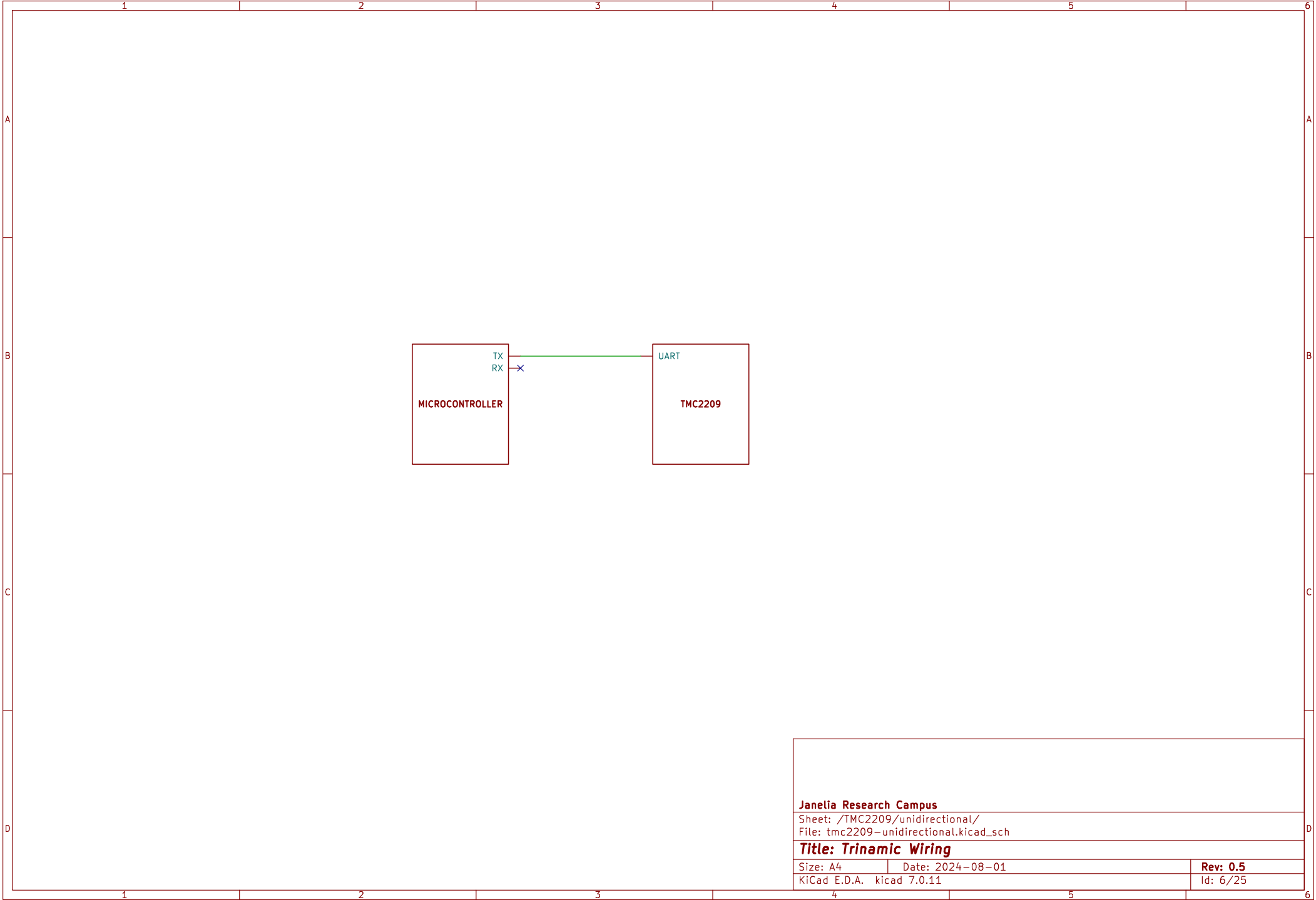
Rev: 0.5

KiCad E.D.A. kicad 7.0.11

Id: 3/25







Janelia Research Campus

Sheet: /TMC2209/unidirectional/  
File: tmc2209-unidirectional.kicad\_sch

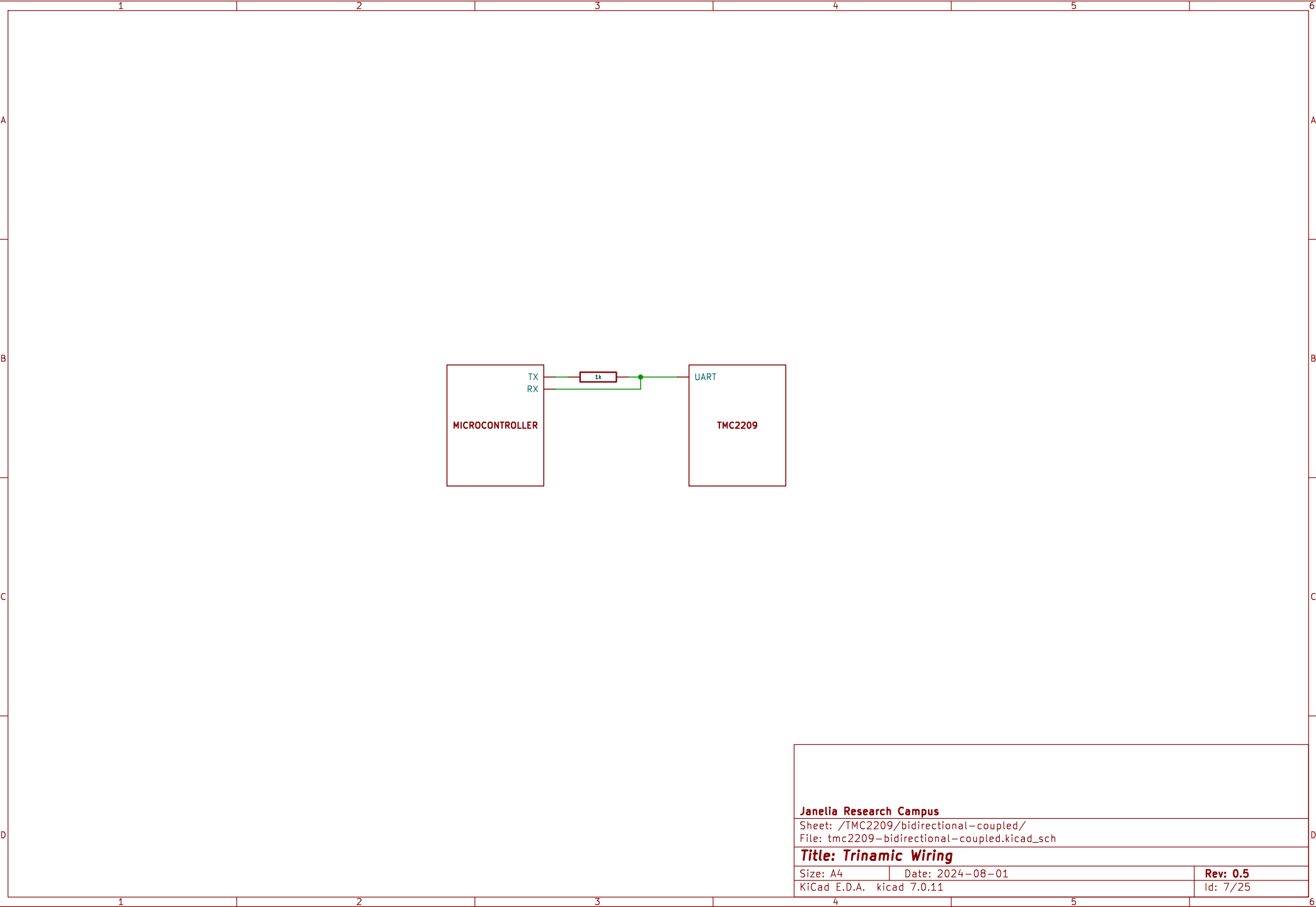
**Title: Trinamic Wiring**

Size: A4 Date: 2024-08-01

KiCad E.D.A. kicad 7.0.11

**Rev: 0.5**

Id: 6/25

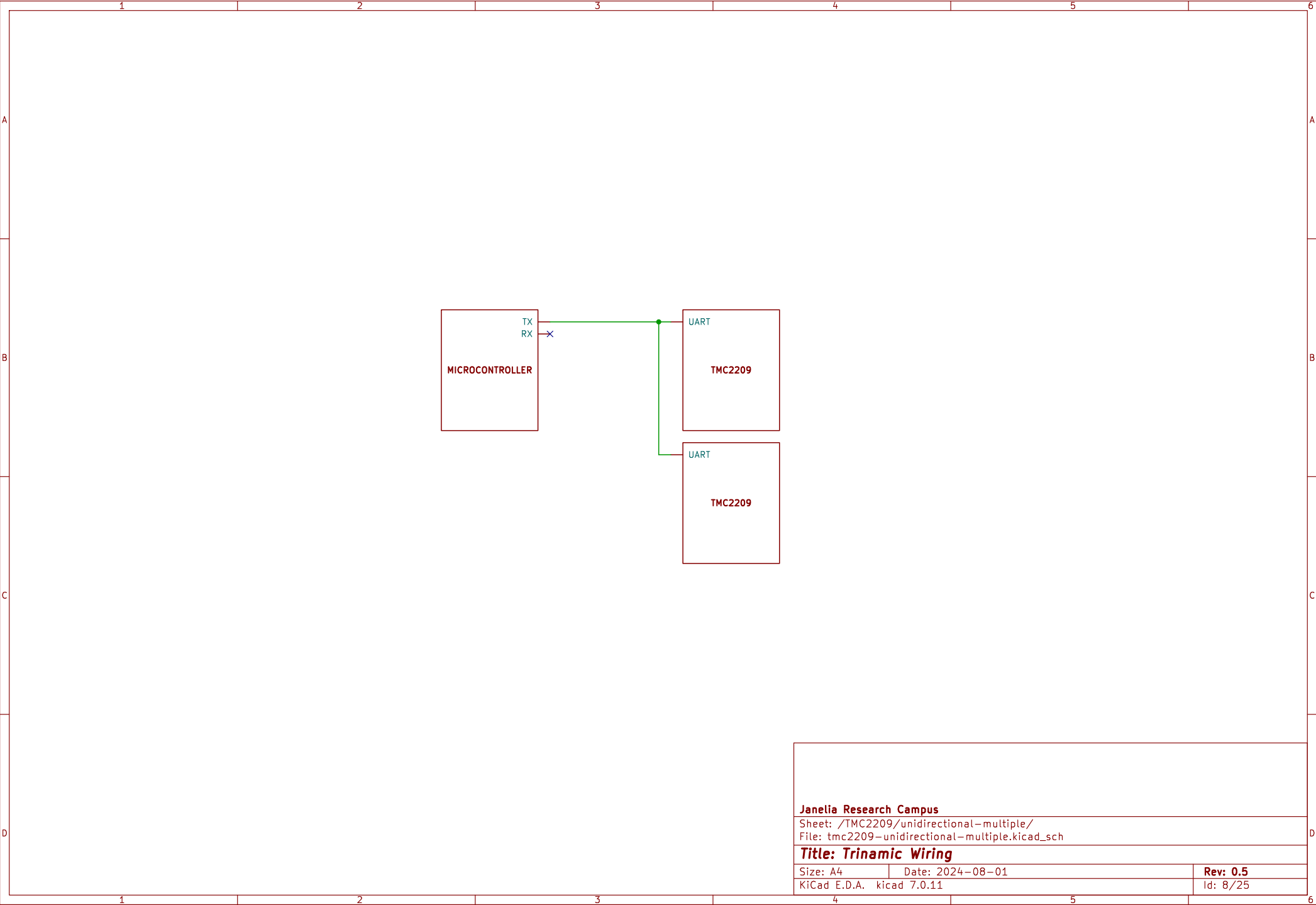


Janelia Research Campus

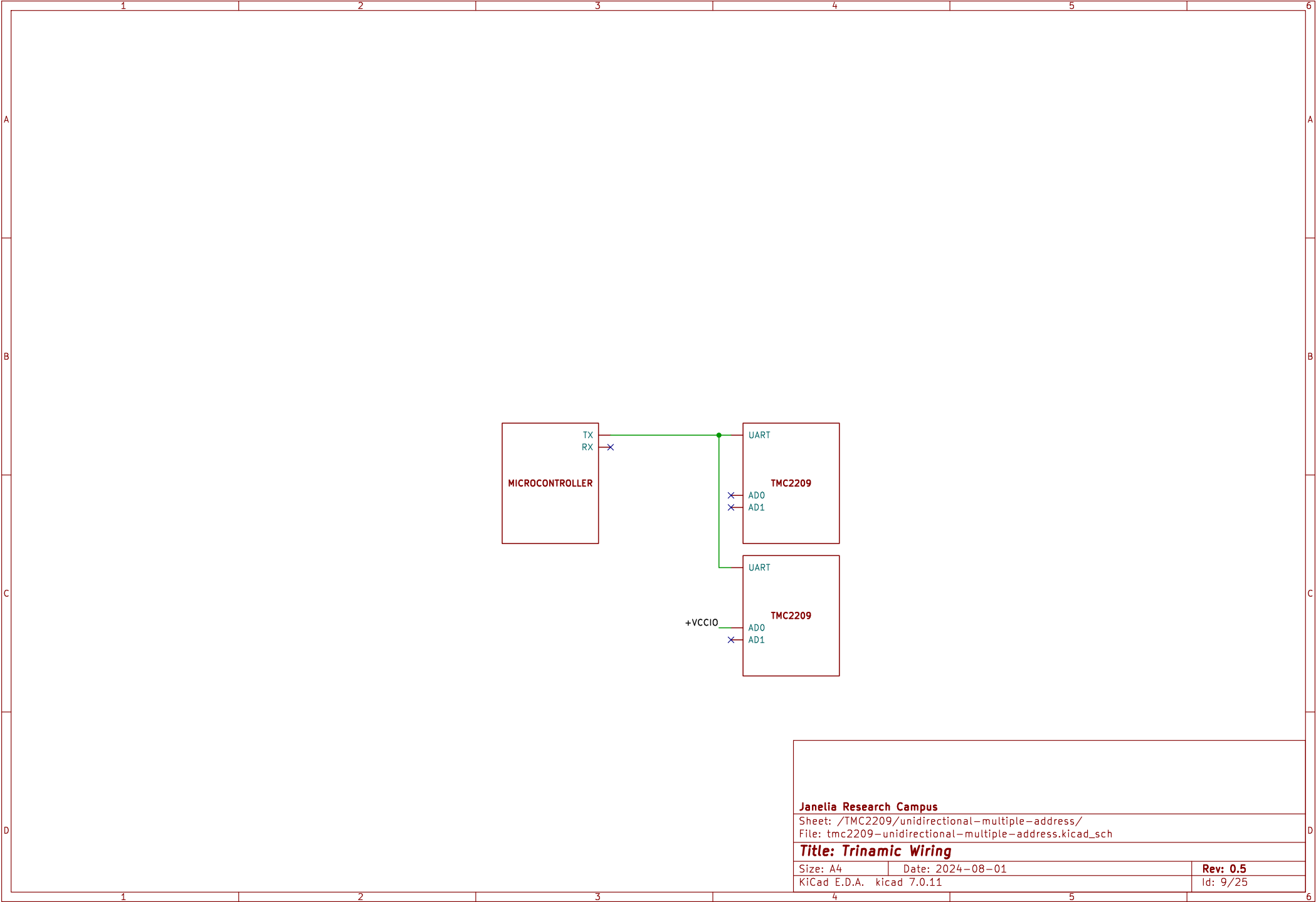
Sheet: /TMC2209/bidirectional-coupled/  
File: tmc2209-bidirectional-coupled.kicad\_sch

**Title: Trinamic Wiring**

Size: A4	Date: 2024-08-01	Rev: 0.5
KiCad E.D.A. kicad 7.0.11		Id: 7/25

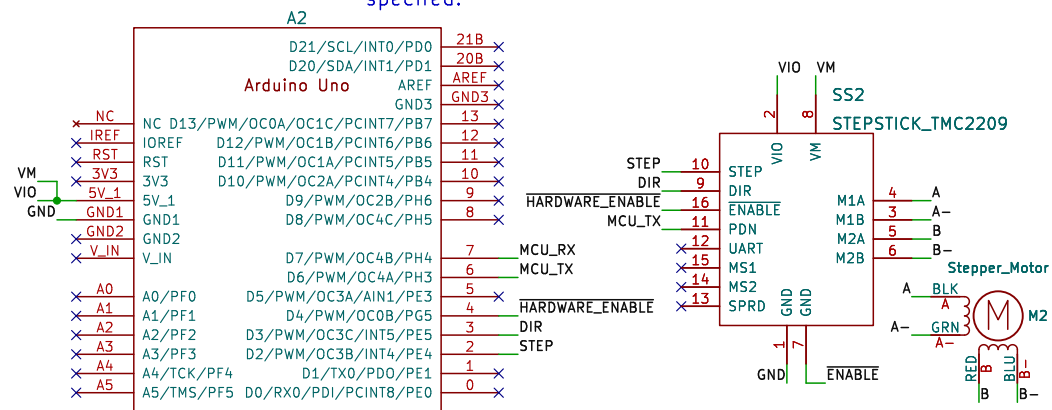






RX and TX pins must be changed in the SoftwareSerial example:  
const uint8\_t RX\_PIN = 7;  
const uint8\_t TX\_PIN = 6;

Arduino Uno is only capable of unidirectional communication, so only TX is connected and used, but the SoftwareSerial library requires that the RX pin must be reserved and specified.



STEP, DIR, and HARDWARE\_ENABLE are optional connections to the microcontroller. STEP and DIR signals may be left disconnected if only moveAtVelocity method is used. STEP and DIR signals usually come from a dedicated stepper controller, like the TMC429. HARDWARE\_ENABLE may be tied to ground if only software enable is desired. Most examples assume STEP, DIR, and HARDWARE\_ENABLE are not connected to the microcontroller and that HARDWARE\_ENABLE is tied to ground on the TMC2209.

Janelia Research Campus

Sheet: /TMC2209/uno/  
File: tmc2209-uno.kicad\_sch

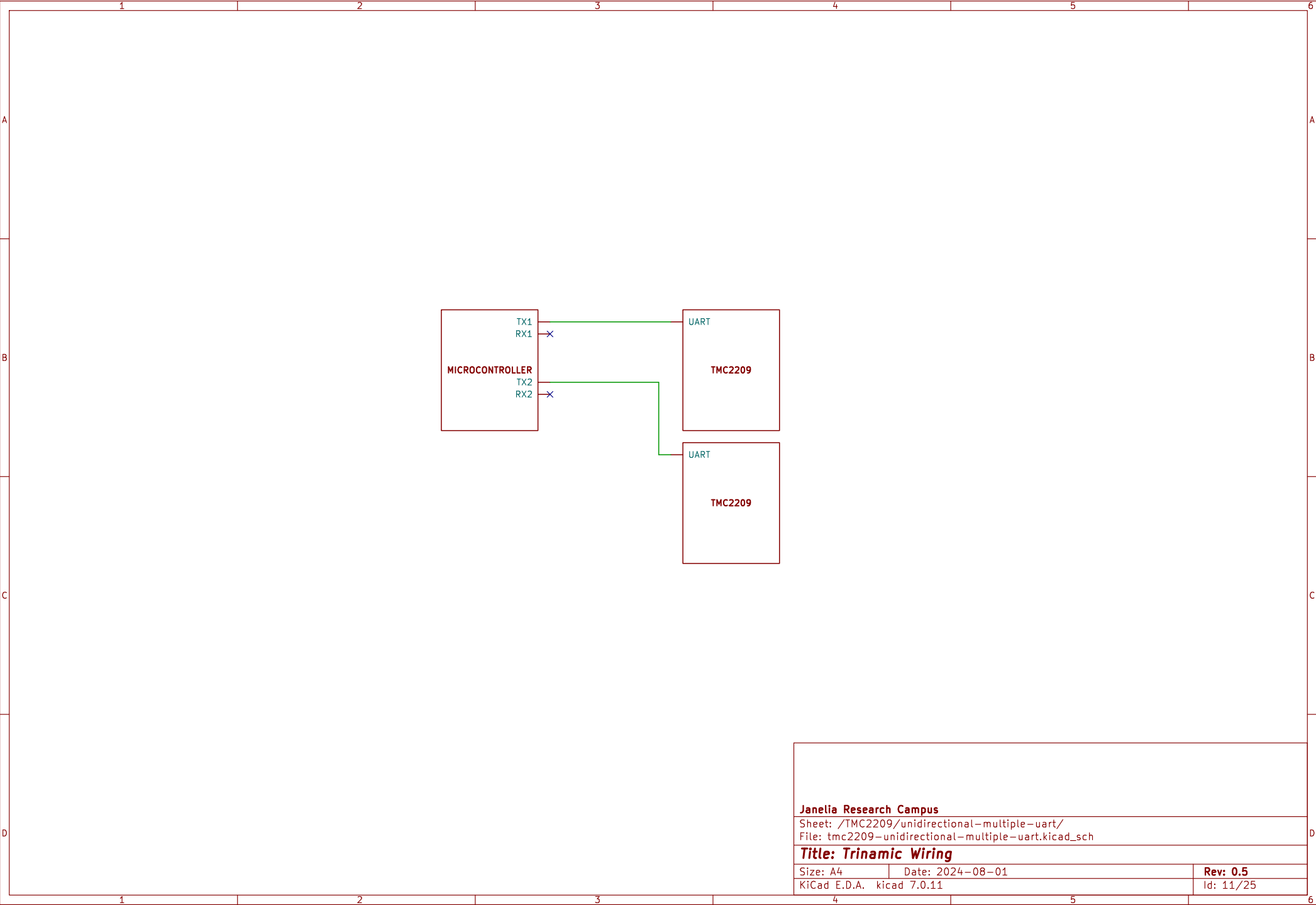
**Title: Trinamic Wiring**

Size: A4 Date: 2024-08-01

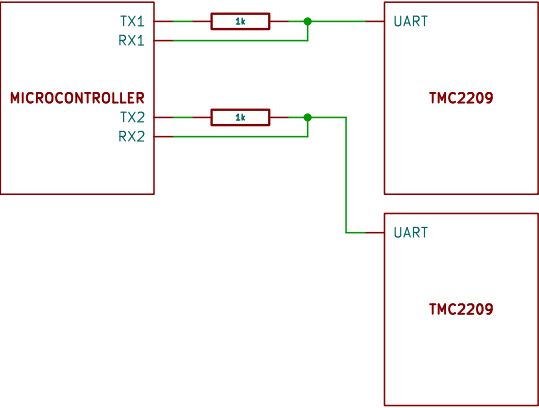
KiCad E.D.A. kicad 7.0.11

**Rev: 0.5**

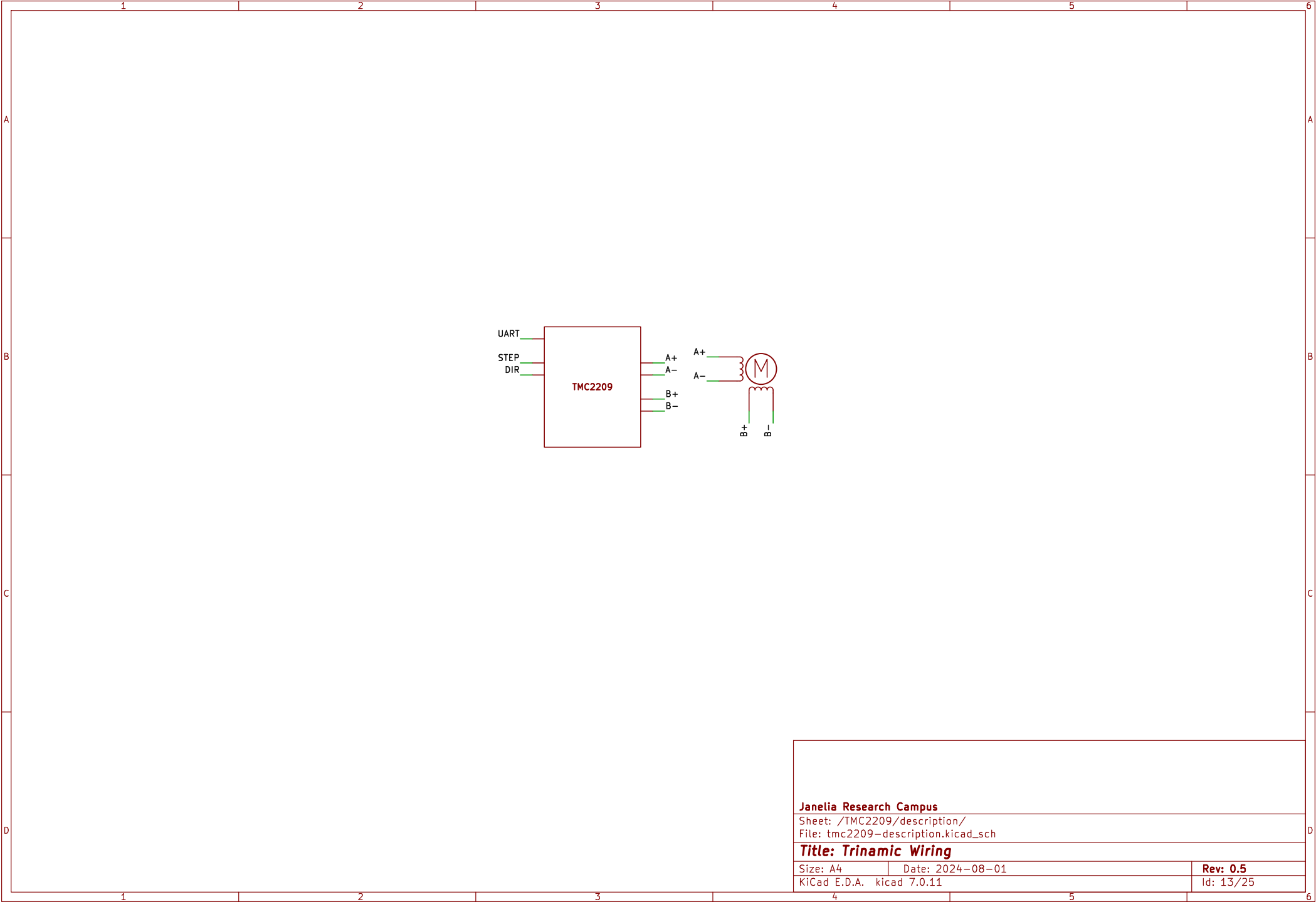
Id: 10/25



Janelia Research Campus		
Sheet: /TMC2209/unidirectional-multiple-uart/		
File: tmc2209-unidirectional-multiple-uart.kicad_sch		
Title: Trinamic Wiring		
Size: A4	Date: 2024-08-01	Rev: 0.5
KiCad E.D.A. kicad 7.0.11	Id: 11/25	



Janelia Research Campus		
Sheet: /TMC2209/bidirectional-coupled-multiple-uart/		
File: tmc2209-bidirectional-coupled-multiple-uart.kicad_sch		
Title: Trinamic Wiring		
Size: A4	Date: 2024-08-01	Rev: 0.5
KiCad E.D.A. kicad 7.0.11		Id: 12/25



Janelia Research Campus

Sheet: /TMC2209/description/  
File: tmc2209-description.kicad\_sch

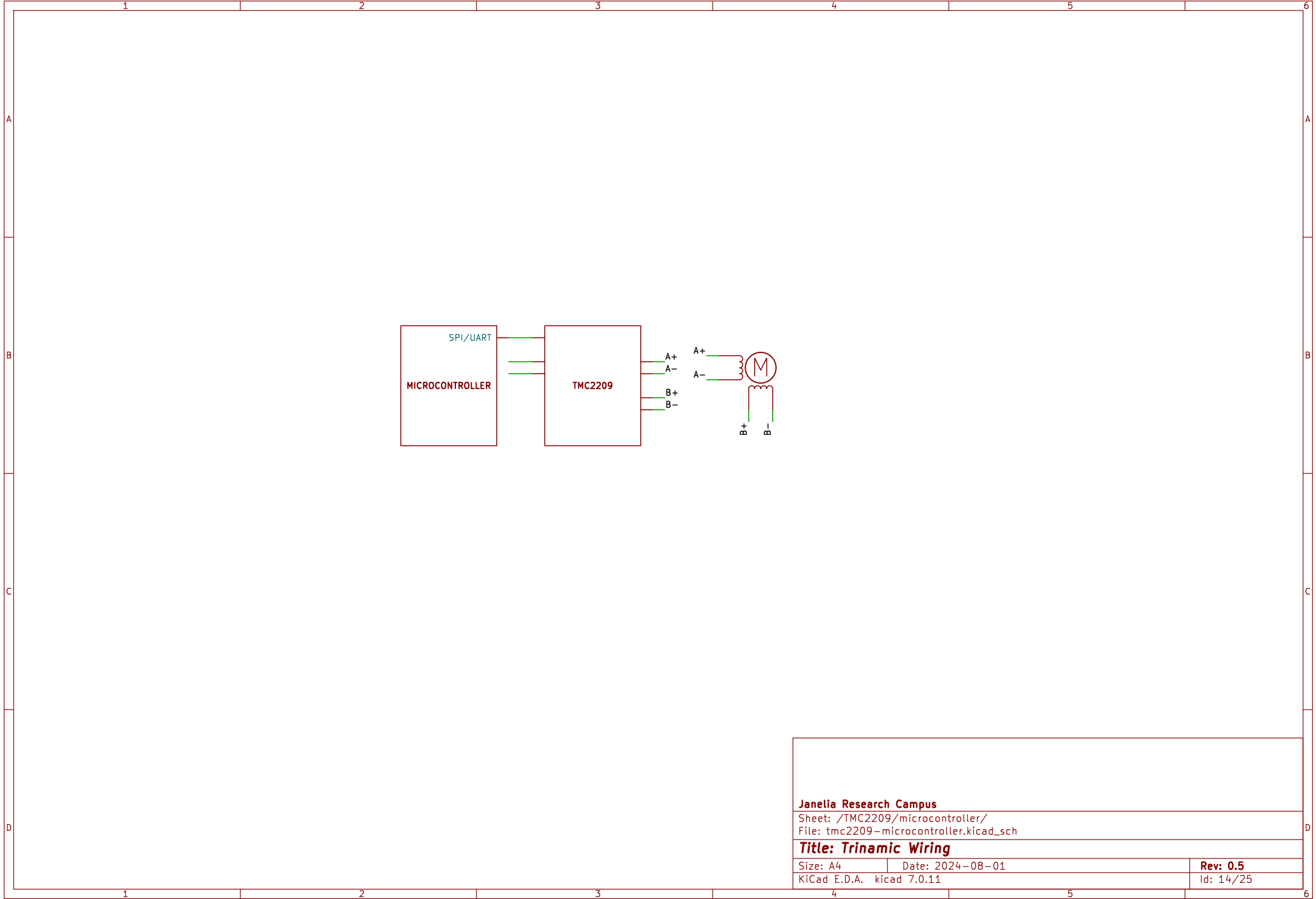
**Title: Trinamic Wiring**

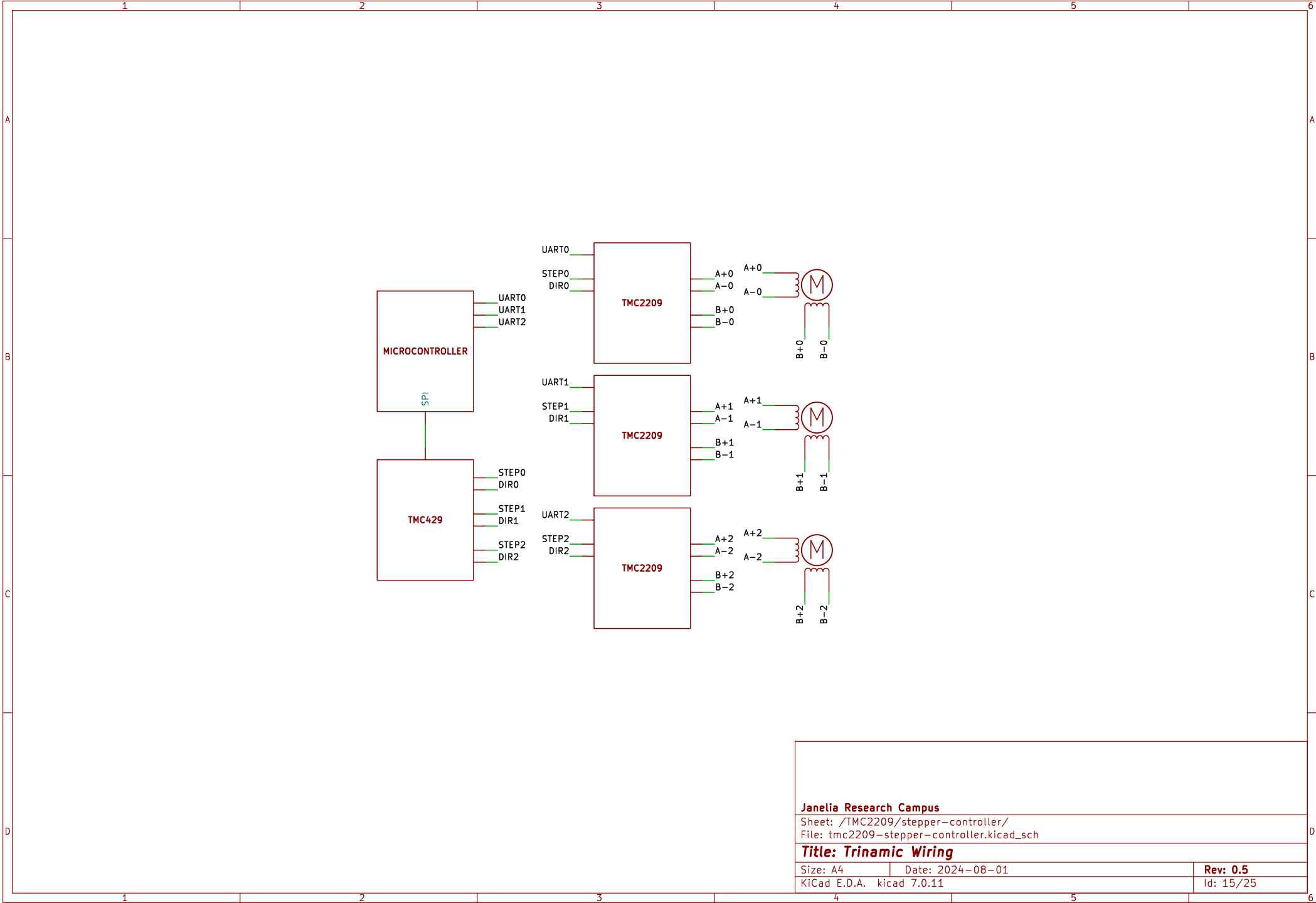
Size: A4 Date: 2024-08-01

KiCad E.D.A. kicad 7.0.11

**Rev: 0.5**

Id: 13/25





Janelia Research Campus

Sheet: /TMC2209/stepper-controller/  
File: tmc2209-stepper-controller.kicad\_sch

**Title: Trinamic Wiring**

Size: A4 Date: 2024-08-01

KiCad E.D.A. kicad 7.0.11

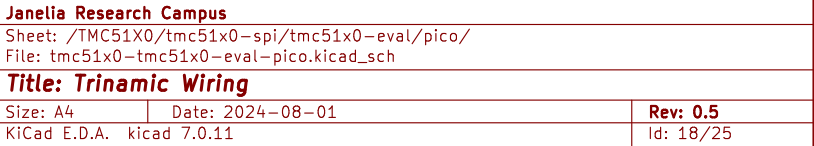
**Rev: 0.5**

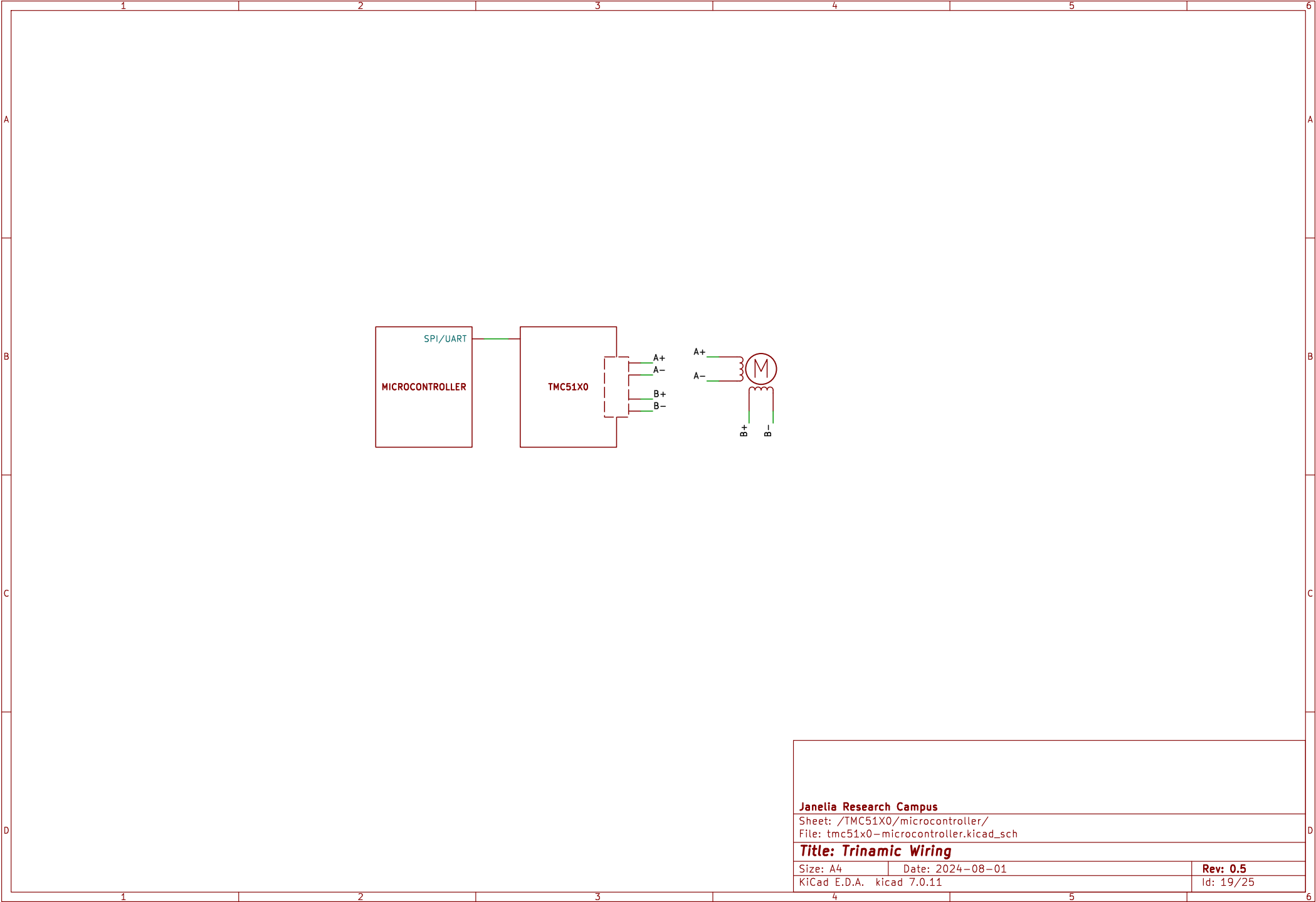
Id: 15/25

1	2	3	4	5	6	
A	<div><div><div>description</div><div></div><div>File: tmc51x0-description.kicad_sch</div></div><div><div>tmc51x0-spi</div><div></div><div>File: tmc51x0-spi.kicad_sch</div></div><div><div>microcontroller</div><div></div><div>File: tmc51x0-microcontroller.kicad_sch</div></div><div><div>tmc51x0-uart</div><div></div><div>File: tmc51x0-uart.kicad_sch</div></div></div>					A
B						B
C						C
D	<div><div>Janelia Research Campus</div><div>Sheet: /TMC51X0/ File: tmc51x0.kicad_sch</div><div>Title: Trinamic Wiring</div><div><div>Size: A4</div><div>Date: 2024-08-01</div><div>Rev: 0.5</div></div><div>KiCad E.D.A. kicad 7.0.11</div><div>Id: 16/25</div></div>					D
1	2	3	4	5	6	









	1	2	3	4	5	6
A						
B						
C						
D						
	1	2	3	4	5	6

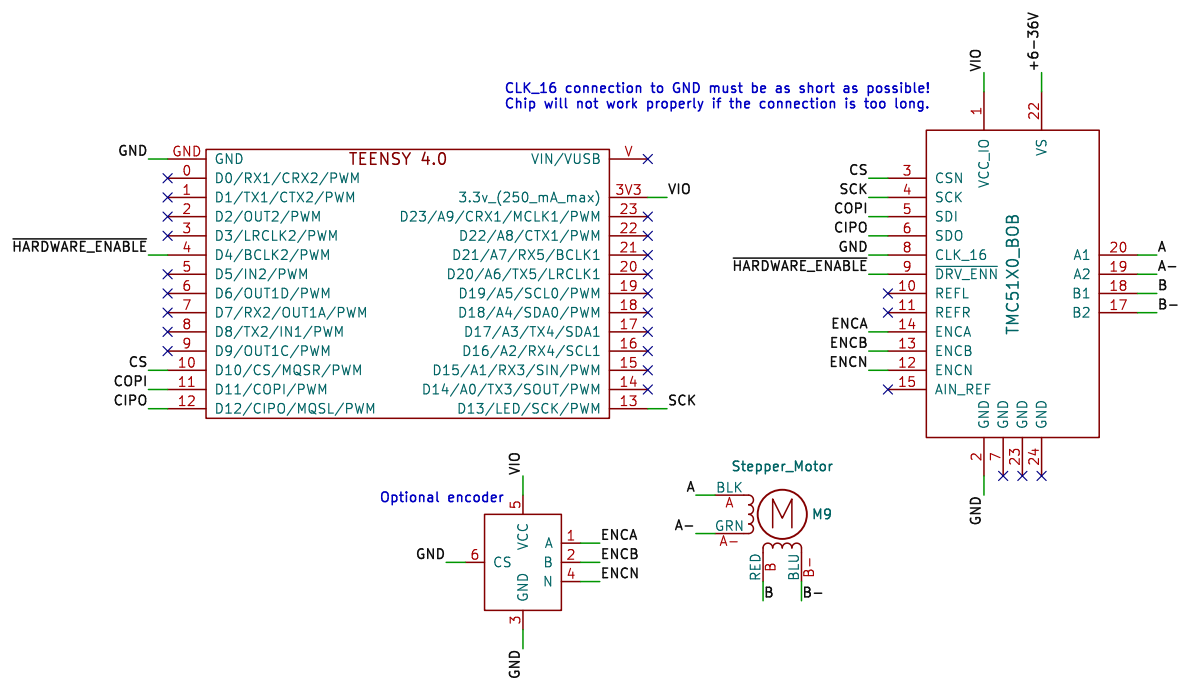
Janelia Research Campus

Sheet: /TMC51X0/tmc51x0-uart/  
File: tmc51x0-uart.kicad\_sch

**Title: Trinamic Wiring**

Size: A4	Date: 2024-08-01	Rev: 0.5
KiCad E.D.A. kicad 7.0.11		Id: 20/25





# Janelia Research Campus

Sheet: /TMC51X0/tmc51x0-spi/tmc51x0-bob/teensy40/  
File: tmc51x0-tmc51x0-bob-teensy40.kicad\_sch

## Title: Trinamic Wiring

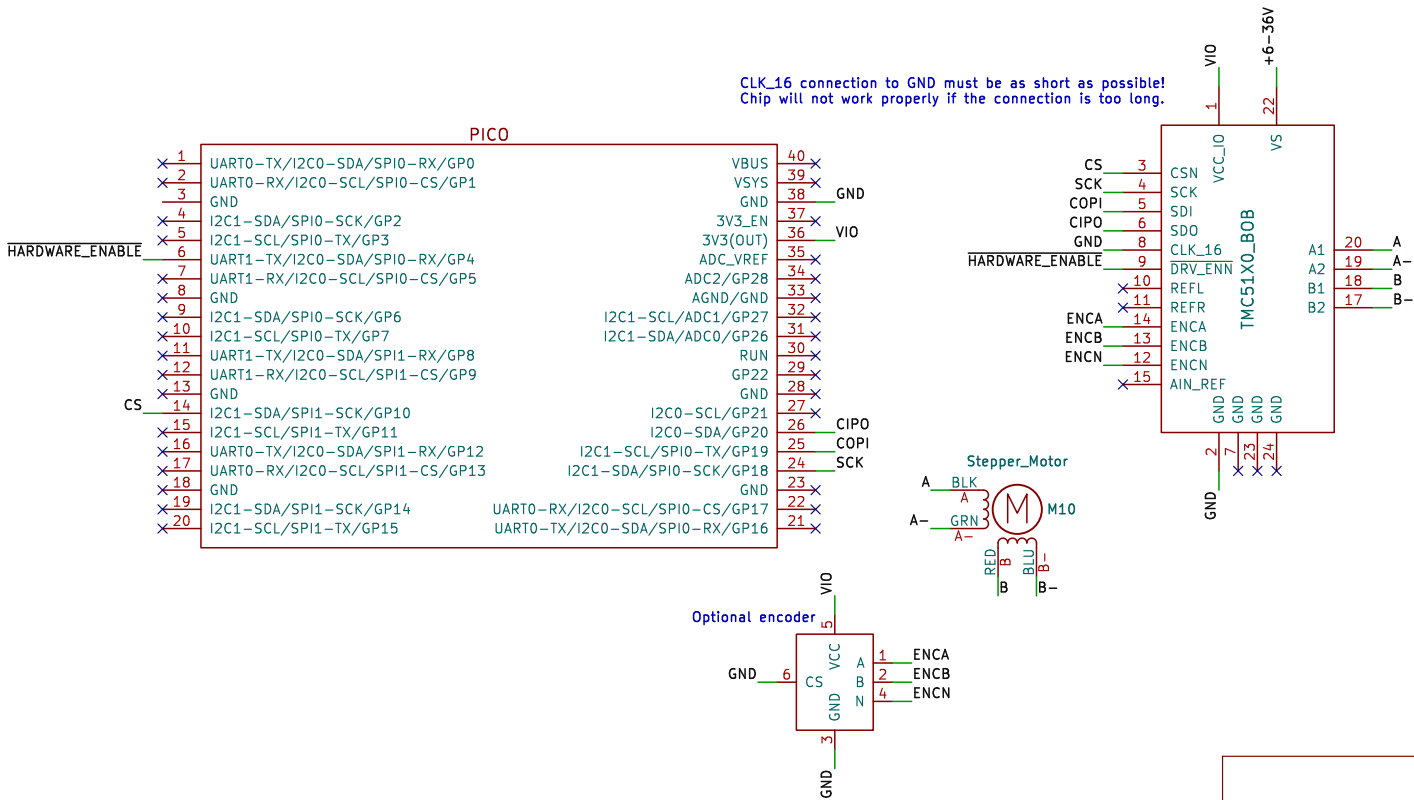
Size: A4 Date: 2024-08-01

KiCad E.D.A. kicad 7.0.11

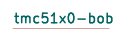
Rev: 0.5

Id: 22/25

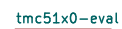
CLK\_16 connection to GND must be as short as possible!  
Chip will not work properly if the connection is too long.



Janelia Research Campus		
Sheet: /TMC51X0/tmc51x0-spi/tmc51x0-bob/pico/		
File: tmc51x0-tmc51x0-bob-pico.kicad_sch		
Title: Trinamic Wiring		
Size: A4	Date: 2024-08-01	Rev: 0.5
KiCad E.D.A. kicad 7.0.11	Id: 23/25	



File: tmc51x0-bob.kicad\_sch



File: tmc51x0-eval.kicad\_sch

<b>Janelia Research Campus</b>		D
Sheet: /TMC51x0/tmc51x0-spi/		
File: tmc51x0-spi.kicad_sch		
<b>Title: Trinamic Wiring</b>		
Size: A4	Date: 2024-08-01	
KiCad E.D.A. kicad 7.0.11	Rev: 0.5	
	Id: 24/25	



