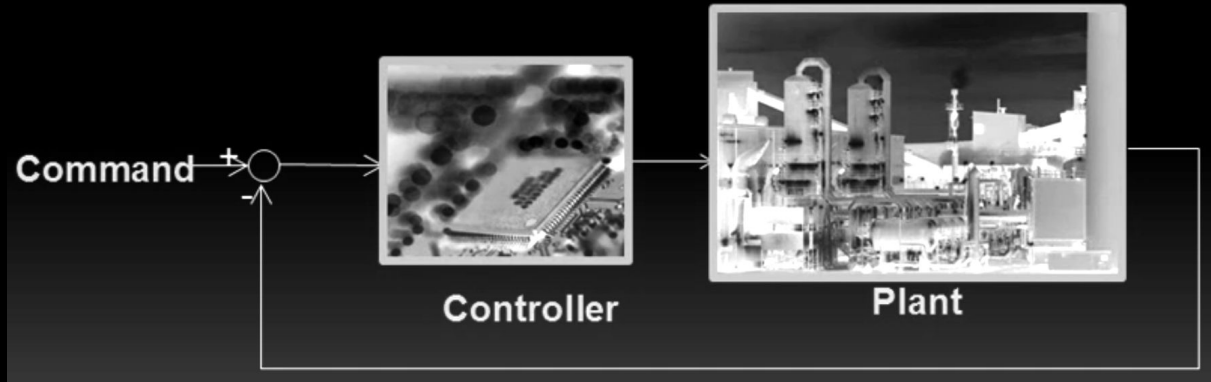


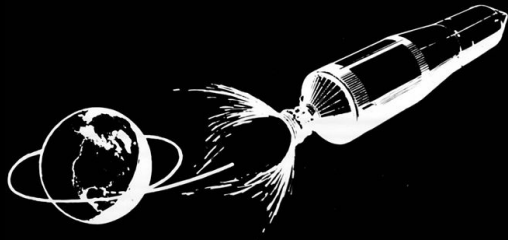
# Data-Driven Control for DC motor

Oraz Ospanov  
Asset Malik  
Andrey Yershov

# What is control theory?



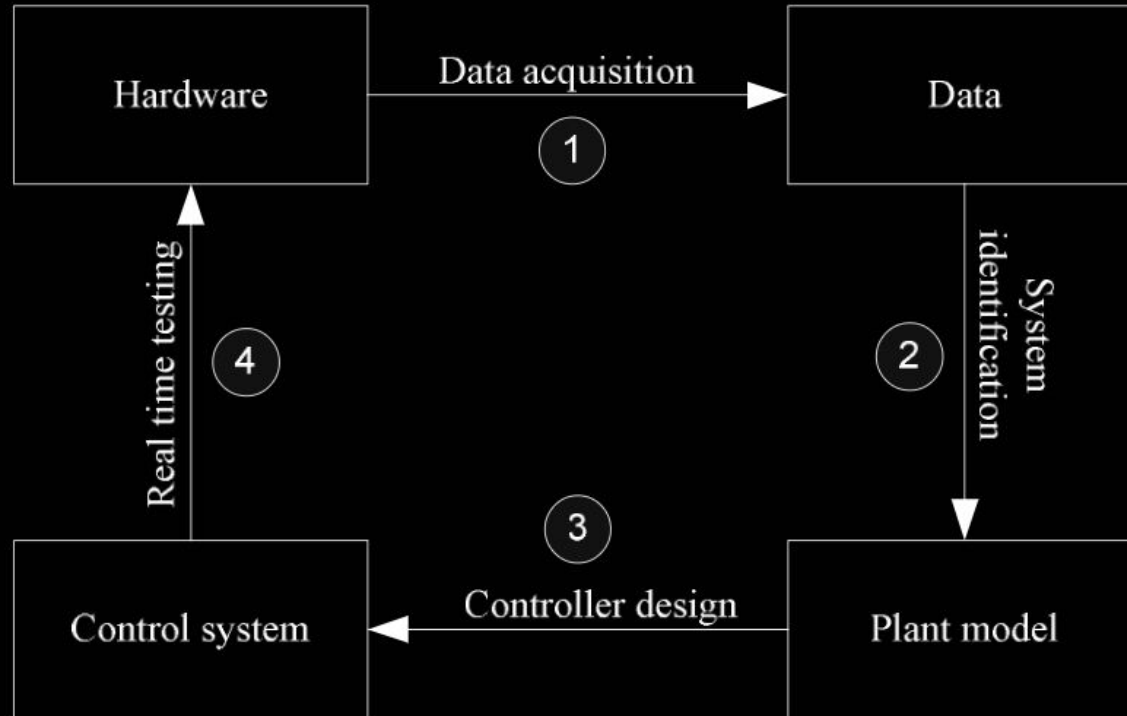
# Motivation for Data-Driven approach



$\neq$



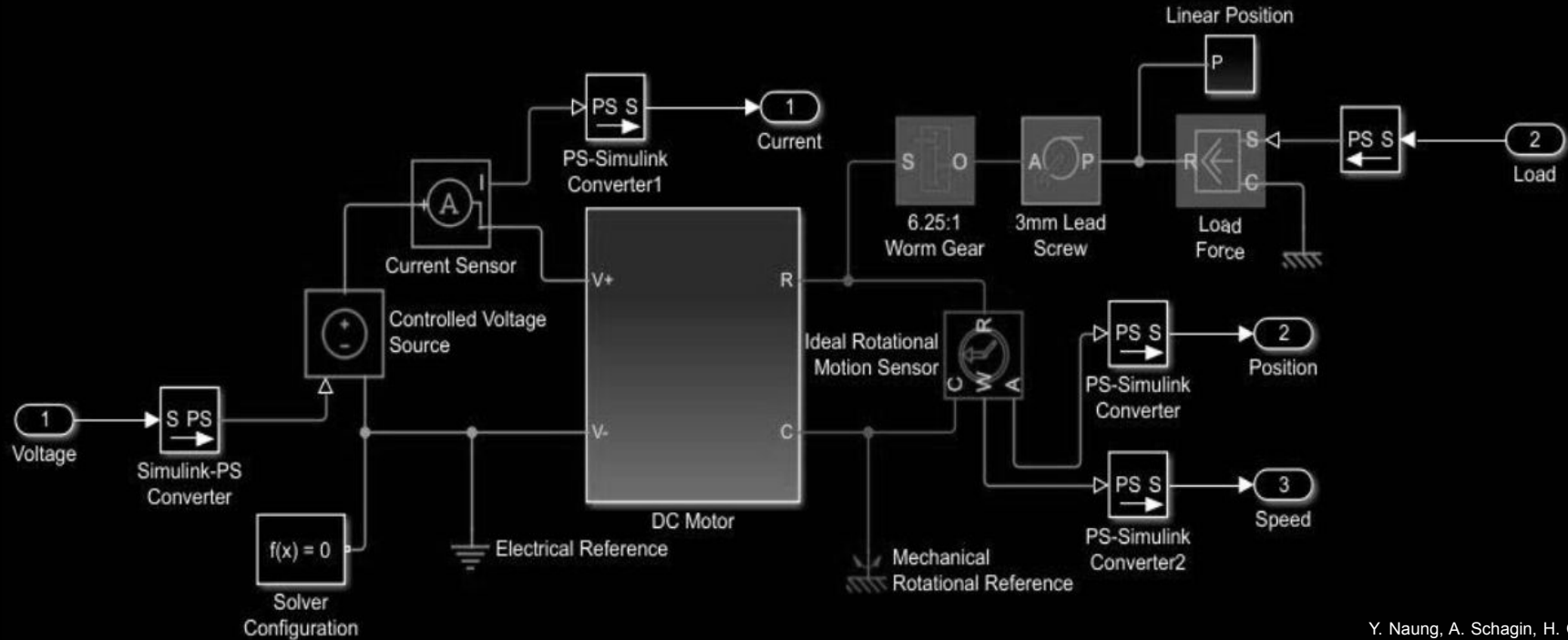
# Data-Driven approach



Y. Naung, A. Schagin, H. Oo, K. Ye, and Z. Khaing, "Implementation of data driven control system of dc motor by using system identification process," in 2018 IEEE Conference of Russian Young Researchers in Electrical and Electronic Engineering

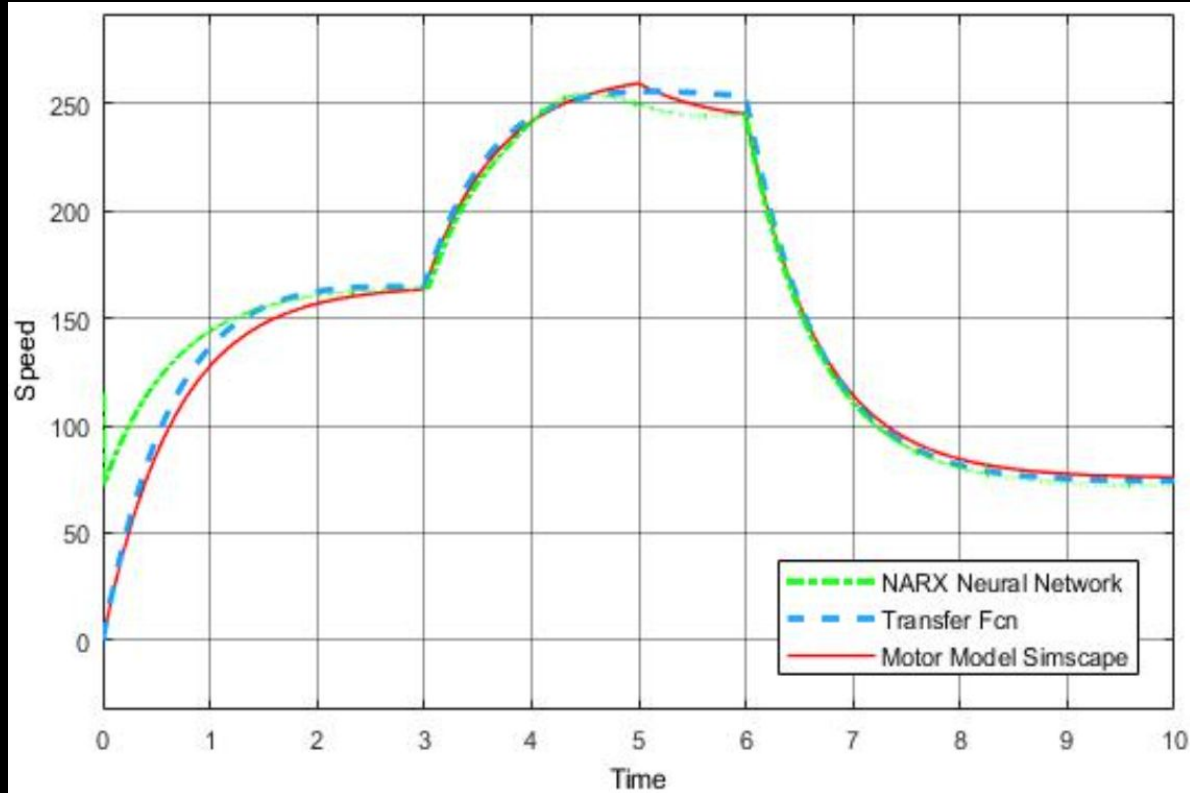
# Related work

## DDC for Simulated DC motors



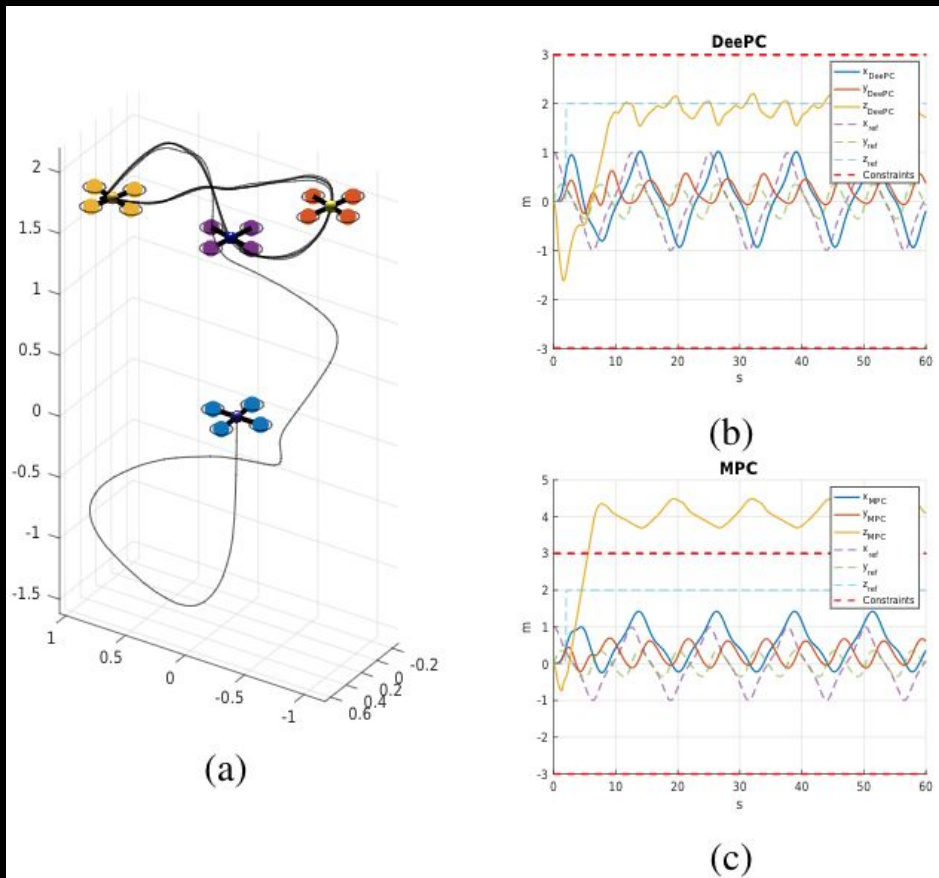
Y. Naung, A. Schagin, H. Oo, K. Ye, and Z. Khaing, "Implementation of data driven control system of dc motor by using system identification process," in 2018 IEEE Conference of Russian Young Researchers in Electrical and Electronic Engineering

# DeePC algorithm for real-time DDC



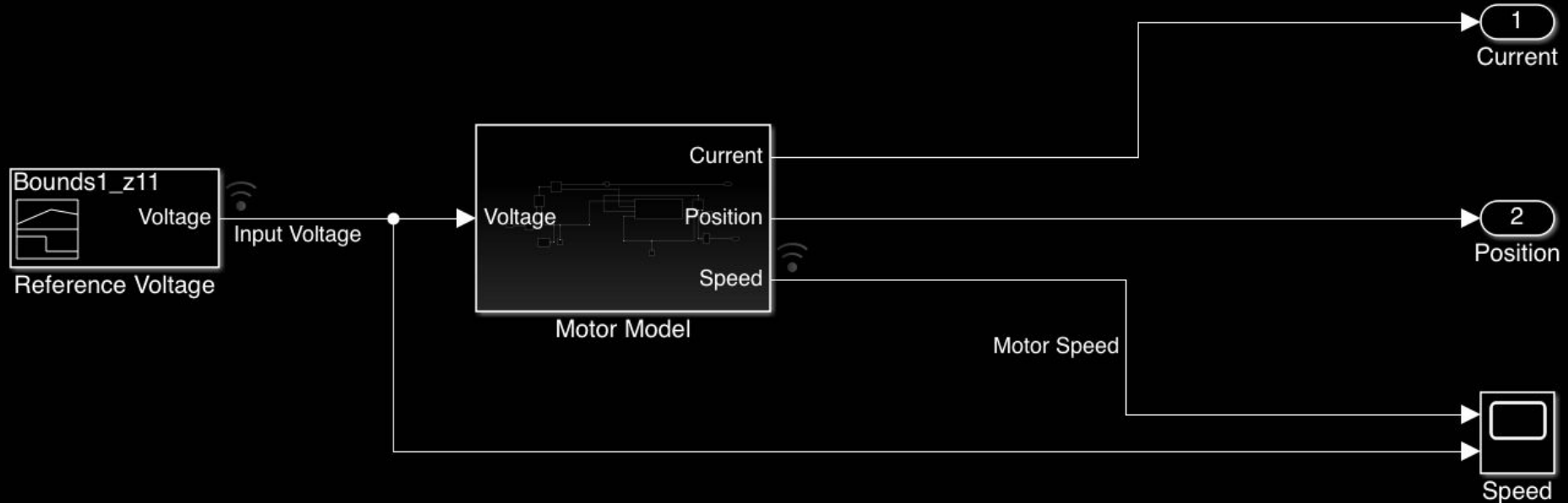
P. G. Carlet, A. Favato, S. Bolognani, and F. D'örfler, "Data-driven predictive current control for synchronous motor drives," in 2020 IEEE Energy Conversion Congress and Exposition (ECCE), pp. 5148–5154, IEEE, 2020.

# Real-Time Data Driven Predictive Control



J. Coulson, J. Lygeros, and F. D'örfler, "Data-enabled predictive control: In the shallows of the deepc," in 2019 18th European Control Conference (ECC) pp. 307–312, IEEE, 2019.

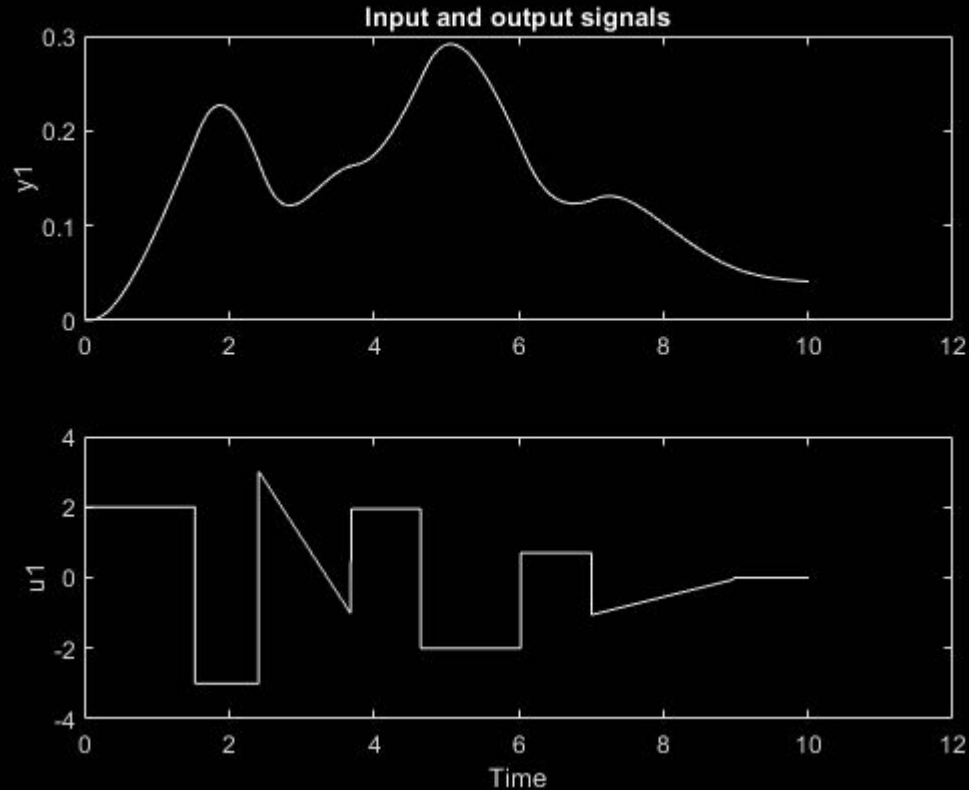
# #1: Model for Data acquisition with MATLAB simulation



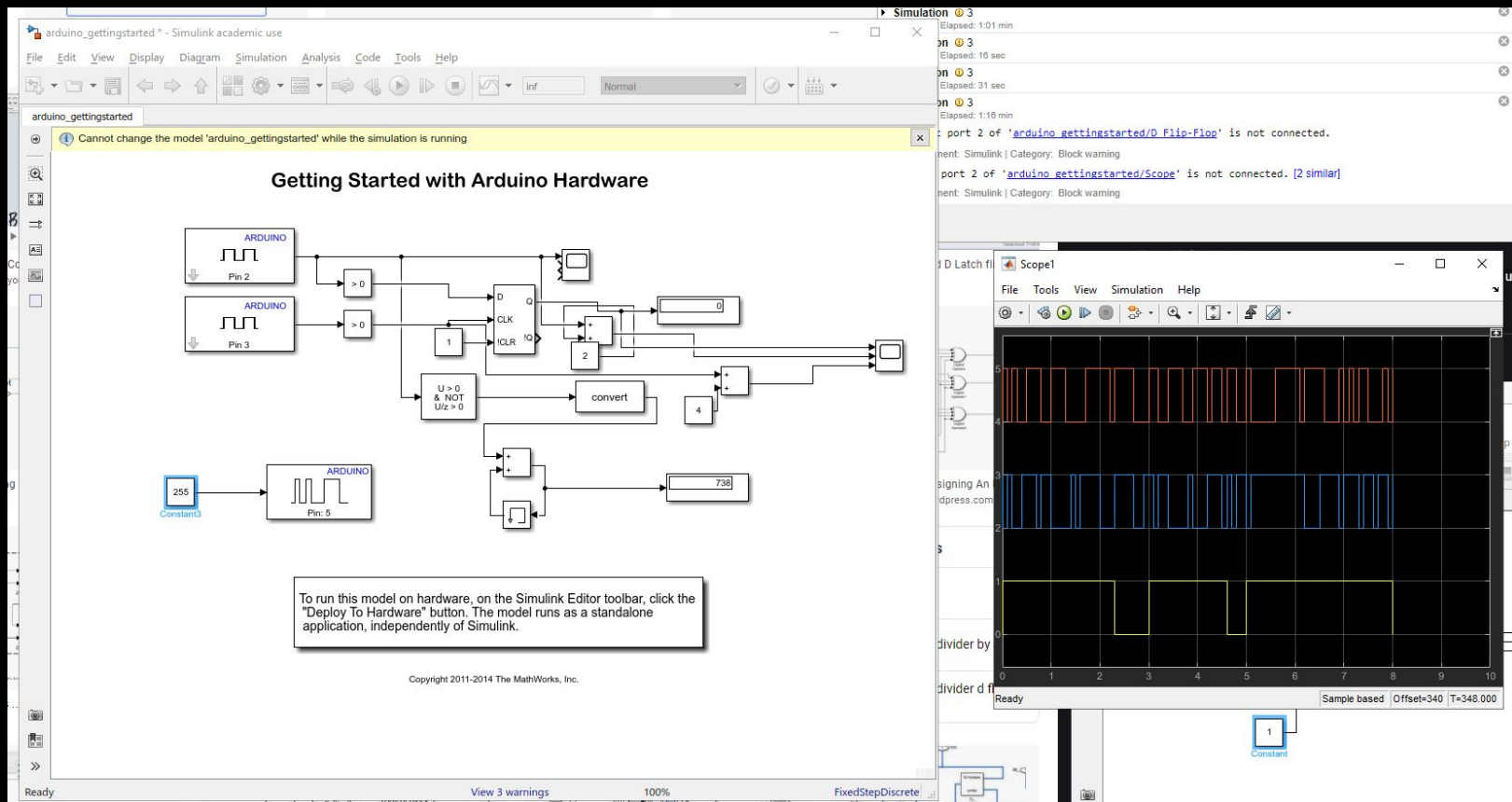


# DC motor model in MATLAB simulation

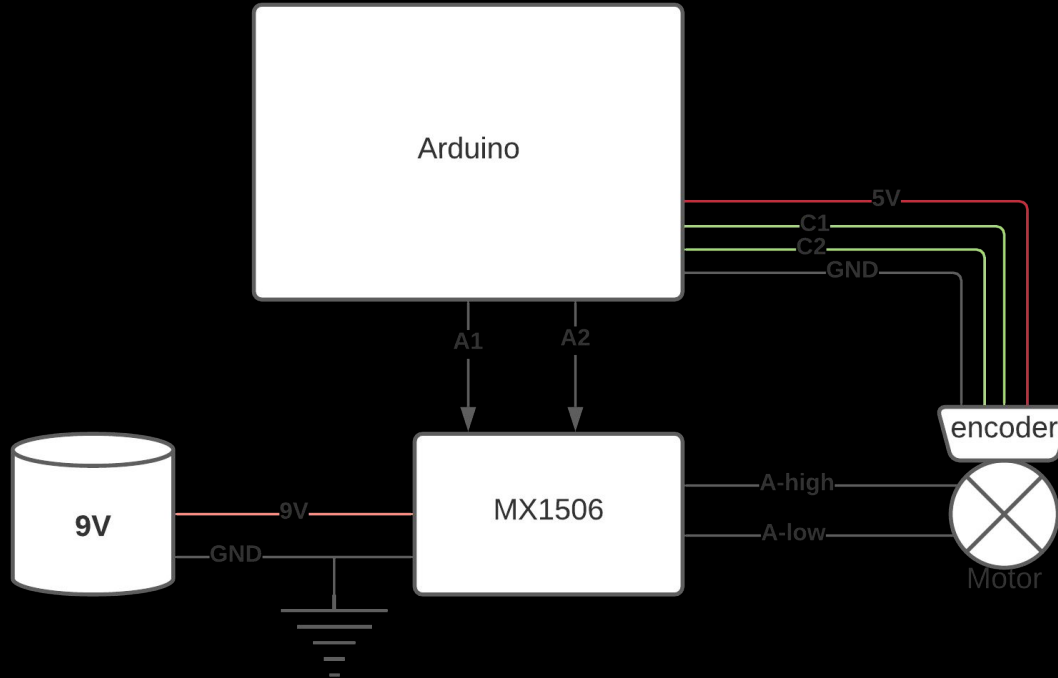
# Sample of data acquisition experiment



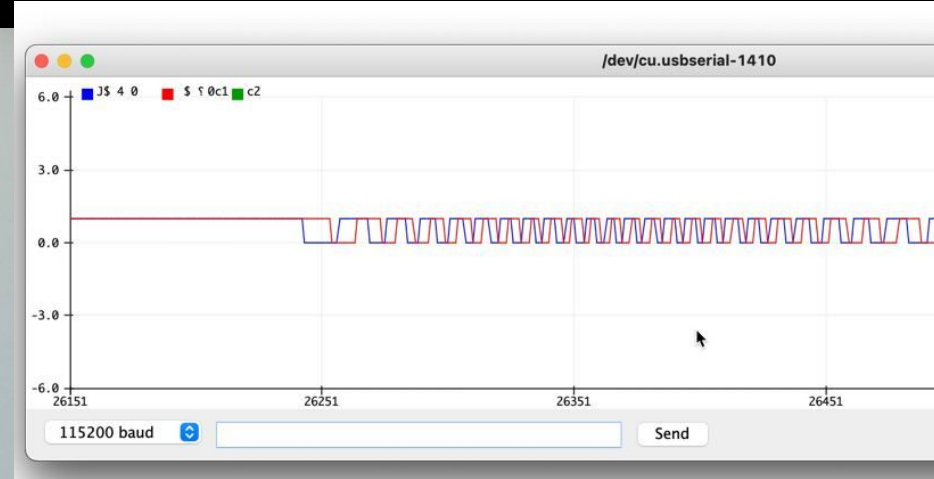
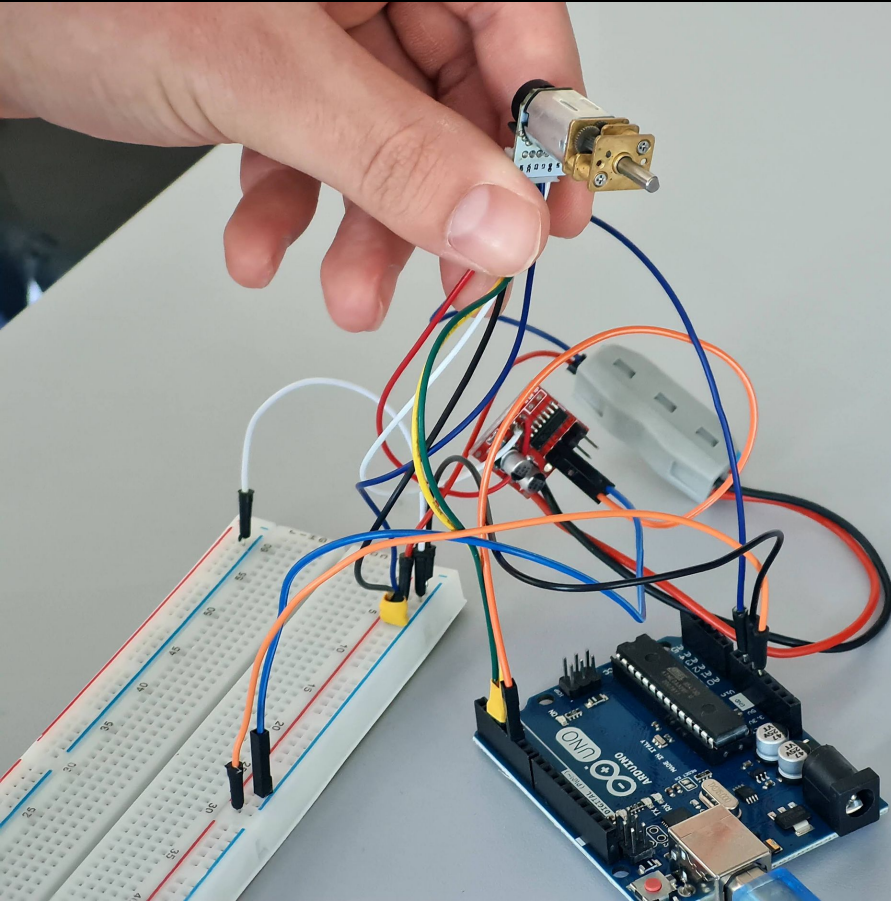
# #2: Arduino Hardware



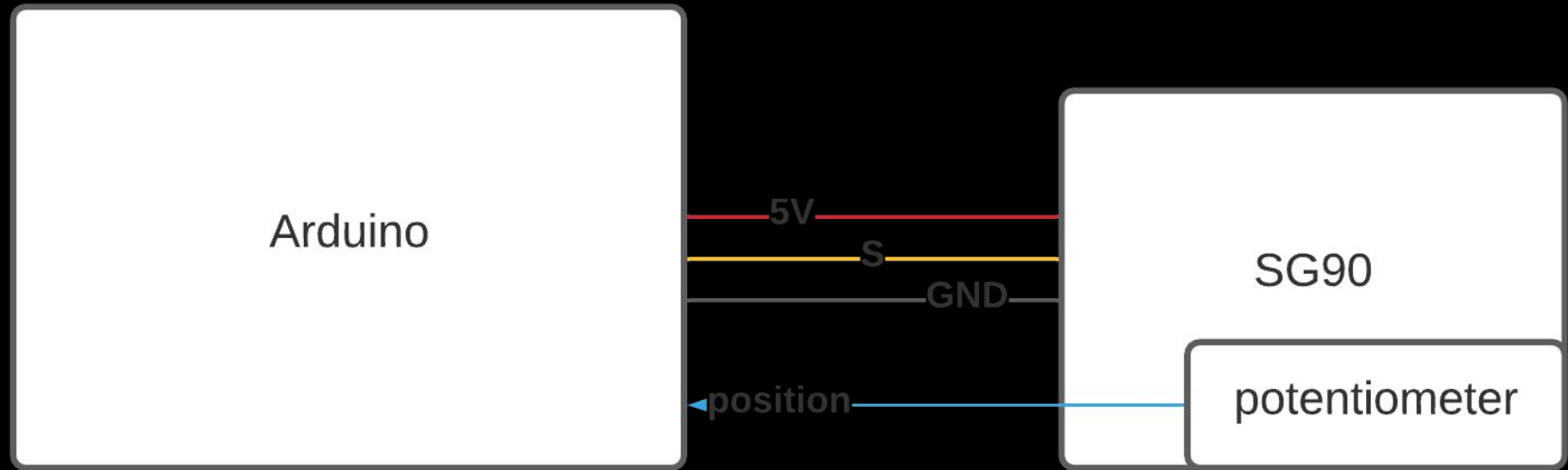
# Arduino Hardware Setup #1

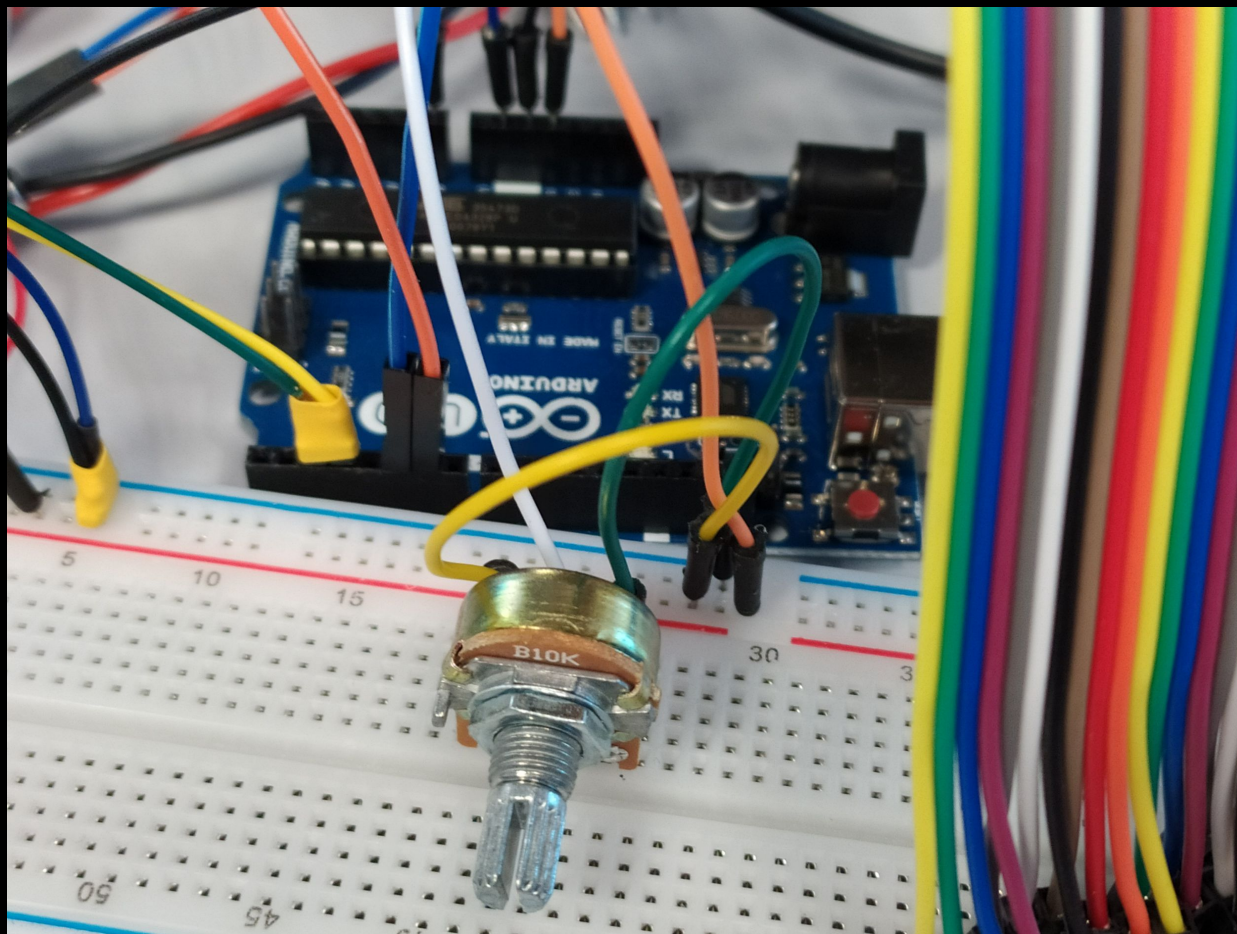


# Arduino Hardware Setup #2



## Arduino Hardware Setup #2





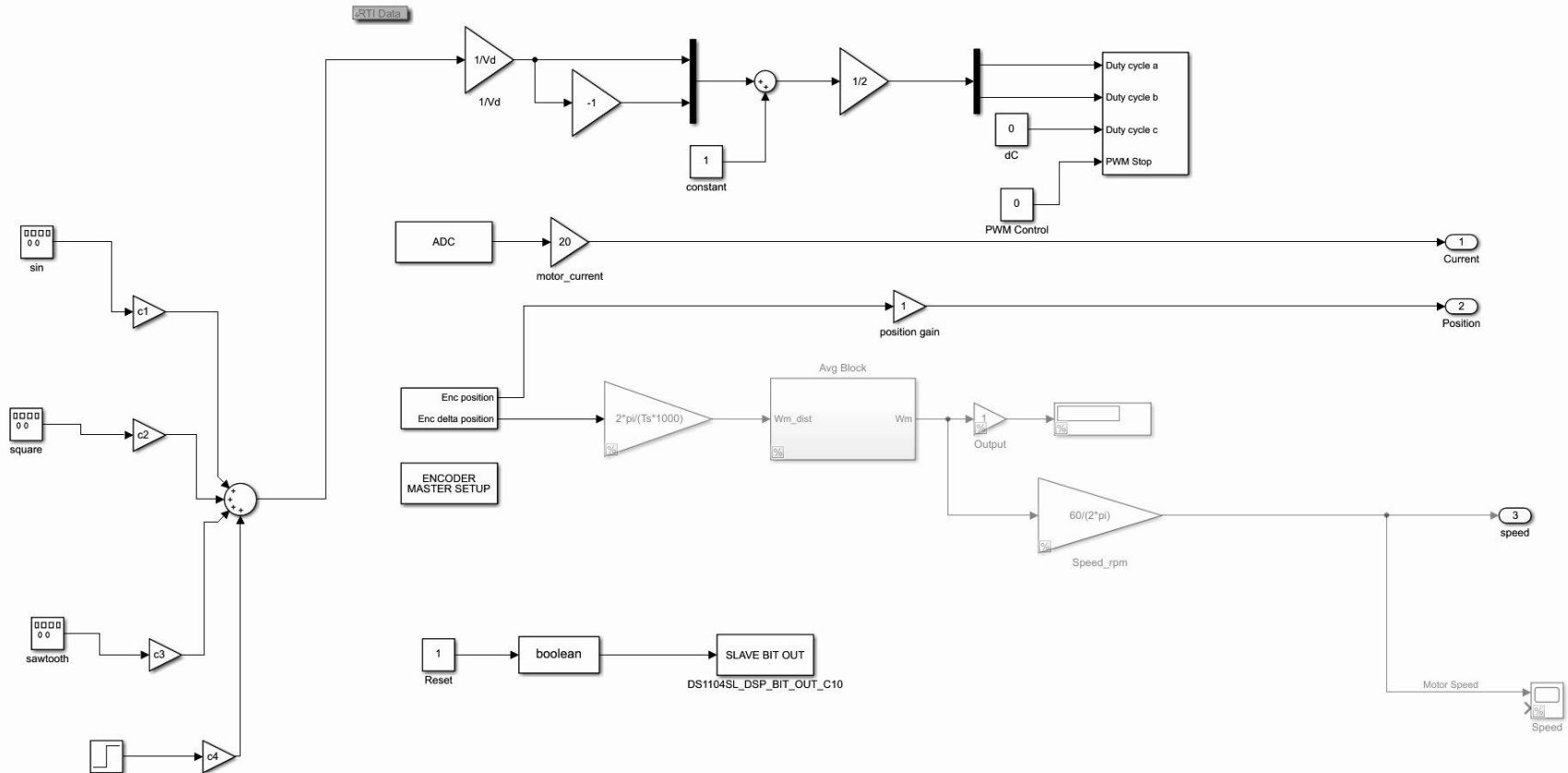


# #3 dSpace Hardware setup

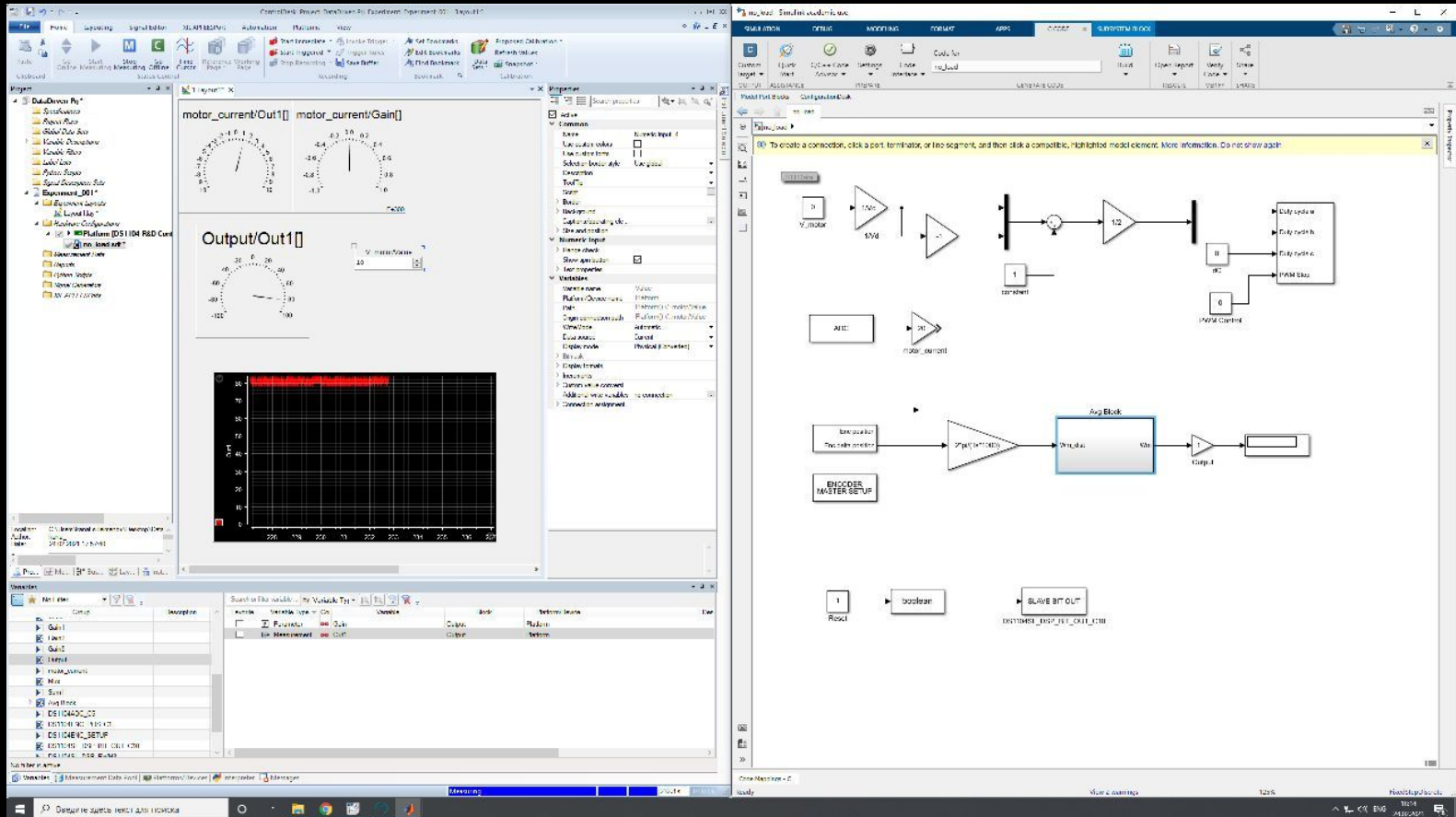




# dSpace control model

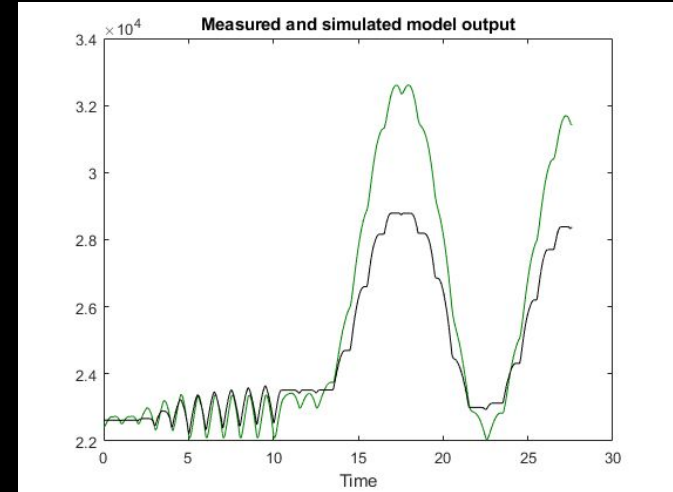
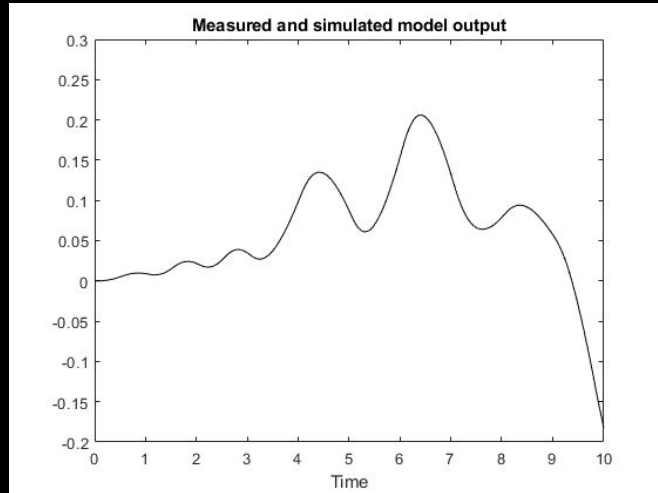


# dSpace Model for data acquisition



# Synthesized plant model Results

- MATLAB simulation - 97% accuracy, linear approximation
- Arduino setup - aliasing issue, further work needed
- dSpace setup - 73% accuracy, linear approximation



# Conclusion and Future Work

- 4 different setups were built for DDC
- The acquired data was analyzed in MATLAB, controllers were synthesized
- **Next up:** fine tune the controller on dSpace
- Try another microcontroller setup
- In case of success, implement reinforcement learning based on microcontroller.