

# Linear time temporal logic

Systems are often usefully modeled as **TRANSITION SYSTEMS**, where

**STATES** represent distinct states of system being modelled and  
**TRANSITIONS** represent possible actual transitions between real-world states.

In addition we may have a number of basic **PROPERTIES** that may hold at states; eg.

- it is an error state
- flag  $t_1$  is set to true
- printer "Tiskaj" is busy ...

## MOTIVATION EXAMPLE : MUTUAL EXCLUSION

**IDEA:**

- We have 2 parallel processes accessing a shared resource
- different processes are not allowed simultaneous access
- a process puts in a result if it wants to access the resource
- it uses the resource only once the request is granted
- once finished, the resource is released for other processes to use

We model this as a transition system:

$$\text{Atoms} = \{n_1, n_2, t_1, t_2, C_1, C_2\}$$

$n$  = process is noncritical

(not accessing or trying to access resource)

$t$  = is trying to access resource

$C$  = is critical (it is accessing the resource)

LTL allows us to express useful properties of transition systems.

The basic idea is to express properties of infinite runs of the system.

Properties of above example:

- Mutual exclusion: the system is never in a state in which both process 1 and process 2 are critical simultaneously.

In LTL:  $G(\neg(C_1 \wedge C_2))$  This is an example of **SAFETY PROPERTY**: the system avoids some specified kind of undesirable state.

Our model (obviously) satisfies mutual exclusion.

- If a process requests the resource then eventually the request is granted.

In LTL:  $G((t_1 \rightarrow F C_1) \wedge (t_2 \rightarrow F C_2))$

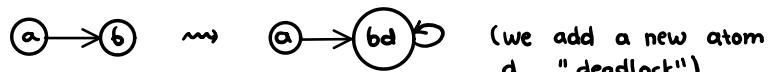
Our model doesn't guarantee this. Eg. consider the run  $s_0 \rightarrow s_1 \rightarrow s_3 \rightarrow s_7$

This is an ex. of **LIVENESS PROPERTY**: Something good eventually happens.

**DEF:** A **TRANSITION SYSTEM**  $M = (S, \rightarrow, L)$  is:

- $S$  is a set (of states)
- $\rightarrow$  is a binary transition relation on  $S$  ( $\rightarrow \subseteq S \times S$ ) satisfying  $\forall s. \exists s'. s \rightarrow s'$
- $L$  is a labeling function  $L: S \rightarrow P(\text{Atoms})$ ; ie.  $L$  assigns to each state  $s \in S$  a subset  $L(s) \subseteq \text{Atoms}$  (Possibly one state is identified as a start state)

This says that we can't get stuck in a state (ie. there is a **DEADLOCK**).  
 Nonetheless we can model deadlock:



# LTL syntax

As with propositional logic, formulas are built over a collection of propositional atoms.

FORMULAS  $\Phi, \Psi$  OF LTL ARE GIVEN BY:

- $P$  - every prop. atom is a formula
- if  $\Phi, \Psi$  are formulas, then so are  $T, \perp, \neg\Phi, \Phi \vee \Psi, \Phi \wedge \Psi, \Phi \rightarrow \Psi$  - so all formulas of prop. logic are formulas of LTL
- $X\Phi$  -  $\Phi$  holds at the next state
- $F\Phi$  -  $\Phi$  holds at some future state
- $G\Phi$  -  $\Phi$  holds Globally at all future states
- $\Phi U \Psi$  -  $\Phi$  holds Until (eventually)  $\Psi$  holds
- $\Phi W \Psi$  -  $\Phi$  holds Weakly until  $\Psi$
- $\Phi R \Psi$  -  $\Phi$  Reaches  $\Psi$

$\Pi$  satisfies  $\Phi$

The semantics of LTL is specified by defining a SATISFACTION RELATION of the form  $\Pi \models \Phi$ , where  $\Pi$  is a path through  $M$  and  $\Phi$  is an LTL formula.

A PATH (or run) through  $M$  is an infinite sequence of transition-related states  $\Pi = s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$

Notation:  $\Pi^i = s_i \rightarrow s_{i+1} \rightarrow s_{i+2} \rightarrow \dots$  "tail"

$\Pi \models p \iff p \in L(s_i)$

$\Pi \models \Phi \wedge \Psi \iff \Pi \models \Phi$  and  $\Pi \models \Psi$  and similar for the other propositional connectives

$\Pi \models X\Phi \iff \Pi^2 \models \Phi$

$\Pi \models F\Phi \iff \exists i \geq 1. \Pi^i \models \Phi$

$\Pi \models G\Phi \iff \forall i \geq 1. \Pi^i \models \Phi$

$\Pi \models \Phi U \Psi \iff \exists i \geq 1 \exists j \geq 1. \Pi^i \models \Psi$  and  $\Pi^j \models \Phi$  for all  $j \in \{1, \dots, i-1\}$

$\Pi \models \Phi W \Psi \iff$  either  $\exists i \geq 1 \dots$  as for until... }  $\Phi U \Psi \vee G\Phi$   
or  $\forall i \geq 1. \Pi^i \models \Phi$

$\Pi \models \Phi R \Psi \iff$  either  $\exists i \geq 1. \Pi^i \models \Phi$  and  $\forall j=1, \dots, i. \Pi^j \models \Psi$  }  $\gamma(\gamma\Phi U \gamma\Psi)$   
or  $\forall k \geq 1. \Pi^k \models \Psi$

# LTL model checking

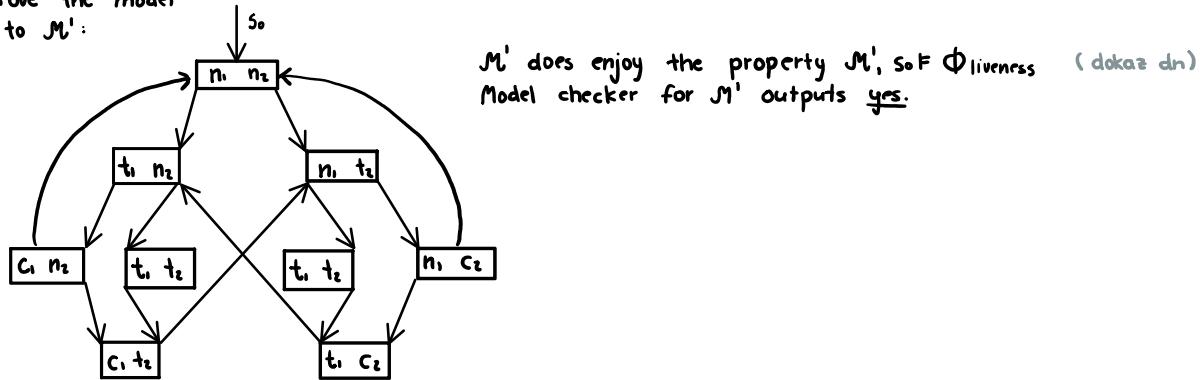
$M, s \models \Phi \iff \forall \text{run } \Pi = s_1 \rightarrow s_2 \rightarrow \dots \text{ through } M \text{ with } s_1 = s, \text{ we have } \Pi \models \Phi$

Suppose we had designed earlier transition system as example protocol for mutual exclusion.  
We could test the model for liveness by asking "is it the case that every run starting from  
so satisfies  $\Phi_{\text{liveness}} := G(t_1 \rightarrow F c_1) \wedge (t_2 \rightarrow F c_2)$ ?"  
Equivalently does  $M, s_0 \models \Phi_{\text{liveness}}$ ;  $M$  our mutual exclusion model

We submit this to a MODEL CHECKER.

The model checker gives no and it gives a counter example run, eg.  $s_0 \rightarrow s_1 \rightarrow s_6 \xrightarrow{\quad} s_7$ .

Improve the model  
 $M$  to  $M'$ :



An alternative to reducing the system: keep same system, but assume that it behaves in a fair way.  
FAIRNESS PROPERTY:

$$\Phi_{\text{fair}} := GF(t_1 \wedge t_2) \rightarrow (GF(t_1 \wedge t_2 \wedge X c_1) \wedge GF(t_1 \wedge t_2 \wedge X c_2))$$

To test a property  $\Psi$  of  $M$  under our fairness assumption we test  $M, s_0 \models \Phi_{\text{fair}} \rightarrow \Psi$ .  
In particular, it does hold  $M, s_0 \models \Phi_{\text{fair}} \rightarrow \Phi_{\text{liveness}}$ !

## LTL MODEL CHECKING PROBLEM:

This is a nontrivial problem.

INPUT: • transition system  $M$  (finite)

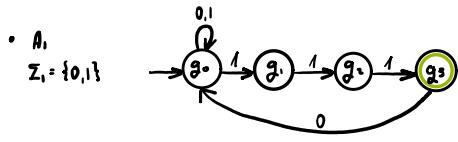
• start state  $s \in M$

• LTL formula  $\Phi$

OUTPUT: yes if  $M, s \models \Phi$

no otherwise, together with a path  $\Pi$  through  $M$  starting at  $s$ , for which  $\Pi \not\models \Phi$  ( $\equiv \Pi \models \neg \Phi$ )

# Nondeterministic Büchi automata



We run an NBA on an infinite word, e.g.

0 1 1 1 0 0 1 1 1 1 0 0 0 1 1 1 1 1 0 1 1 ...

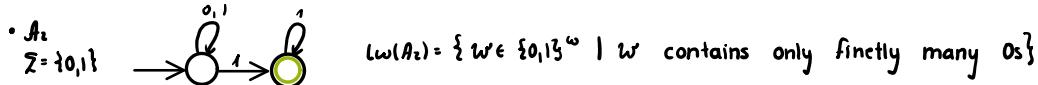
$g_0 g_0 g_1 g_1 g_2 g_0 g_0 g_1 g_2 g_3 g_0 g_0 g_1 g_2 g_3 g_0 \dots$

An NBA accepts an infinite word if there exists a run for that word which goes through a final state  $\omega$ -krat.

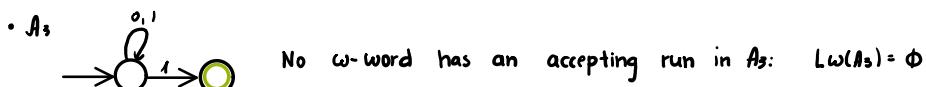
Eg.  $(1110)^\omega := 11101110110\dots$  is accepted

$1^\omega := 111\dots$  and  $0^\omega := 000\dots$  are not accepted.

The  $\omega$ -language of the automata  $A_1$  is  $L_w(A_1) = \{w \in \{0,1\}^\omega \mid w \text{ contains infinitely many substrings } 1110\}$



$L_w(A_2) = \{w \in \{0,1\}^\omega \mid w \text{ contains only finitely many } 0s\}$



No  $\omega$ -word has an accepting run in  $A_3$ :  $L_w(A_3) = \emptyset$

A **NONDETERMINISTIC BÜCHI AUTOMATA** over an alphabet  $\Sigma$  is  $(Q, I, \Delta, F)$  where:

$Q$  = finite set of states

$I \subseteq Q$  = set of initial states

$\Delta \subseteq Q \times \Sigma \times Q$  = set of transitions

$F \subseteq Q$  = set of final states

A  $\omega$ -word  $a_0 a_1 a_2 \dots \in \Sigma^\omega$  is **ACCEPTED** by the automata if there exists a path  $g_0 \xrightarrow{a_0} g_1 \xrightarrow{a_1} g_2 \xrightarrow{a_2} \dots$  in  $\Delta$  such that  $g_0 \in I$  and  $g_i \in F$  for infinitely many  $i$ .

## TESTING ON NBA FOR EMPTINESS

**PROPOSITION:** Let  $A$  be an NBA. Then  $L_w(A) \neq \emptyset$  iff there exists a path in  $A$  (a lasso) of the form

$g_0 \rightarrow \dots \rightarrow g_k \rightarrow \dots$ , where  $g_0 \in I$   
 $g_k \in F$

## $\omega$ -REGULAR LANGUAGES

We call sets  $L \subseteq \Sigma^\omega$   $\omega$ -languages.

An  $\omega$ -language is said to be  $\omega$ -regular if there exists a NBA  $A$  s.t.  $L = L_w(A)$ .

## THEOREM: CLOSURE PROPERTIES OF $\omega$ -REGULAR LANGUAGES

If  $L_1$  and  $L_2$  are  $\omega$ -regular then so are

- $L_1 \cup L_2$  (dn)
- $L_1 \cap L_2$  (dn, prove using GNBA's)
- $L^\omega - L_1$  (a deep result due to Büchi)

## LTL MODEL CHECKING PROBLEM

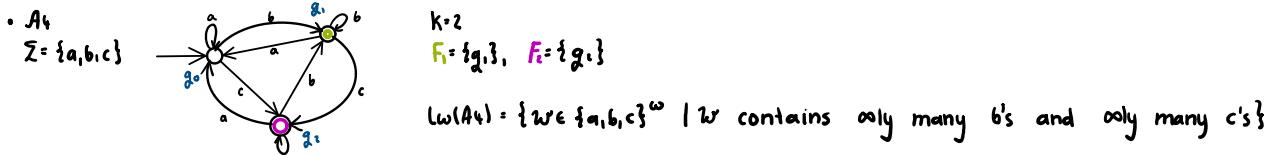
We have a transition system  $M$ , LTL property  $\Phi$ , some start state  $s_1$ .

Question: Does  $s_1 \models \Phi$ ? (Does every infinite run  $\pi$  starting from  $s_1$  satisfy  $\Phi$ ?)  $\rightsquigarrow$  Yes or No, together with a lasso  $\pi$  for which  $\pi \not\models \Phi$ .

# Generalized NBAs

**GENERALISED NBA** is  $(Q, I, \Delta, \{F_j\}_{1 \leq j \leq k})$ , where  $\forall 1 \leq j \leq k, k \geq 1. F_j \subseteq Q$ .

An  $\omega$ -word  $a_1 a_2 a_3 \dots$  is accepted if there is a run  $g_0 \xrightarrow{a_1} g_1 \xrightarrow{a_2} g_2 \xrightarrow{a_3} \dots$  with  $g_0 \in I$  and  $\forall j. \forall i, j \leq k. g_i \in F_j$  for only many  $i$ .



**PROPOSITION:** TFAE for  $L \subseteq \Sigma^\omega$ .

- 1.)  $\exists$  NBA  $A \exists: L = Lw(A)$
- 2.)  $\exists$  GNBAs  $A \exists: L = Lw(A)$

**PROOF:** 1  $\Rightarrow$  2 easy, 2  $\Rightarrow$  1 dn

## TRACE LANGUAGE OF AN LTL FORMULA

Consider two runs (paths)  $\Pi = s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  in  $M$  and  $\Pi' = s'_1 \rightarrow s'_2 \rightarrow s'_3 \rightarrow \dots$  in  $M'$  two (potentially) different transition systems

Suppose also that  $\forall n. L(s_n) = L(s'_n)$ . Then it follows that  $\forall$  LTL formulas  $\phi: \Pi^n \models \phi \Leftrightarrow (\Pi')^n \models \phi \quad \forall n$ . So whether or not a path  $\Pi$  satisfies a formula  $\phi$  depends only on the TRACE of the path.

$$\text{trace}(\Pi) := n \mapsto L(s_n)$$

Or equivalently, we view trace( $\Pi$ ) as  $\omega$ -word over alphabet  $\mathcal{P}(\text{Atoms}) : L(s_1) \ L(s_2) \ L(s_3) \ \dots$

$\text{Traces}(\phi) := \{A, A_1 A_2 \dots \mid A, A_1 A_2 \dots \text{ can arise as trace}(\Pi) \text{ for some } \Pi \exists: \Pi \models \phi\}$

Given  $\phi$ , we define a GNBAs  $A_\phi \exists: Lw(A_\phi) = \text{Traces}(\phi)$  so language Traces( $\phi$ ) is  $\omega$ -regular

To simplify matters, assume  $\phi$  uses only  $\neg, V, T, X, U$ . Our goal is to construct  $A_\phi$ .

DN: Show that LTL formula is equivalent to one involving the above connectives only.

$$F\phi = TU\phi, G\phi = \neg F \neg \phi$$

States will be certain sets of formulas.

**COMPLEMENTED SUBFORMULAS** of  $\phi$  are defined by:

- $\phi \in CS(\phi)$
- $\psi \in CS(\phi)$  and it is not a negation  $\Rightarrow \neg \psi \in CS(\phi)$
- $\neg \psi \in CS(\phi) \Rightarrow \psi \in CS(\phi)$
- $X\psi \in CS(\phi) \Rightarrow \psi \in CS(\phi)$
- $\psi \vee \psi' \in CS(\phi)$  or  $\psi \vee \psi' \in CS(\phi) \Rightarrow \psi, \psi' \in CS(\phi)$

Ex.  $CS(a \cup b) = \{a \cup b, \neg(a \cup b), a, b, \neg a, \neg b\}$

A subset  $S \subseteq CS(\phi)$  is **ELEMENTARY** if

- $\forall \psi \in CS(\phi)$  either  $\neg \psi \in S$  or  $\psi \in S$ , but not both
- $\psi \vee \psi' \in S \Rightarrow \psi \in S$  or  $\psi' \in S$
- if  $T \in CS(\phi) \Rightarrow T \in S$
- $\psi \in S$  and  $\psi \vee \psi' \in CS(\phi) \Rightarrow \psi \vee \psi' \in S$
- $\psi \in S$  and  $\psi' \in S \Rightarrow \psi \vee \psi' \in S$

Ex. elementary subsets  $CS(a \cup b)$  are:

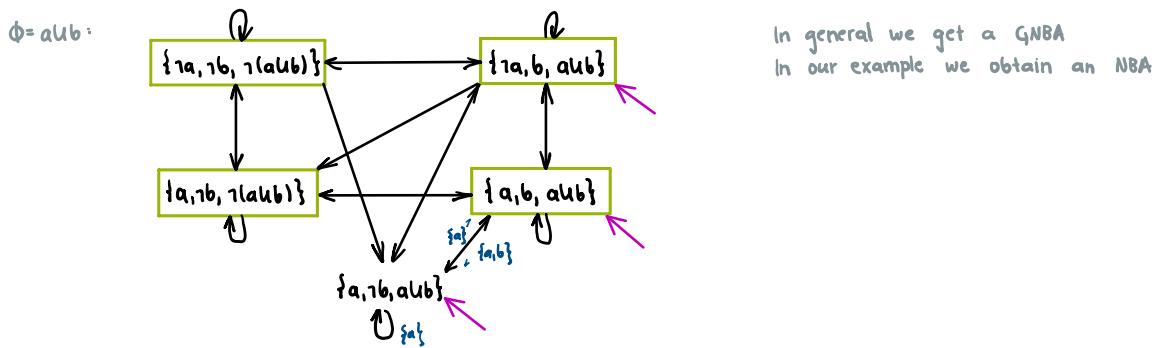
- $\{a, b, a \cup b\}$
- $\{\neg a, b, a \cup b\}$
- $\{a, \neg b, a \cup b\}$
- $\{\neg a, \neg b, a \cup b\}$
- $\{\neg a, b, \neg(a \cup b)\}$
- $\{a, \neg b, \neg(a \cup b)\}$
- $\{\neg a, \neg b, \neg(a \cup b)\}$

States of GNBAs are elementary subsets of  $CS(\phi)$

$S \xrightarrow{A} S' \Leftrightarrow A = SA$  Atoms and  $X\psi \in S \Rightarrow \psi \in S'$   
and  $\neg X\psi \in S \Rightarrow \neg \psi \in S'$   
and  $(\psi \vee \psi' \in S \text{ and } \psi' \in S) \Rightarrow \psi \vee \psi' \in S'$   
and  $(\neg(\psi \vee \psi') \in S \text{ and } \psi \in S) \Rightarrow \neg(\psi \vee \psi') \in S'$

$$I = \{s \mid \phi \in s\}$$

Let  $\psi_1 \cup \psi'_1, \dots, \psi_k \cup \psi'_k$  be all until formulas in  $cs(\phi)$   
 For every such formula  $\psi_j \cup \psi'_j$  ( $1 \leq j \leq k$ ):  $T_j = \{s \mid \psi_j \in s \text{ or } \gamma(\psi_j \cup \psi'_j) \in s\}$



### LTL MODEL CHECKING - GENERAL ALGORITHM

INPUT:  $M, s, \Phi$

QUESTION: does  $M, s \models \Phi$  hold?

STEP 1: We construct a GNBA  $A^{\gamma\Phi}$ . Convert  $A^{\gamma\Phi}$  to an equivalent NBA  $A^{\gamma\Phi}$ .  
 An accepting run in  $A^{\gamma\Phi}$  corresponds to a trace  $a_0 a_1 \dots \exists: a_0 a_1 \dots \in \text{Traces}(\Phi)$

STEP 2: Construct a PRODUCT NBA  $A^{\gamma\Phi} \otimes M$ .

Accepting runs in the product NBA correspond to paths through  $M$  starting from  $s$  along which  $\gamma\Phi$  holds,  
 i.e. paths  $\pi$  from  $s$ :  $\pi \models \gamma\Phi$ .

STEP 3: Test whether  $Lw(A^{\gamma\Phi} \otimes M) = \emptyset$  (use emptiness testing for NBAs)

- if it is empty  $\rightarrow$  return yes,  $M, s \models \Phi$
- if it is not empty  $\rightarrow$  return no, use the lasso path given by emptiness test to extract a lasso  
 $s = s_0 \rightarrow s_1 \rightarrow \dots \rightarrow s_k \rightarrow \dots$  in  $M$ .

This lasso path  $\pi$  satisfies  
 $\pi \models \gamma\Phi$ .