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5.1 SOLUTIONS Notes: Exercises 1–6 reinforce the definitions of eigenvalues and eigenvectors. The subsection on eigenvectors and difference equations, along with Exercises 33 and 34, refers to the chapter introductory example and anticipates discussions of dynamical systems in Sections 5.2 and 5.6. 1.

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360 CHAPTER 6 † Orthogonality and Least Squares ... is a linear transformation. To confirm this, let  $x$  and  $y$  be in  $n$ , and let  $c$  be any scalar. Then ... 6.2 SOLUTIONS Notes: The nonsquare matrices in Theorems 6 and 7 are needed for the QR factorization in Section 6.4. It

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1.1.8. In any vector space  $V$ , show that  $(a+b)(x+y) = ax+ay+bx+by$  for any  $x,y \in V$  and any  $a,b \in F$ .

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