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An industrial robot is a robot system used for manufacturing.Industrial robots are automated, programmable and capable of movement on three or more axis. Typical applications of robots include welding, painting, assembly, pick and place for printed circuit boards, packaging and labeling, palletizing, product inspection, and testing; all accomplished with high endurance, speed, and precision.

Industrial robot - Wikipedia

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Robot software is the set of coded commands or instructions that tell a mechanical device and electronic system, known together as a robot, what tasks to perform. Robot software is used to perform autonomous tasks. Many software systems and frameworks have been proposed to make programming robots easier. Some robot software aims at developing intelligent mechanical devices.

Robot software - Wikipedia

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Ch 8 Industrial Robotics Learning Objectives: By the end of the lecture the student should be able to: Outline robot anatomy and related attributes. Explain robot control systems. Outline and explain end effectors. Outline and explain sensors in robotics. Provide industrial robot applications. Outline and explain different robot programming.

Ch 8 Industrial Robotics - Montana State University

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Unfortunately, you will never get a simple answer if you asked "What's the best programming language for robotics?" to a whole roomful of robotics professionals (or on forums like Stack Overflow, Quora, Trossen, Reddit or Research Gate). Electronic engineers will give a different answer from industrial robotic technicians.

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