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## Math 311: Vector Analysis

Again note that the origin is at the tails of the vectors in the figure. Also, -1(1,2,1) = (-1,-2,-1). This would be pictured by drawing the vector (1, 2, 1) in the opposite direction. Finally, 4(1,2,1) = (4,8,4)which is four times vector a and so is vector a stretched four times as long in the same direction.

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The solutions to these equations are A= 1, B= -1 and C= 0, and hence we obtain the above identity. This can be easily used to prove:  $\nabla \times \nabla \times u = \varphi i j k \varphi k l m \partial j \partial l u m$ . =  $(\delta i l \delta j m - \delta i m \delta j l) \partial j \partial l u m$ . =  $\partial i \partial j u j - \partial$ . 2 j ui. =  $\nabla (\nabla \cdot u) - \nabla 2u$  (20) (c) If B= SijAij, (B is a scalar), then we find that B= -SjiAji (since Sij = Sji and Aij = -Aji).

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engineering we frequently encounter quantities that have magnitude and magnitude only: mass, time, and temperature. These we label scalar quantities, which re- main the same no matter what coordinates we use.

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CHAPTER 3. VECTOR ANALYSIS 3.1.3 Position and Distance Vectors  $z2 \ y2 \ z1 \ y1 \ x1 \ x2 \ x \ yR1 \ 2R12 \ z$   $P1 = (x1, y1, z1) \ P2 = (x2, y2, z2)$  O Figure 3-4 Distance vectorR12 = P1P2 = R2!R1, whereR1 andR2 are the position vectors of pointsP1 andP2,respectively. Figure 3.3: The notion of the position vector to a point, P

#### **Vector Analysis - College of Engineering and Applied Science**

2 Chapter 1 Vector Analysis B C A Figure 1.1 Triangle Law of Vector Addition B A C F E D Figure 1.2 Vector Addition Is Associative this representation, vector addition C = A + B (1.1) consists of placing the rear end of vector B at the point of vector A (head to tail rule).

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