CS441: Applied ML - HW 5

Part 1: Applications of Al

Nothing to code for this part.

Part 2: Fine-Tune for Pets Image Classification

Include all the code for Part 2 in this section

2.1 Prepare Data

```
In []: import torch
    import torch.nn as nn
    import torch.optim.lr_scheduler as lrs
    from torch.utils.data import DataLoader
    import torchvision
    from torchvision import datasets
    from torchvision import transforms
    import matplotlib.pyplot as plt
    from tqdm import tqdm

    import os
    from pathlib import Path
    import numpy as np
In []: datadir = "."
    save_dir = "." # change to your directory
```

```
In []: train_set, test_set = load_pet_dataset()

# Display a sample in OxfordIIIPet dataset
sample_idx = 3000 # Choose an image index that you want to display
print("Label:", train_set.classes[train_set[sample_idx][1]])
train_set[sample_idx][0]
```

Label: Persian





2.2 Data Preprocess

```
In []: from torchvision import transforms
from torch.utils.data import DataLoader
In []: # Feel free to add augmentation choices
# Apply data augmentation
```

train_transform = transforms.Compose([

```
transforms.Resize(224),
                    transforms.CenterCrop(224),
                    transforms.ToTensor(),
                    transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                          std= [0.229, 0.224, 0.225]),
                1)
        test transform = transforms.Compose([
                    transforms.Resize(224), # resize to 224x224 because that's the
                    transforms.CenterCrop(224),
                    transforms.ToTensor(),
                    transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                          std= [0.229, 0.224, 0.225]),
                ])
In [ ]: # Feel free to change
        train_set, test_set = load_pet_dataset(train_transform, test_transform)
        train_loader = DataLoader(dataset=train_set,
                                   batch size=64,
                                   shuffle=True,
                                   num workers=2)
        test_loader = DataLoader(dataset=test_set,
                                   batch_size=64,
                                   shuffle=False,
```

num workers=2)

2.3 Helper Functions

```
In [ ]: # Display the number of parameters and model structure
        def display model(model):
          # Check number of parameters
          summary_dict = {}
          num params = 0
          summary_str = ['='*80]
          for module_name, module in model.named_children():
              summary_count = 0
              for name, param in module.named_parameters():
                  if(param.requires_grad):
                       summary_count += param.numel()
                       num_params += param.numel()
              summary_dict[module_name] = [summary_count]
              summary str+= [f'- {module name: <40} : {str(summary count):^34s}']</pre>
          summary_dict['total'] = [num_params]
          # print summary string
```

```
summary_str += ['='*80]
summary_str += ['--' + f'{"Total":<40} : {str(num_params) + " params":^34
print('\n'.join(summary_str))

# print model structure
print(model)</pre>
```

```
In [ ]: # Plot loss or accuracy
        def plot_losses(train, val, test_frequency, num_epochs):
            plt.plot(train, label="train")
            indices = [i for i in range(num_epochs) if ((i+1)%test_frequency == 0 or
            plt.plot(indices, val, label="val")
            plt.title("Loss Plot")
            plt.ylabel("Loss")
            plt.xlabel("Epoch")
            plt.legend()
            plt.show()
        def plot_accuracy(train, val, test_frequency, num_epochs):
            indices = [i for i in range(num_epochs) if ((i+1)%test_frequency == 0 or
            plt.plot(indices, train, label="train")
            plt.plot(indices, val, label="val")
            plt.title("Accuracy Plot")
            plt.ylabel("Accuracy")
            plt.xlabel("Epoch")
            plt.legend()
            plt.show()
        def save_checkpoint(save_dir, model, save_name = 'best_model.pth'):
            save_path = os.path.join(save_dir, save_name)
            torch.save(model.state_dict(), save_path)
        def load_model(model, save_dir, save_name = 'best_model.pth'):
            save path = os.path.join(save dir, save name)
            model.load_state_dict(torch.load(save_path))
            return model
```

2.4 YOUR TASK: Fine-Tune Pre-trained Network on Pets

Read and understand the code and then uncomment it. Then, set up your learning rate, learning scheduler, and train/evaluate. Adjust as necessary to reach target performance.

```
In []: # set device, using GPU 'cuda' will be faster
device = 'cuda'
In []: def train(train_loader, model, criterion, optimizer):
```

```
1111111
    Train network
    :param train_loader: training dataloader
    :param model: model to be trained
    :param criterion: criterion used to calculate loss (should be CrossEntro
    :param optimizer: optimizer for model's params (Adams or SGD)
    :return: mean training loss
    model.train()
    loss_ = 0.0
    losses = []
    # TO DO: read this documentation and then uncomment the line below; http
    it_train = tqdm(enumerate(train_loader), total=len(train_loader), desc="
    for i, (images, labels) in it_train:
        # TO DO: read/understand these lines and then uncomment the code bel
        images, labels = images.to(device), labels.to(device)
        # zero the gradient
        optimizer.zero_grad()
        # predict labels
        prediction = model(images)
        # compute loss
        loss = criterion(prediction, labels)
        # set text to display
        it train.set description(f'loss: {loss:.3f}')
        # compute gradients
        loss.backward()
        # update weights
        optimizer.step()
        # keep track of losses
        losses.append(loss)
    return torch.stack(losses).mean().item()
def test(test_loader, model, criterion):
    Test network.
    :param test_loader: testing dataloader
    :param model: model to be tested
    :param criterion: criterion used to calculate loss (should be CrossEntro
    :return: mean_accuracy: mean accuracy of predicted labels
```

```
test_loss: mean test loss during testing
model.eval()
losses = []
correct = 0
total = 0
# TO DO: read this documentation and then uncomment the line below; http
it_test = tqdm(enumerate(test_loader), total=len(test_loader), desc="Val
for i, (images, labels) in it_test:
 # TO DO: read/understand and then uncomment these lines
  images, labels = images.to(device), labels.to(device)
  with torch.no_grad(): # https://pytorch.org/docs/stable/generated/tor
   output = model(images) # do not compute gradient when performing pred
  preds = torch.argmax(output, dim=-1)
  loss = criterion(output, labels)
  losses.append(loss.item())
  correct += (preds == labels).sum().item()
  total += len(labels)
mean_accuracy = correct / total
test_loss = np.mean(losses)
print('Mean Accuracy: {0:.4f}'.format(mean_accuracy))
print('Avg loss: {}'.format(test_loss))
return mean_accuracy, test_loss
```

```
In []: # loads a pre-trained ResNet-34 model
    model = torch.hub.load('pytorch/vision:v0.10.0', 'resnet34', pretrained=True
    num_target_classes = 37

# TO DO: replace the last layer (classification head) with a new linear laye
    in_features = model.fc.in_features
    model.fc = torch.nn.Linear(in_features, num_target_classes)

model = model.to(device)
    display_model(model) # displays the model structure and parameter count
```

Using cache found in /home/janghl/.cache/torch/hub/pytorch_vision_v0.10.0

```
layer4
                                                           13114368
                                            :
avgpool
                                                              0
                                            :
                                                            18981
– fc
--Total
                                                       21303653 params
ResNet(
  (conv1): Conv2d(3, 64, kernel\_size=(7, 7), stride=(2, 2), padding=(3, 3),
bias=False)
  (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running
stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1, ceil
mode=False)
  (layer1): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 2)
1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning_stats=True)
    )
    (1): BasicBlock(
      (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1)
1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track run
ning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track run
ning_stats=True)
    )
    (2): BasicBlock(
      (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning stats=True)
  )
```

```
(layer2): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(64, 128, kernel_size=(3, 3), stride=(2, 2), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
      (downsample): Sequential(
        (0): Conv2d(64, 128, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
      )
    (1): BasicBlock(
      (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
    (2): BasicBlock(
      (conv1): Conv2d(128, 128, kernel\_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel\_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
    (3): BasicBlock(
      (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
```

```
)
  (layer3): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(128, 256, kernel\_size=(3, 3), stride=(2, 2), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (downsample): Sequential(
        (0): Conv2d(128, 256, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning stats=True)
      )
    (1): BasicBlock(
      (conv1): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
    (2): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
    (3): BasicBlock(
      (conv1): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_ru
nning_stats=True)
```

```
)
    (4): BasicBlock(
      (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_ru
nning_stats=True)
    (5): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
 (layer4): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(256, 512, kernel size=(3, 3), stride=(2, 2), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
nning_stats=True)
      (downsample): Sequential(
        (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
nning_stats=True)
     )
    (1): BasicBlock(
      (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
```

```
nning_stats=True)
           (2): BasicBlock(
             (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(
       1, 1), bias=False)
             (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track ru
       nning stats=True)
             (relu): ReLU(inplace=True)
             (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(
       1, 1), bias=False)
             (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
       nning stats=True)
           )
         )
         (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
         (fc): Linear(in features=512, out features=37, bias=True)
In [ ]: # Training Setting. Feel free to change.
        num_epochs = 10
        test interval = 1
        # TO DO: set initial learning rate
        learn_rate = 1e-4
        optimizer = torch.optim.Adam(model.parameters(), lr=learn_rate)
        # TO DO: define your learning rate scheduler, e.g. StepLR
        # https://pytorch.org/docs/stable/optim.html#module-torch.optim.lr_scheduler
        lr scheduler = torch.optim.lr scheduler.StepLR(optimizer, step size=1, gamm
        criterion = torch.nn.CrossEntropyLoss()
        train_losses = []
        train_accuracy_list = []
        test_losses = []
        test accuracy list = []
        # Iterate over the DataLoader for training data
        for epoch in tgdm(range(num_epochs), total=num_epochs, desc="Training ...",
            # Train the network for one epoch
            train_loss = train(train_loader, model, criterion, optimizer)
            # TO DO: uncomment the line below. It should be called each epoch to app
            lr_scheduler.step()
            train_losses.append(train_loss)
            print(f'Loss for Training on epoch {str(epoch)} is {str(train_loss)} \n'
            # Get the train accuracy and test loss/accuracy
```

```
if(epoch%test interval==0 or epoch==1 or epoch==num epochs-1):
         print('Evaluating Network')
         train_accuracy, _ = test(train_loader, model, criterion) # Get train
         train_accuracy_list.append(train_accuracy)
         print(f'Training accuracy on epoch {str(epoch)} is {str(train accura
         test_accuracy, test_loss = test(test_loader, model, criterion) # Get
         test_losses.append(test_loss)
         test_accuracy_list.append(test_accuracy)
         print(f'Test (val) accuracy on epoch {str(epoch)} is {str(test_accur
         # Checkpoints are used to save the model with best validation accura
         if test accuracy >= max(test accuracy list):
          print("Saving Model")
           save_checkpoint(save_dir, model, save_name = 'best_model.pth') # 5
loss: 0.388: 100%| 58/58 [00:15<00:00, 3.76it/s]
Loss for Training on epoch 0 is 1.3497225046157837
Evaluating Network
Validating ...: 100%
                      | 58/58 [00:06<00:00, 9.33it/s]
Mean Accuracy: 0.9747
Avg loss: 0.24443417993085137
Training accuracy on epoch 0 is 0.9747282608695652
Validating ...: 100% | 58/58 [00:07<00:00, 7.77it/s]
Mean Accuracy: 0.8913
Avg loss: 0.505778176003489
Test (val) accuracy on epoch 0 is 0.8912510220768601
Saving Model
loss: 0.256: 100%|| 58/58 [00:15<00:00, 3.84it/s]
Loss for Training on epoch 1 is 0.19841448962688446
Evaluating Network
Validating ...: 100% | 58/58 [00:06<00:00, 9.16it/s]
Mean Accuracy: 0.9962
Avg loss: 0.05935830410955281
Training accuracy on epoch 1 is 0.996195652173913
Validating ...: 100% | 58/58 [00:06<00:00, 8.72it/s]
Mean Accuracy: 0.8972
Avg loss: 0.387282551491055
Test (val) accuracy on epoch 1 is 0.8972472063232488
Saving Model
```

loss: 0.045: 100%| 58/58 [00:15<00:00, 3.84it/s]

Loss for Training on epoch 2 is 0.057415686547756195

Evaluating Network

Validating ...: 100% | 58/58 [00:06<00:00, 9.44it/s]

Mean Accuracy: 1.0000

Avg loss: 0.01590884475294372

Training accuracy on epoch 2 is 1.0

Validating ...: 100% | 58/58 [00:06<00:00, 9.03it/s]

Mean Accuracy: 0.9122

Avg loss: 0.31880737738362674

Test (val) accuracy on epoch 2 is 0.9122376669392205

Saving Model

loss: 0.032: 100%| 58/58 [00:15<00:00, 3.82it/s]

Loss for Training on epoch 3 is 0.02456776797771454

Evaluating Network

Validating ...: 100%

Mean Accuracy: 1.0000

Avg loss: 0.00957316209176748

Training accuracy on epoch 3 is 1.0

Validating ...: 100% | 58/58 [00:06<00:00, 8.53it/s]

Mean Accuracy: 0.9106

Avg loss: 0.31288707840802343

Test (val) accuracy on epoch 3 is 0.9106023439629327

loss: 0.027: 100%| 58/58 [00:14<00:00, 3.89it/s]

Loss for Training on epoch 4 is 0.016316721215844154

Evaluating Network

Validating ...: 100% | 58/58 [00:06<00:00, 8.88it/s]

Mean Accuracy: 1.0000

Avg loss: 0.0059770000456222175 Training accuracy on epoch 4 is 1.0

Validating ...: 100%

Mean Accuracy: 0.9207

Avg loss: 0.2894534972849591

Test (val) accuracy on epoch 4 is 0.9206868356500408

Saving Model

loss: 0.012: 100%| 58/58 [00:15<00:00, 3.80it/s]

Loss for Training on epoch 5 is 0.010935946367681026

Evaluating Network

Validating ...: 100% | 58/58 [00:06<00:00, 9.03it/s]

Mean Accuracy: 1.0000

Avg loss: 0.004317048186404181 Training accuracy on epoch 5 is 1.0

Validating ...: 100% | 58/58 [00:06<00:00, 8.93it/s]

Mean Accuracy: 0.9210

Avg loss: 0.2850372875109315

Test (val) accuracy on epoch 5 is 0.9209593894794222

Saving Model

loss: 0.010: 100%| 58/58 [00:15<00:00, 3.80it/s]

Loss for Training on epoch 6 is 0.00921674631536007

Evaluating Network

Validating ...: 100% | 58/58 [00:06<00:00, 9.26it/s]

Mean Accuracy: 1.0000

Avg loss: 0.0036559286166046715 Training accuracy on epoch 6 is 1.0

Validating ...: 100% | 58/58 [00:06<00:00, 9.21it/s]

Mean Accuracy: 0.9204

Avg loss: 0.2835886925780054

Test (val) accuracy on epoch 6 is 0.9204142818206595

loss: 0.008: 100% | 58/58 [00:15<00:00, 3.84it/s]

Loss for Training on epoch 7 is 0.007689479738473892

Evaluating Network

Validating ...: 100% | 58/58 [00:06<00:00, 9.33it/s]

Mean Accuracy: 1.0000

Avg loss: 0.0029499575511777194 Training accuracy on epoch 7 is 1.0

Validating ...: 100%

Mean Accuracy: 0.9199

Avg loss: 0.28181350989074544

Test (val) accuracy on epoch 7 is 0.919869174161897

loss: 0.005: 100%|| 58/58 [00:15<00:00, 3.84it/s]

Loss for Training on epoch 8 is 0.00715823145583272

Evaluating Network

Validating ...: 100%| 58/58 [00:06<00:00, 9.24it/s]

Mean Accuracy: 1.0000

Avg loss: 0.0027045900692585214 Training accuracy on epoch 8 is 1.0

Validating ...: 100% | 58/58 [00:06<00:00, 8.88it/s]

Mean Accuracy: 0.9185

Avg loss: 0.28851110982740746

Test (val) accuracy on epoch 8 is 0.9185064050149905

loss: 0.009: 100%| 58/58 [00:15<00:00, 3.84it/s]

Loss for Training on epoch 9 is 0.006114728283137083

Evaluating Network

Validating ...: 100% | 58/58 [00:06<00:00, 9.39it/s]

Mean Accuracy: 1.0000

Avg loss: 0.0022216173077548116 Training accuracy on epoch 9 is 1.0

Validating ...: 100% | 58/58 [00:06<00:00, 8.89it/s] Training ...: 100% | 10/10 [04:43<00:00, 28.36s/it]

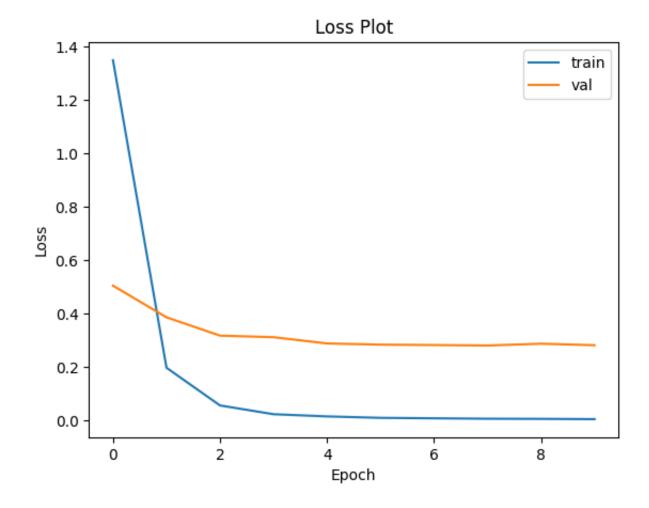
Mean Accuracy: 0.9185

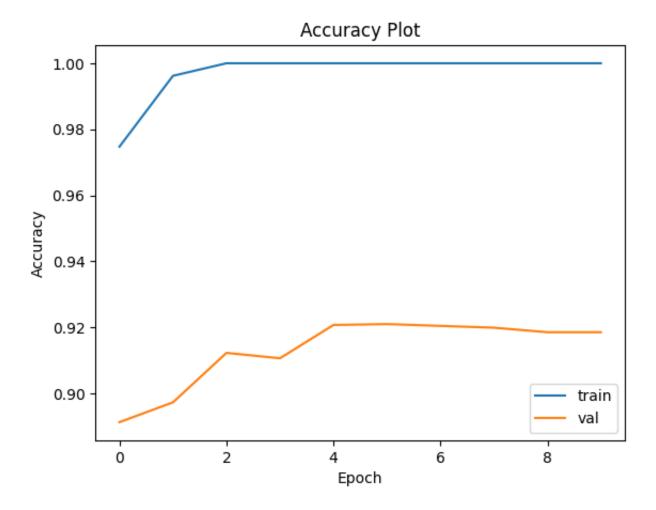
Avg loss: 0.282880000994894

Test (val) accuracy on epoch 9 is 0.9185064050149905

2.5 Plotting of losses and accuracy

In []: plot_losses(train_losses, test_losses, test_interval, num_epochs)
 plot_accuracy(train_accuracy_list, test_accuracy_list, test_interval, num_ep





2.6 Evaluating trained model

```
In []: # TO DO: initialize your trained model as you did before so that you can loa
model = torch.hub.load('pytorch/vision:v0.10.0', 'resnet34', pretrained=True
# replace last layer
in_features = model.fc.in_features
model.fc = torch.nn.Linear(in_features, num_target_classes)

model = model.to(device)
load_model(model, save_dir) # Load the trained weight

test_accuracy, test_loss= test(test_loader, model, criterion)
print(f"Validation accuracy is {str(test_accuracy)} \n")
Using each found in (home/jargh)/ each (test_hub/pytorch vision v0.10.0)
```

Using cache found in /home/janghl/.cache/torch/hub/pytorch_vision_v0.10.0 Validating ...: 100%| 58/58 [00:12<00:00, 4.59it/s]

Mean Accuracy: 0.9210

Avg loss: 0.2850372875109315

Validation accuracy is 0.9209593894794222

Part 3: CLIP: Contrastive Language-Image Pretraining

Include all the code for Part 3 in this section

3.1 Prepare data

Here is the json file you need for labels of flowers 102

```
In [ ]: import json
        import os
        import os.path as osp
        import numpy as np
        import torch
        from torchvision.datasets import Flowers102
        %matplotlib inline
        from matplotlib import pyplot as plt
In [ ]: datadir = "."
In [ ]: def load_flower_data(img_transform=None):
            if os.path.isdir(datadir+ "flowers-102"):
              do download = False
            else:
              do_download = True
            train_set = Flowers102(root=datadir, split='train', transform=img_transf
            test_set = Flowers102(root=datadir, split='val', transform=img_transform
            classes = json.load(open(osp.join(datadir, "flowers102 classes.json")))
            return train_set, test_set, classes
In [ ]: # READ ME! This takes some time (a few minutes), so if you are using Colabs
                    first set to use GPU: Edit->Notebook Settings->Hardware Accelera
        # Data structure details
           flower_train[n][0] is the nth train image
            flower_train[n][1] is the nth train label
          flower_test[n][0] is the nth test image
            flower_test[n][1] is the nth test label
            flower_classes[k] is the name of the kth class
        flower_train, flower_test, flower_classes = load_flower_data()
In [ ]: len(flower_train), len(flower_test) # output should be (1020, 1020)
```

Out[]: (1020, 1020)

In []: # Display a sample in Flowers 102 dataset
sample_idx = 5 # Choose an image index that you want to display
print("Label:", flower_classes[flower_train[sample_idx][1]])
flower_train[sample_idx][0]

Label: hard-leaved pocket orchid



3.2 Prepare CLIP model

In []: !pip install git+https://github.com/openai/CLIP.git

```
Collecting git+https://github.com/openai/CLIP.git
```

Cloning https://github.com/openai/CLIP.git to /tmp/pip-req-build-4_ff0q1l Running command git clone --filter=blob:none --quiet https://github.com/openai/CLIP.git /tmp/pip-req-build-4_ff0q1l

Resolved https://github.com/openai/CLIP.git to commit ald071733d7111c9c014 f024669f959182114e33

Preparing metadata (setup.py) ... done

Requirement already satisfied: ftfy in /home/janghl/anaconda3/envs/DNN/lib/p ython3.9/site-packages (from clip==1.0) (6.2.0)

Requirement already satisfied: regex in /home/janghl/anaconda3/envs/DNN/lib/python3.9/site-packages (from clip==1.0) (2023.12.25)

Requirement already satisfied: tqdm in /home/janghl/anaconda3/envs/DNN/lib/p ython3.9/site-packages (from clip==1.0) (4.66.2)

Requirement already satisfied: torch in /home/janghl/anaconda3/envs/DNN/lib/python3.9/site-packages (from clip==1.0) (1.11.0+cu113)

Requirement already satisfied: torchvision in /home/janghl/anaconda3/envs/DN N/lib/python3.9/site-packages (from clip==1.0) (0.12.0+cu113)

Requirement already satisfied: wcwidth<0.3.0,>=0.2.12 in /home/janghl/anacon da3/envs/DNN/lib/python3.9/site-packages (from ftfy->clip==1.0) (0.2.13)

Requirement already satisfied: typing-extensions in /home/janghl/anaconda3/e nvs/DNN/lib/python3.9/site-packages (from torch->clip==1.0) (4.11.0)

Requirement already satisfied: numpy in /home/janghl/anaconda3/envs/DNN/lib/python3.9/site-packages (from torchvision->clip==1.0) (1.26.4)

Requirement already satisfied: requests in /home/janghl/anaconda3/envs/DNN/lib/python3.9/site-packages (from torchvision->clip==1.0) (2.31.0)

Requirement already satisfied: pillow!=8.3.*,>=5.3.0 in /home/janghl/anacond a3/envs/DNN/lib/python3.9/site-packages (from torchvision->clip==1.0) (10.3.0)

Requirement already satisfied: charset-normalizer<4,>=2 in /home/janghl/anac onda3/envs/DNN/lib/python3.9/site-packages (from requests->torchvision->clip ==1.0) (3.3.2)

Requirement already satisfied: idna<4,>=2.5 in /home/janghl/anaconda3/envs/D NN/lib/python3.9/site-packages (from requests->torchvision->clip==1.0) (3.6) Requirement already satisfied: urllib3<3,>=1.21.1 in /home/janghl/anaconda3/envs/DNN/lib/python3.9/site-packages (from requests->torchvision->clip==1.0) (2.2.1)

Requirement already satisfied: certifi>=2017.4.17 in /home/janghl/anaconda3/envs/DNN/lib/python3.9/site-packages (from requests->torchvision->clip==1.0) (2024.2.2)

```
In [ ]: import clip
```

```
In []: # Sets device to "cuda" if a GPU is available
device = "cuda" if torch.cuda.is_available() else 'cpu'
print(device)
# If this takes a really long time, stop and then restart the download
clip_model, clip_preprocess = clip.load("ViT-B/32", device=device)
```

cuda

3.3 CLIP zero-shot prediction

```
"""The following is an example of using CLIP pre-trained model for zero-shot
In [ ]:
        # Prepare the inputs
        n = 500 # image index to use
        image, class_id = flower_train[n]
        image_input = clip_preprocess(image).unsqueeze(0).to(device) # extract image
        text inputs = torch.cat([clip.tokenize(f"a photo of a {c}, a type of flower.
        # Calculate features
        with torch.no grad():
            image_features = clip_model.encode_image(image_input) # compute image fe
            text_features = clip_model.encode_text(text_inputs) # compute text featu
        image_features /= image_features.norm(dim=-1, keepdim=True) # unit-normalize
        text features /= text features.norm(dim=-1, keepdim=True) # unit-normalize t
        # Pick the top 5 most similar labels for the image
        similarity = (100.0 * image_features @ text_features.T) # score is cosine si
        p_class_given_image= similarity.softmax(dim=-1) # P(y|x) is score through s
        values, indices = p_class_given_image[0].topk(5) # gets the top 5 labels
        # Print the probability of the top five labels
        print("Ground truth:", flower_classes[class_id])
        print("\nTop predictions:\n")
        for value, index in zip(values, indices):
            print(f"{flower_classes[index]:>16s}: {100 * value.item():.2f}%")
        image
       Ground truth: wild pansy
       Top predictions:
```

mexican petunia: 28.22% petunia: 27.34% geranium: 9.75% balloon flower: 6.81% mallow: 5.39%

Out[]:



3.4 YOUR TASK: Test CLIP zero-shot performance on Flowers 102

Use pre-trained text and image representations to classify images. For zero-shot recognition, text features are computed from the CLIP model for phrases such as "An image of [flower_name], a type of flower" for varying [flower_name] inserts. Then, image features are computed using the CLIP model for an image, and the cosine similarity between each text and image is computed. The label corresponding to the most similar text is assigned to the image. You'll get that working using a data loader, which enables faster batch processing; then, compute the accuracy over the test set. You should see top-1 accuracy in the 60-70% range.

For zero-shot, you do not use the training set at all. You should only have to compute the text vectors once and re-use them for all test images.

Basic steps:

1. Create the normalized CLIP text vectors for each class label.

- 2. For each batch:
 - Create normalized CLIP image vectors
 - Compute similarity between text and image vectors
 - Get index of most likely class label and check whether it matches the ground truth
 - Keep a count of number correct and number total
- 3. Return accuracy = # correct / # total

```
In [ ]: from tqdm import tqdm
        from torch.utils.data import DataLoader
In [ ]: # Load flowers dataset again. This time, with clip_preprocess as transform (
        flower train trans, flower test trans, flower classes = load flower data(imc
In [ ]: def clip_zero_shot(data_set, classes):
            # data_loader = DataLoader(data_set, batch_size=32, shuffle=False) # data_loader
            # TO DO: Needs code here
            correct = 0
            total = 0
            for batch in tqdm(data_set):
                image_input = batch[0].unsqueeze(0).to(device)
                text_inputs = torch.cat([clip.tokenize(f"a photo of a {c}, a type of
                with torch.no_grad():
                    image_features = clip_model.encode_image(image_input)
                    text features = clip model.encode text(text inputs)
                image_features /= image_features.norm(dim=-1, keepdim=True)
                text_features /= text_features.norm(dim=-1, keepdim=True)
                similarity = (100.0 * image features @ text features.T).softmax(dim-
                values, indices = similarity[0].topk(5)
                # print(f"{indices[0]}, {batch[1]}")
                if batch[1] == indices[0]:
                    correct += 1
                total += 1
            accuracy = correct / total
            return accuracy
In [ ]: |accuracy = clip_zero_shot(data_set=flower_test_trans, classes=flower_classes
        print(f"\nAccuracy = {100*accuracy:.3f}")
                 1020/1020 [01:50<00:00, 9.24it/s]
       Accuracy = 0.686
```

3.5 YOUR TASK: Test CLIP linear probe performance on Flowers

102

We do not use text features for the linear probe method. Train on the train set, and evaluate on the test set and report your performance. You can get top-1 accuracy in the 90-95% range. If you're getting in the 80's, try both normalizing and not normalizing the features.

```
In [ ]: from sklearn.linear model import LogisticRegression
In [ ]:
       1111111
        Returns image features and labels in numpy format.
        The labels should just be integers representing class index, not text vector
        def get_features(data_set):
            # TO DO: Needs code here to extract features and labels
            all features = []
            all_labels = []
            with torch.no_grad():
                for images, labels in tqdm(DataLoader(data set, batch size=100)):
                    features = clip_model.encode_image(images.to(device))
                    all_features.append(features)
                    all_labels.append(labels)
            return torch.cat(all_features).cpu().numpy(), torch.cat(all_labels).cpu(
In [ ]: # Calculate the image features
        train_features, train_labels = get_features(flower_train_trans)
        test_features, test_labels = get_features(flower_test_trans)
        # TO DO: Needs code here
        # Train logistic regression model with train_features, train_labels
        classifier = LogisticRegression(random_state=0, C=0.316, max_iter=1000, verb
        classifier.fit(train_features, train_labels)
        # Evaluate accuracy on test_features, test_labels
        predictions = classifier.predict(test features)
        accuracy = np.mean((test_labels == predictions).astype(float)) * 100.
        print(f"Accuracy = {accuracy:.3f}")
                     11/11 [00:05<00:00, 1.90it/s]
       100%
                   11/11 [00:05<00:00, 1.96it/s]
        This problem is unconstrained.
```

RUNNING THE L-BFGS-B CODE

* * *

```
Machine precision = 2.220D-16
N =
           52326
                     M =
                                   10
At X0
              0 variables are exactly at the bounds
At iterate
                   f= 4.62497D+00
                                      |proj g| = 1.33024D-02
At iterate 50 f= 9.06565D-01
                                      |proj g| = 9.95379D-04
           * * *
     = total number of iterations
     = total number of function evaluations
Tnint = total number of segments explored during Cauchy searches
Skip = number of BFGS updates skipped
Nact = number of active bounds at final generalized Cauchy point
Projg = norm of the final projected gradient
      = final function value
           * * *
```

```
N Tit Tnf Tnint Skip Nact Projg F
52326 84 90 1 0 0 7.270D-05 9.039D-01
F = 0.90393596410274291
```

CONVERGENCE: NORM_OF_PROJECTED_GRADIENT_<=_PGTOL Accuracy = 93.431

3.6 YOUR TASK: Evaluate a nearest-neighbor classifier on CLIP features

Extract features based on the pre-trained model (can be the same features as 3.5) and apply a nearest neighbor classifier. You can use your own implementation of nearest neighbor or a library like sklearn or FAISS for this. Try K={1, 3, 5, 7, 11, 21}. If using sklearn, you can also experiment with 'uniform' and 'distance' weighting. Report performance for best K on the test set. You can also experiment with using unnormalized or normalized features. You should see top-1 accuracy in the 80-90% range.

```
In []: # TO DO: code for KNN prediction and evaluation (may use sklearn.neighbors.N
from sklearn.neighbors import KNeighborsClassifier

for k in [1, 3, 5, 7, 11, 21]:
    classifier = KNeighborsClassifier(n_neighbors=k)
```

```
classifier.fit(train_features, train_labels)
predictions = classifier.predict(test_features)
accuracy = np.mean((test_labels == predictions).astype(float)) * 100.
print(f"k={k}\nAccuracy = {accuracy:.3f}%")
```

k=1
Accuracy = 85.000%
k=3
Accuracy = 84.216%
k=5
Accuracy = 84.706%
k=7
Accuracy = 85.196%
k=11
Accuracy = 83.627%
k=21
Accuracy = 78.725%

Part 4: Stretch Goals

Include any new code needed for Part 4 here.

4.a Compare word tokenizers

Train at least two 8K token word tokenizers (e.g. BPE, WordPiece, SentencePiece) on the WikiText-2, and compare their encodings. You can use existing libraries, such as those linked below to train and encode/decode. Report the encodings for "I am learning about word tokenizers. They are not very complicated, and they are a good way to convert natural text into tokens." E.g. "I am the fastest planet" may end up being tokenized as [I, _am, _the, _fast, est, _plan, et]. Also, report the tokenizations of an additional sentence of your choice that results in different encodings by the two models.

https://github.com/huggingface/tokenizers

```
In []: # Choose your model between Byte-Pair Encoding, WordPiece or Unigram and ins
    from tokenizers import Tokenizer
    from tokenizers.models import BPE
    from datasets import load_dataset

dataset = load_dataset(path="wikitext", name="wikitext-2-raw-v1")
    tokenizer = Tokenizer(BPE())
# You can customize how pre-tokenization (e.g., splitting into words) is dor
    from tokenizers.pre_tokenizers import Whitespace
```

```
tokenizer.pre_tokenizer = Whitespace()
# Then training your tokenizer on a set of files just takes two lines of cod
from tokenizers.trainers import BpeTrainer

trainer = BpeTrainer(special_tokens=["[UNK]", "[CLS]", "[SEP]", "[PAD]", "[Ntokenizer.train(files=[], trainer))
# Once your tokenizer is trained, encode any text with just one line:

output = tokenizer.encode("I am learning about word tokenizers. They are not print(output.tokens)
# ["Hello", ",", "y", "'", "all", "!", "How", "are", "you", "[UNK]","?"]
```

4.b Implement your own network

For the Oxford Pets dataset, try to write the network by yourself. You can get ideas from existing works, but you cannot directly import them using packages, and the parameter number should be lower than 20M. Train your network from scratch. You would get points if your network can reach an accuracy of 35% (15 pts), and another 15 pts if it reaches 45%. You would want to pay more attention to data augmentation and other hyper-parameters during this part. Feel free to re-use any functions defined in Part 2.

```
In []: # example network definition that needs to be modified for custom network st
from torch import nn

class ResBlock(nn.Module):
    def __init__(self, in_channels, out_channels, downsample):
        super().__init__()
        if downsample:
            self.conv1 = nn.Conv2d(in_channels, out_channels, kernel_size=3,
```

```
self.shortcut = nn.Sequential(
            nn.Conv2d(in_channels, out_channels, kernel_size=1, stride=2),
            nn_BatchNorm2d(out_channels)
        else:
            self.conv1 = nn.Conv2d(in channels, out channels, kernel size=3,
            self.shortcut = nn.Sequential()
            self.conv2 = nn.Conv2d(out channels, out channels, kernel size=3
            self.bn1 = nn.BatchNorm2d(out_channels)
            self.bn2 = nn.BatchNorm2d(out channels)
    def forward(self, input):
        shortcut = self.shortcut(input)
        input = nn.ReLU()(self.bn1(self.conv1(input)))
        input = nn.ReLU()(self.bn2(self.conv2(input)))
        input = input + shortcut
        return nn.ReLU()(input)
class Network(nn.Module):
    def __init__(self, num_classes=37):
        super().__init__()
        resblock = ResBlock
        self.layer0 = nn.Sequential(
        nn.Conv2d(3, 64, kernel_size=7, stride=2, padding=3),
        nn.MaxPool2d(kernel_size=3, stride=2, padding=1),
        nn.BatchNorm2d(64),
        nn.ReLU()
        self.layer1 = nn.Sequential(
        resblock(64, 64, downsample=False),
        resblock(64, 64, downsample=False)
        self.layer2 = nn.Sequential(
        resblock(64, 128, downsample=True),
        resblock(128, 128, downsample=False)
        self.layer3 = nn.Sequential(
        resblock(128, 256, downsample=True),
        resblock(256, 256, downsample=False)
        self.layer4 = nn.Sequential(
        resblock(256, 512, downsample=True),
        resblock(512, 512, downsample=False)
        self.gap = torch.nn.AdaptiveAvgPool2d(1)
        self.fc = torch.nn.Linear(512, num classes)
    def forward(self, input):
        input = self.layer0(input)
        input = self.layer1(input)
```

```
input = self.layer2(input)
input = self.layer3(input)
input = self.layer4(input)
input = self.gap(input)
input = torch.flatten(input, 1)
input = self.fc(input)
return input
```

```
In [ ]: model = Network()
        # Feel free to change
        train_set, test_set = load_pet_dataset(train_transform, test_transform)
        train_loader = DataLoader(dataset=train_set,
                                   batch_size=64,
                                   shuffle=True,
                                   num workers=2)
        test_loader = DataLoader(dataset=test_set,
                                   batch size=64,
                                   shuffle=False,
                                   num workers=2)
        # TO DO: replace the last layer (classification head) with a new linear laye
        # in_features = model.fc.in_features
        # model.fc = torch.nn.Linear(in_features, num_target_classes)
        device = 'cuda'
        model = model.to(device)
        display_model(model) # displays the model structure and parameter count
```

==== - layer0 9600 layer1 148224 - laver2 378112 - layer3 1509888 layer4 6034432 : – gap 0 18981 ______ ______ --Total 8099237 params Network((layer0): Sequential((0): $Conv2d(3, 64, kernel_size=(7, 7), stride=(2, 2), padding=(3, 3))$ (1): MaxPool2d(kernel_size=3, stride=2, padding=1, dilation=1, ceil_mode =False) (2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running _stats=True) (3): ReLU()

```
)
 (layer1): Sequential(
    (0): ResBlock(
      (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1)
1))
      (shortcut): Sequential()
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 2)
1))
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning stats=True)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning_stats=True)
    (1): ResBlock(
      (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1)
1))
      (shortcut): Sequential()
      (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 2)
1))
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning stats=True)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_run
ning_stats=True)
    )
 (layer2): Sequential(
    (0): ResBlock(
      (conv1): Conv2d(64, 128, kernel_size=(3, 3), stride=(2, 2), padding=(
1. 1))
      (shortcut): Sequential(
        (0): Conv2d(64, 128, kernel size=(1, 1), stride=(2, 2))
        (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning_stats=True)
      )
    )
    (1): ResBlock(
      (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(
1, 1))
      (shortcut): Sequential()
      (conv2): Conv2d(128, 128, kernel\_size=(3, 3), stride=(1, 1), padding=(
1, 1))
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_ru
nning stats=True)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track ru
nning_stats=True)
  (layer3): Sequential(
    (0): ResBlock(
      (conv1): Conv2d(128, 256, kernel\_size=(3, 3), stride=(2, 2), padding=(
```

```
(shortcut): Sequential(
               (0): Conv2d(128, 256, kernel_size=(1, 1), stride=(2, 2))
               (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_ru
       nning_stats=True)
           )
           (1): ResBlock(
             (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(
       1, 1))
             (shortcut): Sequential()
             (conv2): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(
       1, 1))
             (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
       nning stats=True)
             (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track ru
       nning_stats=True)
           )
         (layer4): Sequential(
           (0): ResBlock(
             (conv1): Conv2d(256, 512, kernel_size=(3, 3), stride=(2, 2), padding=(
       1, 1))
             (shortcut): Sequential(
               (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(2, 2))
               (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
       nning stats=True)
             )
           (1): ResBlock(
             (conv1): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(
       1, 1))
             (shortcut): Sequential()
             (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(
       1, 1))
             (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track ru
       nning stats=True)
             (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_ru
       nning_stats=True)
         (gap): AdaptiveAvgPool2d(output_size=1)
         (fc): Linear(in_features=512, out_features=37, bias=True)
       )
In []: # Training Setting. Feel free to change.
        num_epochs = 10
        test_interval = 1
        # TO DO: set initial learning rate
```

1, 1))

```
optimizer = torch.optim.Adam(model.parameters(), lr=learn_rate)
 # TO DO: define your learning rate scheduler, e.g. StepLR
 # https://pytorch.org/docs/stable/optim.html#module-torch.optim.lr_scheduler
 lr scheduler = torch.optim.lr scheduler.StepLR(optimizer, step size=1, gamm
 criterion = torch.nn.CrossEntropyLoss()
 train losses = []
 train_accuracy_list = []
 test losses = []
 test accuracy list = []
 # Iterate over the DataLoader for training data
 for epoch in tgdm(range(num_epochs), total=num_epochs, desc="Training ...",
     # Train the network for one epoch
     train_loss = train(train_loader, model, criterion, optimizer)
     # TO DO: uncomment the line below. It should be called each epoch to app
     lr_scheduler.step()
     train_losses.append(train_loss)
     print(f'Loss for Training on epoch {str(epoch)} is {str(train_loss)} \n'
     # Get the train accuracy and test loss/accuracy
     if(epoch%test interval==0 or epoch==1 or epoch==num epochs-1):
         print('Evaluating Network')
         train_accuracy, _ = test(train_loader, model, criterion) # Get train
         train_accuracy_list.append(train_accuracy)
         print(f'Training accuracy on epoch {str(epoch)} is {str(train_accura
         test_accuracy, test_loss = test(test_loader, model, criterion) # Get
         test_losses.append(test_loss)
         test_accuracy_list.append(test_accuracy)
         print(f'Test (val) accuracy on epoch Test (val) accuracy on epoch {s
         # Checkpoints are used to save the model with best validation accura
         if test_accuracy >= max(test_accuracy_list):
           print("Saving Model")
           save checkpoint(save dir, model, save name = 'own best model.pth')
                             | 0/58 [00:00<?, ?it/s]
Training ...:
                0%|
Training ...:
                0%|
                             | 0/10 [00:01<?, ?it/s]
                                          Traceback (most recent call last)
AttributeError
Cell In[17], line 24
```

learn_rate = 1e-3

```
21 # Iterate over the DataLoader for training data
     22 for epoch in tqdm(range(num_epochs), total=num_epochs, desc="Trainin
g ...", position=1):
            # Train the network for one epoch
     23
---> 24
           train_loss = train(train_loader, model, criterion, optimizer)
           # TO DO: uncomment the line below. It should be called each epoc
     26
h to apply the lr_scheduler
           lr scheduler.step()
     27
Cell In[16], line 26, in train(train_loader, model, criterion, optimizer)
     23 optimizer zero_grad()
     25 # predict labels
---> 26 prediction = model(images)
     28 # compute loss
     29 loss = criterion(prediction, labels)
File ~/anaconda3/envs/DNN/lib/python3.9/site-packages/torch/nn/modules/modul
e.py:1110, in Module._call_impl(self, *input, **kwargs)
   1106 # If we don't have any hooks, we want to skip the rest of the logic
in
   1107 # this function, and just call forward.
   1108 if not (self._backward_hooks or self._forward_hooks or self._forward
_pre_hooks or _global_backward_hooks
                or _global_forward_hooks or _global_forward_pre_hooks):
   1109
-> 1110
            return forward_call(*input, **kwargs)
   1111 # Do not call functions when jit is used
   1112 full_backward_hooks, non_full_backward_hooks = [], []
Cell In[13], line 59, in Network.forward(self, input)
     57 input = self.layer0(input)
     58 input = self.layer1(input)
---> 59 input = self.layer2(input)
     60 input = self_layer3(input)
     61 input = self.layer4(input)
File ~/anaconda3/envs/DNN/lib/python3.9/site-packages/torch/nn/modules/modul
e.py:1110, in Module._call_impl(self, *input, **kwargs)
   1106 # If we don't have any hooks, we want to skip the rest of the logic
in
   1107 # this function, and just call forward.
   1108 if not (self._backward_hooks or self._forward_hooks or self._forward
_pre_hooks or _global_backward_hooks
                or _global_forward_hooks or _global_forward_pre_hooks):
   1109
            return forward call(*input, **kwargs)
-> 1110
   1111 # Do not call functions when jit is used
   1112 full backward hooks, non full backward hooks = [], []
File ~/anaconda3/envs/DNN/lib/python3.9/site-packages/torch/nn/modules/conta
iner.py:141, in Sequential.forward(self, input)
    139 def forward(self, input):
```

```
140
            for module in self:
                input = module(input)
--> 141
    142
            return input
File ~/anaconda3/envs/DNN/lib/python3.9/site-packages/torch/nn/modules/modul
e.py:1110, in Module. call impl(self, *input, **kwargs)
   1106 # If we don't have any hooks, we want to skip the rest of the logic
   1107 # this function, and just call forward.
   1108 if not (self._backward_hooks or self._forward_hooks or self._forward
_pre_hooks or _global_backward_hooks
   1109
                or _global_forward_hooks or _global_forward_pre_hooks):
            return forward call(*input, **kwargs)
-> 1110
   1111 # Do not call functions when jit is used
   1112 full_backward_hooks, non_full_backward_hooks = [], []
Cell In[13], line 22, in ResBlock.forward(self, input)
     20 def forward(self, input):
            shortcut = self.shortcut(input)
     21
 --> 22
            input = nn.ReLU()(self.bn1(self.conv1(input)))
            input = nn.ReLU()(self.bn2(self.conv2(input)))
     23
            input = input + shortcut
     24
File ~/anaconda3/envs/DNN/lib/python3.9/site-packages/torch/nn/modules/modul
e.py:1185, in Module.__getattr__(self, name)
   1183
            if name in modules:
                return modules[name]
   1184
-> 1185 raise AttributeError("'{}' object has no attribute '{}'".format(
            type(self).___name___, name))
AttributeError: 'ResBlock' object has no attribute 'bn1'
```

```
In [ ]: plot_losses(train_losses, test_losses, test_interval, num_epochs)
    plot_accuracy(train_accuracy_list, test_accuracy_list, test_interval, num_ep
```

