

PAPER: [Tensor-tensor products for invertible linear transforms] (Kilmer, 2015)

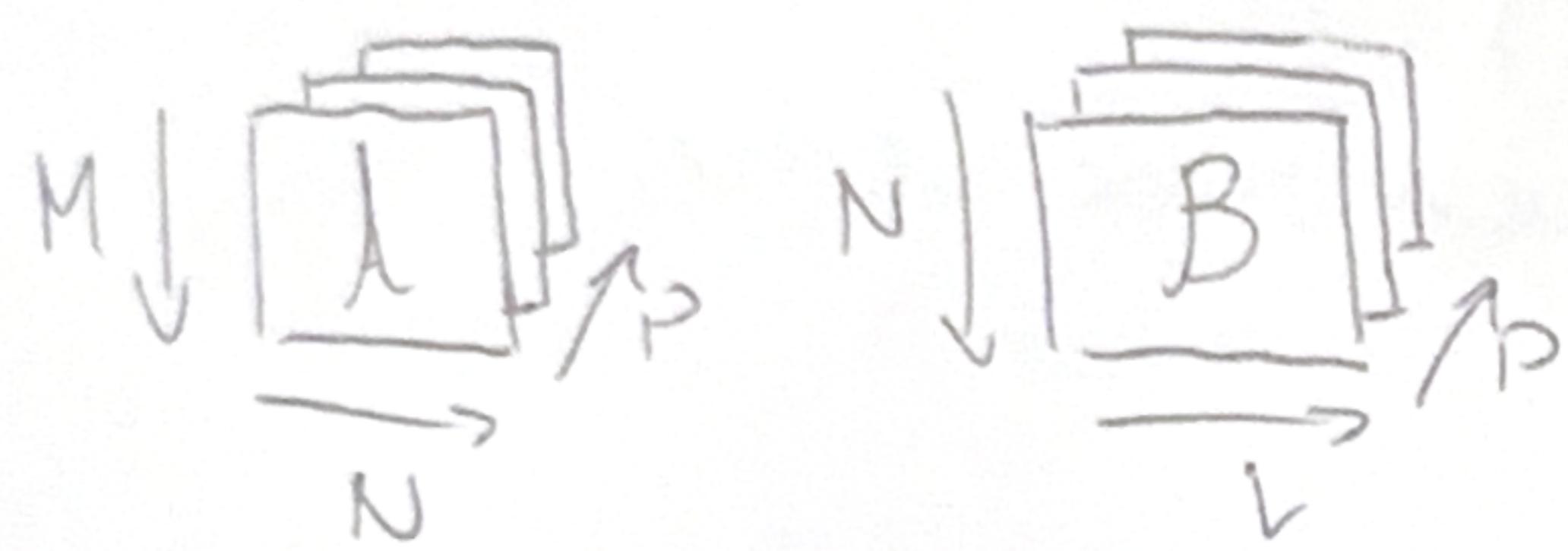
TOPIC: \*M-product for Tensor Multiplication

outline:

- i) short review of t-product
  - ii) structure for \*M-product
  - iii) some Algebraic properties
  - iv) Eckart-Young optimality
- 

Problem / notation

Find  $*_M : \mathbb{C}^{M \times N \times P} \times \mathbb{C}^{N \times L \times P} \rightarrow \mathbb{C}^{M \times L \times P}$



Frontal Face:  $(A)_{ik}, k \in \{1, \dots, P\}$

Tube Fiber:  $(a)_{ij}, i \in \{1, \dots, M\}$

$j \in \{1, \dots, N\}$

Recall: t-product

$$DFT^{-1}(DFT(A) \Delta DFT(B))$$

where  $\hat{A}_{ijk} := DFT(A_{ijk}) = \sum_{p=1}^P A_{ijp} \cdot e^{i2\pi(\frac{k}{P})}$

Notice: requires complex arithmetic

↳ Not optimal for real-valued tensors

IDEA: substitute some other invertible linear transform  
that better suits the problem.

Want:  $*_L$  s.t.  $L *_L B = L^{-1}(L(A) \Delta L(B))$

Similar structure to t-product, more flexible

We call this the  $*_M$  product for some linear transform  $L$ .

DEF (Mode-3 product)

$$*_3 : \mathbb{C}^{M \times N \times P} \times \mathbb{C}^{P \times P} \rightarrow \mathbb{C}^{M \times N \times P}$$

by  $(L *_3 M)_{ijk} = \sum_{p=1}^P A_{ijp} M_{kp}$

Q: Can we generalize this to any invertible linear transform?

DEF Let  $L: \mathbb{C}^n \rightarrow \mathbb{C}^n$  be invertible, linear defined by

$$L((y)_{ij}) = M \text{vec}[(y)_{ij}]$$

for some invertible  $P \times P$  matrix  $M$  and length- $P$  tube fiber  $(y)_{\#ij}$

Then,

DEF  $*_L: \mathbb{C}^{M \times N \times P} \times \mathbb{C}^{N \times L \times P} \rightarrow \mathbb{C}^{M \times L \times P}$  so that

~~$$L(A *_L B) = L(A) \Delta L(B)$$~~

performs linear transform across each tube vector  
then takes face-wise product.

NOTE: we observe that for  $\lambda \in \mathbb{C}^{M \times N \times P}$ ,  $M \in \mathbb{C}^{P \times P}$

$$L(A) = A \times_3 M, \quad L^{-1}(A) = A \times_3 M^{-1}$$

e.g.  $*_c$  cosine Transform Product

Def  $\text{mat}(A) := \begin{bmatrix} (A)_1 (A)_2 & \cdots & (A)_P \\ (A)_2 & \ddots & \vdots \\ \vdots & \ddots & (A)_2 \\ (A)_P & \cdots & (A)_2 (A)_1 \end{bmatrix}, \quad \begin{bmatrix} (A)_2 (A)_3 & \cdots & (A)_P & 0 \\ (A)_3 & \ddots & \ddots & (A)_P \\ \vdots & \ddots & 0 & \ddots \\ (A)_P & \cdots & 0 & \ddots \\ 0 & (A)_P & \ddots & \ddots \\ & & \ddots & (A)_2 \end{bmatrix}$

~~ten~~

$$\text{ten}(\text{mat}(A)) = A$$

$$\Rightarrow A *_c B := \text{ten}(\text{mat}(A) \text{mat}(B))$$

or let  $M = \text{dct}(\text{eye}(P))$  in Matlab (requires toolbox)

such that

$$A *_c B = L^{-1}(L(A) \Delta L(B))$$

can be computed efficiently in the transform domain,  
similarly to  $\text{t}$ -product, using DCT instead of FFT

↳ doesn't require complex arithmetic

↳ optimized for tasks like image processing

## ECKART - YOUNG OPTIMALITY

\*<sub>L</sub> evokes important properties like

- i) operator norms
  - ii) Hermitian Transposes
  - iii) inner products
- } allows us to have unitary operators

With these properties, we can produce:

TENSOR SVD induced by \*<sub>L</sub>

↳ Given  $A$ , compute  $\hat{A} = L(A)$

$$[\hat{U}^{(k)}, \hat{S}^{(k)}, \hat{V}^{(kH)}] \leftarrow \text{svd}(\hat{A}^{(k)}) \quad \forall k \in \{1, \dots, p\}$$

compute  $U \leftarrow L^{-1}(\hat{U})$ ,  $S \leftarrow L^{-1}(\hat{S})$ ,  $V \leftarrow L^{-1}(\hat{V})$

$$\Rightarrow A = U^* S V^H, \text{ with } U, V \text{ *}_L\text{-unitary}$$