

```
In [1]: import os
import time
import numpy as np
from matplotlib import pyplot as plt
import cv2 as cv
import mediapipe as mp
import seaborn as sns
from sklearn.model_selection import train_test_split
import tensorflow as tf
from tensorflow.keras import models
from tensorflow.keras import layers
from sklearn.metrics import confusion_matrix ,classification_report
```

```
In [2]: tf.__version__
```

```
Out[2]: '2.1.0'
```

```
In [4]: tf.test.is_gpu_available('gpu')
```

```
Out[4]: True
```

```
In [5]: input_types = ['palm', 'fist', 'thumbsup', 'gun', 'call']
```

```
In [6]: path = 'Inputs/'
data = []

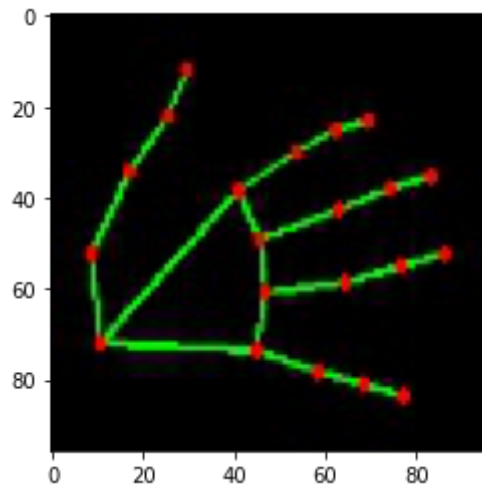
for types in input_types:
    temp = path + types + '/'
    l = []
    for file in os.listdir(temp):
        if file.endswith('.jpg'):
            image_matrix = plt.imread(temp + file)
            l.append(image_matrix)
    data.append(l)
data = np.array(data)
```

```
In [7]: data.shape
```

```
Out[7]: (5, 2000, 96, 96, 3)
```

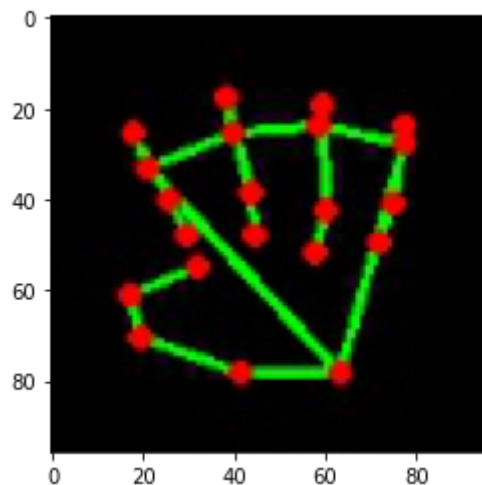
```
In [8]: plt.imshow(data[0][30])
```

```
Out[8]: <matplotlib.image.AxesImage at 0x1941b3c48c8>
```



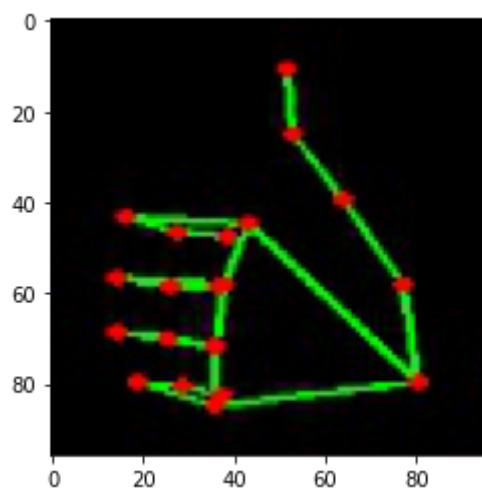
```
In [9]: plt.imshow(data[1][70])
```

```
Out[9]: <matplotlib.image.AxesImage at 0x1941056ebc8>
```



```
In [10]: plt.imshow(data[2][700])
```

```
Out[10]: <matplotlib.image.AxesImage at 0x1942be5c5c8>
```



```
In [11]: data.shape
```

```
Out[11]: (5, 2000, 96, 96, 3)
```

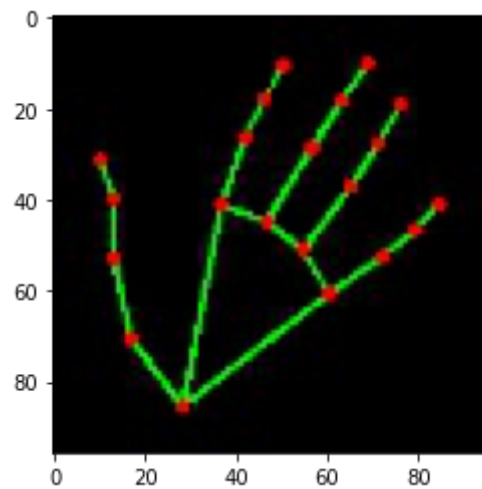
```
In [12]: X = []  
Y = []  
  
i = 0  
for class_ in data:  
    for image in class_:  
        X.append(image)  
        Y.append(i)  
    i += 1  
  
X = np.array(X)  
Y = np.array(Y)  
  
print(X.shape)  
print(Y.shape)
```

```
(10000, 96, 96, 3)  
(10000,)
```

```
In [13]: i = 77  
print(Y[i])  
plt.imshow(X[i])
```

0

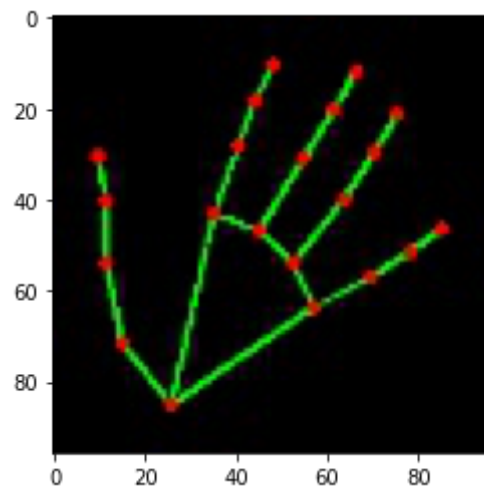
Out[13]: <matplotlib.image.AxesImage at 0x1942bf41388>



```
In [14]: i = 1999  
print(Y[i])  
plt.imshow(X[i])
```

0

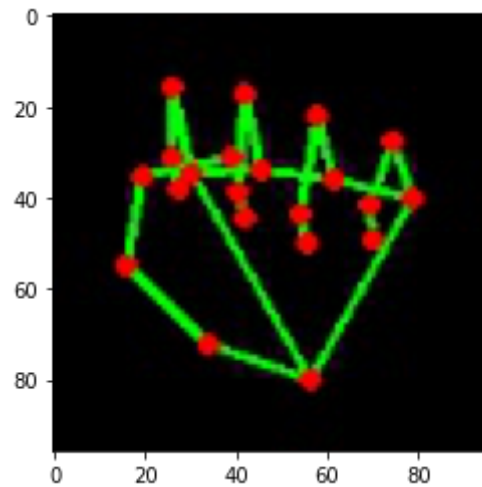
Out[14]: <matplotlib.image.AxesImage at 0x1942bedeac8>



```
In [15]: i = 2700  
print(Y[i])  
plt.imshow(X[i])
```

1

Out[15]: <matplotlib.image.AxesImage at 0x1943c742508>



```
In [16]: X = X / 255
```

In [17]: X[56]


```
Out[17]: array([[0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.],
               ...,
               [0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.]],

               [[0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.],
               ...,
               [0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.]],

               [[0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.],
               ...,
               [0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.]],

               ...,

               [[0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.],
               ...,
               [0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.]],

               [[0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.],
               ...,
               [0., 0., 0.],
               [0., 0., 0.],
               [0., 0., 0.]])
```

```
[[0., 0., 0.],  
 [0., 0., 0.],  
 [0., 0., 0.],  
 ...,  
 [0., 0., 0.],  
 [0., 0., 0.],  
 [0., 0., 0.]])
```

```
In [18]: X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size = 0.2, random_state = 20, shuffle = True)
```

```
In [19]: cnn = models.Sequential([
    #conv Layer 01
    layers.Conv2D(input_shape = X.shape[1:], #Layer 01
                  filters = 32,
                  kernel_size = (3,3),
                  strides = (1, 1),
                  padding = 'same',
                  activation = 'relu'),

    #maxpool Layer 01
    layers.MaxPooling2D(pool_size = (2, 2), #Layer 02
                       strides = (2,2),
                       padding = 'same'),

    #dropout Layer 01
    layers.Dropout(0.2), #Layer 04

    #conv Layer 02
    layers.Conv2D(input_shape = X.shape[1:], #Layer 05
                  filters = 64,
                  kernel_size = (3,3),
                  strides = (1, 1),
                  padding = 'same',
                  activation = 'relu'),

    #maxpool Layer 02
    layers.MaxPooling2D(pool_size = (2, 2), #Layer 06
                       strides = (2,2),
                       padding = 'same'),

    #dropout Layer 02
    layers.Dropout(0.2), #Layer 07

    #input layer
    layers.Flatten(), #Layer 08

    #hidden Layer 01
    layers.Dense(units = 512, #Layer 09
                 activation = 'relu'),

    #dropout Layer 03
```

```

layers.Dropout(0.2), #Layer 10

#output layer
layers.Dense(units = len(input_types), #Layer 11
             activation = 'softmax')
])

```

```

In [20]: cnn.compile(optimizer = 'adam',
                    loss = 'sparse_categorical_crossentropy',
                    metrics = ['accuracy'])

```

```

In [21]: start_time = time.time()
cnn.fit(X_train, Y_train, epochs = 10)
end_time = time.time()
print("total time in seconds", (end_time - start_time))

```

Train on 8000 samples

Epoch 1/10

8000/8000 [=====] - 18s 2ms/sample - loss: 0.1218 - accuracy: 0.9621

Epoch 2/10

8000/8000 [=====] - 5s 612us/sample - loss: 0.0138 - accuracy: 0.9952

Epoch 3/10

8000/8000 [=====] - 4s 562us/sample - loss: 0.0061 - accuracy: 0.9975

Epoch 4/10

8000/8000 [=====] - 4s 516us/sample - loss: 0.0063 - accuracy: 0.9984

Epoch 5/10

8000/8000 [=====] - 4s 514us/sample - loss: 0.0082 - accuracy: 0.9974

Epoch 6/10

8000/8000 [=====] - 4s 516us/sample - loss: 0.0012 - accuracy: 0.9996: 0s - loss: 9

Epoch 7/10

8000/8000 [=====] - 4s 514us/sample - loss: 0.0012 - accuracy: 0.9998

Epoch 8/10

8000/8000 [=====] - 4s 511us/sample - loss: 0.0059 - accuracy: 0.9977

Epoch 9/10

8000/8000 [=====] - 4s 510us/sample - loss: 0.0049 - accuracy: 0.9983

Epoch 10/10

8000/8000 [=====] - 4s 507us/sample - loss: 4.8045e-04 - accuracy: 1.0000

total time in seconds 55.98964047431946

```
In [22]: cnn.evaluate(X_test, Y_test)
```

```
2000/2000 [=====] - 1s 347us/sample - loss: 0.0203 - accuracy: 0.9950
```

```
Out[22]: [0.02028128568033543, 0.995]
```

```
In [23]: Y_pred = cnn.predict(X_test)
Y_pred_classes = [np.argmax(e) for e in Y_pred]

print("Classification Report: \n", classification_report(Y_test, Y_pred_classes))
```

```
Classification Report:
              precision    recall  f1-score   support

     0           0.99         1.00         1.00         399
     1           1.00         1.00         1.00         408
     2           0.99         1.00         0.99         373
     3           1.00         0.99         0.99         411
     4           1.00         0.99         0.99         409

 accuracy              0.99         2000
 macro avg           0.99         1.00         0.99         2000
 weighted avg        1.00         0.99         0.99         2000
```

In [24]: `cnn.summary()`

Model: "sequential"

Layer (type)	Output Shape	Param #
=====	=====	=====
conv2d (Conv2D)	(None, 96, 96, 32)	896
max_pooling2d (MaxPooling2D)	(None, 48, 48, 32)	0
dropout (Dropout)	(None, 48, 48, 32)	0
conv2d_1 (Conv2D)	(None, 48, 48, 64)	18496
max_pooling2d_1 (MaxPooling2D)	(None, 24, 24, 64)	0
dropout_1 (Dropout)	(None, 24, 24, 64)	0
flatten (Flatten)	(None, 36864)	0
dense (Dense)	(None, 512)	18874880
dropout_2 (Dropout)	(None, 512)	0
dense_1 (Dense)	(None, 5)	2565
=====	=====	=====
Total params: 18,896,837		
Trainable params: 18,896,837		
Non-trainable params: 0		

```
In [25]: cnn.get_weights()
```

```
Out[25]: [array([[[[-4.28520143e-02,  4.36444543e-02,  1.59608930e-01,
  1.85733419e-02, -1.76627964e-01, -5.17254472e-02,
  1.54973298e-01,  1.52638137e-01, -5.96843921e-02,
  9.16987583e-02, -7.56276622e-02,  1.28879249e-01,
 -1.04584612e-01,  1.06672294e-01, -3.59708071e-03,
 -2.83434894e-02, -5.81433587e-02, -1.46537960e-01,
 -1.40992641e-01,  7.00010434e-02, -1.15938611e-01,
  1.51752919e-01,  4.53807190e-02, -3.70776281e-02,
  2.67298166e-02,  1.20139748e-01, -2.12287139e-02,
  5.76514937e-03,  3.40608172e-02,  2.66641732e-02,
  9.95498225e-02,  3.47049385e-02],
 [ 1.24757126e-01,  2.18364112e-02, -1.07748955e-01,
 -1.67609006e-01,  6.19483255e-02,  1.07955396e-01,
  1.45916596e-01,  8.77300203e-02, -4.40291055e-02,
 -3.93620431e-02,  8.53522345e-02, -7.14429617e-02,
 -4.09310609e-02,  1.11101434e-01, -6.19888566e-02,
  1.34559140e-01,  1.45799443e-01, -9.37778577e-02,
  4.06562909e-02,  4.98728603e-02,  1.39217839e-01,
  1.69269502e-01,  1.08848564e-01, -8.74814466e-02,
 -8.37267097e-03, -9.63342637e-02,  2.84434427e-02,
  1.16600014e-01, -1.46336481e-01,  2.22849566e-02,
 -5.36732487e-02,  1.41608968e-01],
 [-4.85812873e-03,  5.51559143e-02, -4.77876514e-02,
  6.68440089e-02, -1.92726299e-01,  1.39218450e-01,
  2.82772500e-02,  1.13179721e-01,  1.89193320e-02,
  1.27390832e-01, -5.07281013e-02,  2.93888021e-02,
  6.15407787e-02,  1.15959113e-02, -1.31116033e-01,
  1.02262676e-01, -5.39021902e-02, -4.15763482e-02,
  1.48542196e-01, -6.26639128e-02, -9.96292308e-02,
  1.26438931e-01,  5.79981506e-02,  7.03374892e-02,
  1.54981017e-01, -5.81746027e-02,  1.21636979e-01,
  4.84964736e-02,  1.07926615e-02,  1.03315562e-01,
 -5.19787893e-02, -3.22834635e-03]],
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  4.24062982e-02, -1.54515788e-01, -7.97641948e-02,
 -7.76617825e-02, -1.35561332e-01,  6.85818344e-02,
  3.29237059e-02, -3.63977291e-02,  1.15845680e-01,
  8.99454951e-02,  1.59379140e-01, -7.30772838e-02,
  6.14315160e-02,  1.69435889e-02, -1.10391386e-01,
 -6.85885549e-02,  1.84984967e-01, -1.23387843e-01,
```


3.92439254e-02, 2.95328014e-02, 5.05197560e-03,
-6.68328851e-02, -3.71791283e-03, 1.50715441e-01,
8.70548040e-02, -1.29327103e-01, -4.76575755e-02,
1.53815359e-01, -1.18578836e-01],
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-1.89749181e-01, 9.24612135e-02, 7.00220317e-02,
-5.25212027e-02, 2.02823170e-02, -6.83283284e-02,
-1.01530634e-01, -7.31651932e-02, -1.83818936e-01,
1.16775535e-01, 1.75797287e-03, -1.22805648e-01,
1.22662149e-01, -8.30495283e-02, 3.93665098e-02,
4.27106731e-02, 1.03711352e-01, 1.20188475e-01,
-1.55766541e-02, -1.03493139e-01, -7.54922107e-02,
3.37243229e-02, -5.19191884e-02, -5.54912984e-02,
-2.04783194e-02, -1.65224344e-01, -4.70946431e-02,
1.97476638e-03, -3.46633159e-02],
[-1.24302894e-01, -1.82111248e-01, 5.62388822e-02,
-1.25474408e-01, -2.56664045e-02, -3.60028110e-02,
-5.74664772e-02, 1.01127021e-01, -4.74841893e-02,
3.94921489e-02, -6.02993332e-02, -7.03132451e-02,
1.41236484e-01, 9.56109166e-02, -9.35035050e-02,
9.01390463e-02, 3.66556644e-03, -9.60493162e-02,
1.17124371e-01, -2.85387579e-02, -3.10916454e-02,
1.44075528e-01, 8.30006152e-02, 1.10915698e-01,
1.67114120e-02, -4.11828384e-02, 1.38709366e-01,
7.67610222e-02, -8.82508755e-02, -3.83544108e-03,
3.02454410e-03, 8.96851812e-03]],
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1.28605917e-01, -1.31432980e-01, 1.17688417e-01,
3.54333185e-02, -7.29179084e-02, -1.07030243e-01,
3.67022939e-02, 1.38840392e-01, 6.88146949e-02,
-1.27811000e-01, -1.14382610e-01, -4.95465659e-03,
7.00943321e-02, 1.52391613e-01, -8.78099278e-02,
-1.55963928e-01, 5.30446768e-02, -2.06147525e-02,
-1.37059465e-02, 1.31358564e-01, 8.29909071e-02,
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9.80370492e-02, 1.44432366e-01],
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-9.48083848e-02, 1.26117868e-02, 7.32767805e-02,
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-8.05041790e-02, -1.28127173e-01, -7.56547078e-02,
8.64235610e-02, -4.24838737e-02, -2.99068488e-04,
1.06451415e-01, -3.68188657e-02, -7.96692595e-02,
-1.48392111e-01, -1.28999978e-01, 9.67338681e-02,
3.46082039e-02, -5.55897467e-02, 8.63774344e-02,
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-3.54661280e-03, -6.46771863e-02, 8.92770812e-02,
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-6.06778217e-03, -1.22044213e-01, -6.08186796e-02,
3.68744470e-02, -1.27556667e-01, 1.33689255e-01,
5.03318012e-02, -1.04411200e-01, -1.97228212e-02,
-8.67015719e-02, 1.79675251e-01, 4.67115790e-02,
1.29238605e-01, -1.08463846e-01],
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-1.26746356e-01, -5.83564378e-02, -4.35363241e-02,
-6.99516386e-02, -8.73355381e-03, 6.99344277e-02,
1.01653017e-01, 1.08869128e-01, -1.02209657e-01,
-1.03588082e-01, 1.31505951e-01, 9.20896903e-02,
1.76718619e-04, -1.07962877e-01, 9.03707519e-02,
4.84215468e-02, -9.59647000e-02, 6.67123497e-02,
-4.48843613e-02, -6.96909502e-02],

[1.00330308e-01, 1.11114666e-01, -1.45347640e-02,
9.46790352e-02, -8.83034393e-02, 4.69644219e-02,
1.02333426e-01, -2.77465712e-02, 7.84563739e-03,
7.02427700e-02, -3.97369787e-02, 1.30657583e-01,
3.50758084e-04, -3.72191742e-02, 1.20221116e-01,
1.20657898e-01, 7.17914104e-02, -1.13882363e-01,
9.44648683e-03, 9.45191085e-02, -2.14922559e-02,
1.69780699e-03, 1.51151508e-01, 1.13324456e-01,
-1.02751236e-03, 5.41279744e-03, 3.28579023e-02,
-3.81403379e-02, -1.26237243e-01, 4.45276350e-02,
7.60251889e-03, -7.54458457e-02]],

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5.50987199e-03, -1.02641344e-01, -8.47098306e-02,
4.22903337e-02, -3.22911236e-03, 1.06394954e-01,
-1.75006330e-01, -1.45461308e-02, -1.27740800e-01,
-1.49168074e-01, 6.95187375e-02, -1.21643424e-01,
1.19282342e-01, 6.48809522e-02, -2.87600458e-02,
-2.68885940e-02, 4.71640229e-02, -8.43802094e-02,
2.60377210e-02, -1.07900023e-01, 8.37432519e-02,
1.41519353e-01, -4.88128290e-02],

[1.58930924e-02, -1.34825051e-01, -2.27533542e-02,
-1.65982783e-01, -7.52273574e-02, 6.86361194e-02,
-5.23933992e-02, 1.23333901e-01, -7.50305876e-02,
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```

Saving model

```

In [27]: if os.path.isfile("cnn.h5") is False:
         cnn.save("cnn.h5")

```

Real time acc

```

In [28]: def Predict(img):
         class_ = np.argmax(cnn.predict(img))
         return input_types[class_]

```

```

In [29]: mp_drawing = mp.solutions.drawing_utils
         mp_holistic = mp.solutions.holistic

```

```
In [30]: holistic = mp_holistic.Holistic()
```

```
In [31]: R = 25
thickness = 2

webcam = 0
capture = cv.VideoCapture(webcam)

fps = int(capture.get(cv.CAP_PROP_FPS))
print("fps is "+str(fps))

_, frame = capture.read()
height, width, channel = frame.shape

while capture.isOpened():
    #time.sleep()
    if cv.waitKey(1) & 0xFF == 13:
        break

    black = np.zeros(shape = frame.shape)

    _, frame = capture.read()

    frame_rgb = cv.cvtColor(frame, cv.COLOR_BGR2RGB)

    result = holistic.process(frame_rgb)

    try:
        hand_landmarks = result.right_hand_landmarks.landmark
        if hand_landmarks:
            x_max = 0
            y_max = 0
            x_min = width
            y_min = height
            for i in range(0,21,1):
                lm = hand_landmarks[i]
                x, y = int(lm.x * width), int(lm.y * height)
                if x > x_max:
                    x_max = x
                if x < x_min:
                    x_min = x
                if y > y_max:
```



```

        y_max = y
        if y < y_min:
            y_min = y

    frame_bgr = cv.cvtColor(frame_rgb, cv.COLOR_RGB2BGR)

    mp_drawing.draw_landmarks(frame_bgr, result.right_hand_landmarks, mp_holistic.HAND_CONNECTIONS)

    cv.rectangle(frame_bgr, (x_min - R, y_min - R), (x_max + R, y_max + R), (0, 255, 0), thickness)

    result1 = frame_bgr

    mirror1 = cv.flip(result1, 1)

    '''

    '''

    mp_drawing.draw_landmarks(black, result.right_hand_landmarks, mp_holistic.HAND_CONNECTIONS)

    cropped = black[y_min - R + thickness: y_max + R - thickness, x_min - R + thickness : x_max + R - thickness
]

    resized = cv.resize(cropped, (96, 96))

    mirror2 = cv.flip(resized, 1)

    result2 = mirror2

    img_mat = np.array([result2])

    class_ = Predict(img_mat)

    cv.putText(mirror1, str(class_), (100, 100), cv.FONT_HERSHEY_PLAIN, 2, (255,0,0), 1)

    cv.imshow("Frame2", result2)
except:
    result1 = frame
    mirror1 = cv.flip(result1, 1)
    #result2 = black
    pass

```

```
cv.imshow('frame1', mirror1)  
capture.release()  
cv.destroyAllWindows()
```

fps is 30

In []: