

```
In [1]: import os
import time
import numpy as np
from matplotlib import pyplot as plt
import cv2 as cv
import mediapipe as mp
import seaborn as sns
from sklearn.model_selection import train_test_split
import tensorflow as tf
from tensorflow.keras import models
from tensorflow.keras import layers
from sklearn.metrics import confusion_matrix ,classification_report
from gtts import gTTS
from playsound import playsound
```

```
In [2]: tf.__version__
```

```
Out[2]: '2.1.0'
```

```
In [4]: tf.test.is_gpu_available('gpu')
```

```
Out[4]: True
```

```
In [39]: input_types = ['palm', 'fist', 'thumbsup', 'gun', 'call']
```

```
In [40]: description_types = ['01', '02', '03', '04', '05']
```

```
In [41]: defination_types = ['a', 'b', 'c', 'd', 'e']
```

Load Model

```
In [6]: cnn = models.load_model("cnn.h5")
```

```
In [7]: cnn.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 96, 96, 32)	896
max_pooling2d (MaxPooling2D)	(None, 48, 48, 32)	0
dropout (Dropout)	(None, 48, 48, 32)	0
conv2d_1 (Conv2D)	(None, 48, 48, 64)	18496
max_pooling2d_1 (MaxPooling2D)	(None, 24, 24, 64)	0
dropout_1 (Dropout)	(None, 24, 24, 64)	0
flatten (Flatten)	(None, 36864)	0
dense (Dense)	(None, 512)	18874880
dropout_2 (Dropout)	(None, 512)	0
dense_1 (Dense)	(None, 5)	2565
Total params: 18,896,837		
Trainable params: 18,896,837		
Non-trainable params: 0		

```
In [8]: l = []
        for i in range(5):
            image_matrix = plt.imread('Inputs/call/' + 'call_' + str(i + 1) + '.jpg')
            l.append(image_matrix)
        l = np.array(l)
        l = l / 255
```

```
In [9]: cnn.predict(1)
```

```
Out[9]: array([[2.6413172e-10, 3.2406274e-13, 5.9979181e-11, 1.3836636e-07,  
               9.9999988e-01],  
              [4.7895166e-10, 3.6021318e-12, 5.4874799e-10, 3.0129550e-07,  
               9.9999964e-01],  
              [1.0681169e-10, 2.1262924e-13, 1.7447507e-11, 3.5530383e-07,  
               9.9999964e-01],  
              [3.1814351e-09, 3.2657731e-11, 6.4703887e-09, 5.8453224e-08,  
               9.9999988e-01],  
              [2.3002328e-10, 2.8322423e-12, 2.8186053e-10, 2.9070209e-08,  
               1.0000000e+00]], dtype=float32)
```

```
In [10]: l.shape
```

```
Out[10]: (5, 96, 96, 3)
```

```
In [11]: def Predict(img):  
         class_ = np.argmax(cnn.predict(img))  
         return input_types[class_]
```

```
In [12]: Predict(np.array([l[0]]))
```

```
Out[12]: 'call'
```

New code

```
In [13]: def saving_sounds():  
         language = 'en'  
         for types in input_types:  
             obj = gTTS(text = types, lang = language, slow = False)  
             if os.path.isfile(str(types) + ".mp3") is False:  
                 obj.save(str(types) + ".mp3")
```

```
In [14]: saving_sounds()
```

```
In [15]: types = 'thumbsup'
playsound(str(types) + ".mp3")
```

```
In [16]: def playing_sounds():
        for types in input_types:
            playsound(str(types) + ".mp3")
```

```
In [18]: playing_sounds()
```

linkers

```
In [42]: def message_class(mirror1, class_):
        cv.putText(mirror1, str(class_), (100, 100), cv.FONT_HERSHEY_PLAIN, 2, (255,0,0), 1)
        return mirror1
```

```
In [43]: def message_sound(class_):
        # if os.path.isfile(str(class_) + ".mp3") is False:
        #     obj.save(str(class_) + ".mp3")
        playsound(str(class_) + ".mp3")
        block = True
```

```
In [44]: message_sound("palm")
```

```
In [45]: def message_description(black1, class_):
        text1 = description_types[input_types.index(class_)]
        cv.putText(black1, str(text1), (100, 100), cv.FONT_HERSHEY_PLAIN, 5, (255,0,0), 1)
        return black1
```

```
In [46]: def message_definition(black2, class_):
        text2 = definition_types[input_types.index(class_)]
        cv.putText(black2, str(text2), (100, 100), cv.FONT_HERSHEY_PLAIN, 5, (255,0,0), 1)
        return black2
```

Real Time Acc

```
In [22]: mp_drawing = mp.solutions.drawing_utils  
         mp_holistic = mp.solutions.holistic
```

```
In [23]: holistic = mp_holistic.Holistic()
```

```
In [47]: R = 25
thickness = 2

webcam = 0
capture = cv.VideoCapture(webcam)

pre_class = ''

fps = int(capture.get(cv.CAP_PROP_FPS))
print("fps is " + str(fps))

_, frame = capture.read()
height, width, channel = frame.shape

while capture.isOpened():
    #time.sleep()
    if cv.waitKey(1) & 0xFF == 13:
        break

    black = np.zeros(shape = frame.shape)

    black1 = np.zeros(shape = frame.shape)
    black2 = np.zeros(shape = frame.shape)

    _, frame = capture.read()

    frame_rgb = cv.cvtColor(frame, cv.COLOR_BGR2RGB)

    result = holistic.process(frame_rgb)

    try:
        hand_landmarks = result.right_hand_landmarks.landmark
        if hand_landmarks:
            x_max = 0
            y_max = 0
            x_min = width
            y_min = height
            for i in range(0,21,1):
                lm = hand_landmarks[i]
                x, y = int(lm.x * width), int(lm.y * height)
```

```

        if x > x_max:
            x_max = x
        if x < x_min:
            x_min = x
        if y > y_max:
            y_max = y
        if y < y_min:
            y_min = y

    frame_bgr = cv.cvtColor(frame_rgb, cv.COLOR_RGB2BGR)

    mp_drawing.draw_landmarks(frame_bgr, result.right_hand_landmarks, mp_holistic.HAND_CONNECTIONS)

    cv.rectangle(frame_bgr, (x_min - R, y_min - R), (x_max + R, y_max + R), (0, 255, 0), thickness)

    result1 = frame_bgr

    mirror1 = cv.flip(result1, 1)

    ...

    ...

    mp_drawing.draw_landmarks(black, result.right_hand_landmarks, mp_holistic.HAND_CONNECTIONS)

    cropped = black[y_min - R + thickness: y_max + R - thickness, x_min - R + thickness : x_max + R - thickness

]

    resized = cv.resize(cropped, (96, 96))

    mirror2 = cv.flip(resized, 1)

    result2 = mirror2

    img_mat = np.array([result2])

    class_ = Predict(img_mat)

    # msg 01
    message_class(mirror1, class_)

    #msg 02

```

```

#         if pre_class != class_:
#             message_sound(class_)
#             pre_class = class_

#msg 03
black1 = message_description(black1, class_)
result3 = black1

#msg 04
black2 = message_defination(black2, class_)
result4 = black2

cv.imshow("Frame2", result2)
cv.imshow("Frame3", result3)
cv.imshow("Frame4", result4)
except:
    result1 = frame
    mirror1 = cv.flip(result1, 1)
    #result2 = black
    pass

cv.imshow('frame1', mirror1)

capture.release()
cv.destroyAllWindows()

```

fps is 30

In []: