Supplementary Material

smdi: An R package to perform structural missing data investigations on partially observed confounders in real-world evidence studies

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1 Supplementary Methods

1.1 Missingness assumptions

For the design and validation of the smdi R package functions, we employed comprehensive simulations and a real-world example [1]. These simulations followed structural assumptions on realistic missingness generating mechanisms that could be expected in electronic health record (EHR) data. The below directed acyclic diagrams (DAG) [2,3], where a directed edge represents a causal effect of one variable on another variable, outline and illustrate these assumptions along with a brief explanations and exemplary real-world EHR scenarios. Since the smdi package was developed with focus on partially observed confounders (as opposed to missingness in exposure or outcome), we simplified the below DAGs by leaving out the nodes for exposure and outcome.

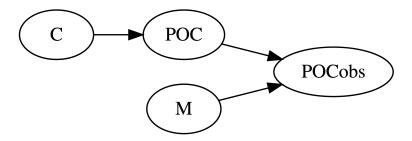
Notation: C = Fully observed confounder, POC = True values of the partially observed confounder, POCobs = Observed portion of the partially observed confounder, M = Missingness of POC with M=0 fully observed and M=1 fully missing, U = Unobserved confounder.

1.1.1 Missing completely at random (MCAR)

The missingness (M) of the partially observed confounder (POC) is independent of any observed and unobserved confounders. That is, no edge directs to M and the missingness is completely at random (MCAR).

Real-world example: A machine breaks that is used to measure and analyze a certain biomarker.

Supplementary Figure 1: Directed acyclic graph displaying a missing completely at random (MCAR) scenario.

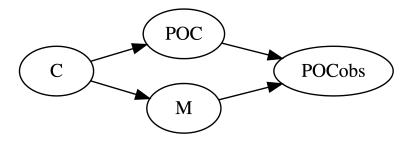


1.1.2 Missing at random (MAR)

The missingness (M) of the partially observed confounder (POC) can be explained by one or multiple fully observed confounders (C). That is, there is an edge between C to M and the missingness is at random (MAR).

Real-world example: Older patients are more likely to receive a certain biomarker test and age is a fully observed confounder which is measured for every patient in the dataset.

Supplementary Figure 2: Directed acyclic graph displaying a missing completely at random scenario.

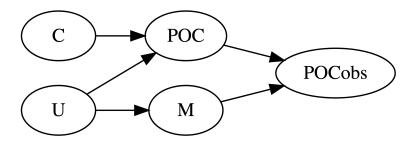


1.1.3 Missing not at random - unmeasured (MNAR_{unmeasured})

The missingness (M) of the partially observed confounder (POC) can only be explained by one or multiple confounder(s) which are not observed in the dataset.

Real-world example: Patients with a certain performance status, which not observed in the dataset, are more likely to receive a lab test.

Supplementary Figure 3: Directed acyclic graph displaying a missing not at random (unmeasured) scenario.

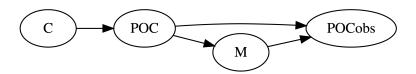


1.1.4 Missing not at random - value (MNAR_{value})

The missingness (M) of the partially observed confounder (POC) depends on the true value of the partially observed confounder itself.

Real-world example: Patients with a history of normal biomarker values are systematically less likely to be tested again for the same biomarker.

Supplementary Figure 4: Directed acyclic graph displaying a missing not at random (value) scenario.



1.2 Missingness characterization

This sections provides extensive information and details on key statistical principles and methods employed in the smdi package. Details on all package functions can also be found in the corresponding documentation section of the smdi package website

https://janickweberpals.gitlab-pages.partners.org/smdi/reference/index.html

or accessed in R by executing the the function name preceded with a question mark, e.g.:

?smdi_diagnose()

1.2.1 Group 1 diagnostics

The featured group 1 diagnostics in smdi focus on investigating potential differences in the distribution of characteristics between patients with and without an observed value for a partially observed confounder. To that end, different analytic approaches are leveraged which are described in detail for each function below.

• smdi_hotelling(): This function computes a two-sample Hotelling's T-squared test for the difference in two multivariate means based on the Hotelling's T-Square test statistic [4,5]. It assesses whether there is a statistically significant difference between the means of two groups in multivariate data. This test is an extension of the univariate t-test that examines for two groups (i.e., patients with and without a value observed for the confounder of interest) with p variables (e.g., patient or disease characteristics) whether

their mean vectors (p-dimensional vectors of means) are significantly different. To that end, the T^2 statistic is derived by a vector of covariate means (i.e, one element for each covariate) [6], which are represented as \bar{x}_1 (vector of covariate means in group 1) and \bar{x}_2 (vector of covariate means in group 2) in Equation 1 below (with n_1 and n_2 representing the sample sizes of group 1 and 2, respectively, and S_p representing the pooled variance-covariance matrix) (Equation 1 adapted from [7]). To implement Hotelling's test in the smdi package, we built a wrapper around the Hotelling::hotelling.test() function [5].

$$T^{2} = (\mathbf{\bar{x}_{1}} - \mathbf{\bar{x}_{2}})^{T} \{ \mathbf{S}_{p} (\frac{1}{n_{1}} + \frac{1}{n_{2}}) \}^{-1} (\mathbf{\bar{x}_{1}} - \mathbf{\bar{x}_{2}})$$
 (1)

smdi_little(): Little's test, as opposed to Hotelling's test, performs a single global test to evaluate the missing completely at random (MCAR) assumption [8]. It was developed since with an approach like Hotelling's test, there can be concerns regarding multiplicity due to the multiple testing of each variable. Little's test first identifies a set of subgroups that share the same missing data patterns j. Across these missing data patterns (n_i) , it then tests for mean differences on every variable by comparing the observed means $(\hat{\mu}_i)$ versus expected population means $(\hat{\mu}_i)$ which are estimated using a maximum likelihood (ML) expectation-maximization (EM) algorithm as implemented by the norm::prelim.norm() and norm::em.norm() functions in R (Equation 2 adapted from [9]). Under the assumption of MCAR, the test statistic (d^2) approximates a chi-square distribution and is derived by computing the sum of squared standardized differences between the subgroup means and the expected population means weighted by both the estimated variance-covariance matrix (where Σ_i is the maximum likelihood estimate of the covariance matrix) and the respective subgroup sizes [9,10]. To implement Little's test in the smdi package, we built a wrapper around the naniar::mcar_test() function [11].

$$d^{2} = \sum_{j=1}^{J} n_{j} (\hat{\mu}_{j} - \hat{\mu} j^{(\text{ML})})^{T} \hat{\Sigma}_{j}^{-1} (\hat{\mu}_{j} - \hat{\mu} j^{(\text{ML})})$$
 (2)

For both smdi_hotelling() and smdi_little(), a high test statistic and a low p-value would indicate differences in the groups compared. A limitation of both Hotelling's and Little's test is that they assume continuous variables following multivariate normality. Real-world data, however, are often of binary nature and to consider categorical data in the computation of these tests, categorical data are one-hot encoded to binary dummy variables before performing each test. In addition, these tests are sensitive to just small differences when study sizes are large which is why we recommend to perform these tests jointly with smdi_asmd.

• smdi_asmd(): The smdi_asmd functions computes the absolute standardized mean difference (ASMD) as a statistical measure for assessing dissimilarities in disease and patient characteristics between individuals with and without observed value for a specific partially observed confounder (POC) of interest. If the median/average ASMD is high, this may indicate imbalance in patient covariate distributions which may be indicative of the POC following a missing at random (MAR) mechanims, i.e. the missingness is explainable by other observed covariates. Similarly, no imbalance between observed covariates may be indicative that missingness cannot be explained with observed covariates and the underlying missingness mechanism may be completely at random (MCAR) or not at random (e.g., missingness is only associated with unobserved factors or through the POC itself). This methodological approach follows the same theory that is often applied to measure covariate balance between two groups before and after matching or weighting on propensity scores, which are balancing scores often used to reduce confounding in real-world evidence studies [12]. While there isn't a universally established standard for the threshold of the ASMD indicating significant imbalance, an ASMD below 0.1 is often considered indicative of a negligible difference in the mean or prevalence of a covariate between two groups [12,13]. The advantage of ASMDs to assess the balance of patient characteristics between two groups with and without an observed value for the POC is that they are not influenced by sample size, do not come with many assumptions, are easy to interpret and applicable to various types of covariates. Equation 3 and Equation 4 illustrate how ASMDs are computed for continuous and binary covariates with \bar{x} , s^2 and \hat{p} indicating the mean, sample variance and prevalence of the binary variable of the covariate in patients with a missing (M) and an observed (O) value for the POC, respectively. In the smdi package, ASMDs are extracted from tableone objects using the ExtractSmd function [14].

$$ASMD_{continous} = \left| \frac{(\bar{x}_M - \bar{x}_O)}{\sqrt{\frac{s_M^2 + s_O^2}{2}}} \right| \tag{3}$$

$$ASMD_{binary} = |\frac{(\hat{p_M} - \hat{p_O})}{\sqrt{\frac{\hat{p_M}(1 - \hat{p_M}) + \hat{p_O}(1 - \hat{p_O})}{2}}}|$$
(4)

1.2.2 Group 2 diagnostics

• smdi_rf(): The Group 2 diagnostics, implemented in the smdi_rf() function, assesses the ability to predict missingness based on observed covariates via the smdi_rf() function. This function trains and fits a random forest classification model [3,15] to predict the missing indicator of each POC given exposure, outcome, follow-up time, and covariates plus missingness indicator for other POC as the predictors. We chose a random forest classification model for the purpose of this package due its many beneficial features within the context of data structures that are frequently encountered in routine healthcare databases:

- Ability to implicitly model nonlinear and non-additive relationships between observed variables (i.e., higher order terms do not need to be explicitly specified).
- Recursive partitioning models like random forests have been found to work particularly well with sparse tabular data, which is the typical data type that is used for real-world evidence studies [16,17].
- Random Forests provide transparent feature importance measures, indicating the variables contributing significantly to predicting missingness. This aids in identifying key features driving the missingness mechanisms in the dataset.
- Multiple other studies have also reported good result of this random forest-based approach [3,18].

The default training parameters of the random forest model include a train-test split of the data (default if 70% training and 30% testing) which can be changed using the train_test_ratio parameter and the number of trees to grow using ntree (default is 1000 decision trees since a higher number of trees typically give more stable results). Users can optionally select tune = TRUE which will perform a 5-fold cross validation and a random search for the optimal number of variables randomly sampled as candidates at each split (mtry). However, users should be aware that this may lead to longer computation times with larger datasets which is why the default is set to FALSE. In summary, the following parameters are part of this function:

- data: dataframe or tibble object with partially observed/missing variables
- covar: character covariate or covariate vector with partially observed variable/column name(s) to investigate. If NULL, the function automatically includes all columns with at least one missing observation and all remaining covariates will be used as predictors
- train_test_ratio: numeric vector to indicate the test/train split ratio, e.g. c(.7, .3) which is the default
- set_seed: seed for reproducibility, defaults to 42
- ntree: integer, number of trees (defaults to 1000 trees)
- n_cores: integer, if >1, computations will be parallelized across the amount of cores specified in n_cores. This is important especially for larger datasets as the random forest training can be very time-consuming if done sequentially.

1.2.3 Group 3 diagnostics

To evaluate the association of the misssing indicator variable of a POC (M_{POC}) and the studied outcome in Group 3 Diagnostics, conventional univariate and multivariate regression models which are found used in the vast majority of real-world evidence studies are employed. The selection of regression type needs to be chosen using the model parameter and is determined

by the type of outcome that is studied. The possible outcome models include linear regression [19] for continuous outcomes (Equation 5), logistic regression [20] for binary outcomes (Equation 6) and a Cox proportional hazards regression [21] for time-to-event outcomes (Equation 7) with X_j indicating other covariates included in the multivariate models. The form_lhs specifies the left-hand side of the outcome formula, which, in case of model = "linear" or model = "logistic just reflects the name of the column that contains the outcome and the form Surv(time, status) for model ="cox" indicating the time-to-event variable and the event status (0/1). The output of the functions automatically returns results for both the univariate and the multivariate models and a user has the choice to have the $\beta_1 M_{POC}$ estimate exponentiated or not using the logical exponentiated parameter.

$$Y = \beta_0 + \beta_1 M_{POC} + \dots + \beta_2 X_i \tag{5}$$

$$\ln(\frac{p}{p-1}) = \beta_0 + \beta_1 M_{POC} + \dots + \beta_2 X_j \tag{6}$$

$$h(t) = h_0(t)e^{\sum \beta_1 M_{POC} + \dots + \beta_2 X_j}$$
(7)

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