## ADVANCEMENTS IN ESTIMATING DIFFERENTIAL PISTONS FOR

## THE EXTREMELY LARGE TELESCOPE USING DEEP LEARNING



JANIN-POTIRON, P. (a), GRAY, M. (a), NEICHEL, B. (a), DUMONT, M. (b,c,a), SAUVAGE, J.-F. (b,a), FETICK, R. JL. (b,a), FUSCO, T. (d,a) (a) Aix Marseille Univ, CNRS, CNES, LAM, Marseille, France (b) DOTA, ONERA, F-13661 Salon Cedex Air - France (c) Faculdade de Engenharia da Universidade do Porto, Rua Dr. Roberto Frias, 4200-465Porto, Portugal



Our previous study (Chauvet et al. 23) demonstrated

that the network achieves high performances (RMSE

< 10nm @ 2.2µm) when using single frames



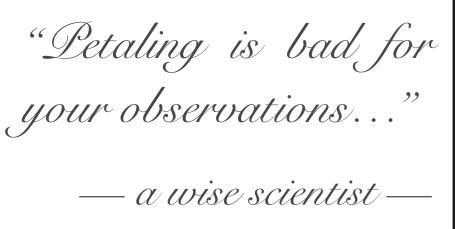


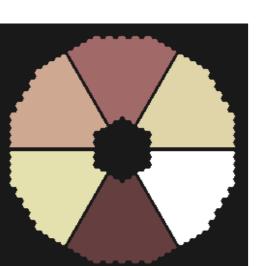
Aix\*Marseille

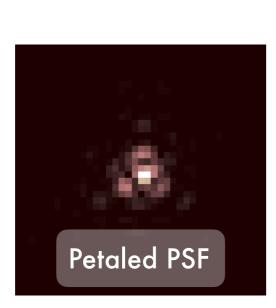
## PETALING BASICS

#### DIFFERENTIAL PISTON (OR PETALING) ARISES FROM VARIOUS SOURCES

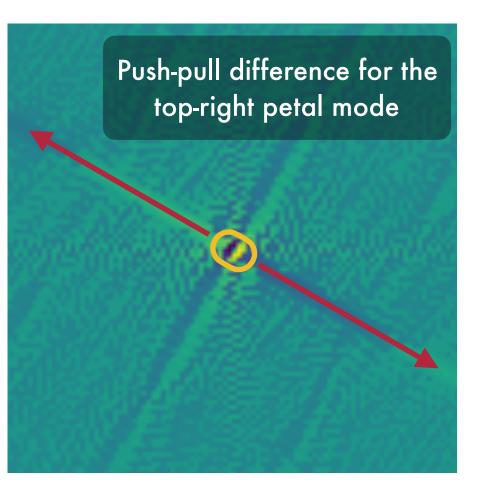
e.g. atmosphere, thermal or mechanical effects, control loop properties.







(d) DOTA, ONERA, Université Paris Saclay, 91123 Palaiseau, France



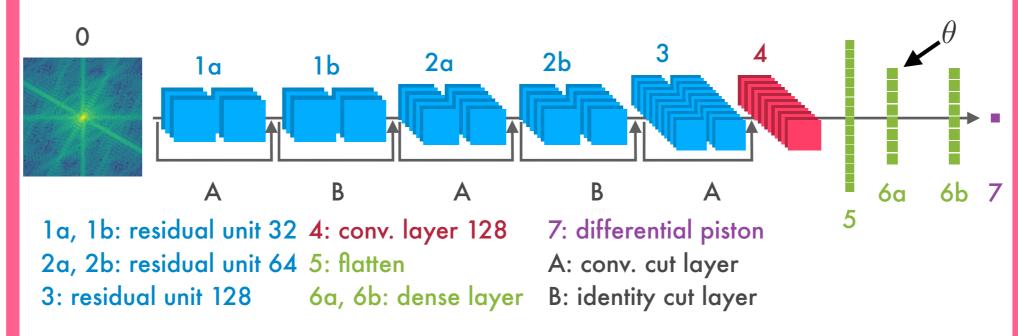
#### **PETALING HAS A DISTINCTIVE PATTERN**

Strong effect at low frequencies and ranges along a preferential direction perpendicular to the spider.

## NEURAL NETWORK

#### RESNET ARCHITECTURE

Suited for our image application with a residual unit based architecture. The pupil rotation angle  $\theta$  is integrated in the first dense layer.



#### ONE NETWORK PER DIFFERENTIAL PISTON

Each differential piston has its own personal network as it clearly improve the performances.

#### THE MODEL HAS 610K PARAMETERS AND IS TRAINED ON 300K IMAGES

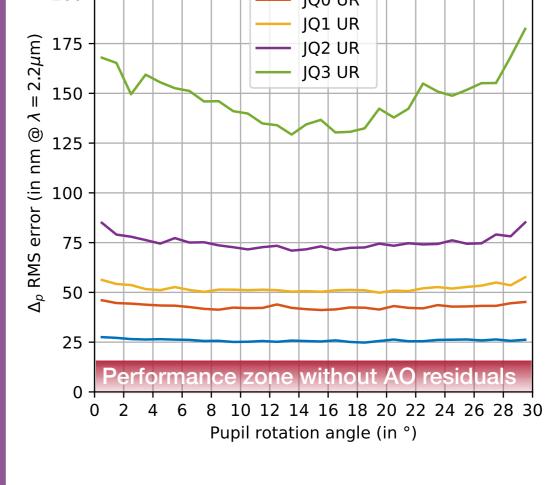
We perform a hyper-parameter search on the scheduler defining the learning rate values for each configuration.

# —— JQ2 UR

containing only turbulence residuals.

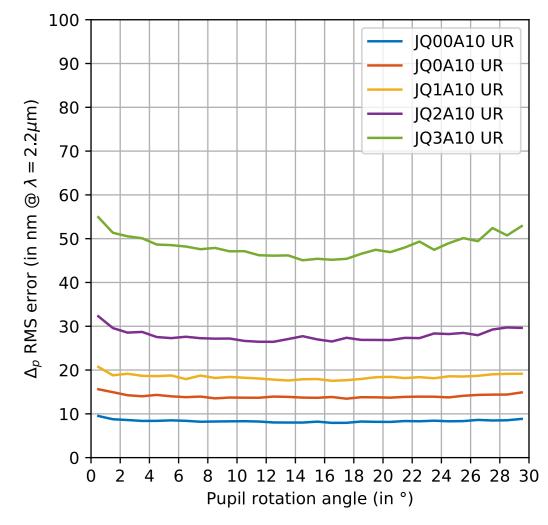
#### **AO RESIDUALS** SIGNIFICANTLY DEGRADE **PERFORMANCES**

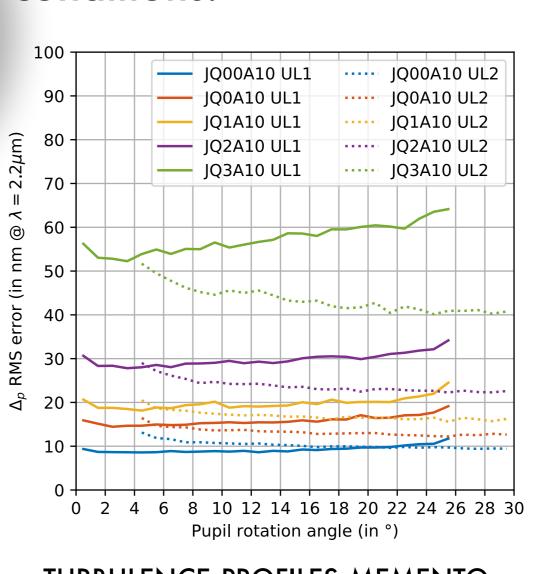
Introducing AO residuals (e.g., fitting errors or temporal errors) into the simulation leads to a decline in performance on single frames.



#### **AVERAGING RESTORE PERFORMANCES**

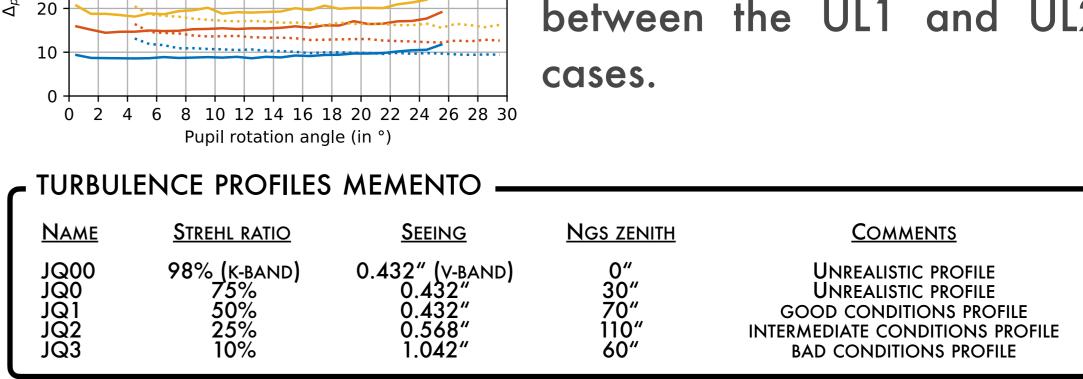
Averaging the results across 10 images (uncorrelated realizations of the turbulence) significantly improves the network's performance over all conditions.





#### **UL TYPES SUB PUPILS PERFORMANCE**

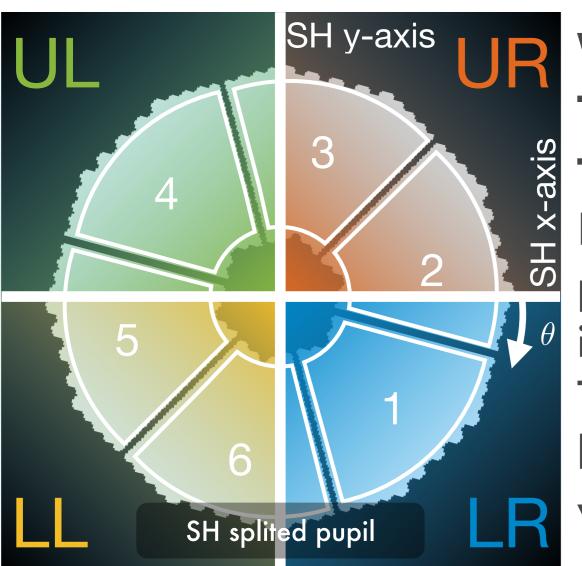
Differential piston estimation is in the same range as the UR case. Anisotropy in the PSD causes the asymmetry between the UL1 and UL2



## **CPHILOSOPHY**

#### WE MEASURE DIFFERENTIAL PISTON FROM FOCAL PLANE **IMAGES**

Harmoni will integrate a 2x2 Shack-Hartmann WFS dedicated to the measure of low-order aberrations. The PSF produce by the sensor contains information on the differential piston.



## TO ESTIMATE PISTON FROM THESE PSF

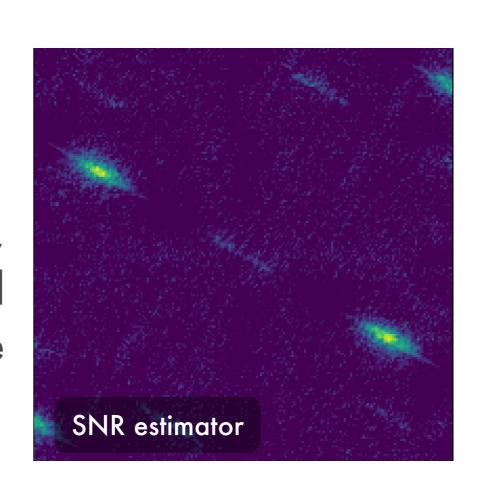
Each of the four sub-apertures produces a PSF that encodes the information on differential piston. The network learns the relation between the differential piston value and the PSF.

#### THE SYMMETRIES OF THE PUPIL REDUCE THE CASES TO BE TESTED We only have to study the two upper sub pupils UL and UR. **DIFFERENTIAL NEURAL** NETWORK ' **PISTONS** (see NEURAL **NETWORK** PSFs at the SH focal plane section)

## -IN THE FUTURE

### TAKING A STEP FURTHER TOWARD **REAL WORLD APPLICATION**

We will include noise, polychromatism and use correlated turbulence phase screens in the coming simulations.



#### BUILDING MORE INSIGHTS ON THE IMAGE FORMATION **PROCESS**

We will try to better understand the behavior of the speckles created by the petaling to propose ameliorations to our algorithm.

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