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METAS Uncertainty Library

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Introduction

Problem

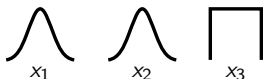
Computation of measurement uncertainties according to ISO-GUM.

Solution

1. Identify all uncertainty influences.
2. Set up a measurement model.
3. Propagate all uncertainties through this model.

Uncertainty according to ISO-GUM (scalar)

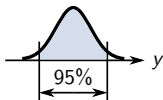
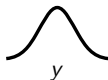
Input quantities



Measurement model



Output quantity



Linear uncertainty propagation

Input standard uncertainties $u(x_1)$, $u(x_2)$, $u(x_3)$

Sensitivities $\frac{\partial f}{\partial x_1}$, $\frac{\partial f}{\partial x_2}$, $\frac{\partial f}{\partial x_3}$

Output standard uncertainty $u^2(y) = \left(\frac{\partial f}{\partial x_1}\right)^2 u^2(x_1) + \left(\frac{\partial f}{\partial x_2}\right)^2 u^2(x_2) + \left(\frac{\partial f}{\partial x_3}\right)^2 u^2(x_3)$

Expanded uncertainty $U^2(y) = (1.96)^2 u^2(y)$

Derivative $f'(x) = \frac{d}{dx}f(x)$

The **derivative** $f'(x)$ of a **function** $y = f(x)$ of a real variable measures the sensitivity to change of the function value (**output value** y) with respect to a change in its argument (**input value** x).

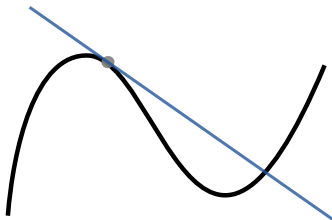


Figure: The graph of a function, drawn in black, and a tangent line to that function, drawn in blue. The slope of the tangent line is equal to the derivative of the function at the marked point.

The basic rules for derivatives

Derivatives $f'(x) = \frac{d}{dx}f(x)$

- ▶ $\frac{d}{dx}ax = a$
- ▶ $\frac{d}{dx}x^b = bx^{b-1}$
- ▶ $\frac{d}{dx}e^x = e^x$
- ▶ $\frac{d}{dx}\ln(x) = \frac{1}{x}$
- ▶ $\frac{d}{dx}\sin(x) = \cos(x)$
- ▶ $\frac{d}{dx}\cos(x) = -\sin(x)$

Partial derivatives $\frac{\partial}{\partial x_i}f(x_1, \dots, x_N)$

- ▶ $\frac{\partial}{\partial a}(a + b) = 1, \frac{\partial}{\partial b}(a + b) = 1$
- ▶ $\frac{\partial}{\partial a}ab = b$ and $\frac{\partial}{\partial b}ab = a$

Sum rule

$$(\alpha f + \beta g)' = \alpha f' + \beta g'$$

Chain rule

If $f(x) = h(g(x))$ then

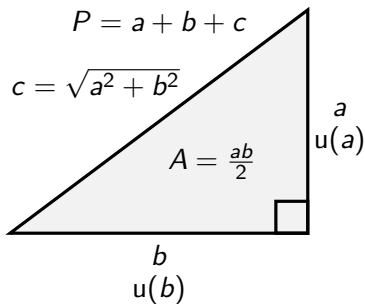
$$f'(x) = h'(g(x)) \cdot g'(x)$$

If $z = h(y)$ and $y = g(x)$
then

$$\frac{dz}{dx} = \frac{dz}{dy} \cdot \frac{dy}{dx}$$

Right triangle example

- ▶ Cathetus $a = 3$, $u(a) = 0.3$
- ▶ Cathetus $b = 4$, $u(b) = 0.4$
- ▶ What's the value and unc of the hypotenuse c ?
- ▶ What's the value and unc of the perimeter P ?
- ▶ What's the value and unc of the area A ?



Solving the right triangle example by hand

| Step | Function | Partial Derivatives | Chain Rule |
|------|-------------------------|--|--|
| 1, 2 | $a = 3, b = 4$ | | |
| 3 | $x_1 = a^2 = 9$ | $\frac{\partial x_1}{\partial a} = 2a = 6$ | |
| 4 | $x_2 = b^2 = 16$ | $\frac{\partial x_2}{\partial b} = 2b = 8$ | |
| 5 | $x_3 = x_1 + x_2 = 25$ | $\frac{\partial x_3}{\partial x_1} = 1, \frac{\partial x_3}{\partial x_2} = 1$ | $\frac{\partial x_3}{\partial x_1} \frac{\partial x_1}{\partial a} = 6, \frac{\partial x_3}{\partial b} = 8$ |
| 6 | $c = \sqrt{x_3} = 5$ | $\frac{\partial c}{\partial x_3} = \frac{1}{2\sqrt{x_3}} = 0.1$ | $\frac{\partial c}{\partial a} = 0.6, \frac{\partial c}{\partial b} = 0.8$ |
| 7 | $x_4 = a + b = 7$ | $\frac{\partial x_4}{\partial a} = 1, \frac{\partial x_4}{\partial b} = 1$ | |
| 8 | $P = x_4 + c = 12$ | $\frac{\partial P}{\partial x_4} = 1, \frac{\partial P}{\partial c} = 1$ | $\frac{\partial P}{\partial a} = 1.6, \frac{\partial P}{\partial b} = 1.8$ |
| 9 | $x_5 = ab = 12$ | $\frac{\partial x_5}{\partial a} = b, \frac{\partial x_5}{\partial b} = a$ | |
| 10 | $A = \frac{x_5}{2} = 6$ | $\frac{\partial A}{\partial x_5} = 0.5$ | $\frac{\partial A}{\partial a} = 2, \frac{\partial A}{\partial b} = 1.5$ |

Solving the right triangle example by hand

11. What's the value and unc of the hypotenuse c ?

▶ $c = 5$

▶ $u^2(c) = \left(\frac{\partial c}{\partial a}\right)^2 u^2(a) + \left(\frac{\partial c}{\partial b}\right)^2 u^2(b) = (0.6 \cdot 0.3)^2 + (0.8 \cdot 0.4)^2$

▶ $u(c) = \sqrt{0.1348} = 0.3672$

12. What's the value and unc of the perimeter P ?

▶ $P = 12$

▶ $u^2(P) = \left(\frac{\partial P}{\partial a}\right)^2 u^2(a) + \left(\frac{\partial P}{\partial b}\right)^2 u^2(b) = (1.6 \cdot 0.3)^2 + (1.8 \cdot 0.4)^2$

▶ $u(P) = \sqrt{0.7488} = 0.8653$

13. What's the value and unc of the area A ?

▶ $A = 6$

▶ $u^2(A) = \left(\frac{\partial A}{\partial a}\right)^2 u^2(a) + \left(\frac{\partial A}{\partial b}\right)^2 u^2(b) = (2 \cdot 0.3)^2 + (0.8 \cdot 1.5)^2$

▶ $u(A) = \sqrt{0.7200} = 0.8485$

Solving the right triangle example using a PC

Which steps could be automated?

1. Decomposition of the measurement model into elementary functions. Implemented in any compiler or interpreter.
2. Partial derivatives of elementary functions $\frac{\partial}{\partial x_i} f(x_1, \dots, x_N)$.
3. Sum $(\alpha f + \beta g)' = \alpha f' + \beta g'$ and Chain rule $\frac{\partial z}{\partial x} = \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial x}$.
4. Uncertainty propagation

$$u^2(y) = \left(\frac{\partial f}{\partial x_1}\right)^2 u^2(x_1) + \left(\frac{\partial f}{\partial x_2}\right)^2 u^2(x_2) + \dots + \left(\frac{\partial f}{\partial x_N}\right)^2 u^2(x_N).$$

Combination of steps 2 and 3 is called **automatic differentiation**.
METAS UncLib implements steps 2 to 4 in the **LinProp** module.

Solving the right triangle example using Python

```
# Definition of the input uncertainty objects
from metas_unclib import *           # import METAS UncLib
use_linprop()                        # linear unc propagation
a = ufloat(3.0, 0.3, desc='a')      # value 3, stdunc 0.3
b = ufloat(4.0, 0.4, desc='b')      # value 4, stdunc 0.4

# Compute output quantities
c = umath.sqrt(a**2 + b**2)         # hypotenuse
P = a + b + c                       # perimeter
A = a * b / 2.0                     # area
```

```
--> c = (5.0 +/- 0.367151)
--> P = (12.0 +/- 0.865332)
--> A = (6.0 +/- 0.848528)
```

METAS UncLib

- ▶ METAS UncLib is a C# software library.
- ▶ It supports creation of uncertainty objects and subsequent calculation with them as well as storage of the results.
- ▶ It's able to handle complex-valued and multivariate quantities.
- ▶ Object-oriented implementation and overloaded operators hide the complexity from the user.
- ▶ It has been developed with Visual Studio 2008, 2013 and 2019.
- ▶ METAS UncLib V2.8 requires the .NET Framework V4.6.2.
- ▶ An Installer (msi-file) for METAS UncLib is available for free at www.metas.ch/unclib.

Python Wrapper

- ▶ METAS UncLib Python is an extension to Python.
- ▶ It supports creation of uncertainty objects and subsequent calculation with them as well as storage of the results.
- ▶ It's able to handle complex-valued and multivariate quantities.
- ▶ It has been developed with Python V3.6 ([numpy](#), [pythonnet](#)).
- ▶ It requires the C# library [METAS UncLib](#) in the background.
- ▶ The classes `ufloat`, `ucomplex`, `ufloatarray` and `ucomplexarray` wrap [METAS UncLib](#) to Python over the .NET interface ([pythonnet](#)).
- ▶ The Python wrapper, several examples and a tutorial are part of the [METAS UncLib Installer](#) (msi-file) or the [metas-unclib](#) (pypi package).

Pendulum example

Gravitational acceleration in m/s^2

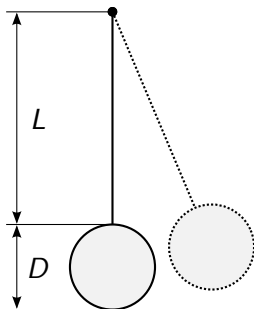
$$g = \frac{4\pi^2}{\tau^2} \left(L + \frac{D}{2} + \frac{D^2}{5(2L + D)} \right)$$

where

τ is the period in s

L is the length in m

D is the diameter in m



Solving the pendulum example using Python

```
from metas_unclib import * # import METAS UncLib
use_linprop()              # linear unc propagation

# Input quantities time measurement
n_periods = 20

n_tau_meas = ufloatfromdistribution(
    StudentTDistribution(24.9060, 0.0712 / np.sqrt(10), 9),
    desc='Time_N_Periods_Measurement_/s')

dtau_react = ufloatfromdistribution(
    UniformDistribution(-0.1, 0.1),
    desc='Time_Reaction_/s')

dtau_res = ufloatfromdistribution(
    UniformDistribution(-0.005, 0.005),
    desc='Time_Resolution_/s')
```

Solving the pendulum example using Python

```
# Input quantities length measurement
L_meas = ufloatfromdistribution(
    StudentTDistribution(0.33316, 0.00026 / np.sqrt(6), 5),
    desc='Length_Measurement_/_m')

dL_res = ufloatfromdistribution(
    UniformDistribution(-0.0005, 0.0005),
    desc='Length_Resolution_/_m')

dL_read = ufloatfromdistribution(
    TriangularDistribution(-0.0005, 0.0005),
    desc='Length_Reading_/_m')
```


Solving the pendulum example using Python

```
# Input quantities diameter measurement
D_meas = ufloatfromdistribution(
    StudentTDistribution(0.1005, 0.000058 / np.sqrt(4), 3),
    desc='Diameter_Measurement_/_m')

dD_res = ufloatfromdistribution(
    UniformDistribution(-0.001, 0.001),
    desc='Diameter_Resolution_/_m')

dD_read = ufloatfromdistribution(
    TriangularDistribution(-0.0005, 0.0005),
    desc='Diameter_Reading_/_m')
```

Solving the pendulum example using Python

```
# Measurement model
n_tau = n_tau_meas + dtau_res + dtau_react
tau = n_tau / n_periods
L = L_meas + dL_res + dL_read
D = D_meas + dD_res + dD_read

g = 4 * np.pi**2 / tau**2 * (L + D / 2 +
                              (D**2 / (5 * (2 * L + D))))

# Output quantatly
print(g)
unc_budget(g)

--> g = (9.8276 +/- 0.0507)
```

Solving the pendulum example using Python


| <div>  Id Detail Dof Flat Expand All Collapse All Numeric Format: f6 Copy </div> | | | | | | | |
|---|--------------|-----------|--------------|----------------|---------------|----------------|-----|
| Value | | Std Unc | | U95 (k = 1.96) | | Effective Dof | |
| 9.827633 | | 0.050571 | | 0.099321 | | 590 | |
| Description | Distribution | Value | Standard Unc | Sensitivity | Unc Component | Unc Percentage | Dof |
| <input type="checkbox"/> Diameter Measurement / m | StudentT | 0.100500 | 0.000029 | 13.975757 | 0.000405 | 0.006 | 3 |
| <input type="checkbox"/> Diameter Reading / m | Triangular | 0.000000 | 0.000204 | 13.975757 | 0.002853 | 0.318 | ∞ |
| <input type="checkbox"/> Diameter Resolution / m | Uniform | 0.000000 | 0.000577 | 13.975757 | 0.008069 | 2.546 | ∞ |
| <input type="checkbox"/> Length Measurement / m | StudentT | 0.333160 | 0.000106 | 25.282355 | 0.002684 | 0.282 | 5 |
| <input type="checkbox"/> Length Reading / m | Triangular | 0.000000 | 0.000204 | 25.282355 | 0.005161 | 1.041 | ∞ |
| <input type="checkbox"/> Length Resolution / m | Uniform | 0.000000 | 0.000289 | 25.282355 | 0.007298 | 2.083 | ∞ |
| <input type="checkbox"/> Time N Periods Measurement / s | StudentT | 24.906000 | 0.022515 | -0.789178 | 0.017769 | 12.345 | 9 |
| <input type="checkbox"/> Time Reaction / s | Uniform | 0.000000 | 0.057735 | -0.789178 | 0.045563 | 81.175 | ∞ |
| <input type="checkbox"/> Time Resolution / s | Uniform | 0.000000 | 0.002887 | -0.789178 | 0.002278 | 0.203 | ∞ |

Figure: Uncertainty budget of gravitational acceleration g in m/s^2

Conclusion

METAS UncLib

- ▶ Generic software library for propagation of uncertainties.
- ▶ Is able to handle complex-valued and multivariate quantities.
- ▶ Can be used from C# (Visual Studio), MATLAB or Python.
- ▶ Used in many labs at METAS and around the world.
- ▶ Used in large applications like METAS VNA Tools.
- ▶ Available for free since 2009 at www.metas.ch/unclib.

Validation

- ▶ Only derivatives of elementary functions are programmed. Elementary functions are easy to check.
- ▶ Overloaded operators hide the complexity from the user.
- ▶ User has the possibility to check if the unc budget is plausible.