

(Autonomous) (ISO/IEC - 27001 - 2013 Certified)

WINTER – 2019 EXAMINATION

Subject Name: Operating System <u>Model Answer</u> Subject Code: 22516

Important Instructions to examiners:

- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more Importance (Not applicable for subject English and Communication Skills.
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

	a .		3.5. 1.
Q.	Sub	Answer	Marking
No	Q.		Scheme
•	N.		
1.		Attempt any Five of the following:	10 M
	. 3	Define real time operating system. List its any four applications of	2 M
		it.	
	Ans	Real time Operating System:	1 Mark :-
		A real time system has well defined fixed time constraints. Processing	Definition;
		should be done within the defined constraints -Hard and Soft real time	1 Mark :-
		system.	for any 4
		OR	correct
		The real-time operating system used for a real-time application means	application
		for those applications where data processing should be done in the fixed	S
		and small quantum of time.	~
		Types of real time operating system	
		1. Hard real-time	
		2. Soft real-time	
		Applications:	
		1. Flight Control System	
		2. Simulations	
		3. Industrial control	
		4. Military applications	



b	Explain any 4 services provided by OS. + +xt pg (2-2)	2 M
Ans	1.User Interface: All operating systems have a user interface that allows users to communicate with the system. Three types of user interfaces are available: a. Command line interface (CLI) b. Batch interface c. Graphical user interface (GUI)	1 marks for explaining any 4 services
	2. Program execution: The operating system provides an environment where the user can conveniently run programs. It also performs other important tasks like allocation and deallocation of memory, CPU scheduling etc. It also provides service to end process execution either normally or abnormally by indicating error.	
•	3. I/O operations: When a program is running, it may require input/output resources such as a file or devices such as printer. So the operating system provides a service to do I/O.	
•	4.File system manipulation: Programs may need to read and write data from and to the files and directories. Operating system manages the secondary storage. Operating system makes it easier for user programs to accomplish their task such as opening a file, saving a file and deleting a file from the storage disk.	
•	5.Communication: In the system, one process may need to exchange information with another process. Communication can be implemented via shared memory or through message passing, in which packets of information are moved between processes by the operating system.	
	6.Error detection: Operating systems detects CPU and memory hardware such as a memory error or power failure, a connection failure on a network or lack of paper in the printer etc.	
•	7.Resource allocation: Operating system manages resource allocation to the processes. These resources are CPU, main memory, file storage and I/O devices.	
•	8.Accounting: Operating system keeps track of usages of various computer resources allocated to users.	
	9.Protection & security: When several separate processes execute concurrently, one process should not interfere with the other processes or operating system itself. Protection provides controlled access to system resources. Security is provided by user authentication such as password for accessing information.	



	Draw process state diagram.	2 M
Ans	new admitted interrupt exit terminated ready running l/O or event completion waiting process state diagram	2 Marks:- for correct well labelled diagram (1 mark:- specifying correct states in the diagram)
d	Explain any four scheduling criteria.	2 M
Ans	 CPU utilization: In multiprogramming the main objective is to keep CPU as busy as possible. CPU utilization can range from 0 to 100 percent. Throughput: It is the number of processes that are completed per unit time. It is a measure of work done in the system. When CPU is busy in executing processes, then work is being done in the system. Throughput depends on the execution time required for any process. For long processes, throughput can be one process per unit time whereas for short processes it may be 10 processes per unit time. Turnaround time: The time interval from the time of submission of a process to the time of completion of that process is called as turnaround time. It is the sum of time period spent waiting to get into the memory, waiting in the ready queue, executing with the CPU, and doing I/O operations. Waiting time: It is the sum of time periods spent in the ready queue by a process. When a process is selected from job pool, it is loaded into the main memory (ready queue). A process waits in ready queue till CPU is allocated to it. Once the CPU is allocated to the process, it starts its execution and if required request for resources. When the resources are not available that process goes into waiting state and when I/O request completes, it goes back to ready queue. In ready queue again it waits for CPU allocation. 	Any four scheduling criteria: 1/2 mark each
	5.Response time: The time period from the submission of a request until the first response is produced is called as response time. It is the time when system responds to the process request not the completion of	



a process. In the system, a process can Produce some output fairly early and can continue computing new results while previous results are being output to the user.			
e Define virtual memory			
Virtual memory is a memory management capability of an operating system (OS) that uses hardware and software to allow a computer to compensate for physical memory shortages by temporarily transferring data from random access memory (RAM) to disk storage. OR Virtual memory is the separation of user logical memory from physical memory. This separation allows an extremely large virtual memory to be provided for programmers when only a smaller physical memory is available. Virtual memory makes the task of programming much easier, because the programmer no longer needs to worry about the amount of	2 M 2 marks for any relevant definition		
<u> </u>			
· · · · · · · · · · · · · · · · · · ·	2 M		
Syntax: sleep NUMBER[SUFFIX] sleep OPTION ii) kill	1 mark each for correct syntax		
· ·	2 M		
 File attributes: Name: The symbolic file name is the only information kept in human readable form. Identifier: File system gives a unique tag or number that identifies file within file system and which is used to refer files internally. Type: This information is needed for those systems that support different types. Location: This information is a pointer to a device and to the location of the file on that device. Size: The current size of the file (in bytes, words or blocks) and possibly the maximum allowed size are included in this attribute. Protection: Access control information determines that who can do reading, writing, executing and so on. Time, Date and User Identification: This information may be kept for creation, Last modification and last use. These data can be useful for protection, security and usage monitoring. 	Any four attributes: ½ mark each		
	and can continue computing new results while previous results are being output to the user. Define virtual memory Virtual memory is a memory management capability of an operating system (OS) that uses hardware and software to allow a computer to compensate for physical memory shortages by temporarily transferring data from random access memory (RAM) to disk storage. OR Virtual memory is the separation of user logical memory from physical memory. This separation allows an extremely large virtual memory to be provided for programmers when only a smaller physical memory is available. Virtual memory makes the task of programming much easier, because the programmer no longer needs to worry about the amount of physical memory available, or about what code can be placed in overlays, but can concentrate instead on the problem to be programmed. Write syntax for following commands: i)Sleep ii)Kill isleep Syntax: sleep NUMBER[SUFFIX] sleep OPTION ii) kill Syntax: kill pid Describe any four file attributes File attributes: Name: The symbolic file name is the only information kept in human readable form. Identifier: File system gives a unique tag or number that identifies file within file system and which is used to refer files internally. Type: This information is needed for those systems that support different types. Location: This information is a pointer to a device and to the location of the file on that device. Size: The current size of the file (in bytes, words or blocks) and possibly the maximum allowed size are included in this attribute. Protection: Access control information determines that who can do reading, writing, executing and so on. Time, Date and User Identification: This information may be kept for creation, Last modification and last use. These data can		



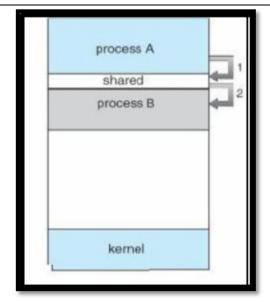
2.	Attempt any Three of the following:	12M		
a	Enlist types of operating system. Explain multiprogramming OS in	4M		
	detail.			
Ar		1 Mark:-		
	1.Batch Systems	Listing;		
	2.Multiprogramming	1 Mark:-		
	3.Multitasking	Diagram		
حمالقالمح	4.Time-Sharing Systems			
תהם אוווו	5.Desktop Systems	Explanatio		
	6.Distributed system	n		
	7.Clustered system			
	8.Real Time system:			
	Multiprogramming:			
	• In multiprogramming, more than one program lies in the			
	memory.			
	• The scheduler selects the jobs to be placed in ready queue from a			
	number of programs.			
	• The ready queue is placed in memory and the existence of more			
	than one program in main memory is known as			
	multiprogramming.			
	• Since there is only one processor, there multiple programs			
	cannot be executed at a time.			
	• Instead the operating system executes part of one program, then			
	the part of another and so on.			
	• Example of multiprogramming: user can open word, excel,			
	access and other applications in a system.			
	Program A Run Wait Run Wait Operating System			
	Program B Wait Run Wait Run Wait OR			
	Program C Wait Run Wait Run Wait Program 2			
	Combined A B C Wait A B C Wait A B C Program 3			
	Fig- Multiprogramming with three programs			
	1 ig- whiteprogramming with three programs			
la	List components of OS. Explain process management in detail.	4M		
Aı		1 Mark:-		
	1 Day again managament	Listing;		
	2. Main memory management 3. File management	3 Marks:-		
	3. File management	Explanation		
	4. I/O system management	_		
	5. Secondary storage management			
	3. Secondary storage management			

			diagram of model - 1 mark; explanation
		1. Shareu memory	mark;
		There are two models of IPC 1. Shared memory	communica tion -1
		exchange data and information.	process
		process communication (IPC) mechanism that will allow them to	inter
V	Ans	Inter-process communication: Cooperating processes require an Inter-	Define
	مرعر	With neat diagram explain inter process communication model.	4M
]	5. A mechanism for deadlock handling.	
		4. A mechanism for process communication.	
		3. A mechanism for process synchronization.	
		 Creation and deterior of user and system processes. Suspension and resumption of processes. 	
		process management are 1. Creation and deletion of user and system processes.	
		• The five major activities of an operating system in regard to	
		interrupts and user input.	
		suspending the execution only long enough to deal with	
		• The operating system allows the application to begin running,	
		tasking system, the schedule is straightforward.	
		controls and schedules for execution by the CPU. In a single-	
		 It is processes, rather than applications, that the operating system 	
		other applications or by the operating system.	
		direct evidence that they ever exist. A process, then, is software that performs some action and can be controlled by a user, by	
		• There are also numerous processes that run without giving you	
		devices or other computers.	
		processes to begin, for tasks like communications with other	
		is, indeed, a process, but that application may cause several other	
		• The application you see (word processor or spreadsheet or game)	
		operating system and hardware.	
		gives an incomplete picture of how processes relate to the	
		a thread, depending on the operating system.It's tempting to think of a process as an application, but that	
		scheduling the work done by the processor is either a process or	
		• The basic unit of software that the operating system deals with in	
		PC, registers, OS resources in use etc.).	
		• A process includes the complete execution context (code, data,	
		Each of these activities is encapsulated in a process.	
		spooler, name servers, file server etc.	
		activities ranging from user programs to system programs like printer	



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- 2 marks



- In this, all processes who want to communicate with other processes can access a region of the memory residing in an address space of a process creating a shared memory segment.
- All the processes using the shared memory segment should attach to the address space of the shared memory. All the processes can exchange information by reading and/or writing data in shared memory segment.
- The form of data and location are determined by these processes who want to communicate with each other.
- These processes are not under the control of the operating system.
- The processes are also responsible for ensuring that they are not writing to the same location simultaneously.
- After establishing shared memory segment, all accesses to the shared memory segment are treated as routine memory access and without assistance of kernel.

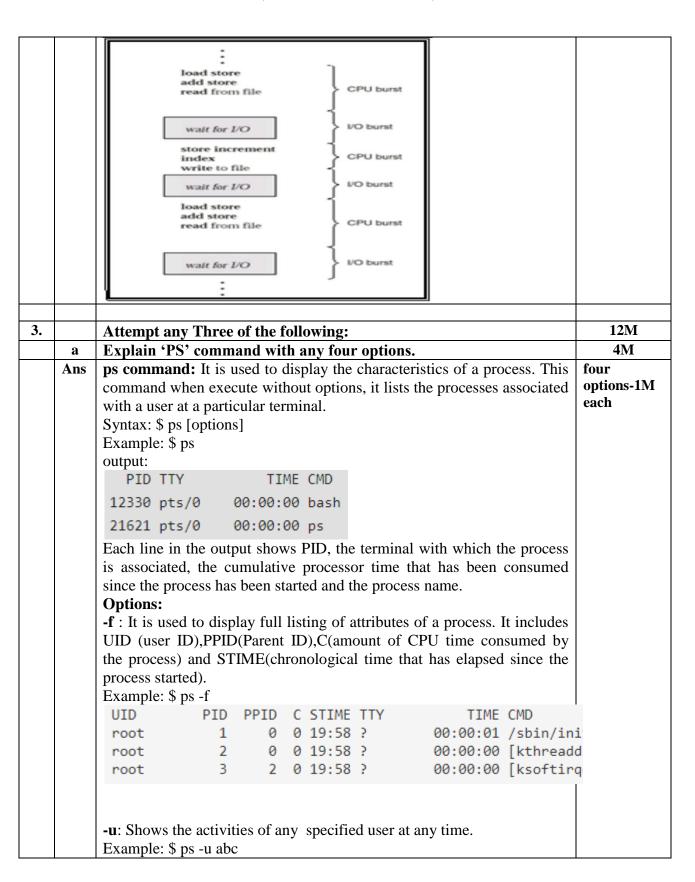
2. Message Passing

- In this model, communication takes place by exchanging messages between cooperating processes.
- It allows processes to communicate and synchronize their action without sharing the same address space.
- It is particularly useful in a distributed environment when communication process may reside on a different computer connected by a network.
- Communication requires sending and receiving messages through the kernel.



d	• The processes that want to communicate with each other must have a communication link between them. Between each pair of processes exactly one communication link. Describe I/O Burst and CPU Burst cycle with neat diagram.	4M
Ans		Explanatio n: 2 marks, Diagram:2 marks







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PID TTY TIME CMD 1053 ? 00:00:00 systemd 1062 ? 00:00:00 (sd-pam) 00:00:00 zsh 1074 tty1 -a: It shows the processes of all users. Example: \$ ps -a PID TTY TIME CMD 27011 pts/0 00:00:00 man 27016 pts/0 00:00:00 less 27499 pts/1 00:00:00 ps -e: It displays processes including user and system processes. example: \$ ps -e PID TTY TIME CMD 00:00:05 systemd 00:00:00 kthreadd 3 00:00:00 ksoftirgd/0 5 00:00:00 kworker/0:0H 00:00:01 rcu sched 7 ? 8 ? 00:00:00 rcu bh **4M** b Explain deadlock? What are necessary conditions for deadlock? In multiprogramming environment, several processes may compete for a finite Deadlock Ans number of resources. A process requests resources and if the resources are not descriptionavailable then the process enters into the waiting state. Sometimes a waiting 2M, process is never again able to change its status because the resources requested necessary by it are held by other waiting processes. This situation is called as **deadlock**. conditions -When a process request for resources held by another waiting process which in 1/2 M each turn is waiting for resources held by another waiting process and not a single process can execute its task, then deadlock occurs in the system. **Example:** Consider a system with three disk drives and three processes. When each process request one disk drive, system allocates one disk drive to each process. Now there is no more drive available in the system. If all three processes request for one more disk drive, then all three processes will go into the waiting state and system will go in deadlock state. Because any one process from the three can execute only when one of them will release the disk drive allocated to it. **Necessary Conditions:** 1. Mutual exclusion: At least one resource must be held in a nonsharable mode; that is, only one process at a time can use the resource. 2. Hold and Wait: A process must be holding at least one resource and waiting to acquire additional resources that are currently being held by



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other processes. **3. No pre-emption:** Resources cannot be pre-empted i.e a resource can be released only voluntarily by the process holding it. **4. Circular wait:** A set $\{P_0, P_1 \dots P_n\}$ of waiting processes must exist such that P₀ is waiting for a resource held by P₁,P₁ is waiting for a resource held by $P_2,...,P_{n-1}$ is waiting for a resource held by P_n and P_n is waiting for a resource held by P₀. Each process is waiting for the resources held by other waiting processes in circular form. Explain partitioning and its types. **4M** c An important operation of memory management is to bring programs **Explanation** Ans into main memory for execution by the processor. Partitioning is a of fixed technique that divides a memory into multiple partitions. These partitioning partitions can be of different size or same size. -2M, Types of partitioning Variable • Fixed partitioning i.e. static partitioning partitioning-Variable partitioning i.e. dynamic partitioning 2M**Fixed Partitioning:** Main memory is divided into multiple partitions of fixed size at the time of system generation. A process may be loaded into a partition of equal size or greater size. Partitions can be of equal size or unequal size. **Equal size partitioning**: Main memory is divided into equal size partitions. Any process with less or equal size can be loaded in any available partition. OR ting syste Unequal size partitioning: Main memory is GNI divided into multiple partitions of unequal size. Each process can be loaded into the smallest partition within which the process will fit. Variable partitioning: When a process enters in main memory, it is allocated exact size that is required by that process. So in this method, partitions can vary in size depending on memory space required by a process entering in main memory. Operating system maintains a table indicating which parts of memory are available and which are occupied. When new process arrives and it needs space, system searches for

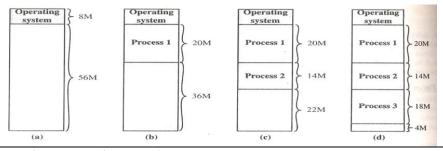


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available memory space in main memory. If it is available, then memory is allocated to the process by creating a partition in memory.

For example: Consider following table with process and memory space.

Process	Memory space
P1	20 M
P2	14 M
P3	18 M



d Describe sequential and direct access method.

4M

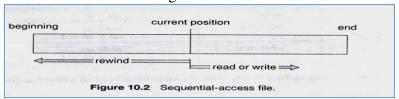
Ans

Sequential access: Information from the file is processed in order i.e. one record after another. It is commonly used access mode. For example, editors and compilers access files in sequence.

A read operation read information from the file in a sequence i.e. read next reads the next portion of the file and automatically advances a file pointer.

A write operation writes information into the file in a sequence i.e. write next appends to the end of the file and advances to the end of the newly written material. Such a file can be reset to the beginning.

In some operating systems, a program may be able to skip forward or backward n records for some integer n.



As shown in above diagram, a file can be rewind (moved in backward direction) from the current position to start with beginning of the file or it can be read or write in forward direction.

Direct access: It is also called as relative access. A file is made up of fixed length logical records that allow programs to read and write records rapidly in no particular order. Direct access method is based on disk model of a file which allows random access to any file block.

For direct access a file is viewed as a numbered sequence of blocks or records. So we can directly read block 14, then block 53 and so on. This method is used for immediate access to large amount of information. Database can be accessed with direct access method. For example, when

description of sequential access-2M, Direct access-2M



		a query concerning a particular subject arrives, we compute which block contains the answer and then read that block directly to provide the	
		desired information.	
		Read n operation is used to read the nth block from the file whereas	
		write n is used to write in that block. The block numbers provided by	
		the user to the operating system is a relative block number. A relative	
		block number is an index relative to the beginning of the file. The first	
		relative block of file is 0; the next is 1 and so on. Actual absolute disk	
		address of the block is different from the relative address. The use of	
		relative block numbers allow the operating system to decide where the	
		file should be placed and helps t prevent the user from accessing	
		portions of the file system that may not be part of his file.	
		portions of the me system that may not be part of his me.	
4		Attempt any Three of the following:	12M
	a	Write Unix command for following:	4M
		i)create a folder OSY ii) create a file FIRST in OSY folder	
		iii) List/display all files and directories.	
		iv) Write command to clear the screen	
	Ans	i) create a folder OSY:	Each correct
		\$mkdir OSY	command-
			1M
		ii)create a file FIRST in OSY folder:	
		\$cd OSY	
		\$cat>FIRST or \$ touch FIRST	
		iii) List/display all files and directories:	
		\$1s	
		410	
		iv) to clear screen:	
		\$clear	
	. 16	What is purpose of system call? State two system calls with their	4M
		functions.	
	Ans	System call provides an interface between a running program and	purpose of
		operating system. It allows user to access services provided by	system call-
		operating system. This system calls are procedures written using C,	2M, Two
		C++ and assembly language instructions. Each operating system has its	system calls- 1M each
		own name for each system call. Each system call is associated with a	11vi each
		number that identifies itself.	
		System calls:	
		Process Control: Program in execution is a process. A process to be	
		executed must be loaded in main memory. while executing it may need	
		to wait, terminate or create & terminate child processes.	
		• end, abort	
		load, execute	
1	I	 create process, terminate process 	

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- get process attributes, set process attributes
- wait for time
- wait event, signal event
- allocate and free memory

File Management: System allows us to create and delete files. For create and delete operation system call requires the name of the file and other attributes of the file. File attributes include file type, file size, protection codes, accounting information and so on. Systems access these attributes for performing operations on file and directories. Once the file is created, we can open it and use it. System also allows performing reading, writing or repositioning operations on file.

- create file, delete file
- open, close
- read, write, reposition
- get file attributes, set device attributes
- logically attach or detach devices
- **3. Device Management:** When a process is in running state, it requires several resources to execute. These resources include main memory, disk drives, files and so on. If the resource is available, it is assigned to the process. Once the resource is allocated to the process, process can read, write and reposition the device.
 - request device, release device
 - read, write, reposition
 - get device attributes, set device attributes
 - logically attach or detach devices
- **4. Information Maintenance:** Transferring information between the user program and the operating system requires system call. System information includes displaying current date and time, the number of current user, the version number of the operating system, the amount of free memory or disk space and so on. Operating system keeps information about all its processes that can be accessed with system calls such as get process attributes and set process attributes.
 - get time or date, set time or date
 - get system data, set system data
 - get process, file, or devices attributes
 - set process, file, or devices attributes
- **5. Communication:** Processes in the system, communicate with each other. Communication is done by using two models: message passing and shared memory. For transferring messages, sender process connects itself to receiving process by specifying receiving process



	name or identity. Once the communication is over existen close the	
	name or identity. Once the communication is over system close the	
	connection between communicating processes.	
	 create, delete communication connection 	
	 send, receive messages 	
	• transfer status information	
	attach or detach remote devices.	
/	State and describe types of scheduler.	4M
Ans	There are three types of scheduler:	list-1M,
	• Long term scheduler	description
	Short term scheduler	of each-1
	Medium term scheduler	01 04011 1
	• Wediam term scheduler	
02	 Long term scheduler: It selects programs from job pool and loads them into the main memory. It controls the degree of multiprogramming. The degree of multiprogramming is the number of processes loaded (existing) into the main memory. System contains I/O bound processes and CPU bound processes. An I/O bound process spends more time for doing I/O operations whereas CPU bound process spends more time in doing computations with the CPU. So It is the responsibility of long term scheduler to balance the system by loading some I/O bound and some CPU bound processed into the main memory. Long term scheduler executes only when a process leaves the system, so it executes less frequently. When long term scheduler selects a process from job pool, the state of process changes from new to ready state. Short term scheduler: It is also known as CPU scheduler. This scheduler selects processes that are ready for execution from the ready queue and allocates the CPU to the selected process. Frequency of execution of short term scheduler is more than other 	
	schedulers. When short term scheduler selects a process, the state of process changes from ready to running state.	
	3.Medium term scheduler : When a process is in running state, due to some interrupt it is blocked. System swaps out blocked process and store it into a blocked and swapped out process queue. When space is	
	available in the main memory, the operating system looks at the list of swapped out but ready processes. The medium term scheduler selects one process from that list and loads it into the ready queue. The job of	
	medium term scheduler is to select a process from swapped out	
	process queue and to load it into the main memory. This scheduler	
	works in close communication with long term scheduler for loading	
	process into the main memory.	
	process into the main memory.	
ماور	Explain Round Robin algorithm with suitable example.	4M



Ans	It is preemptive scheduling algorithm. A small unit of time known as a	explanation						
	time quantum or time slice is used for pre-emption of a currently	of round						
	running process. Ready queue is implemented as a circular queue. CPU	robin -2M,						
	is assigned to the entire processes one by one, on first come first serve							
	basis, for a specific time period. Every process executes for specified							
	time period and CPU is given to the next process when time quantum							
	expires.							
	A new process is added at the tail of the ready queue when it enters							
	the system. CPU scheduler selects first process from head of the ready							
	queue and executes it for a specified time quantum. Once the time							
	quantum expires, dispatcher is invoked to pre-empt current running							
	process and CPU is given to the next process placed at the head of the							
	ready queue. The running process may have a CPU burst time less or							
	greater than time quantum. If burst time of running process is less than							
	the time quantum then, the process itself releases the CPU. The							
	scheduler then selects next process from ready queue and executes it. If							
	burst time of running process is longer than time quantum then, context							
	switch occurs and the process is place at the tail of ready queue for							
	remaining burst time execution.							
	Example:							
	Process Burst Time							
	$\overline{P_1}$ 24							
	P_2 3							
	P_3 3							
	Time quantum: 4 ms							
	The resulting RR schedule is as follows:							
	$egin{array}{ c c c c c c c c c c c c c c c c c c c$							
	0 4 7 10 14 18 22 26 30							
	CPU is allocated to process P ₁ for 4 ms. Since it requires another 20							
	milliseconds, it is preempted after the first time quantum and the CPU							
	is given to the next process in the queue, process P ₂ . Process P ₂ does							
	not need 4 milliseconds, so it quits before its time quantum expires.							
	The CPU is then given to the next process, process P ₃ . Once each							
	process has received 1 time quantum, the CPU returns to process P ₁							
	for an additional time quantum.							
V	Explain PCB with diagram.	4M						
Ans	Each process is represented as a process control block (PCB) in the	explanation-						
	operating system. It contains information associated with specific	2M, diagram-2M						
	process. Process States It indicates suggests of a process Process state can	uiagi aiii-21VI						
	Process State: It indicates current state of a process. Process state can							
	be new, ready, running, waiting and terminated.							
	Process number: Each process is associated with a unique number							
		16 2 6						



		which is known process such as list of the care process and designed.			
		designed.	process state process number		
			registers		
			memory limits		
			list of open files		
			• • •		
5		Attempt any Two o			12M
	a	_ `	g system tools. Explain an	y two in detail.	6M
	Ans	Following are the o			For List=2
		User ManageSecurity poli			Marks and Explanatio
		Security pointDevice Mana	-		n any two
		Performance	for 4		
		Task Schedu	Marks		
		A) User manageme			
		 User manage deleting a use in three ways Command linusermod, pasadministrator Useradd: With users 			



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Syntax: useradd -m -d /home/<userName> -

c "<userName>" <userName>

Example: useradd -m -d /home/xyz -c "xyz" xyz

File /etc/default/useradd contains some user default options. The command useradd -D can be used to display this file.

Syntax: useradd -D

Userdel: To delete a user account userdel command is used.

Syntax: userdel -r <userName>

Usermod: The command usermod is used to modify the properties of

an existing user.

Syntax: usermod -c <'newName'> <oldName>

Example: usermod -c 'vppoly' john

Using passwd command

Passwd: A user can set the password with the command passwd. Old

password has to be typed twice before entering the new one.

Syntax: passwd <userName> Example: passwd vppoly

B) Device Management:

Device management is the process of managing the implementation, operation and maintenance of a physical and/or virtual device.

All Linux device files are located in the /dev directory, which is an integral part of the root (/) filesystem because these device files must be available to the operating system during the boot process.

Example: ls -l /dev

Above example gives the list of device file from kernel.

Udev supplies a dynamic device directory containing only the nodes for devices which are connected to the system. It creates or removes the device node files in the /dev directory.

C) Performance Monitor:

It is very tough job for every system or network administrator to monitor and debug Linux System Performance problems every day.

The commands discussed below are some of the most fundamental commands when it comes to system analysis and debugging Linux server issues such as:

1) vmstat: Virtual memory statistics

The vmstat command reports information about processes, memory, paging, block IO, traps, and cpu activity.

\$ vmstat 3

2)top: Process activity monitoring command

	top command display Linux processes. It provides a dynamic real-time view of a running system i.e. actual process activity. By default, it displays the most CPU-intensive tasks running on the server and updates the list every five seconds. \$ top 3) free: Show Linux server memory usage free command shows the total amount of free and used physical and swap memory in the system, as well as the buffers used by the kernel. # free 4) iostat: Montor Linux average CPU load and disk activity iostat command report Central Processing Unit (CPU) statistics and input/output statistics for devices, partitions and network filesystems (NFS). # iostat 5) netstat Linux network and statistics monitoring tool netstat command displays network connections, routing tables, interface statistics, masquerade connections, and multicast memberships.	
	# netstat –tulpn	CD #
Ama	Explain multithreading model in detail.	6M
Ans	Many systems provide support for both user and kernel threads, resulting in different multithreading models. Following are three multithreading model:	Each model=2M
	Many-to-One Model	
	The many-to-one model maps many user-level threads to one	
	kernel thread.	
	 Thread management is done by the thread library in user space, so it is efficient; but the entire process will block if a thread makes a blocking system call. 	
	 Also, because only one thread can access the kernel at a time, multiple threads are unable to nm in parallel on multiprocessors. 	
	• Example: Green threads- a thread library available for Solaris	
	wernel thread	



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Advantages:

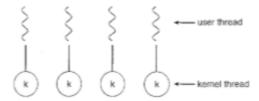
- More concurrency because of multiple threads can run in parallel on multiple CPUs.
- Less complication in the processing.

Disadvantages:

- Thread creation involves light-weight process creation.
- Kernel thread is an overhead.
- Limiting the number of total threads.

One-to-One Model

- The one-to-one model maps each user thread to a kernel thread.
- It provides more concurrency than the many-to-one model by allowing another thread to run when a thread makes a blocking system call; it also allows multiple threads to run in parallel on multiprocessors.
- The only drawback to this model is that creating a user thread requires creating the corresponding kernel thread.
- Because the overhead of creating kernel threads can burden the performance of an application, most implementations of this model restrict the number of threads supported by the system.
- Linux, along with the family of Windows operating systems, implement the one-to-one model.



Advantages:

- Mainly used in language system, portable libraries.
- One kernel thread controls multiple user thread.

Disadvantages:

- Parallelism is not supported by this model.
- One block can blocks all user threads.

Many-to-Many Model

- The many-to-many model multiplexes many user-level threads to a smaller or equal number of kernel threads.
- The number of kernel threads may be specific to either a particular application or a particular machine (an application may be allocated more kernel threads on a multiprocessor than on a uniprocessor).

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4χ ^t (۵	P		The one-to-one model allows for greater concurrency, but the developer has to be careful not to create too many threads within an application (and in some instances may be limited in the number of threads she can create). The many-to-many model suffers from neither of these shortcomings: developers can create as many user threads as necessary, and the corresponding kernel threads can run in parallel on a multiprocessor. Also, when a thread performs a blocking system call, the kernel can schedule another thread for execution. Advantages: Advantages:	
4X2	1		Many threads can be created as per user's requirement.	
	ر ا ا	7	Multiple kernel or equal to user threads can be created.	
(3	· TP	1	Disadvantages:	
			True concurrency cannot be achieved.	
-			Multiple threads of kernel is an overhead for operating system	0.5
		c	Explain LRU page replacement algorithm for following reference string. 7 0 1 2 0 3 0 4 2 3 0 3 2 1 2 0 1 7 0 1 Calculate the page fault.	6M
-		Ans	LRU:	LRU
			• The Least Recently Used (LRU) page replacement policy	explanation
			replaces the page that has not been used for the longest	=2M
			period of time.	Calculation =4 M
			• LRU replacement associates with each page the time of that page's last use.	— '+ 1 V 1
			 When a page must be replaced, LRU chooses the page that has 	
			not been used for the longest period of time.	
			The LRU policy is often used as a page-replacement algorithm	
			and is considered to be good.	
			An LRU page-replacement algorithm may require substantial hardware assistance.	
			hardware assistance.	
L				

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Counters:

- In the simplest case, we associate with each page-table entry a time-of-use field and add to the CPU a logical clock or counter.
- The clock is incremented for every memory reference.
- Whenever a reference to a page is made, the contents of the clock register are copied to the time-of-use field in the pagetable entry for that page.
- In this way, we always have the "time" of the last reference to each page. We replace the page with the smallest time value.

Stack:

- Another approach to implementing LRU replacement is to keep a stack of page numbers.
- Whenever a page is referenced, it is removed from the stack and put on the top.
- In this way, the most recently used page is always at the top of the stack and the least recently used page is always at the bottom.

Reference String: 7 0 1 2 0 3 0 4 2 3 0 3 2 1 2 0 1 7 0 1 (Frame size have not mentioned in question so assume frame size as 3 or 4)

LRU: Assume frame size=3

7	0	1	2	0	3	0	4	2	3	0	3	2	1	2	0	1	7	0	1
7	7	7	2		2		4	4	4	0			1		1	*	1		*
	0	0	0	*	0	*	0	0	3	3	*		3		0		0	*	
		1	1		3		3	2	2	2		*	2	*	2		7		

Page Fault=12

Assume frame size=4

	7	0	1	2	0	3	0	4	2	3	0	3	2	1	2	0	1	7	0	1
	7	7	7	7		3		3		*		*		3				7		
		0	0	0	*	0	*	0			*			0		*		0	*	
			1	1		1		4						1			*	1		*
-				2		2		2	*				*	2	*			2		

Page fault=08

6		Attempt any Two of the following:	12M
	a	The jobs are scheduled for execution as follows:	6M
			SJF=3 m
			FCFS=3 m
			(1m-gantt
			chart, 2m
			calculation



		Process	Arriv	val Time	Burst Ti	me		of AWT)
		P1		0	7			
		P2		1	4			
		P3		2	10			
		P4		3	6			
		P5		4	8			
	i)	SJF						
	,	FCFS						
	Also fin	nd average v	waiting tin	ne using Ga	antt chart.			
Ans	SJF:							Note:
		nptive SJF						
	Gantt Cha		1					
	P1	P2	P4	P5	P3			
	0	7	11	17	25	35		
	Process	Arrival	Burst	Waiti	nσ			
	Trocess	Time	Time	Time				
	P1	0	7	0				
	1	ŭ						
	P2	1	4	17-1=6				
	P2 P3	2	10	7-1=6 25-2=				
	P3	2	10	25-2=	23			
					23 8			
	P3 P4 P5	2 3	10 6 8	25-2= 11-3= 17-4=	23 8 13	0		
	P3 P4 P5	3 4	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5	23 8 13	0		
	P3 P4 P5	3 4	10 6 8 e=(0+6+23	25-2= 11-3= 17-4=	23 8 13	0		
	P3 P4 P5 Average w	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5	23 8 13	0		
	P3 P4 P5 Average w	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5	23 8 13	0		
	P3 P4 P5 Average w	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5	23 8 13	0 P3		
	P3 P4 P5 Average w	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5	23 8 13 5 = 50/5=1		35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5 OR	23 8 13 5 = 50/5=1	P3	35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1 0 1	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5 OR	23 8 13 5 = 50/5=1 P5 17 2	P3	35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1	2 3 4 vaiting Time	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5 OR	23 8 13 5 = 50/5=1	P3	35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1 0 1	2 3 4 vaiting Time	10 6 8 e=(0+6+23 P1 5 Burst Time	25-2= 11-3= 17-4= 3+08+13)/5 OR P4 11	23 8 13 5 = 50/5=10 P5 17 2	P3	35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1 0 1 Process P1	2 3 4 vaiting Time P2 Arrival Time 0	10 6 8 e=(0+6+23	25-2= 11-3= 17-4= 3+08+13)/5 OR P4 11 Waiti 0+(5-1)	23 8 13 5 = 50/5=1 P5 17 2 ng Time 1)=4	P3	35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1 0 1 Process P1 P2	2 3 4 vaiting Time	10 6 8 e = (0+6+23 10 10 10 10 10 10 10 1	25-2= 11-3= 17-4= 3+08+13)/5 OR P4 11 Waiti 0+(5-1) 1-1=0	23 8 13 5 = 50/5=10 P5 17 2 ng Time 1)=4	P3	35	
	P3 P4 P5 Average w Preemptiv Gantt Cha P1 0 1 Process P1	2 3 4 vaiting Time ee SJF nrt: P2 Arrival Time 0 1	10 6 8 8	25-2= 11-3= 17-4= 3+08+13)/5 OR P4 11 Waiti 0+(5-1)	23 8 13 5 = 50/5=1 P5 17 2 ng Time 1)=4	P3	35	



	ii) <u>FC</u>	TEC																
	Gant			•														
	P1	<i>.</i> C11		<u>P</u> 2	2	P.	3		P	P4		P5			1			
	0		7			11		2	21		2	7		3	5			
	Process Arrival Burst Waiting Time																	
					me		_	ime	!			_						
	P1			0			7)-0=(
	P2			1			4			_	7-1=6							
	P3			2			10)		_	1-2=							
	P4 P5			3 4			8				21-3= 27-4=							
	P5			4			ð			4	2/ -4 =	=23						
	Avera	аσе	wai	itin	σΤ	ime	=0+	-6+9)+1:	8+2	3/5 =	-56/5	=11	2				
	111016	uge	vv atı		5 •	11110	- 0 i	U I Z	/ I I	4	JI	-50/5	-11.	_				
b	List f	ree	spa	ice	mai	nag	eme	nt 1	tech	nia	ues?	Des	cribe	anv	one	in		6M
	detail		1			8				1								
Ans	A file	sys	stem	is	resp	ons	sible	to	allo	cate	the	free	olock	s to	the f	ïle		Listing=1M
	theref	ore	it h	as t	o k	eep	trac	k of	all	the	free	bloc	ks pr	esen	t in t	he d	isk.	Explanation
	There				-		ppro	oacl	nes	by τ	ısing	whi	ch, th	e fre	e blo	ocks	in	=3M
	the di				_	d.												And
	•		it V															Diagram=2
	•	Li	inke	ed I	List													M
	•		rou _]		_													
	•		oun	ting	3													
	Bit V																	
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	•			_			10, .	11,	12,	13 8	are ir	ee ar	ia th	e res	tori	ine b	locks	•
					ated		.:	20.5	****	.1.1.1	ha . (0011	1100	1111	1100	1		
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	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14			
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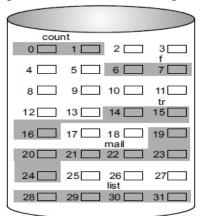
	Timbed Tiet	
	Linked List In this approach the free disk blocks are linked together in a	
	• In this approach, the free disk blocks are linked together i.e. a free block contains a pointer to the next free block.	
	 The block number of the very first disk block is stored at a 	
	separate location on disk and is also cached in memory.	
	• In this approach, link all the disk blocks together, keeping a	
	pointer to the first free block.	
	 This block contains a pointer to the next free disk block, and so on. 	
	free-space list head	
	0 1 2 3	
	4 5 6 7	
	8 9 10 11	
	12 13 14 15	
	16 17 18 19	
	20 21 22 23	
	24 25 26 27	
	28 29 30 31	
	20 29 30 31	
С		
·	Enlist different file allocation methods? Explain configuous	
	Enlist different file allocation methods? Explain contiguous allocation method in detail.	
Ans		1m- listing,
	allocation method in detail.	1m- listing, 2m for
	allocation method in detail. From the user's point of view, a file is an abstract data type. It can be created, opened, written, read, closed and deleted without any real concern for its implementation. The implementation of a file is a problem for the operating	2m for diagram, 3m
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access.

- For direct access to block 'i' of a file, which starts at block 'b', we can immediately access block b+i. The difficulty with contiguous allocation is finding space for a new file.
- For direct access to block 'i' of a file, which starts at block 'b', we can immediately access block b+i.
- The difficulty with contiguous allocation is finding space for a new file.
- If file to be created are 'n' blocks long, we must search free space list for 'n' free contiguous blocks.



	Directory	
File	Start	Length
count tr mail list f	0 14 19 28 6	2 3 6 4 2

Advantages of Contiguous File Allocation Method:

- 1. Supports both sequential and direct access methods.
- 2. Contiguous allocation is the best form of allocation for sequential files. Multiple blocks can be brought in at a time to improve I/O performance for sequential processing.
- 3. It is also easy to retrieve a single block from a file. For example, if a file starts at block 'n' and the ith block of the file is wanted, its location on secondary storage is simply n + i.
- 4. Reading all blocks belonging to each file is very fast.
- 5. Provides good performance.

Disadvantages of Contiguous File Allocation Method:

- 1. Suffers from external fragmentation.
- 2. Very difficult to find contiguous blocks of space for new files.
- 3. Also with pre-allocation, it is necessary to declare the size of the file at the time of creation which many a times is difficult to estimate.
- 4. Compaction may be required and it can be very expensive.