

Abstract

In this contribution we study Rényi pseudodistance estimators which are based on minimization of information-theoretic divergences between empirical and hypothetical probability distribution. These distances are more robust (than e.g. MLE estimators) against outliers and other measurement errors potentially present in the data sets. Robustness of these estimators is described by influence function. In [1] and [4] authors found explicit formulas for enumeration of Rényi distances in normal families and for their influence functions. We focus on finding explicit formulas for other families (Weibull, Cauchy, Exponential) and finding influence functions for these estimators. We perform computer simulations for pseudorandom contaminated and uncontaminated data sets, different sample sizes and different Rényi distance parameters.

1 Introduction and basic definitions

Let $\mathcal{P} = \{P_\theta : \theta \in \Theta \subset \mathbb{R}^m\}$ be set of probability measures on measurable space $(\mathcal{X}, \mathcal{A})$. We will apply the estimators in the statistical model with i.i.d. observations X_1, \dots, X_n governed by distribution P_0 . Because we will be interested in robustness, we allow the case $P_0 \notin \mathcal{P}$ and therefore we define another set $\mathcal{P}^+ = \mathcal{P} \cup \{P_r\}$.

Definition 1.1. We say that mapping $\mathfrak{D} : \mathcal{P} \times \mathcal{P}^+ \rightarrow \mathbb{R}$ is *pseudodistance* between probability measures $P \in \mathcal{P}$ and $Q \in \mathcal{P}^+$ if it holds

$$\mathfrak{D}(P_\theta, Q) \geq 0 \quad \forall \theta \in \Theta \quad \text{and} \quad Q \in \mathcal{P}^+$$

and

$$\mathfrak{D}(P_\theta, P_{\tilde{\theta}}) = 0 \Leftrightarrow \theta = \tilde{\theta}.$$

This pseudodistance is *decomposable* if there exist functionals so that $\mathfrak{D}^0 : \mathcal{P} \rightarrow \mathbb{R}$, $\mathfrak{D}^1 : \mathcal{P}^+ \rightarrow \mathbb{R}$ and measurable mapping $\rho_\theta : \mathcal{X} \rightarrow \mathbb{R}$, $\theta \in \Theta$, so that $\forall \theta \in \Theta$ and $\forall Q \in \mathcal{P}^+$ the expectation $\int \rho_\theta dQ$ exists and

$$\mathfrak{D}(P_\theta, Q) = \mathfrak{D}^0(P_\theta) + \mathfrak{D}^1(Q) + \int \rho_\theta dQ.$$

Definition 1.2. We say that a functional $T_{\mathfrak{D}} : \mathcal{Q} \rightarrow \Theta$, for $\mathcal{Q} = \mathcal{P}^+ \cup \mathcal{P}_{\text{emp}}$ defines minimum pseudodistance estimator (min \mathfrak{D} -estimator) if $\mathfrak{D}(P_\theta, Q)$ is a decomposable pseudodistance on $\mathcal{P} \times \mathcal{P}^+$ and parameters $T_{\mathfrak{D}}(Q) \in \Theta$ minimize $\mathfrak{D}^0 + \int \rho_\theta dQ$, that means

$$T_{\mathfrak{D}}(Q) = \arg \min_{\theta \in \Theta} \left[\mathfrak{D}^0 + \int \rho_\theta dQ \right] \quad \forall Q \in \mathcal{Q}. \quad (1)$$

References

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