# Nature-Inspired Computing (NIC) Methods in Wind Generator Design Project Documentation

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#### **Abstract**

This document is the documentation for the project Nature-Inspired Computing (NIC) Methods in Wind Generator Design for the course AS-0.3200 Automaatio- ja systeemitekniikan projektityöt. NIC methods include various different algorithms for efficiently finding near-optimal solutions for many optimizing problems.

#### I. THE GOAL

The goal of this project is to implement two nature-inspired algorithms for optimizing wind generator design. The generator design module is provided by VTT and it is handled as a black box. The methods used in this project are Genetic Algorithms (GA) and Particle Swarm Optimization (PSO). We describe the basics of the algorithms, our implementations and the findings.

At the end of this project we should atleast have ready implementations for both of the algorithms for optimization of one objective. Depending on the workload and difficulty of implementation multiobjective optimization is also considered.

The aim for the workload was 4cr which equals approximately 100 hours.

We acknowledge the computational resources provided by Aalto Science-IT project.

#### II. STRUCTURE

#### III. THE OPTIMIZATION PROBLEM

Our optimization problem is a black box model of a wind turbine generator developed by VTT. The model has 14 inputs and 6 outputs. Two of the inputs are integer values and the rest are floating point numbers. In addition to this there are 3 constraints that should be met for the design.

An ideal generator would produce exactly 3 MW power and have a maximised torque density, minimum weight, high efficiency, high power factor and minimised costs. All the goals can't be optimised simultaneously as they require different parameter combinations. The optimal solution is a compromise where improving some value would deteriorate the others.

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#### IV. Particle Swarm Optimization

Implementing the Particle Swarm Optimization algorithm was assigned to Janne. The algorithm was first proposed by James Kennedy and Russel Eberhart in 1995 and in our project is their version of the algorithm is implemented with some minor modifications.

The algorithm itself is quite simple. The solution space is first initialized with particles set to random locations with zero velocity. Then the fitness function is evaluated for each particle and the best coordinates are stored. Then the velocities are calculated with the following formula: [1]

```
vx[][]=vx[][]+
2*rand()*(pbestx[][]-presentx[][])+
2*rand()*(pbestx[][gbest]-presentx[][])
```

The positions and velocities are updated until a set criterion is fulfilled. The velocity function has a constant 2 for the stochastic part so that the particles would have the possibility to move over the previous best value. This value yields the best results as there is no good way to individually guess which one of the velocity increments should be weighted more. [1]

Our optimization problem is a hybrid of discrete and continuous parameters whereas the original algorithm was developed for continuous case only. Therefore we have to make some special arrangements for the two discrete parameters. Pole pair number is an integer between 20 and 80. The first idea was to approximate handle this parameter as continuous and always round the result. The number of slots per pole per pahse has the possible values of 1, 2 and 3 so the idea was to calculate the optimization for each of the three possible parameter values.

In the implementation it was decided, however, that in the eyes of the algorithm itself all the parameters would be continous. The simulation model doesn't allow for non-integer parameters so before each run the corresponding values are rounded to the nearest integer before running the model.

The implementation began with defining the required variables for the swarm and the limitations. The easy part was to fill the solution space with random particles. After implementing the basic algorithm some problems emerged.

The first disturbing observation was that the computer resources weren't used to their full potential as the calculations were performed mostly on one core at a time. After some research the Matlab Parallel Computing Toolbox, and especially the parfor loop, was found. This allowed for the parallelization of the generator simulation and somewhat improved the performance. Not everything is parallelizable though as the particles have to

be synchronized.

The next problem was how to enforce the modeling limitations. The initial attempt was to enforce the parameters to stay inside the defined problem space but this is against the nature of the algorithm. As a result the particles would often hit the hard limits and gather near the edges. The decision was made to check the boundaries but skip the calculations and assign a bad fitness value if any of the parameters were out of bounds.

After the change in handling the boundaries it was noticed that the swarm diverges for some reason. In spite of penalizing out of bounds values the particles seemed to wander far from the desired area. This had to be looked into.

After finding the document by Engelbrecht [2] it became evident that the particle velocities exploded. Using a simpler model  $f(x,y) = -x^2 - y^2$  yielded similar results, so the next step was to introduce velocity clamping. By changing the fraction of the maximum allowed velocity related to the size of the parameter space it is possible to adjust the particle convergence speed and the tendency of the particles wandering off.

There was also the fundamental mistake that the best particle index was not updated properly so the best value remained to be the one that happened to be the best one on the initialization. This was observed as one of the particles would not move at all.

Running the provided simulation model was inconsistent performance wise. Usually the simulation was calculated in much less than one second but sometimes the calculation could take several seconds, though. This might happen because of nearly singular matrices in the model but the issue is out of our reach.

To manage the large amount of computations in a reasonable time we chose to take advantage of the Aalto University Triton computing cluster. The usage of Triton is described in its own chapter.

#### V. Genetic Algorithm

Genetic Algorithm was implemented by Eero. The algorithm is modeled from DarwinâĂŹs theory of evolution. A good overview and discussion on the genetic algorithm is presented in [3]. In terms of actual implementation, the Genetic Algorithm is based on 5 different steps [4]:

- 1. New Population
- 2. Fitness evaluation
- Testing whether the solution is satisfactory
- 4. Creating a new population
- 5. Looping from step 2.

In step 1, a random new population is generated. Population size may vary, but a too large population will lead to unacceptable waste of calculating time and offers very little in return when compared to smaller population sizes. A good population size is around 20-40 candidates.

In steps 2 and 3, the fitness of each candidate is evaluated. Fitness describes how well the candidate satisfies our criteria. Our fitness evaluation is based on the simulation model provided to us by VTT. If the best candidate passes the pre-set goal in terms of fitness, the looping is stopped and algorithm is complete.

In step 4 a new population is created. First, 10 survivals are selected based on "pie chart roulette", that is, most fit candidates are most likely to survive, but the process is also based on randomness. Next, the survivals produce offspring, and stand a chance to create corssovers with each other. This means that the survivals' offspring inherit attributes from both parents. The best candidate is passed on to the next generation as is. This is called elitism. Finally, a random, low-chance, mutation may occur. In our case this means that a random parameter of a random candidate will be incremented or decremented by a small amount.

The methods used in step 4 and how often they occur are based on empirical evidence. Good chance for crossover is determined to be around 0.7, for example. Mutation chance needs to be low, or else the process loses it's properties and becomes essentially a randomwalk process. However, a low mutation chance is required to make the system evolve.

Finally, in step 5 the process is repeated from step 2. The process is repeated maximum in our case maximum of 100 times, to make the calculations run smoothly and in reasonable timeframe.

Currently the program code for the algorithm is complete, but fails to compile, due to errors with the provided simulation model. Further evaluation of the selected methods and parameters, such as crossover and mutation chance, are needed. After the code is complete, the results are analyzed and parameters tuned for best possible results.

#### VI. Computing in the Cluster

The calculation capabilities of the home computers proved to be inadequate when we decided to run multiple iterations of the algorithms so that we could investigate the consistency of the results. For example running the PSO algorithm with a swarm size of 50 and 150 simulation time steps took several hours to produce 70 results. The performance felt insufficient so we chose to search for alternative methods.

The next attempt was to try to utilize the new Aalto servers Brute and Force. However, their Matlab license allows only for 12 parallel workers and as the server CPU cores run only at a bit over 2 GHz the performance was very similar to the home computer.

Disappointed with the performance of the available resources we came upon the Aalto Triton computing cluster. Running some 400 compute nodes it was even more than we were looking for.

The cluster is running Scientific Linux and the computation tasks are delivered as batch jobs. We had to adapt the Matlab scripts to the requirements of the environment. The algorithms run as functions that among other parameters take the batch ID so that the computation results can be stored to different files. The batch system runs multiple instances of Matlab on different compute nodes simultaneously.

After the calculations the saved .mat files are transferred for further analysis. A script reads the output files one by one and then analyzes the results.

#### VII. ANALYZING THE RESULTS

We performed many and more calculations which to analyze. For each algorithm we selected the goal of 10,000 iterations as a baseline. The time allocated for the task was four hours with a grace period of approximately one hour. In the analysis we only used the base versions of the algorithms. Therefore the different velocity

As noted previously, we only considered the single goal optimization problem of the efficiency. A more practical result could be achieved if the optimization goal was altered in a way that the other generator properties are taken into account. Initially, we tried this approach by setting certain weights to the parameters but the results didn't have any real meaning and they weren't very easy to interpret.

TEE SAMA TAULUKKO KUIN NI-ISSÃĎ SLAIDEISSA (GENERAATTORIEN VERTAILU) LAITA KUVAT APPENDIXIIN MUTTA SELITÃĎ TULOKSISTA TÃĎSSÃĎ

A better way of doing this multiple goal optimization could be setting some restrictions to the desired properties. As was seen in the comparison of the best generators the one that we got from the PSO algorithm was almost twice the price of the GA version. We could simultaneously optimize the generator efficiency and the power factor by simply taking the sum of these properties. For the other parameters we could set some desired conditions that should be fulfilled and give some penalty if the limits are exceeded. For example, we could set the maximum allowed cost to be 7M and the minimum torque density to 11.

## VIII. CONCLUSIONS AND FURTHER RESEARCH

# IX. TIME AND TEAMWORK MANAGEMENT

The initial project plan had quite amibitous goals for the time management. Due to many reasons they were delayed to the official course deadlines. For example in March and April the project was on halt for almost 4 weeks because of other more urgent assignments.

The workload wasn't evenly distributed because Janne handled the cluster computing in addition to his own algorithm design. Also the available data had to be analyzed so that the feasibility of the results could be verified. This analysis later became the core of the achieved results.

LIITETÃĎÃĎN KANSSA TAULUKKO AJANKÃĎYTÃŰSTÃĎ VAIKKA AP-PENDIXIKSI

#### REFERENCES

- [1] Kennedy, J. and Eberhart, R. *Particle Swarm Optimization*, Proceedings of IEEE international conference on neural networks. Vol. 4. No. 2. 1995.
- [2] Engelbrecht, A. Particle Swarm Optimization: Pitfalls and Convergence Aspects. Department of Computer Science, University of Pretoria, South Africa
- [3] Mitchell, M. An Introduction to Genetic Algorithms. First MIT paperback edition, fifth printing, 1999.
- [4] Obitko, M., Introduction to genetic algorithms, Hochschule für Technik und Wirtschaft Dresden (FH), http://www.obitko.com/tutorials/genetic-algorithms/index.php, accessed 3.3.2014

## A. RESULT COMPARISON

### B. TIME MANAGEMENT

lectures	12		
Janne	total	95	
<b>J</b>	total + lectures	107	
date	time (h)	description	
20.1.2014	2	Familiarization with the project and exploring different algo-	
		rithms	
21.1.2014	1	Checking the Matlab files	
24.1.2014	2	Project planning	
25.1.2014	2.5	Updating the plan to LaTeX	
30.1.2014	0.5	First meeting	
15.2.2014	1	Reading about the PSO algorithm	
17.2.2014	7	Implementing PSO	
17.2.2014	2	Studying parallelization	
18.2.2014	1	Figuring out performance issues	
24.2.2014	4	Matlab movie capture, wondering why the algorithm doesn't	
		work	
2.3.2014	5	Intermediate report writing	
2.3.2014	1.5	Troubleshooting with simpler algorithm	
3.3.2014	1	Preparing presentation slides	
3.3.2014	1	Velocity clamping	
3.3.2014	1	Finding suitable software to capture video from screen	
4.3.2014	1	Intermediate report writing	
4.3.2014	0.5	Video editing and upload to YouTube	
15.3.2014	1	Started a clean attempt of PSO in order to improve code readabil-	
		ity	
15.3.2014	1	How to apply a function only to a subset of matrix elements	
16.3.2014	1	Wondering one particle immobility	
16.3.2014	1	Found the reason for the problem, there was a typo in the bestidx	
		parameter	
17.3.2014	3	Improve plotting, run simulation with large swarm, parametrize	
		velocity calculation	
17.3.2014	1	Print text to console, run multiple simulations	
18.3.2014	1	Explore multidimensional data visualization	
19.3.2014	2	Gather data for multiple runs of PSO	
22.3.2014	1	Found out that the data from the 5 hour run was not saved.	
		Started new calculation runs.	
23.3.2014	1.5	Write script to analyze the optimal parameter distributions. Find	
		info about the computing facilities in Aalto.	
23.3.2014	0.5	Apply for a Triton account.	
23.3.2014	1	Reading about various inertia handling methods.	
24.3.2014	1	Ask for Triton account, discuss with Eero about the project.	
25.3.2014	1.5	Read Triton manuals and about Bash scripting	
26.3.2014	1.5	Read about SLURM and sbatch, project discussion	

26.3.2014	1.5	Implementing PSO to be used in Triton	
26.3.2014	1.5	Experiment with Bash scripting, script .mat file upload from	
20.3.2014	1.5	Triton to Kosh	
26.3.2014	1	Run tests and benchmark on home computer. Run hundred	
20.3.2014	1		
26.2.2014	1	iterations on cluster.	
26.3.2014	1	Every calculation produced the same results, set the random	
		number seed manually. Start new calculation with 200 tasks.	
27.3.2014	0.5	Basic analyzation of the data.	
22.4.2014	0.5	Telling Eero what kind of function he should make so that it	
	_	could be run in Triton, fixed random number generation	
23.4.2014	2	Documentation	
23.4.2014	0.5	For some reason the PSO_SLURM folder was deleted. Recovered	
		missing files.	
24.4.2014	0.5	Fixed documentation	
24.4.2014	1.5	Run simulations for random inertia	
25.4.2014	1	Some shell wizardry to find the failed (old) results and remove	
		them as I forgot to clean the folder before running the job	
26.4.2014	1	What to do with the data and is the collected data sufficient?	
26.4.2014	0.5	Set up SSH tunneling so that the file transfering is easier	
26.4.2014	1	Prepare and run new batch jobs	
26.4.2014	1	The previous run was erroneous, made some modifications and	
		started new batch jobs	
27.4.2014	0.5	Check the simulation results	
29.4.2014	1	Lunch discussion with Eero about the	
29.4.2014	0.5	Write e-mail	
29.4.2014	1	Prepare and run the GA simulations	
2.5.2014	2	Change the fitness function to efficiency only, remove the saving	
		of the development of the swarm from PSO_function, test, start	
		new calculation in cluster	
2.5.2014	2	Checking results and plotting plots	
9.5.2014	1	Prepare and run GA with updated fitness function	
9.5.2014	0.5	Start making presentation slides	
10.5.2014	1	Changed GA to utilize parfor and started new runs. The previous	
10.0.2011		run had only 1000 iterations and the convergence limit of 200.	
10.5.2014	1	Prepare slides and make changes so that the values are stored to	
10.5.2014	1	the disk after always after certain amount of iterations instead of	
		at the end.	
10.5.2014	1	Fight with the batch jobs	
10.5.2014	1	Data analysis	
10.5.2014	3	Visualizations and making slides	
10.5.2014	0.5	Check and upload last GA runs	
11.5.2014	2	Fighting with network problems	
11.5.2014	3	Development of PSO fitness visualization	
		1	
11.5.2014	2	Prepare slides	
12.5.2014 12.5.2014	1.5	Prepare slides	
1 12.5.2014	0.5	Run GA, then run it again	

22.5.2014   2.5	Documentation	
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Eero	total	62.5
total + lectures	71.5	
2.3.2014	32	intermediate report total
14.3.2014	3	Trouoble with the sum function, calculating fitness
17.3.2014	2	Fine-tuning the selection process
17.3.2014	2.5	Fixed a bug with crossover, first working model
24.3.2014	1	Miscellaneous discussion (including Triton)
26.3.2014	1.5	Modifying GA to handle negative fitness values
28.4.2014	6	Huge revamp to reduce convergence to single solution
29.4.2014	1	Lunch with Janne, discussion about data analysis
10.5.2014	4	Mutation chance analysis
11.5.2014	6	Mutation chance analysis, average fitness analysis
12.5.2014	1	Tweaking mutation chance, one more iteration on Triton
12.5.2014	2.5	Making slides