Education

Swiss Federal Institute of Technology Zurich (ETH Zurich)

Zurich, Switzerland

ROBOTICS, SYSTEMS AND CONTROL MSC

Sep 2022 — Nov 2024

- Final Grade pending
- · Master's Thesis: Uncertainty Model Unfalsification via Semi-Infinite Programming and Local Reduction; conducted at Imperial College London
- Semester Project: Diffusion Spline-Based Navigation Policy in Dynamic Environments (5.75 / 6.0)
- · Core Courses: Linear System Theory, Dynamic Programming and Optimal Control, Recursive Estimation, Model Predictive Control, Vision Algorithms for Mobile Robotics, Nonlinear Dynamics and Chaos, Introduction to Machine Learning
- · Additional Courses: Advanced Model Predictive Control, Convex Optimization, Probabilistic Artificial Intelligence, Orbital Dynamics

MECHANICAL ENGINEERING BSC Sep 2018 — Oct 2021

- Final Grade: 5.56 / 6.0 (top 2% of the class)
- Thesis: Distributed Trajectory Planning for Multiple Autonomous Aerial Vehicles (5.75 / 6.0)
- · Core Courses: Calculus, Linear Algebra, Mechanics, Dynamics, Physics, Thermodynamics, Fluid Mechanics, Electrical Engineering, Informatics
- · Electives: Control Systems, Signals & Systems, System Modeling, Advanced Topics in Control, Quantum Mechanics, Models, Algorithms and Data

Gymnasium Raabeschule Braunschweig, Germany

ABITUR (GERMAN UNIVERSITY-ENTRANCE QUALIFICATION)

graduated Jun 2017

- · Average Grade: 1.1 / Salutatorian
- Advanced Courses (German "Leistungskurse"): Mathematics, Physics, Chemistry

Research & Work Experience

Control and Power Research Group, Imperial College London

London, United Kingdom

MASTER'S THESIS

• Title: Uncertainty Model Unfalsification via Semi-Infinite Programming and Local Reduction

- Conducted as a visiting student under supervision of Prof. Dr Eric Kerrigan
- Explored the use of optimization problems (semi-infinite programs in particular) and data to inform uncertainty models
- Developed a Julia package for dynamical systems simulation called % SimpleSim. jl available on the Julia registry
- · Final Grade: pending

Robotic Systems Lab, ETH Zurich

Zurich, Switzerland

Apr 2024 - Oct 2024

SEMESTER PROJECT

Oct 2023 - Feb 2024

- · Title: Diffusion Spline-based Navigation Policy in Dynamic Environments
- · Investigated the use of denoising diffusion probabilistic models (DDPMs) for spline-based robot navigation
- Final Grade: 5.75 / 6.0

Zipline International Inc.

South San Francisco, California, USA

GUIDANCE, NAVIGATION AND CONTROL INTERN

- · Supported development work on guidance, navigation and controls algorithms for a novel autonomous aircraft
- Worked extensively with Julia (for simulation) and C++ (for prototyping and embedded systems)
- % What I worked on (YouTube)

Institute for Dynamic Systems and Control, ETH Zurich

Zurich, Switzerland

Summer 2021

Sep 2021 — Aug 2022

BACHELOR'S THESIS

• Title: Distributed Trajectory Planning for Multiple Autonomous Aerial Vehicles

- Developed a distributed trajectory planner using ADMM and ALADIN and contributed to the 🦠 CRS framework
- Final Grade: 5.75 / 6.0

Academic Space Initiative Switzerland (ARIS)

Zurich & Dübendorf, Switzerland

CONTROL SYSTEMS ENGINEER

Sep 2020 — Aug 2021

- · Two-semester project with the goal of developing an autonomous guided recovery system for a student rocket
- Worked with a team of eight students from different fields and universities
- Developed a fully functional embedded control system from the ground up
- % Link to ARIS Website

ETH Zurich Zurich, Switzerland

TEACHING ASSISTANT FOR SIGNALS & SYSTEMS, MECHANICS 1 & 2 AND DIMENSIONING 1

Feb 2020 — Feb 2024

- · Independently taught weekly classes of approx. 25 students
- Prepared practice material and exercise sessions
- Supported lectures by preparing slides, grading assignments and monitoring online forums

DECEMBER 22, 2024 JANNES HÜHNERBEIN · CV

Honors & Awards

Scholarship Recipient % More Information in English 2020 - 2024German National Academic Foundation

May 2019 **1st Place** Innovation Project ("Innovationsprojekt"), % Information in German

ETH Zurich Jul 2017 **High-School Graduate Prize** % More Information in German German Physical Society

Specialized Skills

Programming Julia, Python, C++, C

Robotics MATLAB/Simulink, ROS, Gazebo, Eigen, PyTorch **Optimization** JuMP, CasADi, FORCESPRO, Acados, CVXPY **Hardware** RaspberryPi, Arduino, STM32, ESP32

> Other Git, Linux, LaTeX, Siemens NX, SQL, PHP, Javascript (...)

Other_

German — Native Proficiency

English — Full Professional Proficiency Languages

French — Elementary Proficiency

Mentoring-Program for First-Semester Students at ETH Zurich 2020/2021 **Volunteering**

Advisor for Digital Infrastructure & IT at Youth Against AIDS (Jugend gegen AIDS e. V.) 2014-2017