■ hjannes@ethz.ch | • huehnerbe.in | • jhuehnerbein | • janneshb

Education

Swiss Federal Institute of Technology Zurich (ETH Zurich)

Zurich, Switzerland

ROBOTICS, SYSTEMS AND CONTROL MSC

Sep 2022 — present

- Expected to graduate in September 2024
- Semester Project: Diffusion Spline-Based Navigation Policy in Dynamic Environments (5.75 / 6.0)
- Core Courses: Linear System Theory, Dynamic Programming and Optimal Control, Recursive Estimation, Model Predictive Control, Vision Algorithms for Mobile Robotics, Nonlinear Dynamics and Chaos, Introduction to Machine Learning
- · Additional Courses: Advanced Model Predictive Control, Convex Optimization, Probabilistic Artificial Intelligence, Orbital Dynamics

Mechanical Engineering BSc Sep 2018 — Aug 2021

- Final Grade: 5.56 / 6.0 (top 2% of the class)
- Thesis: Distributed Trajectory Planning for Multiple Autonomous Aerial Vehicles (5.75 / 6.0)
- Core Courses: Calculus, Linear Algebra, Mechanics, Dynamics, Physics, Thermodynamics, Fluid Mechanics, Electrical Engineering, Informatics, Chemistry
- Electives: Control Systems, Signals & Systems, System Modeling, Advanced Topics in Control, Quantum Mechanics, Models, Algorithms and Data

Gymnasium Raabeschule Braunschweig, Germany

ABITUR (GERMAN UNIVERSITY-ENTRANCE QUALIFICATION)

- Average Grade: 1.1 (second best in class)
- · A-courses: Mathematics, Physics, Chemistry

Work Experience

Robotic Systems Lab, ETH Zurich

Zurich, Switzerland

graduated Jun 2017

Semester Project Oct 2023 — Feb 2024

- Title: Diffusion Spline-based Navigation Policy in Dynamic Environments
- Investigated the use of denoising diffusion probabilistic models (DDPMs) for spline-based robot navigation
- Part of the Robotics, Systems and Control MSc program at ETH Zurich
- Final Grade: 5.75 / 6.0

Zipline International Inc.

South San Francisco, CA, USA

GUIDANCE, NAVIGATION AND CONTROL INTERN

Sep 2021 — Aug 2022

- · Supported development work on guidance, navigation and controls algorithms for a novel autonomous aircraft
- Worked extensively with Julia (for simulation and prototyping) and C++ (embedded)
- % What I worked on (YouTube)

Institute for Dynamic Systems and Control, ETH Zurich

Zurich, Switzerland

Summer 2021

BACHELOR'S THESIS

Title: Distributed Trajectory Planning for Multiple Autonomous Aerial Vehicles

- Developed a distributed trajectory planner using ALADIN
- Contributed to the % CRS framework
- Final Grade: 5.75 / 6.0

Academic Space Initiative Switzerland (ARIS)

Zurich & Dübendorf, Switzerland

CONTROL SYSTEMS ENGINEER

· Two-semester project with the goal of developing an autonomous guided recovery system for a student rocket

- Worked with a team of eight students from different fields and universities
- Developed a fully functional embedded control system from the ground up
- % Link to ARIS Website

ETH Zurich Zurich, Switzerland

Teaching Assistant for Mechanics 1 & 2, Dimensioning 1 and Signals & Systems

Feb 2020 — Feb 2024

Sep 2020 — Aug 2021

- Independently taught weekly classes of approx. 25 students
- Prepared practice material and exercise sessions
- Supported lectures by preparing slides, grading assignments and monitoring online forums

Honors & Awards

since 2020 **Scholarship Recipient** More Information in English German National Academic Foundation

2019 **1st Place** Innovation Project ("Innovationsprojekt"), More Information in German

ETH Zurich

2017 **High-School Graduate Prize** Society More Information in German German German Physical Society

FEBRUARY 19, 2024 JANNES HÜHNERBEIN · CV

Skills

Programming Julia, Python, C++, C

Robotics MATLAB/Simulink, ROS, Gazebo, Eigen, PyTorch

OptimizationCasADi, FORCESPRO, Acados, CVXPYHardwareRaspberryPi, Arduino, STM32, ESP32OtherSiemens NX, SQL, PHP, Javascript

Other_

German: Native

Languages English: Professional

French: Basic

VolunteeringMentoring-Program for First-Semester Students at ETH Zurich 2020/2021
Advisor for Digital Infrastructure & IT at Youth Against AIDS (Jugend gegen AII)

Advisor for Digital Infrastructure & IT at Youth Against AIDS (Jugend gegen AIDS e. V.) 2014 - 2017