

view_frames Result
Recorded at time: 1521796923.148

map

Broadcaster: /slam_gmapping
Average rate: 20.204 Hz
Most recent transform: 1521796923.155 (-0.007 sec old)
Buffer length: 4.900 sec

odom

Broadcaster: /ukf_localization_node
Average rate: 30.241 Hz
Most recent transform: 1521796922.993 (0.155 sec old)
Buffer length: 4.894 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

chassis_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1521796923.083 (0.065 sec old)
Buffer length: 4.800 sec

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Average rate: 10.208 Hz
Most recent transform: 1521796923.083 (0.065 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot_state_publisher
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Buffer length: 4.800 sec

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Most recent transform: 1521796923.083 (0.065 sec old)
Buffer length: 4.800 sec

camera_link

zed_center

base_laser

sw_arm_left_1

sw_arm_right_1

base_ultrasonic_bl

base_ultrasonic_bml

base_ultrasonic_bmr

base_ultrasonic_br

base_ultrasonic_fl

base_ultrasonic_fml

base_ultrasonic_fmr

base_ultrasonic_fr

back_left_wheel

back_right_wheel

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

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Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

camera_depth_frame

camera_rgb_frame

zed_left_camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

camera_depth_optical_frame

camera_rgb_optical_frame

zed_depth_camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

sw_arm_left_2

sw_arm_right_2

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

sw_arm_left_3

sw_arm_right_3

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1521796923.148 sec old)
Buffer length: 0.000 sec

sw_arm_left_4

sw_arm_right_4

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1521796923.083 (0.065 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1521796923.083 (0.065 sec old)
Buffer length: 4.800 sec

front_left_swivel_wheel

front_right_swivel_wheel