view\_frames Result Recorded at time: 1509713194.286 map Broadcaster: /amcl Average rate: 100.339 Hz Most recent transform: 1455208554.176 ( 54504640.110 sec old) Buffer length: 4.963 sec odom Broadcaster: /am\_driver\_safe Average rate: 20.251 Hz Most recent transform: 1455208553.988 ( 54504640.298 sec old) Buffer length: 4.889 sec base\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1509713194.286 sec old) Buffer length: 0.000 sec chassis\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate:  $1\overline{0000.000}$  Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 10000.000 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1455208554.007 ( 54504640.279 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) \Most recent transform: 1455208554.007 ( 54504640.279 sec old) \Most recent transform: 1455208554.007 ( 54504640.279 sec old) Most recent transform: 1455208554.007 ( 54504640.279 sec old) Buffer length: 0.000 sec Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 0.000 sec Buffer length: 4.800 sec sw\_arm\_left\_1 sw\_arm\_right\_1 back\_left\_wheel back\_right\_wheel base\_laser zed\_center Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1509713194.286 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec zed\_left\_camera sw\_arm\_left\_2 sw\_arm\_right\_2 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1509713194.286 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec zed\_depth\_camera sw\_arm\_left\_3 sw\_arm\_right\_3 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1509713194.286 sec old) Most recent transform: 0.000 ( 1509713194.286 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec sw\_arm\_left\_4 sw\_arm\_right\_4 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1455208554.007 ( 54504640.279 sec old) Most recent transform: 1455208554.007 ( 54504640.279 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec front\_left\_swivel\_wheel front\_right\_swivel\_wheel