

Capabilities of automatic and manual face morphing

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Abstract—In a common scenario one passport including its biometric features belongs to one person. This and only this person *should be* successfully matched to the biometric picture which is in the person's passport in the situation of an Automatic Border Control (ABC). But what if two or more persons are successfully matched to one passport? With the procedure of morphing faces, it is possible to get a promising acceptance rate for both persons. This work compares an automatic with a manual approach for creating morphed faces. In addition the region, in which a sufficient match rate for both persons is reached, is determined to hide the second face as good as possible from manual inspection.

Keywords—Face morphing, face detection, automatic border controls.

I. INTRODUCTION

Face recognition systems have become one of the most popular biometric authentication methods in the last years. It is based on the fairly unique biometric characteristic of a human face. One of their advantages are the property of a contactless capturing the face images with help of an arbitrary high resolution camera system which is highly accepted by the data subjects. In addition to this, the capability of a visual inspection instead of an automatic process is one of the reasons why face recognition is selected as authentication method for biometric passports. The basic idea is simply to observe certain properties of the human face, such as the shape of the head or wrinkles and furrows, and place landmarks on characterizing points.

Hier knnte noch kurz aging und posing rein.

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Since 2002 face recognition is used as identity confirmation in the electronic Machine Readable Travel Document (eMRTD) by the International Civil Aviation Organisation (ICAO). This means every eMRTD issued by a governmental organisation contains a facial image which has to follow certain properties in order to support the machine based automatic verification.

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In several countries, such as Spain, it is possible to provide own printed pictures to the issuing organisation. This practise leads to the possibility of processing on the photo and therefore altering the biometric data set stored in the eMRTD. Of course these alterations form a potential attack vector on the Automatic Border Control systems (ABC). A feasible attack would be an alteration in the way that another individual than the one which the passport is issued to is recognized by the ABC or both individuals are recognized as the same person.

To achieve this the face of the issuing individual and an attacker has to be morphed together. The goal of this process is to provide a morphed photo to the issuing instance which visually nearly identical with the issuer but automatically accepts both, the issuer and the attacker. Having reached this both, the issuer and the attacker are able to show up at the ABC system and both will be accepted.

What are we doing on the topic?

Outline

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The rest of this paper is organized as follows: In ... we provide some details on the topic of face detection followed by describing the procedure of morphing faces. ... deal with the selected detection algorithm and gives some details on our test setup. Finally in ... the result of test subjects are discussed followed by a conclusion in ...

II. DATABASE AND SELECTION OF TEST SUBJECTS

As test sample a data set of XXX ICAO compliant pictures were given. In order to get promising morph results, a subset of XX pairs of photos were selected for manual morphing III-A1 where as the automatic morphing algorithm III-A was applied on all data sets. For manual morphing only pairs with a visually high coincidence are considered because the acceptance rate of the comparison algorithm is expected to be higher. In summation XX manual and XXX automatic morphs are issued in this paper.

III. MORPHING OF FACES

The main task during the morphing of two pictures is to detect characteristics and place landmarks as an advance for the algorithm. This can be done completely automatic or with support of an user. In this paper both way are discussed.

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A. Automatic morphing

1) Results:

Manual morphing

In contrast to the automatic face morphing approach, manual morphing is discussed in this section.

To achieve morphes, the open source software GNU Image Manipulation Software (GIMP) (Version 2.8.16) with the GIMP Animation Package (GAP) (Version 2.6) was selected for this paper. Morphing with GAP follows the simple approach of manually placing connected landmarks at characterizing points in both faces. The algorithm shifts the landmarks from face one to face two. In addition to this the color of the skin is transmitted.

For the test samples 100 - 125 landmarks were placed, depending on the face characteristics. The output contains a sequence of 30 photos which show different stages of the morphing procedure. In figure 1 a two subjects and three morphing stages (5, 15 and 25) are shown. The visual inspection of III-A1 shows biometric features of both subjects whereas III-A1 and III-A1 has more similarity to the closer subject but also covers features of the other subject. A manual post production of the morphs is not necessary because potential revealing details, like the interference of the clothes, glasses or hair is not considered as characteristic by the algorithm.

Results:

Detailed description of the morphs

IV. FACE DETECTION

Detection algorithm

As face detection algorithm the open source software OpenFace was selected. OpenFace is based on a neural network with is fully trained and has high confidence rates in the shipped version. Because OpenFaces main goal is to detect faces on arbitrary photos, the accuracy level is expected to be higher if it works on ICAO compliant data sets.

Process of work

Both of the two source photos and the sequence of 30 morphs is given as input to the OpenFace comparison algorithm. OpenFace computes the match rate of every morph to both of the two photos. The expected outcome of comparison algorithm is an almost equal match rate for morph no. 15, where both pictures are represented to 50%. The closer the morph gets to one of the original pictures the higher the match rate and the lower to the other picture.

V. RESULTS

Resulting from the work are the squared l2 distances from openface. The distance shows the similarity to the given subjects. A lower distance means the compared two persons are more equal, when the distance is under a given threshold, these two persons are accepted to be the same person and so access is given. The resulting morphed photos were compared to different photos of both subjects, to get a independent distance. For

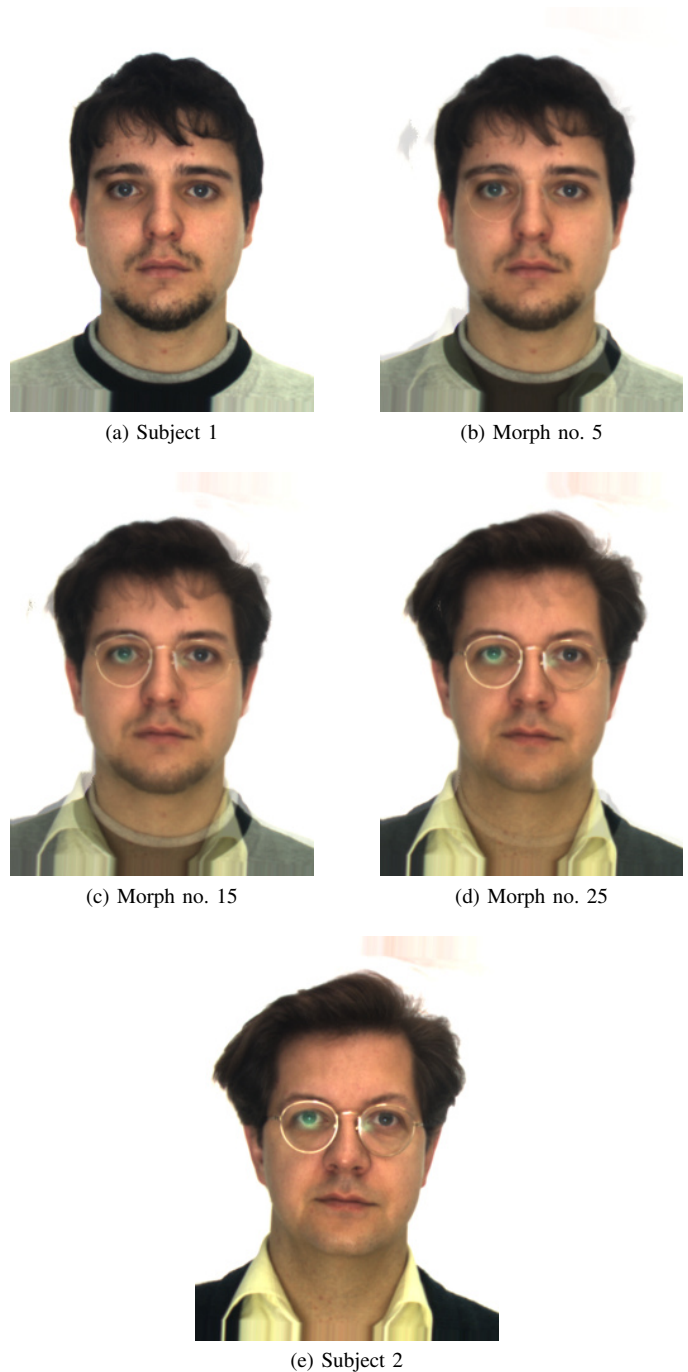


Fig. 1. Example of two ICAO compliant photos (1a and 1e) and morphs at stage 5 (1b), 15 (1c) and 25 (1d)

every morph there were 15 images created from 0% of Subject 1 to 100%, respectively the remaining % of Person 2. So the are images combined of:

- 1. Picture: Person 1 100% - Person 2 0%
- 2. Picture: Person 1 92,86% - Person 2 7,14%
- 3. Picture: Person 1 85,71% - Person 2 14,29%
- 4. Picture: Person 1 78,57% - Person 2 21,43%
- 5. Picture: Person 1 71,43% - Person 2 28,57%
- 6. Picture: Person 1 64,29% - Person 2 35,71%
- 7. Picture: Person 1 57,14% - Person 2 42,86%
- 8. Picture: Person 1 50,00% - Person 2 50,00%
- 9. Picture: Person 1 42,86% - Person 2 57,14%
- 10. Picture: Person 1 35,71% - Person 2 64,29%
- 11. Picture: Person 1 28,57% - Person 2 71,43%
- 12. Picture: Person 1 21,43% - Person 2 78,57%
- 13. Picture: Person 1 14,29% - Person 2 85,71%
- 14. Picture: Person 1 7,14% - Person 2 92,86%
- 15. Picture: Person 1 0% - Person 2 100%

A. Distances

All resulting squared l2 distances for the morphed photos of 01-m-002-27 to 01-m-003-24, 01-m-003-24 to 01-m-005-23, 01-m-004-23 to 01-m-005-23, 01-m-010-23 to 01-m-013-23 and 01-m-014-23 to 01-m-016-23 compared to the corresponding compare images are way too many data. So there is as an example the morphed photo 01-m-002-27 to 01-m-003-24:

Also shown in

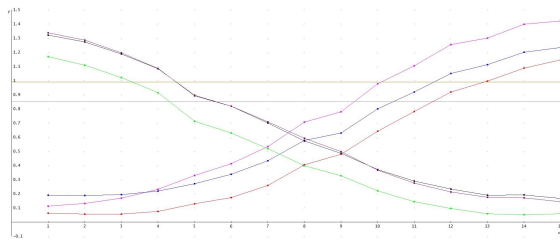


Fig. 2. Squared l2 distances (y axis) of morphs from 01-m-002-27 to 01-m-003-24 (with 15 steps on the x axis) comparing to 01-m-002-28.jpg, 01-m-002-29.jpg, 01-m-002-30.jpg, 01-m-003-25.jpg, 01-m-003-26.jpg and 01-m-003-27.jpg

The results of the 01-m-002-27 to 01-m-003-24, 01-m-003-24 to 01-m-005-23, 01-m-004-23 to 01-m-005-23, 01-m-010-23 to 01-m-013-23 and 01-m-014-23 to 01-m-016-23 morphs are:

For better recognizability the mean value of all the different squared l2 distances is calculated for Person 1 and Person 2. The result is: As visible the lowest distance to both persons is at Picture 9 (Person 1 42,86% - Person 2 57,14%) with a

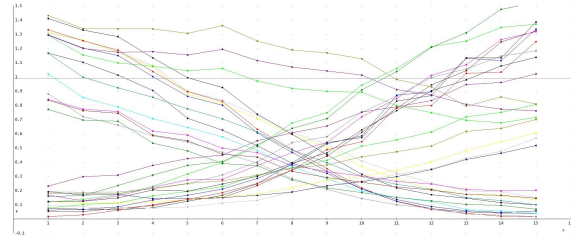


Fig. 3. Squared l2 distances (y axis) of morphs from 01-m-002-27 to 01-m-003-24, 01-m-003-24 to 01-m-005-23, 01-m-004-23 to 01-m-005-23, 01-m-010-23 to 01-m-013-23 and 01-m-014-23 to 01-m-016-23 (with 15 steps on the x axis) comparing to the corresponding compare photos

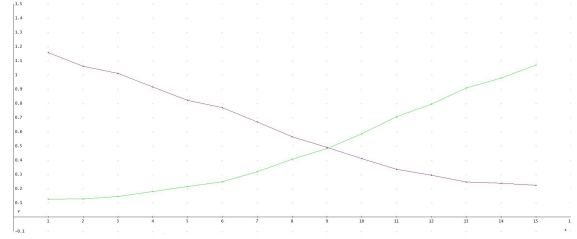


Fig. 4. Mean squared l2 distances (y axis) of morphs from 01-m-002-27 to 01-m-003-24, 01-m-003-24 to 01-m-005-23, 01-m-004-23 to 01-m-005-23, 01-m-010-23 to 01-m-013-23 and 01-m-014-23 to 01-m-016-23 (with 15 steps on the x axis) comparing to the corresponding compare photos

minimal distance of **0.485**.

Openface uses normally a threshold of 0.99, which allows nearly all morphs from Picture 5 to 10 to be successfully acknowledged as shown in 3. Only in 3 cases there is the distance way too high to work properly. The compared photos are 01-m-016-24.jpg, 01-m-016-25.jpg and 01-m-016-26.jpg from the same person, so this morph is not working. As a result in 4 out of 5 cases it is possible to morph two subjects to be successfully acknowledged, this makes a success chance of 80%.

VI. CONCLUSION

VII. FURTHER TOPICS