# Col Complexity (draft)

Abstract. In this article we propose a rational quadratic source code complexity measure [Blo19] from the perspective of path testing with the conjecture of indipendent enclosed scopes, the measure enfolds elementary conditions, nested and cyclic formations.

#### 1 Introduction

A Progam consist of a sequences of instructions. The instructions can be categorized into syntax, logic and arithmetic determining the program control flow.

Software complexity is related with modularity, coupling and cohesion hence quality. 40% to 80% of software costs are emerging due to maintenance and approximatly 40% on fixing defects [SG11].

Analysing source code complexity helps to identify risk, finds potential defects to test critical functionality in detail, increase quality, cohesion and decrease maintainance [RB11].

### 2 Existing measures

Cyclomatic complexity (CC) has been widely discussed by various authors. The most used metric has been formulated by Thomas J. McCabe in 1976 [McC76].

$$m = e - n + 2 \tag{1}$$

Where, e = the amount of edges. n = the amount of nodes.

CC is linear in it's nature and correlation with lines of source code (LOC), which is why Graylin JAY et al. [al.09] are suggesting to implement LOC as complexity measure.

Mir Muhammd Suleman Sarwar et al. [MMSS13] are pointing out that it neither takes into account the difference between combined decisions, elementary conditions nor repeating structures. Their adaptation of CC includes loop iterations

$$V(G)* = V(G) + \prod_{i=1}^{n} P_{i}$$
$$P_{i} = U_{i} - L_{i} + 1$$

Where,  $P_i$  = No. of iterations of ith loop.  $U_i$  = upper bound of ith loop.  $L_i$  = lower bound of ith loop and V(G)\* = adjusted cyclomatic complexity for any control flow graph "G". The measure combines control flow and statements exercised.

Brian A. Neimeh. NPATH [Nei88] TODO.

Tevfik et al. [LB15] are providing a reasonable complutable measure: asymptotic path complexity covering nested structures and loops in comparison with CC and NPATH. TODO

## 2.1 Test Coverage

Test coverage metrics are providing quantitative representation of tested structures. The approach is to maximize coverage while minimizing testing effort. Each condition branches the flow into two control sub-paths, and determines the progression of the programm. The path of an isolated decision  $d_j$  thereby is given due to decisions and conditions (MC/DC) [RB11]. Let's define a condition  $c_j$  and it's path  $\gamma: C \times \Sigma \to C^*$ 

$$\Sigma = \{true, false\}$$

$$D \subset \{C^*, S, E\}, d_h \in D, d_h \mapsto \Sigma$$

The transition function alpha

$$\alpha: D \times \Sigma^* \to \Sigma \times D$$

The condition

$$C = \{c_0, c_1, c_2, c_3, ..., c_n\}, c_i \mapsto \Sigma$$

$$\varepsilon: C \to \Sigma \times C$$

and the transition ⊢

$$\vdash \subseteq (\Sigma^* \times D \times \Sigma) \times (\Sigma^* \times D \times \Sigma)$$

The possible combinations of conditions on  $\gamma$  are arising through  $c_j$ 's preceding and succeeding condition flow. An acyclic transition path through  $c_j$  is described due to passing each condition once

$$B_{\lambda j}^{T} = (v_h, d_h, b_h), \dots \vdash (v_k, d_k, b_k) \vdash^* (v_m, d_m, b_m)$$
  
=  $(c_h, b_h), \dots \vdash (c_j, b_j) \vdash^* (c_n, b_n)$ 

where

$$\alpha(d_m, v_m) \mapsto E$$

with the jacket

$$B_{\lambda} = (b_h, v_h, d_h) \vdash^* (b_m, v_m, d_m)$$

# 3 Hypothesis acyclic complexity

Instead of combining arithmetic and logic we propose a metric [Blo19] reflecting the logical test effort of path testing. The concept of basic paths described by [McC76] neglects loops and nesting. 100% sub-path combination coverage q is intricate due to exponential effort (Table 1). Conditions are providing the logical structure of programs (Listing 1-16). Loops and recursions are construed due to their boundary [RB11] and invariant, which is why their quantitative iteration increases probablility of condition coverage not condition path length. Let's define the inductive start of independent

$$\alpha_i = (c_0, true) \rightarrow (c_1), (c_0, false) \rightarrow (c_1),$$
  
 $(c_1, true) \rightarrow (E), (c_1, false) \rightarrow (E)$ 

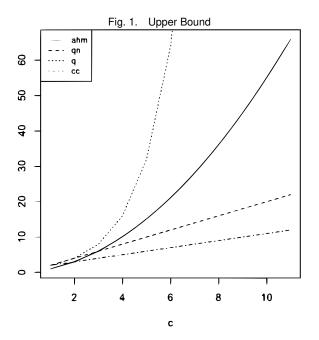
and dependent branches

$$\alpha_d = (c_0, true) \rightarrow (E), (c_0, false) \rightarrow (c_1),$$
  
 $(c_1, true) \rightarrow (E), (c_1, false) \rightarrow (E)$ 

Isolated condition paths are  $log(2^n)$  subset of all q paths. The spanning tree of the first branch expands four leaves, the latter three.

Nesting is diminishing the amount of paths, the effort of combinatorial parameter testing is unaffected. The fallacy of subjective perceived complexity increases contrary due to remembering previous conditions (Table 2).

		Table 1. Co	ndition formation	bound	
	O(n)	O(2n)	$O(n^2)$	$O(2^n)$	$O(4^{n-1})$
C	m	$q_2$	بح	q	P(n)
1	2	2 - 2	$\frac{1}{2} - 1$	2-2	1
2	3	3 - 4	1 - 3	3 - 4	4
3	4	4 - 6	$\frac{3}{2} - 6$	4 - 8	16
4	5	5 – 8	2 - 10	5 - 16	64
5	6	6 - 10	$2\frac{1}{2}-15$	6 - 32	256
6	7	7 - 12	3 - 21	7 - 64	1024
7	8	8 - 14	$3\frac{1}{2} - 28$	8 - 128	4096
9	10	10 - 18	$4\frac{1}{4} - 45$	10 - 512	65536
		•	•		•
19	20	20 - 38	$9\frac{1}{2} - 190$	20 - 524288	$6.87*10^{7}$
		'	·	•	•
49	50	50 – 98	$24\frac{1}{2} - 1225$	$50 - 5 * 10^{14}$	$7.92*10^{27}$



```
if (2>1) {
                                                                                     \phi_0 = 1
             Listing 1. plain singular
if (-1<1) { }
                                  \phi_0 = 1
                                                      if (8>k) {
                                                                                     \varphi_{0..1} = 1 + 1
                                                        if (0 < n) { } \varphi_{0..2} = 1 + 1 + 1
              Listing 2. orthogonal dual
if (3>1 \&\& 0<k) { } \phi_{0..1}=1+\frac{1}{2}
             Listing 3. tertiary orthogonal
                                                             Listing 12. singular nested parallel
if (2>1 \&\& 7>k \&\& 10>n) { } \phi_{0..2} = 1 + \frac{1}{2} + \frac{1}{3}
                                                   if (0<1) {
                                                      if (4>k) { }
                                                                      \varphi_{0..1} = 1 + 1
             Listing 4. orthogonal dual
                                                                          \phi_{0..2} = 1 + 1 + 2
                                                      if (8>n) { }
Listing 5. orthogonal dual nested
if (0<1) {
                                 \varphi_0 = 1
                                                            Listing 13. orthogonal singular parallel
                                                   if (0<1) {
                                                                                     \phi_0 = 1
    if (2>k) { } \varphi_{0..1} = 1+1
                                                      if (8>k) { }
                                                                                     \varphi_{0..1} = 1 + 1
}
                                                   if (0 < n) \{ \}
                                                                                    \varphi_{0..2} = 1 + 1 + 2
          Listing 6. tertiary orthogonal nested
                       \varphi_{0..1} = 1 + \frac{1}{2}
if (0<1 && 4>k) {
                               \varphi_{0..2} = 1 + \frac{1}{2} + 1
                                                                 Listing 14. dual parallel
  if (11>n) { }
                                                   if (0<1) { }
                                                                                     \phi_0 = 1
}
                                                   if (9>k \&\& 1<n) { } \varphi_{0..2}=1+2+\frac{1}{2}
                 Listing 7. tertiary
                                                                 Listing 15. dual parallel
if (0<1) { }
                                                                                     \phi_0 = 1
                                                   if (9>k) {
                                                                                   \varphi_{0..1} = 1 + 2
             Listing 8. tertiary parallel
if (1 < n) { } \varphi_{0..2} = 1 + 2 + 1
                Listing 9. parallel
if (2>1) { }
                                                          Listing 16. tertiary parallel different scope
                                  \phi_0 = 1
                                                   if (-4<1) { }
                                                                                     \varphi_0 = 1
if (8>k) { }
                               \varphi_{0..1} = 1 + 2
                                                   if (4 < k) { }
                                                                                   \varphi_{0..1} = 1 + 2
                                                   if (8>n) { }
                                                                                     \varphi_{0..2} = 1 + 2 + 3
        Listing 10. tertiary parallel identical scope
```

**if**  $(2>1 \mid | 0 < k \mid | 4>n)$  { }  $\phi_{0..2} = 1+1+1$ 

Listing 11. tertiary orthogonal nested

Table 2. Formation complexity Listing ξ loc  $q_2$ q  $1\frac{5}{6}$  $2\tfrac{1}{2}$  $2\frac{1}{2}$ 

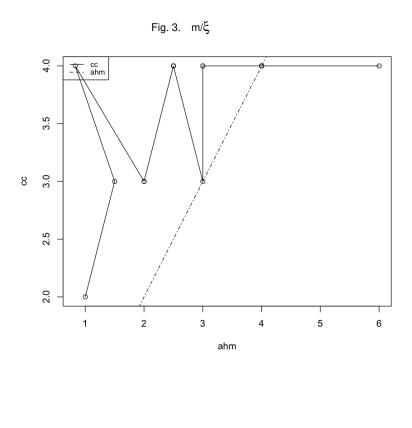
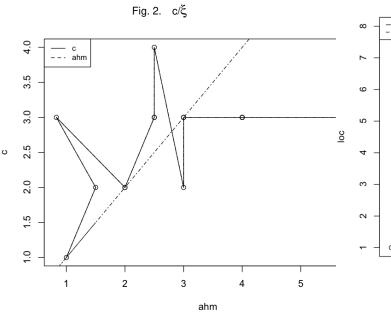
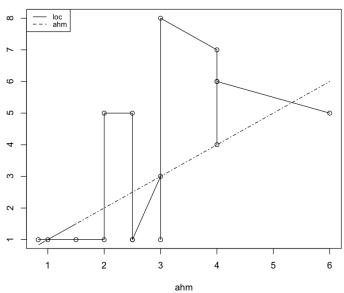
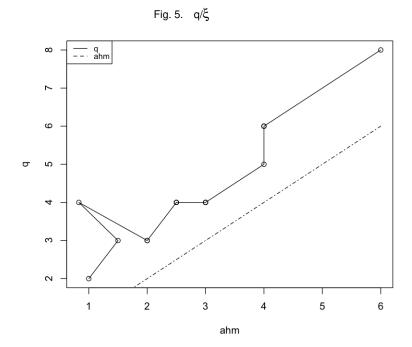


Fig. 4.  $loc/\xi$ 







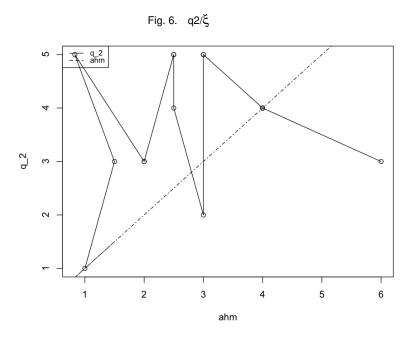


Table 3.  $\alpha_i$  flow matrix,  $q_2(\alpha_i) = 2$ 

	s	$c_0$	$c_1$	e
s		t		
$c_0$			(t,f)	
$c_1$				(t,f)
e				

Table 4.  $\alpha_d$  flow matrix,  $q_2(\alpha_d) = 3$ 

	s	$c_0$	$c_1$	e	
S		t			
$c_0$			f	t	
$c_1$				(t,f)	
e					

The exponential amount of condition path combinations q is parsed into control flow  $q_2$ .

$$n = |C|, \quad n \in \mathbb{N}$$
  
 $2^n <= q <= n+1$  (2)

When every condition is isolated the amount of condensed edges (enclosed scope paths)  $q_2$  in the condition flow matrix represents an intuitive measure (Table 2, 1, 3, 4).

The lower and upper bounds of possible isolated condensed condition paths are

$$2*n>=q_2>=n+1$$

$$C_e \subset C; \quad m_u = |C_e|+n$$
(3)

with  $C_e \subset C$  nested conditions. The metric  $m_u$  is undifferentiated regarding condition formation. Subpath combinations caused from parallel decision scope (flat-style) are neglected, as well as the subjective memory of decisions, therefor we define the nesting function  $\varphi(c_i)$ 

$$\frac{n}{2} <= \xi <= \frac{n(n+1)}{2} \tag{4}$$

Table 5. Complexity Risk [Cha05]

ξ	risk	
1-21	basic program	
22-45	intricate, moderate risk	
45-	circuitous, high risk	

The regional difficulty  $\delta_i$  of a decision  $d_i$  passage depends on its collocation  $k_i$  and conditions  $c_i$ .

$$\delta_i = \xi_i - \xi_h$$

$$\xi = \sum_{i=0}^{m} \delta_i = \sum_{j=0}^{n} \varphi(c_j) = \frac{k_i(k_i+1)}{2} + \sum_{j=0}^{n} \begin{cases} 1, & \text{if or } \\ \frac{1}{1+j}, & \text{if and} \end{cases}$$

(5)

#### 4 Conclusion

The suggested complexity measure  $\xi$  [Blo19] expresses the logical test effort of condensed path coverage, diminishing unapparent complex patterns quantifying control flow into rational numbers.

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